

# Team Notebook

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# 1 Data Structures

## 1.1 Dynamic Convex Hull Trick

```
const ld is_query = -(1LL << 62);
struct Line {
    ld m, b;
    mutable std::function<const Line *(>) succ;
    bool operator<(const Line &rhs) const {
        if (rhs.b != is_query) return m < rhs.m;
        const Line *s = succ();
        if (!s) return 0;
        ld x = rhs.m;
        return b - s->b < (s->m - m) * x;
    }
};
struct HullDynamic : public multiset<Line> { // dynamic
    upper hull + max value query
    bool bad(iterator y) {
        auto z = next(y);
        if (y == begin()) {
            if (z == end()) return 0;
            return y->m == z->m && y->b <= z->b;
        }
        auto x = prev(y);
        if (z == end()) return y->m == x->m && y->b <= x->b;
        return (x->b - y->b) * (z->m - y->m) >= (y->b - z->b) * (y->m - x->m);
    }
    void insert_line(ld m, ld b) {
        auto y = insert({m, b});
        y->succ = [=] { return next(y) == end() ? 0 : &*next(y); };
        if (bad(y)) {
            erase(y);
            return;
        }
        while (next(y) != end() && bad(next(y))) erase(next(y));
        while (y != begin() && bad(prev(y))) erase(prev(y));
    }
    ld best(ld x) {
        auto l = *lower_bound((Line) {x, is_query});
        return l.m * x + l.b;
    }
};
```

## 1.2 Heavy Light

```
const int N = 2000*100 + 10;
const int L = 20;
int par[N][L], h[N], fath[N], st[N], en[N], sz[N];
vector<int> c[N]; //Adjacency List
int dsz(int s, int p) {
    sz[s] = 1;
    for(int xt = 0; xt < (int)c[s].size(); xt++) {
        int x = c[s][xt];
        if( x != p ) {
            sz[s] += dsz( x , s );
            if( sz[x] > sz[c[s][0]] )
                swap( c[s][0], c[s][xt] );
        }
    }
    return sz[s];
}
void dfs(int s, int p) {
    static int ind = 0;
    st[s] = ind++;
    for(int k = 1; k < L; k++)
        par[s][k] = par[par[s][k-1]][k-1];
    for(int xt = 0; xt < (int)c[s].size(); xt++) {
        int x = c[s][xt];
        if( x == p ) continue;
        fath[x] = x;
        if( xt == 0 ) fath[x] = fath[s];
        h[x] = h[s] + 1;
        par[x][0] = s;
        dfs(x, s);
    }
    en[s] = ind;
}
int n, q;
void upset(int u, int w, int qv) {
    int stL = max( st[w] , st[fath[u]] );
    set( stL, st[u] + 1 , qv , 0, n , 1 ); //l,r,val,s,e,id
    if( stL == st[w] ) return;
    upset( par[fath[u]][0] , w , qv );
}
```

## 1.3 Implicit Treap

```
const int MAX=1e6+9;
typedef struct item * pitem;
struct item {
    int prior, value, cnt;
```

```
bool rev;
pitem l, r;
};
int cnt (pitem it) {
    return it ? it->cnt : 0;
}
void upd_cnt (pitem it) {
    if (it)
        it->cnt = cnt(it->l) + cnt(it->r) + 1;
}
void push (pitem it) {
    if (it && it->rev) {
        it->rev = false;
        swap (it->l, it->r);
        if (it->l) it->l->rev ^= true;
        if (it->r) it->r->rev ^= true;
    }
}
void merge (pitem & t, pitem l, pitem r) {
    push (l);
    push (r);
    if (!l || !r)
        t = l ? l : r;
    else if (l->prior > r->prior)
        merge (l->r, l->r, r), t = l;
    else
        merge (r->l, l, r->l), t = r;
    upd_cnt (t);
}
void split (pitem t, pitem & l, pitem & r, int key, int add = 0) {
    if (!t)
        return void( l = r = 0 );
    push (t);
    int cur_key = add + cnt(t->l);
    if (key <= cur_key)
        split (t->l, l, t->l, key, add), r = t;
    else
        split (t->r, t->r, r, key, add + 1 + cnt(t->l)), l = t;
    upd_cnt (t);
}
void reverse (pitem t, int l, int r) {
    pitem t1, t2, t3;
    split (t, t1, t2, l);
    split (t2, t2, t3, r-l+1);
    t2->rev ^= true;
    merge (t, t1, t2);
```

```

merge (t, t, t3);
}
void output (pitem t) {
    if (!t) return;
    push (t);
    output (t->l);
    printf ("%d ", t->value);
    output (t->r);
}

```

## 1.4 Link-Cut tree

```

Node x[N];
struct Node {
    int sz, label; /* size, label */
    Node *p, *pp, *l, *r; /* parent, path-parent, left, right
                           pointers */
    Node() { p = pp = l = r = 0; }
};
void update(Node *x) {
    x->sz = 1;
    if(x->l) x->sz += x->l->sz;
    if(x->r) x->sz += x->r->sz;
}
void rotr(Node *x) {
    Node *y, *z;
    y = x->p, z = y->p;
    if((y->l == x->r)) y->l->p = y;
    x->r = y, y->p = x;
    if((x->p == z)) {
        if(y == z->l) z->l = x;
        else z->r = x;
    }
    x->pp = y->pp;
    y->pp = 0;
    update(y);
}
void rotl(Node *x) {
    Node *y, *z;
    y = x->p, z = y->p;
    if((y->r == x->l)) y->r->p = y;
    x->l = y, y->p = x;
    if((x->p == z)) {
        if(y == z->l) z->l = x;
        else z->r = x;
    }
    x->pp = y->pp;
    y->pp = 0;
    update(y);
}

```

```

}
void splay(Node *x) {
    Node *y, *z;
    while(x->p) {
        y = x->p;
        if(y->p == 0) {
            if(x == y->l) rotr(x);
            else rotl(x);
        }
        else {
            z = y->p;
            if(y == z->l) {
                if(x == y->l) rotr(y), rotr(x);
                else rotl(x), rotr(x);
            }
            else { if(x == y->r) rotl(y), rotl(x);
                    else rotr(x), rotl(x);
                }
        }
        update(x);
    }
    Node *access(Node *x) {
        splay(x);
        if(x->r) {
            x->r->pp = x;
            x->r->p = 0;
            x->r = 0;
            update(x);
        }
        Node *last = x;
        while(x->pp) {
            Node *y = x->pp;
            last = y;
            splay(y);
            if(y->r) {
                y->r->pp = y;
                y->r->p = 0;
            }
            y->r = x;
            x->p = y;
            x->pp = 0;
            update(y);
            splay(x);
        }
        return last;
    }
    Node *root(Node *x) {
        access(x);
        while(x->l) x = x->l;
    }
}

```

```

splay(x);
return x;
}
void cut(Node *x) {
    access(x);
    x->l->p = 0;
    x->l = 0;
    update(x);
}
void link(Node *x, Node *y) {
    access(x);
    access(y);
    x->l = y;
    y->p = x;
    update(x);
}
Node *lca(Node *x, Node *y) {
    access(x);
    return access(y);
}
int depth(Node *x) {
    access(x);
    return x->sz - 1;
}
void init(int n) {
    for(int i = 0; i < n; i++) {
        x[i].label = i;
        update(&x[i]);
    }
}

```

## 1.5 Ordered Set

```

#include <ext/pb_ds/assoc_container.hpp> // Common file
#include <ext/pb_ds/tree_policy.hpp> // Including
tree_order_statistics_node_update
using namespace std;
using namespace __gnu_pbds;
typedef tree<int, null_type, less<int>, rb_tree_tag,
            tree_order_statistics_node_update> ordered_set;

ordered_set X;
X.insert(1);
X.insert(2);
X.insert(4);
X.insert(8);
X.insert(16);

cout<<*X.find_by_order(1)<<endl; // 2

```

```
cout<<*X.find_by_order(2)<<endl; // 4
cout<<*X.find_by_order(4)<<endl; // 16
cout<<(end(X)==X.find_by_order(6))<<endl; // true
```

```
cout<<X.order_of_key(-5)<<endl; // 0
cout<<X.order_of_key(1)<<endl; // 0
cout<<X.order_of_key(3)<<endl; // 2
cout<<X.order_of_key(4)<<endl; // 2
cout<<X.order_of_key(400)<<endl; // 5
```

## 1.6 Seg Lazy

```
const int MAX=1e6+100;
struct node{
    int val,lazy;
}seg[MAX*4];
int n,q;
void merge(int id, int left, int right)
{
    seg[id].val=seg[left].val+seg[right].val;
}
void build(int s=0,int e=n,int id=0)
{
    seg[id].lazy=0;
    if (e-s==1)
    {
        seg[id].val=0;
        return ;
    }
    int mid=(s+e)>>1;
    build(s,mid,id*2+1),build(mid,e,id*2+2);
    merge(id,id*2+1,id*2+2);
}
void shift(int id)
{
    if (seg[id].lazy)
    {
        seg[id*2+1].val+=seg[id].lazy;
        seg[id*2+2].val+=seg[id].lazy;
        seg[id].lazy=0;
    }
}
void update(int l,int r,int val, int s=0,int e=n,int id=0)
{
    if (e<=l || r<=s) return ;
    if (l<=s && e<=r)
    {
        seg[id].val+=val;
        seg[id].lazy+=val;
```

```
        return ;
    }
    int mid=(s+e)>>1;
    shift(id);
    update(l,r,val,s,mid,id*2+1);
    update(l,r,val,mid,e,id*2+2);
    merge(id,id*2+1,id*2+2);
}
```

## 1.7 Seg Persistent

```
typedef pair<pair<int,int>,int > ANS;
#define MX second
#define LE first.first
#define RI first.second

const int MAXN=1e5+9,LOG=22;

int root[MAXN], le[LOG * MAXN * 2], ri[LOG * MAXN * 2], sz,
    lleft[LOG * MAXN * 2], rright[LOG * MAXN * 2];
int maxi[LOG * MAXN * 2];
int n, q;
int h[MAXN], vec[MAXN];
pair<int, int> sec[MAXN];
int build(int b, int e){
    int id = sz++;
    if (e - b == 1) return
        id;
    int mid = (b + e) / 2;
    le[id] = build(b, mid);
    ri[id] = build(mid, e);
    return id;
}
void merge(int id, int b, int e, int mid){
    maxi[id] = max(maxi[le[id]], maxi[ri[id]]);
    maxi[id] = max(maxi[id], rright[le[id]] + lleft[ri[id]]);
    lleft[id] = lleft[le[id]];
    if (lleft[id] == (mid - b))
        lleft[id] += lleft[ri[id]];
    rright[id] = rright[ri[id]];
    if (rright[id] == (e - mid)) rright[id] += rright[le[id]];
}
int modify(int id, int b, int e, int x){
    int nid = sz++;
    if (e - b == 1){
        lleft[nid] = rright[nid] = maxi[nid] = 1;
        return nid;
    }
    int mid = (b+e)/2;
```

```
    le[nid]=le[id];
    ri[nid]=ri[id];
    if (x<mid)
        le[nid]=modify(le[nid],b,mid,x);
    else
        ri[nid] = modify(ri[nid], mid , e, x);
    merge(nid,b,e,mid);
    return nid;
}
ANS mg(ANS a, ANS b, int s1, int s2){
    ANS ret;
    ret.MX = max(a.MX, b.MX);
    ret.MX = max(ret.MX, a.RI + b.LE);
    ret.LE = a.LE;
    if (a.LE == s1) ret.LE += b.LE;
    ret.RI = b.RI;
    if (b.RI == s2) ret.RI += a.RI;
    return ret;
}
ANS get(int id, int b, int e, int l, int r){
    if (l <= b && e <= r)
        return {{maxi[id], lleft[id]}, rright[id]};
    if (r <= b || e <= l)
        return {{0, 0}, 0};

    int mid = (b + e) / 2;
    return mg(get(le[id], b, mid, l, r), get(ri[id], mid, e, l,
        r
        ), min(mid - b, max(0, mid - l)), min(e - mid, max(0, r -
            mid)));
}

void init(){
    copy(h, h + n, vec);
    sort(vec, vec + n);
    reverse(vec, vec + n);
    for (int i = 0; i < n; i++)
        sec[i] = {h[i], i};
    sort(sec, sec + n);
    reverse(sec, sec + n);
    root[0] = build(0, n);
    for (int i = 0; i < n; i++)
        root[i + 1] = modify(root[i], 0, n, sec[i].second);
}
int main(){
    ios::sync_with_stdio(false);
    cin.tie(0);
    cin >> n;
    for (int i = 0; i < n; i++)
```

```

init();
cin >> q;
while (q--){
    int l, r, w;
    cin >> l >> r >> w;
    l--;
    int b = 0, e = n, mid, ret = n;
    while (b <= e){
        mid = (b + e) / 2;
        if (get(root[mid], 0, n, l, r).MX >= w){
            ret = mid;
            e = mid - 1;
        }
        else
            b = mid + 1;
    }
    cout << vec[ret - 1] << "\n";
}
return 0;
}

```

## 1.8 Segment Beats

```

struct JiDriverSegmentTree {
    static const int T = (1 << 20);
    static const int INF = 1e9 + 7;
    struct Node {
        int max;
        long long sum;
    } tree[T];
    int n;
    void updateFromChildren(int v) {
        tree[v].sum = tree[2 * v].sum + tree[2 * v + 1].sum;
        tree[v].max = max(tree[2 * v].max, tree[2 * v + 1].max);
    }
    void build(int v, int l, int r, const vector<int>& inputArray) {
        if (l + 1 == r) {
            tree[v].max = tree[v].sum = inputArray[l];
        } else {
            int mid = (r + 1) / 2;
            build(2 * v, l, mid, inputArray);
            build(2 * v + 1, mid, r, inputArray);
            updateFromChildren(v);
        }
    }
    void build(const vector<int>& inputArray) {
        n = inputArray.size();
    }
}

```

```

    build(1, 0, n, inputArray);
}
void updateModEq(int v, int l, int r, int ql, int qr, int val) {
    if (qr <= l || r <= ql || tree[v].max < val) return;
    if (l + 1 == r) {
        tree[v].max %= val;
        tree[v].sum = tree[v].max;
        return;
    }
    int mid = (r + 1) / 2;
    updateModEq(2 * v, l, mid, ql, qr, val);
    updateModEq(2 * v + 1, mid, r, ql, qr, val);
    updateFromChildren(v);
}
void updateModEq(int ql, int qr, int val) {
    updateModEq(1, 0, n, ql, qr, val);
}
void updateEq(int v, int l, int r, int qi, int val) {
    if (l + 1 == r) {
        tree[v].max = tree[v].sum = val;
        return;
    }
    int mid = (l + r) / 2;
    if (qi < mid) {
        updateEq(2 * v, l, mid, qi, val);
    } else {
        updateEq(2 * v + 1, mid, r, qi, val);
    }
    updateFromChildren(v);
}
void updateEq(int qi, int val) {
    updateEq(1, 0, n, qi, val);
}
long long findSum(int v, int l, int r, int ql, int qr) {
    if (qr <= l || r <= ql) {
        return 0;
    }
    if (ql <= l && r <= qr) {
        return tree[v].sum;
    }
    int mid = (r + 1) / 2;
    return findSum(2 * v, l, mid, ql, qr) + findSum(2 * v + 1, mid, r, ql, qr);
}
long long findSum(int ql, int qr) {
    return findSum(1, 0, n, ql, qr);
}
} segTree;

```

## 1.9 Treap

```

struct item {
    int key, prior;
    item * l, * r;
    item() { }
    item (int key, int prior) : key(key), prior(prior), l(NULL), r(NULL) { }
};
typedef item * pitem;
void split (pitem t, int key, pitem & l, pitem & r) {
    if (!t)
        l = r = NULL;
    else if (key < t->key)
        split (t->l, key, l, t->l), r = t;
    else
        split (t->r, key, t->r, r), l = t;
}
void insert (pitem & t, pitem it) {
    if (!t)
        t = it;
    else if (it->prior > t->prior)
        split (t, it->key, it->l, it->r), t = it;
    else
        insert (it->key < t->key ? t->l : t->r, it);
}
void merge (pitem & t, pitem l, pitem r) {
    if (!l || !r)
        t = l ? l : r;
    else if (l->prior > r->prior)
        merge (l->r, l->r, r), t = l;
    else
        merge (r->l, l, r->l), t = r;
}
void erase (pitem & t, int key) {
    if (t->key == key)
        merge (t, t->l, t->r);
    else
        erase (key < t->key ? t->l : t->r, key);
}
pitem unite (pitem l, pitem r) {
    if (!l || !r) return l ? l : r;
    if (l->prior < r->prior) swap (l, r);
    pitem lt, rt;
    split (r, l->key, lt, rt);
    l->l = unite (l->l, lt);
    l->r = unite (l->r, rt);
    return l;
}
pitem root = NULL;

```

```
int main()
{
    ios_base::sync_with_stdio(false), cin.tie(0);
    item a = item(10,20);
    item b = item(10,20);
    insert(root, &a);
    insert(root, &b);
    return 0;
}
```

## 2 Dp Optimizations

### 2.1 Convex Hull Trick

```
#define F first
#define S second
#define pii pair<int, int>
#define pb psh_back

typedef long long ll;

vector<pair<ll, ll>> > cv;

ll barkhord(pair<ll, ll> p1, pair<ll, ll> p2) { //Make sure
    m1 > m2;
    return (p2.S - p1.S + p1.F - p2.F - 1) / (p1.F - p2.F);
}

ll get(ll t)
{
    int lo = -1, hi = cv.size() - 1;
    while(hi - lo > 1)
    {
        int mid = (lo + hi)/2;
        if(barkhord(cv[mid + 1], cv[mid]) <= t) lo = mid;
        else hi = mid;
    }
    return t * cv[hi].F + cv[hi].S;
}

//{m, h} in points.
void build(vector<pair<ll, ll>> > points) {

    sort(points.begin(), points.end(), cmp); //Make them
        increasing in m and decreasing in h.

    for (auto X : points)
    {
```

```
while((cv.size() >= 1 and cv.back().F == X.F) or
      (cv.size() >= 2 and barkhord(X, cv.back()) <= barkhord(cv
        .back(), cv[cv.size() - 2])))
    cv.pop_back();
    cv.pb(X);
}
//cv is convex hull.
}
```

### 2.2 Knuth

Knuth Optimization is applicable if  $C_{i,j}$  satisfied the following 2 conditions:

- 1- Quadrangle Inequality:  $C_{a,c} + C_{b,d} \leq C_{a,d} + C_{b,c}$  for  $a \leq b \leq c \leq d$
- 2- Monotonicity:  $C_{b,c} \leq C_{a,d}$  for  $a \leq b \leq c \leq d$

Then if the smallest  $k$  that gives optimal answer in  $dp_{i,j} = dp_{i-1,k} + C_{k,j}$  equals to  $A_{i,j}$  we have:

$$A_{i,j-1} \leq A_{i,j} \leq A_{i+1,j}$$

## 3 Geometry

### 3.1 Convex Hull 3D

```
struct pt{
    ld X,Y,Z;
    pt(ld x=0,ld y=0,ld z=0){X=x; Y=y; Z=z;}

    bool operator==(const pt& rhs) const {
        return (rhs.X==this->X && rhs.Y==this->Y && rhs.Z==this->Z);
    }

    bool operator<(const pt& rhs) const {
        return rhs.X > this->X || (rhs.X == this->X && rhs.Y >
            this->Y) || (rhs.X==this->X && rhs.Y==this->Y && rhs.Z >
            this->Z);
    }
};

pt operator -(pt p,pt q){return pt(p.X-q.X,p.Y-q.Y,p.Z-q.Z);
}

ld cross2d(pt p,pt q){return p.X*q.Y-p.Y*q.X;}
```

```
pt _cross(pt u,pt v){return pt(u.Y*v.Z-u.Z*v.Y,u.Z*v.X-u.X*v
    .Z,u.X*v.Y-u.Y*v.X); }

pt cross(pt o,pt p,pt q){return _cross(p-o,q-o);}
ld dot(pt p,pt q){return p.X*q.X+p.Y*q.Y+p.Z*q.Z;}
pt shift(pt p) {return pt(p.Y,p.Z,p.X);}
pt norm(pt p)
{
    if(p.Y<p.X || p.Z<p.X) p=shift(p);
    if(p.Y<p.X) p=shift(p);
    return p;
}

const int MAX=1000;

int n;
pt P[MAX];
vector<pt>ans;
queue<pair<int,int>> >Q;
set<pair<int,int>> >mark;

int main()
{
    cin>>n;
    int mn=0;
    for(int i=0;i<n;i++)
    {
        cin>>P[i].X>>P[i].Y>>P[i].Z;
        if(P[i]<P[mn]) mn=i;
    }
    int nx=(mn==0);
    for(int i=0;i<n;i++)
        if(i!=mn && i!=nx && cross2d(P[nx]-P[mn],P[i]-P[mn])>0)
            nx=i;
    Q.push({mn,nx});
    while(!Q.empty())
    {
        int v=Q.front().first,u=Q.front().second;
        Q.pop();
        if(mark.count({v,u})) continue;
        mark.insert({v,u});
        int p=-1;
        for(int q=0;q<n;q++)
            if(q!=v && q!=u)
                if(p==-1 || dot(cross(P[v],P[u],P[p]),P[q]-P[v])<0)
                    p=q;
        ans.push_back(norm(pt(v,u,p)));
        Q.push({p,u});
        Q.push({v,p});
    }
    sort(ans.begin(),ans.end());
```

```
ans.resize(unique(ans.begin(),ans.end())-ans.begin());
for(int i=0;i<ans.size();i++)
cout<<ans[i].X<<" "<<ans[i].Y<<" "<<ans[i].Z<<endl;
}
```

## 3.2 Delaunay Triangulation $O(N*N)$

```
struct Delaunay{
vector<pt> p;
vector<int> to, nxt, perm;
int add_edge(int q, int bef=-1){
int cnt = sz(to);
to.pb(q);
nxt.pb(-1);
if (bef != -1){
nxt[bef] = cnt;
to.pb(to[bef]);
nxt.pb(-1);
}
return cnt;
}
bool onconvex(int e){
if (nxt[nxt[nxt[e]]] != e) return true;
if (dir(p[to[e^1]], p[to[e]], p[to[nxt[e]]]) < 0) return
true;
return false;
}
int before(int e){
int cur = e, last = -1;
do{
last = cur;
cur = nxt[cur^1];
}while (cur != e);
return last^1;
}
void easy_triangulate(){
to.clear();
nxt.clear();
perm = vector<int>(sz(p));
for (int i = 0; i < sz(p); i++){
perm[i] = i;
sort(perm.begin(), perm.end(), [&] (int i, int j){
return p[i] < p[j]; });
sort(p.begin(), p.end());
if (dir(p[0], p[1], p[2]) > 0){
swap(p[1], p[2]);
swap(perm[1], perm[2]);
}
int to0 = add_edge(0), to0c = add_edge(2),
```

```
to1 = add_edge(1), to1c = add_edge(0),
to2 = add_edge(2), to2c = add_edge(1);
nxt[to1] = to2; nxt[to2] = to0;
nxt[to0] = to1; nxt[to0c] = to2c;
nxt[to2c] = to1c; nxt[to1c] = to0c;
int e = to0;
bool D2 = true;
for (int i = 3; i < sz(p); i++){
pt q = p[i];
if (D2){
int edge = e;
do{
if (dir(q, p[to[edge^1]], p[to[edge]])) {
D2 = false;
break;
}
edge = nxt[edge];
} while (edge != e);
}
vector<int> vis;
if (D2){
while (p[to[e^1]] < p[to[e]])
e = nxt[e];
vis.pb(e);
e = nxt[e];
}
else{
while (dir(q, p[to[e^1]], p[to[e]]) <= 0 || dir(q, p[to[e^1]], p[to[before(e)^1]]) < 0)
e = nxt[e];
while (dir(q, p[to[e^1]], p[to[e]]) > 0){
vis.pb(e);
e = nxt[e];
}
}
int b = before(vis[0]);
int ex = add_edge(i, b);
int last = ex^1;
for (int edge : vis){
nxt[last] = edge;
int eq = add_edge(i, edge);
nxt[edge] = eq;
nxt[eq] = last;
last = eq^1;
}
nxt[ex] = last;
nxt[last] = e;
}
}
bool incircle(pt a, pt b, pt c, pt d){
```

```
if (dir(a, b, c) < 0)
swap(b, c);
return a.z() * (b.x * (c.y - d.y) - c.x * (b.y - d.y)
+ d.x * (b.y - c.y))
- b.z() * (a.x * (c.y - d.y) - c.x * (a.y - d.y) + d.x *
(a.y - c.y))
+ c.z() * (a.x * (b.y - d.y) - b.x * (a.y - d.y) + d.x *
(a.y - b.y))
- d.z() * (a.x * (b.y - c.y) - b.x * (a.y - c.y) + c.x *
(a.y - b.y)) > 0;
}
bool locally(int e){
pt a = p[to[e^1]], b = p[to[e]], c = p[to[nxt[e]]], d = p[
to[nxt[e^1]]];
if (onconvex(e)) return true;
if (onconvex(e^1)) return true;
if (incircle(a, b, c, d)) return false;
if (incircle(b, a, d, c)) return false;
return true;
}
void flip(int e){
int a = nxt[e], b = nxt[a],
c = nxt[e^1], d = nxt[c];
nxt[d] = a;
nxt[b] = c;
to[e] = to[c];
nxt[a] = e;
nxt[e] = d;
to[e^1] = to[a];
nxt[c] = e^1;
nxt[e^1] = b;
}
void delaunay_triangulate(){
if (sz(to) == 0)
easy_triangulate();
bool *mark = new bool[sz(to)];
fill(mark, mark + sz(to), false);
vector<int> bad;
for (int e = 0; e < sz(to); e++){
if (!mark[e/2] && !locally(e)){
bad.pb(e);
mark[e/2] = true;
}
}
while (sz(bad)){
int e = bad.back();
bad.pop_back();
mark[e/2] = false;
if (!locally(e)){
```

```

    int to_check[4] = {nxt[e], nxt[nxt[e]], nxt[e^1], nxt[nxt[e^1]]};
    flip(e);
    for (int i = 0; i < 4; i++)
        if (!mark[to_check[i]/2] && !locally(to_check[i])){
            bad.pb(to_check[i]);
            mark[to_check[i]/2] = true;
        }
    }
}
for (int e = 0; e < sz(to); e++)
    assert(locally(e));
}
vector <tri> get_triangles(){
    vector <tri> res;
    bool *mark = new bool[sz(to)];
    fill(mark, mark + sz(to), false);
    for (int e = 0; e < sz(to); e++){
        if (mark[e]) continue;
        if (onconvex(e)) continue;
        pt a = p[to[e^1]], b = p[to[e]], c = p[to[nxt[e]]];
        mark[e] = mark[nxt[e]] = mark[nxt[nxt[e]]] = true;
        res.pb(tri(perm[to[e^1]], perm[to[e]], perm[to[nxt[e]]]))
        ;
    }
    return res;
}
vector <pair<ls, pt>> get_voronoi_edges(){
    vector <pair<ls, pt>> res;
    for (int e = 0; e < sz(to); e++){
        pt a = p[to[e^1]], b = p[to[e]], c = p[to[nxt[e]]], d = p[to[nxt[e^1]]];
        if (onconvex(e^1)){
            pt o1 = center(a, b, c),
                o2 = (a+b)/2;
            pt ab = (b-a);
            pt per(ab.y, -ab.x);
            o2 = o2 + per*100000; //infinity
            res.pb({{o1, o2}, a});
            continue;
        }
        if (onconvex(e)) continue;
        if (e&1) continue;
        res.pb({{center(a, b, c), center(b, a, d)}, a});
    }
    return res;
}
Delaunay(vector <pt> &p):p(p){
};

```

### 3.3 Delaunay Triangulation $O(N \cdot \log(n) \cdot \log(n))$

```

const int MAXN = 100 * 1000 + 10;
const int MAXLG = 20;
const int INF = 100 * 1000 * 1000 + 10;
const int MAXPOINTS = MAXN * MAXLG;
typedef pair<int, int> point;
struct tria{
    int a, b, c;
    tria(int _a, int _b, int _c){
        a = _a; b = _b; c = _c;
    }
    tria(){a = b = c = 0;}
};
struct Delaunay {
    typedef pair<point, int> ppi;
    typedef pair<int, int> pii;
    typedef pair<pii, int> pip;
    tria t[MAXPOINTS];
    bool mrk[MAXPOINTS];
    int last[MAXPOINTS];
    int childs[MAXPOINTS][3];
    int cnt;
    vector<ppi> points;
    set<pip> edges;
    vector<tria> res;
    int n;
    inline void add_edge(int a, int b, int c){
        edges.insert(pip(pii(min(a, b), max(a, b)), c));
    }
    inline void remove_edge(int a, int b, int c){
        edges.erase(pip(pii(min(a, b), max(a, b)), c));
    }
    int add_triangle(int a, int b, int c){
        if (cross(points[b].first - points[a].first, points[c].first - points[a].first) == 0)
            return -1;
        if (cross(points[b].first - points[a].first, points[c].first - points[a].first) < 0)
            swap(b, c);
        add_edge(a, b, cnt);
        add_edge(b, c, cnt);
        add_edge(c, a, cnt);
        t[cnt] = tria(a, b, c);
        childs[cnt][0] = childs[cnt][1] = childs[cnt][2] = -1;
        mrk[cnt] = false;
        last[cnt] = -1;
        cnt++;
        return cnt - 1;
    }
};

```

```

inline void remove_triangle(int v){
    childs[v][0] = childs[v][1] = childs[v][2] = -1;
    remove_edge(t[v].a, t[v].b, v);
    remove_edge(t[v].b, t[v].c, v);
    remove_edge(t[v].c, t[v].a, v);
}
inline void relax_edge(const int &a, const int &b){
    pii key(min(a, b), max(a, b));
    set<pip>::iterator it = edges.lower_bound(pip(key, -1));
    if (it == edges.end() || it->first != key)
        return;
    set<pip>::iterator it2 = it;
    it2++;
    if (it2 == edges.end() || it2->first != key)
        return;
    int c1 = t[it->second].a + t[it->second].b + t[it->second].c - a - b;
    int c2 = t[it2->second].a + t[it2->second].b + t[it2->second].c - a - b;
    if (c1 > n || c2 > n)
        return;
    if (inCircle(points[a].first, points[b].first, points[c1].first, points[c2].first) < 0 ||
        inCircle(points[a].first, points[b].first, points[c2].first, points[c1].first) < 0)
    {
        int v1 = it->second;
        int v2 = it2->second;
        remove_triangle(v1);
        remove_triangle(v2);
        mrk[v1] = mrk[v2] = true;
        childs[v1][0] = childs[v2][0] = add_triangle(a, c1, c2);
        childs[v1][1] = childs[v2][1] = add_triangle(b, c1, c2);
        relax(childs[v1][0]);
        relax(childs[v1][1]);
    }
}
inline void relax(int v){
    relax_edge(t[v].a, t[v].b);
    relax_edge(t[v].b, t[v].c);
    relax_edge(t[v].c, t[v].a);
}
inline bool inLine(int a, int b, int c){
    return cross(points[b].first - points[a].first, points[c].first - points[a].first) >= 0;
}
inline bool inTriangle(int a, int b, int c, int d){
    return inLine(a, b, d) && inLine(b, c, d) && inLine(c, a, d);
}

```



```

void find(int v, int p, int cl){
    if (last[v] == cl)
        return;
    bool reached = false;
    last[v] = cl;
    for (int i = 0; i < 3; i++){
        int u = childs[v][i];
        if (u == -1)
            continue;
        reached = true;
        if (mrk[u] || inTriangle(t[u].a, t[u].b, t[u].c, p))
            find(u, p, cl);
    }
    if (reached)
        return ;
    remove_triangle(v);
    childs[v][0] = add_triangle(p, t[v].a, t[v].b);
    childs[v][1] = add_triangle(p, t[v].b, t[v].c);
    childs[v][2] = add_triangle(p, t[v].c, t[v].a);
    relax(childs[v][0]);
    relax(childs[v][1]);
    relax(childs[v][2]);
}

void getRes(int v, int cl){
    if (last[v] == cl)
        return;
    last[v] = cl;
    bool reached = false;
    for (int i = 0; i < 3; i++){
        int u = childs[v][i];
        if (u == -1)
            continue;
        reached = true;
        getRes(u, cl);
    }
    if (!reached && t[v].a < n && t[v].b < n && t[v].c < n)
        res.push_back(t[v]);
}

vector<tria> delaunay(vector<point> v){
    cnt = 0;
    int cl = 0;
    points.clear();
    for (int i = 0; i < v.size(); i++)
        points.push_back(ppi(v[i], i));
    random_shuffle(points.begin(), points.end());
    n = points.size();
    points.push_back(ppi(point(INF, INF), n));
    points.push_back(ppi(point(-INF * 3, INF), n + 1));

```

```

    points.push_back(ppi(point(INF, -INF * 3), n + 2));
    int root = add_triangle(n, n + 1, n + 2);
    for (int i = 0; i < n; i++){
        // cout << "0000000000" << inTriangle(n,n+1, n+2, i) << endl;
        find(root, i, cl++);
    }
    res.clear();
    getRes(root, cl++);
    for (int i = 0; i < res.size(); i++){
        res[i].a = points[res[i].a].second;
        res[i].b = points[res[i].b].second;
        res[i].c = points[res[i].c].second;
    }
    return res;
}

long double getRadius(pointD a, pointD b, pointD c){
    pointD v1 = norm(b - a) + ((a + b) / 2);
    pointD v2 = norm(c - b) + ((b + c) / 2);
    pointD center = intersect((a + b) / 2, v1, (b + c) / 2, v2);
    ;
    pointD ret = a - center;
    return sqrt(dot(ret, ret));
}

Delaunay d;
int main(){
    srand(2019);
    ios::sync_with_stdio(false);
    cin.tie(0);
    int n;
    cin >> n;
    vector<point> v;
    for (int i = 0; i < n; i++){
        int x, y;
        cin >> x >> y;
        v.push_back(point(x, y));
    }
    vector<tria> ans = d.delaunay(v);
    long double res = 0;
    for (int i = 0; i < ans.size(); i++){
        res = max(res, getRadius(v[ans[i].a], v[ans[i].b], v[ans[i].c]));
    }
    cout.precision(6);
    cout << fixed << res << endl;
}

```

### 3.4 Find Polynomial from it's Points

$$P(x) = \sum_{i=1}^n y_i \prod_{j=1, j \neq i}^n \frac{x-x_j}{x_i-x_j}$$

### 3.5 Geometry Duality

duality of point (a, b) is  $y = ax - b$  and duality of line  $y = ax + b$  is (a, -b)

Properties:

1. p is on l iff  $l^*$  is in  $p^*$
2. p is in intersection of  $l_1$  and  $l_2$  iff  $l_1^*$  and  $l_2^*$  lie on  $p^*$
3. Duality preserve vertical distance
4. Translating a line in primal to moving vertically in dual
5. Rotating a line in primal to moving a point along a non-vertical line
6.  $li \cap lj$  is a vertex of lower envelope  $\iff (li^*, lj^*)$  is an edge of upper hull in dual

### 3.6 Half Planes

```

typedef int T;
typedef long long T2;
typedef long long T4; // maybe int128_t

```

```

const int MAXLINES = 100 * 1000 + 10;
const int INF = 20 * 1000 * 1000;

```

```

typedef pair<T, T> point;
typedef pair<point, point> line;

```

```

#define X first
#define Y second
#define A first
#define B second

```

```

// REPLACE ZERO WITH EPS FOR DOUBLE

```

```

point operator - (const point &a, const point &b) {
    return point(a.X - b.X, a.Y - b.Y);
}

```

```

}

T2 cross(point a, point b) {
    return ((T2)a.X * b.Y - (T2)a.Y * b.X);
}

bool cmp(line a, line b) {
    bool aa = a.A < b.A;
    bool bb = b.A < b.B;
    if (aa == bb) {
        point v1 = a.B - a.A;
        point v2 = b.B - b.A;
        if (cross(v1, v2) == 0)
            return cross(b.B - b.A, a.A - b.A) > 0;
        else
            return cross(v1, v2) > 0;
    }
    else
        return aa;
}

bool parallel(line a, line b) {
    return cross(a.B - a.A, b.B - b.A) == 0;
}

pair<T2, T2> alpha(line a, line b) {
    return pair<T2, T2>(cross(b.A - a.A, b.B - b.A),
        cross(a.B - a.A, b.B - b.A));
}

bool fcmp(T4 f1t, T4 f1b, T4 f2t, T4 f2b) {
    if (f1b < 0) {
        f1t *= -1;
        f1b *= -1;
    }
    if (f2b < 0) {
        f2t *= -1;
        f2b *= -1;
    }
    return f1t * f2b < f2t * f1b; // check with eps
}

bool check(line a, line b, line c) {
    bool crs = cross(c.B - c.A, a.B - a.A) > 0;
    pair<T2, T2> a1 = alpha(a, b);
    pair<T2, T2> a2 = alpha(a, c);
    bool alp = fcmp(a1.A, a1.B, a2.A, a2.B);
    return (crs ^ alp);
}

bool notin(line a, line b, line c) { // is intersection of a
    and b in ccw direction of c?
    if (parallel(a, b))
        return false;
    if (parallel(a, c))
        return cross(c.B - c.A, a.A - c.A) < 0;
    if (parallel(b, c))
        return cross(c.B - c.A, b.A - c.A) < 0;
    return !(check(a, b, c) && check(b, a, c));
}

void print(vector<line> lines) {
    cerr << " @ @ @ " << endl;
    for (int i = 0; i < lines.size(); i++)
        cerr << lines[i].A.X << " " << lines[i].A.Y << " -> " <<
            lines[i].B.X << " " << lines[i].B.Y << endl;
    cerr << " @ @ @ " << endl << endl;
}

line dq[MAXLINES];

vector<line> half_plane(vector<line> lines) {
    lines.push_back(line(point(INF, -INF), point(INF, INF)));
    lines.push_back(line(point(-INF, INF), point(-INF, -INF)));
    lines.push_back(line(point(-INF, -INF), point(INF, -INF)));
    lines.push_back(line(point(INF, INF), point(-INF, INF)));
    sort(lines.begin(), lines.end(), cmp);
    int ptr = 0;
    for (int i = 0; i < lines.size(); i++)
        if (i > 0 &&
            (lines[i - 1].A < lines[i - 1].B) == (lines[i].A < lines[
                i].B) &&
            parallel(lines[i - 1], lines[i]))
            continue;
        else
            lines[ptr++] = lines[i];
    lines.resize(ptr);
    if (lines.size() < 2)
        return lines;
    //print(lines);
    int f = 0, e = 0;
    dq[e++] = lines[0];
    dq[e++] = lines[1];
    for (int i = 2; i < lines.size(); i++) {
        while (f < e - 1 && notin(dq[e - 2], dq[e - 1], lines[i]))
            e--;
        //print(vector<line>(dq + f, dq + e));
        if (e == f + 1) {

```

```

            T2 crs = cross(dq[f].B - dq[f].A, lines[i].B - lines[i].A
                ) ;
            if (crs < 0)
                return vector<line>();
            else if (crs == 0 && cross(lines[i].B - lines[i].A, dq[f
                ].B - lines[i].A) < 0)
                return vector<line>();
        }
        while (f < e - 1 && notin(dq[f], dq[f + 1], lines[i]))
            f++;
        dq[e++] = lines[i];
    }
    while (f < e - 1 && notin(dq[e - 2], dq[e - 1], dq[f]))
        e--;
    while (f < e - 1 && notin(dq[f], dq[f + 1], dq[e - 1]))
        f++;
    vector<line> res;
    res.resize(e - f);
    for (int i = f; i < e; i++)
        res[i - f] = dq[i];
    return res;
}

```

```

int main() {
    int n;
    cin >> n;
    vector<line> lines;
    for (int i = 0; i < n; i++) {
        int x1, y1, x2, y2;
        cin >> x1 >> y1 >> x2 >> y2;
        lines.push_back(line(point(x1, y1), point(x2, y2)));
    }
    lines = half_plane(lines);
    cout << lines.size() << endl;
    for (int i = 0; i < lines.size(); i++)
        cout << lines[i].A.X << " " << lines[i].A.Y << " " <<
            lines[i].B.X << " " << lines[i].B.Y << endl;
}

```

### 3.7 Minimum Enclosing Circle

```

const int N = 1000*100 + 10;
struct point {
    ll x, y, z;
};
typedef vector<point> circle;
bool ccw(point a, point b, point c) {

```

```

    return (b.x - a.x) * (c.y - a.y) - (c.x - a.x) * (b.y - a.y) >= 0;
}
bool incircle( circle a , point p ) {
    if( sz(a) == 0 ) return false;
    if( sz(a) == 1 )
        return a[0].x == p.x && a[0].y == p.y;
    if( sz(a) == 2 ) {
        point mid = {a[0].x+a[1].x, a[0].y+a[1].y};
        return sq(2*p.x-mid.x) + sq( 2*p.y-mid.y) <= sq(2*a[0].x-mid.x) + sq(2*a[0].y-mid.y);
    }
    if( !ccw(a[0], a[1], a[2]) )
        swap(a[0], a[2]);
    return incircle(a[0],a[1],a[2], p) >= 0;
}
point a[N];
circle solve(int i, circle curr) {
    assert(curr.size() <= 3);
    if( i == 0 )
        return curr;
    circle ret = solve(i-1, curr);
    if( incircle(ret, a[i-1]) )
        return ret;
    curr.pb(a[i-1]);
    return solve(i-1, curr);
}
int n;
void gg(circle c) {
    if( sz(c) == 1 ) {
        cout << ld(a[0].x) << " " << ld(a[0].y) << endl;
        cout << 0.1 << endl;
        return;
    }
    if( sz(c) == 2 ) {
        point mid = {c[0].x+c[1].x, c[0].y+c[1].y};
        ld ret = sqrt(sq(2*c[0].x-mid.x) + sq(2*c[0].y-mid.y)
            )/2;
        cout << ld(mid.x) / 2 << " " << ld(mid.y) / 2 << endl;
        cout << ret << endl;
    } else {
        lpt a[3];
        for(int i = 0; i < 3; i++)
            a[i] = lpt(c[i].x, c[i].y);
        lpt A = ld(0.5) * (a[0] + a[1]), C = ld(0.5) * (a[1] + a[2]);
        lpt B = A + (a[1] - a[0]) * lpt(0, 1), D = C + (a[2] - a[1]) * lpt(0, 1);
        lpt center = intersection( A , B , C , D );
        ld ret = abs(a[0] - center);
    }
}

```

```

    cout << center.real() << " " << center.imag() << endl;
    ;
    cout << ret << endl;
}
}
int main(){
    cin >> n;
    for(int i = 0; i < n; i++) {
        cin >> a[i].x >> a[i].y;
        a[i].z = sq(a[i].x) + sq(a[i].y);
    }
    srand(time(NULL));
    for(int i = 1; i < n; i++)
        swap(a[i], a[rand()%(i+1)]);
    circle ans = solve(n, circle());
    cout << fixed << setprecision(3) ;
    gg(ans);
    return 0;
}

```

### 3.8 Points Inside Polygon

$$S = I + B / 2 - 1$$

### 3.9 Primitives

```

typedef long double ld;
typedef complex<ld> pt;
typedef vector<pt> poly;
#define x real()
#define y imag()

typedef pair<pt, pt> line;
// +, -, * scalar well defined
const ld EPS = 1e-12;
const ld PI = acos(-1);
const int ON = 0, LEFT = 1, RIGHT = -1, BACK = -2, FRONT = 2, IN = 3, OUT = -3;

inline bool Lss(ld a, ld b){ return a - b < -EPS; }
inline bool Grt(ld a, ld b){ return a - b > +EPS; }
inline bool Leq(ld a, ld b){ return a - b < +EPS; }
inline bool Geq(ld a, ld b){ return a - b > -EPS; }
inline bool Equ(ld a, ld b){ return abs(a-b) < EPS; }

bool byX(const pt &a, const pt &b)
{
    if (Equ(a.x, b.x)) return Lss(a.y, b.y);
}

```

```

return Lss(a.x, b.x);
}
bool byY(const pt &a, const pt &b){
    if (Equ(a.y, b.y)) return Lss(a.x, b.x);
    return Lss(a.y, b.y);
}
struct cmpXY{ inline bool operator()(const pt &a, const pt &b)const { return byX(a, b); } };
struct cmpYX{ inline bool operator()(const pt &a, const pt &b)const { return byY(a, b); } };
bool operator < (const pt &a, const pt &b){ return byX(a, b) ; }

istream& operator >> (istream& in, pt p){ld valx,valy; in>> valx>>valy; p={valx,valy}; return in;}
ostream& operator << (ostream& out, pt p){out<<p.x<< ' ' <<p.y ; return out;}

ld dot(pt a, pt b){return conj(a) * b).x;}
ld cross(pt a, pt b){return conj(a) * b).y;}
ld disSQ(pt a, pt b){return norm(a - b);}
ld dis(pt a, pt b){return abs(a - b);}
ld angleX(pt a, pt b){return arg(b - a);}
ld slope(pt a, pt b){return tan(angleX(a,b));}
//polar(r,theta) -> cartesian
pt rotate(pt a, ld theta){return a * polar((ld)1, theta);}
pt rotatePiv(pt a, ld theta, pt piv){return (a - piv) * polar((ld)1, theta) + piv;}
ld angleABC(pt a, pt b, pt c){return abs(remainder(arg(a-b) - arg(c-b), 2.0 * PI));}
pt proj(pt p, pt v){return v * dot(p,v) / norm(v);}
pt projPtLine(pt a, line l){return proj(a - l.first,l.second -l.first)+l.first;}
ld disPtLine(pt p, line l){return dis(p-l.first, proj(p-l.first,l.second-l.first));}

int relpos(pt a, pt b, pt c) //c to a-b
{
    b = b-a, c = c-a;
    if (Grt(cross(b,c), 0)) return LEFT;
    if (Lss(cross(b,c), 0)) return RIGHT;
    if (Lss(dot(b,c), 0)) return BACK;
    if (Lss(dot(b,c), abs(b))) return FRONT;
    return ON;
}
int relpos(line l, pt b){return relpos(l.first, l.second, b) ;}

pair<pt,bool> intersection(line a, line b)
{
}

```

```

ld c1 = cross(b.first - a.first, a.second - a.first);
ld c2 = cross(b.second - a.first, a.second - a.first);
if (Equ(c1,c2))
    return {{-1,-1},false};
return {(c1 * b.second - c2 * b.first) / (c1 - c2), true};
}
bool intersect(line a, line b)
{
    pair<pt, bool> ret = intersection(a,b);
    if (!ret.second) return false;
    if (relpos(a, ret.first) == ON and relpos(b, ret.first) ==
        ON)
        return true;
    return false;
}
bool isconvex(poly &pl)
{
    int n = pl.size();
    bool neg = false, pos = false;
    for (int i=0;i<n;i++)
    {
        int rpos = relpos(pl[i], pl[(i+1)%n], pl[(i+2)%n]);
        if (rpos == LEFT) pos = true;
        if (rpos == RIGHT) neg = true;
    }
    return !(neg&pos);
}
int crossingN(poly &pl, pt a)
{
    int n = pl.size();
    pt b = a;
    for (pt p:pl)
        b.real(max(b.x,p.y));
    int cn = 0;
    for (int i=0;i<n;i++)
    {
        pt p = pl[i], q=pl[(i+1)%n];
        if (intersect({a,b},{p,q}) && (relpos({p,q},a)!= RIGHT ||
            relpos({p,q},b) != RIGHT))
            cn ++;
    }
    return cn;
}
int pointInPoly(poly &pl, pt p)
{
    int n = pl.size();
    for (int i=0;i<n;i++)
        if (relpos(pl[i], pl[(i+1)%n], p) == ON)
            return ON;
    return crossingN(pl,p)%2? IN : OUT;
}

```

```

}
poly getHull(poly &pl, bool lower)
{
    sort(pl.begin(), pl.end(), byX);
    poly res;
    int n = res.size();
    for (auto p : pl)
    {
        while (n >= 2 && relpos(res[n-2], res[n-1], p) == (lower?
            RIGHT : LEFT))
            res.pop_back(), n--;
        res.push_back(p), n++;
    }
    return res;
}
pair<pt, pt> nearestPair(poly &pl)
{
    int n = pl.size();
    sort(pl.begin(), pl.end(), byX);
    multiset<pt, cmpYX> s;
    ld rad = abs(pl[1] - pl[0]);
    pair<pt, pt> res = {pl[0], pl[1]};
    int l = 0, r = 0;
    for (int i=0;i<n;i++)
    {
        while (l<r && Geq(pl[i].x - pl[l].x, rad))
            s.erase(pl[l++]);
        while (r<l && Leq(pl[r].x, pl[i].x))
            s.insert(pl[r++]);
        for (auto it = s.lower_bound(pt(pl[i].x, pl[i].y-rad)); it
            != s.end(); it++)
        {
            if (Grt(it->y, pl[i].y+rad))
                break;
            ld cur = abs(pl[i] - (*it));
            if (Lss(cur, rad))
                rad = cur, res = {*it, pl[i]};
        }
    }
    return res;
}
typedef struct circle{
    pt c;
    ld r;
} cir;
//number of common tangent lines

```

```

int tangentCnt(cir c1, cir c2)
{
    ld d = abs(c1.c-c2.c);
    if (Grt(d, c1.r+c2.r)) return 4; //outside
    if (Equ(d, c1.r+c2.r)) return 3; //tangent outside
    if (Lss(d, c1.r+c2.r) && Grt(d, abs(c1.r-c2.r))) return 2;
        //interfere
    if (Equ(d, abs(c1.r-c2.r))) return 1; //tangent inside
    return 0; //inside
}
line intersection(line l, cir c)
{
    ld dis = disPtLine(c.c, l);
    ld d = sqrt(c.r*c.r - dis*dis);
    pt p = projPtLine(c.c, l);
    pt vec = (l.second-l.first)/abs(l.second - l.first);
    return {p + d * vec, p - d * vec};
}
/*
    0 = other is inside this, zero point
    1 = other is tangent inside of this, one point
    2 = other is intersect with this, two point
    3 = other is tangent outside of this, one point
    4 = other is outside of this, zero point
*/
pair<int, vector<pt> > intersect(cir c, cir other) {
    ld r = c.r;
    pt o = c.c;
    vector<pt> v;
    ld sumr = other.r + r;
    ld rr = r - other.r;
    ld d = dis(o, other.c);
    ld a = (r*r - other.r*other.r + d*d)/(2*d);
    ld h = sqrt(r*r-a*a);
    pt p2 = a * (other.c - o) / d;
    if (Equ(sumr - d, 0)) {
        v.push_back(p2);
        return make_pair(3, v);
    }
    if (Equ(rr - d, 0)) {
        v.push_back(p2);
        return make_pair(1, v);
    }
    if (d <= rr)
        return make_pair(0, v);
    if (d >= sumr)
        return make_pair(4, v);
}

```

```

pt p3(p2.x + h*(other.c.y - o.y)/d, p2.y - h*(other.c.x - o
.x)/d);
pt p4(p2.x - h*(other.c.y - o.y)/d, p2.y + h*(other.c.x - o
.x)/d);
v.push_back(p3);
v.push_back(p4);
return make_pair(2, v);
}
ld arcarea(ld l, ld r, ld R){//circle with radius(r)
    intersect with circle with radius (R) and distance
    between centers equal to (d)
ld cosa = (l*l + r*r - R*R)/(2.0*r*l);
ld a = acos(cosa);
return r*r*(a - sin(2*a)/2);
}

```

### 3.10 Rotating Calipers

```

vector<pair<pt, pt>> get_antipodals(poly &p)
{
    int n = p.size();
    sort(p.begin(), p.end(), byX);
    vector<pt> U, L;
    for (int i = 0; i < n; i++){
        while (U.size() > 1 && relpos(U[U.size()-2], U[U.size()
-1], p[i]) != LEFT)
            U.pop_back();
        while (L.size() > 1 && relpos(L[L.size()-2], L[L.size()
-1], p[i]) != RIGHT)
            L.pop_back();
        U.push_back(p[i]);
        L.push_back(p[i]);
    }
    vector<pair<pt, pt>> res;
    int i = 0, j = L.size()-1;
    while (i+1 < (int)U.size() || j > 0){
        res.push_back({U[i], L[j]});
        if (i+1 == (int)U.size())
            j--;
        else if (j == 0)
            i++;
        else if (cross(L[j]-L[j-1], U[i+1]-U[i]) >= 0) i++;
        else
            j--;
    }
    return res;
}

```

### 3.11 Triangles

```

pt bary(pt A, pt B, pt C, ld a, ld b, ld c) {
    return (A*a + B*b + C*c) / (a + b + c);
}
pt centroid(pt A, pt B, pt C) {
    // geometric center of mass
    return bary(A, B, C, 1, 1, 1);
}
pt circumcenter(pt A, pt B, pt C) {
    // intersection of perpendicular bisectors
    double a = norm(B - C), b = norm(C - A), c = norm(A - B);
    return bary(A, B, C, a*(b+c-a), b*(c+a-b), c*(a+b-c));
}
pt incenter(pt A, pt B, pt C) {
    // intersection of internal angle bisectors
    return bary(A, B, C, abs(B-C), abs(A-C), abs(A-B));
}
pt orthocenter(pt A, pt B, pt C) {
    // intersection of altitudes
    double a = norm(B - C), b = norm(C - A), c = norm(A - B);
    return bary(A, B, C, (a+b-c)*(c+a-b), (b+c-a)*(a+b-c), (c
+a-b)*(b+c-a));
}
pt excenter(pt A, pt B, pt C) {
    // intersection of two external angle bisectors
    double a = abs(B - C), b = abs(A - C), c = abs(A - B);
    return bary(A, B, C, -a, b, c);

    //// NOTE: there are three excenters
    // return bary(A, B, C, a, -b, c);
    // return bary(A, B, C, a, b, -c);
}

```

### 3.12 Useful Geometry Facts

Area of triangle with sides  $a, b, c$ :  $\sqrt{S(S-a)(S-b)(S-c)}$  where  $S = (a+b+c)/2$

Area of equilateral triangle:  $s^2 * \sqrt{3} / 4$  where  $s$  is side length

Pyramid and cones volume:  $1/3 \text{ area}(\text{base}) * \text{height}$

if  $p_1=(x_1, y_1), p_2=(x_2, y_2), p_3=(x_3, y_3)$  are points on circle, the center is

$$x = -((x_2^2 - x_1^2 + y_2^2 - y_1^2)*(y_3 - y_2) - (x_2^2 - x_3^2 + y_2^2 - y_3^2)*(y_1 - y_2)) / (2*(x_1 - x_2)*(y_3 - y_2) - 2*($$

$$x_3 - x_2)*(y_1 - y_2))$$

$$y = -((y_2^2 - y_1^2 + x_2^2 - x_1^2)*(x_3 - x_2) - (y_2^2 - y_3^2 + x_2^2 - x_3^2)*(x_1 - x_2)) / (2*(y_1 - y_2)*(x_3 - x_2) - 2*(y_3 - y_2)*(x_1 - x_2))$$

## 4 Graph

### 4.1 2sat

```

vector<int> adj[2 * N], jda[2 * N], top;
bool mark[2 * N];
int c[2 * N];
void add_clause(int x, int y) {
    adj[x ^ 1].pb(y);
    adj[y ^ 1].pb(x);
    jda[y].pb(x ^ 1);
    jda[x].pb(y ^ 1);
}
void dfs(int u) {
    mark[u] = 1;
    for(auto v : adj[u]) if(!mark[v]) dfs(v);
    top.pb(u);
}
void sfd(int u, int col) {
    c[u] = col;
    for(auto v : jda[u]) if(!c[v]) sfd(v, col);
}
vector<int> two_sat(int n) {
    memset(mark, 0, sizeof mark);
    memset(c, 0, sizeof c);
    top.clear();
    for(int i = 2; i < 2 * n + 2; i++) if(!mark[i]) dfs(i);
    int cnt = 1;
    while(top.size()) {
        int x = top.back(); top.pop_back();
        if(!c[x]) sfd(x, cnt++);
    }
    vector<int> ans, ans1;
    ans1.pb(-1);
    for(int i = 1; i <= n; i++) {
        if(c[2 * i] == c[2 * i + 1]) return ans1;
        if(c[2 * i] > c[2 * i + 1]) ans.pb(i);
    }
    return ans;
}

```

## 4.2 Biconnected-Component

```
vector<int> adj[N];
bool vis[N];
int dep[N], par[N], lowlink[N];
vector<vector<int>> comp;
stack<int> st;
void dfs(int u, int depth = 0, int parent = -1){
    vis[u] = true;
    dep[u] = depth;
    par[u] = parent;
    lowlink[u] = depth;
    st.push(u);
    for (int i = 0; i < adj[u].size(); i++){
        int v = adj[u][i];
        if (!vis[v])
        {
            dfs(v, depth + 1, u);
            lowlink[u] = min(lowlink[u], lowlink[v]);
        }
        else
            lowlink[u] = min(lowlink[u], dep[v]);
    }
    if (lowlink[u] == dep[u] - 1){
        comp.push_back(vector<int>());
        while (st.top() != u)
        {
            comp.back().push_back(st.top());
            st.pop();
        }
        comp.back().push_back(u);
        st.pop();
        comp.back().push_back(par[u]);
    }
}
void bicon(int n){
    for (int i = 0; i < n; i++){
        if (!vis[i])
            dfs(i);
    }
}
```

## 4.3 Directed Minimum Spanning Tree MN

```
/*
GETS:
    call make_graph(n) at first
    you should use add_edge(u,v,w) and
    add pair of vertices as edges (vertices are 0..n-1)
GIVES:
```

```
output of dmst(v) is the minimum arborescence with root v
in directed graph
(-1 if it hasn't a spanning arborescence with root v)
0(mn)
*/
const int INF = 2e7;
struct MinimumAborescence{
    int n;
    struct edge {
        int src, dst;
        int weight;
    };
    vector<edge> edges;
    void make_graph(int _n) {
        n=_n;
        edges.clear();
    }
    void add_edge(int u, int v, int w) {
        edges.push_back({u, v, w});
    }
    int dmst(int r) {
        int N = n;
        for (int res = 0; ; ) {
            vector<edge> in(N, {-1,-1,(int)INF});
            vector<int> C(N, -1);
            for (auto e: edges)
                if (in[e.dst].weight > e.weight)
                    in[e.dst] = e;
            in[r] = {r, r, 0};

            for (int u = 0; u < N; ++u) { // no coming edge ==> no
                aborescence
                if (in[u].src < 0) return -1;
                res += in[u].weight;
            }
            vector<int> mark(N, -1); // contract cycles
            int index = 0;
            for (int i = 0; i < N; ++i) {
                if (mark[i] != -1) continue;
                int u = i;
                while (mark[u] == -1) {
                    mark[u] = i;
                    u = in[u].src;
                }
                if (mark[u] != i || u == r) continue;
                for (int v = in[u].src; u != v; v = in[v].src) C[v] =
                    index;
                C[u] = index++;
            }
            if (index == 0) return res; // found arborescence
```

```
for (int i = 0; i < N; ++i) // contract
    if (C[i] == -1) C[i] = index++;

    vector<edge> next;
    for (auto &e: edges)
        if (C[e.src] != C[e.dst] && C[e.dst] != C[r])
            next.push_back({C[e.src], C[e.dst], e.weight - in[e.dst]
                }.weight});
    edges.swap(next);
    N = index; r = C[r];
}
}
};
```

## 4.4 Directed Minimum Spanning Tree MlogN

```
/*
GETS:
    call make_graph(n) at first
    you should use add_edge(u,v,w) and
    add pair of vertices as edges (vertices are 0..n-1)
GIVES:
    output of dmst(v) is the minimum arborescence with root v in
    directed graph
    (INF if it hasn't a spanning arborescence with root v)
    0(mlogn)
*/
const int INF = 2e7;
struct MinimumAborescence{
    struct edge {
        int src, dst, weight;
    };
    struct union_find {
        vector<int> p;
        union_find(int n) : p(n, -1) { };
        bool unite(int u, int v) {
            if ((u = root(u)) == (v = root(v))) return false;
            if (p[u] > p[v]) swap(u, v);
            p[u] += p[v]; p[v] = u;
            return true;
        }
        bool find(int u, int v) { return root(u) == root(v); }
        int root(int u) { return p[u] < 0 ? u : p[u] = root(p[u]); }
        int size(int u) { return -p[root(u)]; }
    };
    struct skew_heap {
```

```

struct node {
    node *ch[2];
    edge key;
    int delta;
} *root;
skew_heap() : root(0) { }
void propagate(node *a) {
    a->key.weight += a->delta;
    if (a->ch[0]) a->ch[0]->delta += a->delta;
    if (a->ch[1]) a->ch[1]->delta += a->delta;
    a->delta = 0;
}
node *merge(node *a, node *b) {
    if (!a || !b) return a ? a : b;
    propagate(a); propagate(b);
    if (a->key.weight > b->key.weight) swap(a, b);
    a->ch[1] = merge(b, a->ch[1]);
    swap(a->ch[0], a->ch[1]);
    return a;
}
void push(edge key) {
    node *n = new node();
    n->ch[0] = n->ch[1] = 0;
    n->key = key; n->delta = 0;
    root = merge(root, n);
}
void pop() {
    propagate(root);
    node *temp = root;
    root = merge(root->ch[0], root->ch[1]);
}
edge top() {
    propagate(root);
    return root->key;
}
bool empty() {
    return !root;
}
void add(int delta) {
    root->delta += delta;
}
void merge(skew_heap x) {
    root = merge(root, x.root);
}
};
vector<edge> edges;
void add_edge(int src, int dst, int weight) {
    edges.push_back({src, dst, weight});
}
int n;

```

```

void make_graph(int _n) {
    n = _n;
    edges.clear();
}
int dmst(int r) {
    union_find uf(n);
    vector<skew_heap> heap(n);
    for (auto e: edges)
        heap[e.dst].push(e);
    double score = 0;
    vector<int> seen(n, -1);
    seen[r] = r;
    for (int s = 0; s < n; ++s) {
        vector<int> path;
        for (int u = s; seen[u] < 0;) {
            path.push_back(u);
            seen[u] = s;
            if (heap[u].empty()) return INF;
            edge min_e = heap[u].top();
            score += min_e.weight;
            heap[u].add(-min_e.weight);
            heap[u].pop();
            int v = uf.root(min_e.src);
            if (seen[v] == s) {
                skew_heap new_heap;
                while (1) {
                    int w = path.back();
                    path.pop_back();
                    new_heap.merge(heap[w]);
                    if (!uf.unite(v, w)) break;
                }
                heap[uf.root(v)] = new_heap;
                seen[uf.root(v)] = -1;
            }
            u = uf.root(v);
        }
    }
    return score;
}
};

```

## 4.5 Ear Decomposition

Solution:

1- Find a spanning tree of the given graph and choose a root for the tree.

2- Determine, for each edge  $uv$  that is not part of the tree, the distance between the root and the lowest common

ancestor of  $u$  and  $v$ .

3- For each edge  $uv$  that is part of the tree, find the corresponding "master edge", a non-tree edge  $wx$  such that the cycle formed by adding  $wx$  to the tree passes through  $uv$  and such that, among such edges,  $w$  and  $x$  have a lowest common ancestor that is as close to the root as possible (with ties broken by edge identifiers).

4- Form an ear for each non-tree edge, consisting of it and the tree edges for which it is the master, and order the ears by their master edges' distance from the root (with the same tie-breaking rule).

## 4.6 Edmond-Blossom

```

// Order: M * Sqrt(N)
// Edges of 1-based. add_edge for adding edges and calc for
// calculating matching
// output is in match array (match[i] = 0 if i isn't in
// matching)
mt19937 rng(chrono::steady_clock::now().time_since_epoch().
    count());
template<int SZ> struct UnweightedMatch {
    int match[SZ], N;
    vector<int> adj[SZ];

    void add_edge(int u, int v) {
        adj[u].pb(v);
        adj[v].pb(u);
    }

    queue<int> q;
    int par[SZ], vis[SZ], orig[SZ], aux[SZ];

    void augment(int u, int v) { // toggle edges on u-v path
        while (1) { // one more matched pair
            int pv = par[v], nv = match[pv];
            match[v] = pv; match[pv] = v;
            v = nv; if (u == pv) return;
        }
    }

    int lca(int u, int v) { // find LCA of supernodes in O(dist
        )
        static int t = 0;
        for (++t; swap(u, v)) {
            if (!u) continue;
            if (aux[u] == t) return u; // found LCA
        }
    }
};

```



```

    aux[u] = t; u = orig[par[match[u]]];
}
}

void blossom(int u, int v, int a) { // go other way
    for (; orig[u] != a; u = par[v]) { // around cycle
        par[u] = v; v = match[u]; // treat u as if vis[u] = 1
        if (vis[v] == 1) vis[v] = 0, q.push(v);
        orig[u] = orig[v] = a; // merge into supernode
    }
}

bool bfs(int u) { // u is initially unmatched
    for(int i = 0; i < N + 1; i++)
        par[i] = 0, vis[i] = -1, orig[i] = i;
    q = queue<int>();
    vis[u] = 0;
    q.push(u);
    while (q.size()) { // each node is pushed to q at most
        once
        int v = q.front(); q.pop(); // 0 -> unmatched vertex
        for (int x : adj[v]) {
            if (vis[x] == -1) { // neither of x, match[x] visited
                vis[x] = 1; par[x] = v;
                if (!match[x])
                    return augment(u,x),1;
                vis[match[x]] = 0;
                q.push(match[x]);
            } else if (vis[x] == 0 && orig[v] != orig[x]) {
                int a = lca(orig[v],orig[x]); // odd cycle
                blossom(x,v,a), blossom(v,x,a);
            } // contract O(n) times
        }
    }
    return 0;
}

int calc(int _N) { // rand matching -> constant improvement
    N = _N;
    for(int i = 0; i <= N; i++)
        match[i] = aux[i] = 0;
    int ans = 0; vector<int> V(N); iota(V.begin(), V.end(),1);
    shuffle(V.begin(), V.end(),rng); // find rand matching
    for (int x : V) {
        if (!match[x]) {
            for (int y : adj[x]) {
                if (!match[y]) {
                    match[x] = y, match[y] = x; ++ans;
                    break;
                }
            }
        }
    }
}

```

```

    }
}
}
for(int i = 1; i <= N; i++)
    if (!match[i] && bfs(i))
        ++ans;
return ans;
}
};

```

## 4.7 Flow-Dinic

```

//Order : General: mn^2, Bipartite: mn^0.5, Zero-One: mn
~(2/3)

const int maxN = 1000, maxE = 2 * 1e5 + 10;

int from[maxE], to[maxE], cap[maxE], prv[maxE], head[maxN],
    pt[maxN], ec;
void addEdge(int u, int v, int uv, int vu = 0){
    from[ec] = u, to[ec] = v, cap[ec] = uv, prv[ec] = head[u],
    head[u] = ec++;
    from[ec] = v, to[ec] = u, cap[ec] = vu, prv[ec] = head[v],
    head[v] = ec++;
}

int lv[maxN], q[maxN];
bool bfs(int source, int sink){
    memset(lv, 31, sizeof(lv));
    int h = 0, t = 0;
    lv[source] = 0;
    q[t++] = source;
    while (t-h){
        int v = q[h++];
        for (int e = head[v]; ~e; e = prv[e])
        {
            if (cap[e] && lv[v] + 1 < lv[to[e]]){
                lv[to[e]] = lv[v] + 1;
                q[t++] = to[e];
            }
        }
    }
    return lv[sink] < 1e8;
}

int dfs(int v, int sink, int f = 1e9){
    if (v == sink || f == 0)
        return f;
    int ret = 0;
    for (int &e = pt[v]; ~e; e = prv[e])
        if (lv[v]+1 == lv[to[e]]){

```

```

        int x = dfs(to[e], sink, min(f, cap[e]));
        cap[e] -= x;
        cap[e^1] += x;
        ret += x;
        f -= x;
        if (!f)
            break;
    }
    return ret;
}

int dinic(int source, int sink){
    memset(prv, -1, sizeof prv);
    memset(head, -1, sizeof head);

    int ret = 0;
    while (bfs(source, sink)){
        memcpy(pt, head, sizeof(head));
        ret += dfs(source, sink);
    }
    return ret;
}

```

## 4.8 Gomory-Hu

```

bool mark[N];
int p[N], w[N];
void gfs(int u) {
    mark[u] = 1;
    for(int e = head[u]; e != -1; e = prv[e])
        if (!mark[to[e]] && cap[e])
            gfs(to[e]);
}

//edges is one-directed. Order: O(n * flow)
vector<pair<int, pii>> gomory_hu(int n, vector<pair<int, pii>> edges) {
    for(int i = 1; i <= n; i++) p[i] = 1;
    memset(w, 0, sizeof w);
    p[1] = 0;
    for(int i = 2; i <= n; i++) {
        memset(head, -1, sizeof head);
        ec = 0;
        for(auto u : edges) add_edge(u.S.F, u.S.S, u.F);
        w[i] = dinic(i, p[i]);
        memset(mark, 0, sizeof mark);
        gfs(i);
        for(int j = i + 1; j <= n; j++)
            if (mark[j] && p[j] == p[i])
                p[j] = i;
        if (p[p[i]] && mark[p[p[i]]]) {

```



```

    int pi = p[i];
    swap(w[i], w[pi]);
    p[i] = p[pi];
    p[pi] = i;
}
}
vector<pair<int, pii>> tree;
for(int i = 1; i <= n; i++) if(p[i]) tree.pb({w[i], {i, p[i]}});
return tree;
}

```

## 4.9 Hungarian

```

const int N = 2002;
const int INF = 1e9;
int hn, weight[N][N]; //hn should contain number of vertices
                        //in each part. weight must be positive.
int x[N], y[N]; //initial value doesn't matter.

int hungarian() // maximum weighted perfect matching O(n^3)
{
    int n = hn;
    int p, q;
    vector<int> fx(n, -INF), fy(n, 0);
    fill(x, x + n, -1);
    fill(y, y + n, -1);

    for (int i = 0; i < n; ++i)
        for (int j = 0; j < n; ++j)
            fx[i] = max(fx[i], weight[i][j]);

    for (int i = 0; i < n; ) {
        vector<int> t(n, -1), s(n+1, i);
        for (p = 0, q = 1; p < q && x[i] < 0; ++p) {
            int k = s[p];
            for (int j = 0; j < n && x[i] < 0; ++j)
                if (fx[k] + fy[j] == weight[k][j] && t[j] < 0) {
                    s[q++] = y[j], t[j] = k;
                    if (y[j] < 0) // match found!
                        for (int p = j; p >= 0; j = p)
                            y[j] = k = t[j], p = x[k], x[k] = j;
                }
            }
        if (x[i] < 0) {
            int d = INF;
            for (int k = 0; k < q; ++k)
                for (int j = 0; j < n; ++j)

```

```

                    if (t[j] < 0) d = min(d, fx[s[k]] + fy[j] - weight[s[k]
                        ][j]);
                    for (int j = 0; j < n; ++j) fy[j] += (t[j] < 0 ? 0 : d);
                    for (int k = 0; k < q; ++k) fx[s[k]] -= d;
                } else ++i;
            }
        int ret = 0;
        for (int i = 0; i < n; ++i) ret += weight[i][x[i]];
        return ret;
    }

    int main() {
        int n, e; cin >> n >> e;
        for (int i=0; i<e; i++)
        {
            int u, v; cin >> u >> v;
            --u; --v;
            cin >> weight[u][v];
        }
        hn = n;
        cout << hungarian() << '\n';
        return 0;
    }

```

## 4.10 Min-Cost-Max-Flow

```

const int N = 810, E = N * N, INF = 1e9;

int n, ed = 0, from[E], to[E], cap[E], head[N], nex[E], par[
    N];
ld dis[N], cost[E];

void add_edge(int u, int v, int c, ld co)
{
    from[ed] = u, to[ed] = v, cap[ed] = c, cost[ed] = co, nex[
        ed] = head[u], head[u] = ed ++;
    from[ed] = v, to[ed] = u, cap[ed] = 0, cost[ed] = -co, nex[
        ed] = head[v], head[v] = ed ++;
}

pair<int, ld> spfa(int sink, int source)
{
    for(int i=0; i<N; i++)dis[i] = INF;
    memset(mark, 0, sizeof mark);
    memset(par, -1, sizeof par);

    queue<int> q;
    dis[source] = 0, mark[source] = true;
    q.push(source);

```

```

    while(q.size())
    {
        int v = q.front(); q.pop();
        mark[v] = false;

        for(int e = head[v]; e != -1; e = nex[e])
        {
            if(cap[e] && dis[to[e]] > dis[v] + cost[e])
            {
                dis[to[e]] = dis[v] + cost[e];
                par[to[e]] = e;
                if(!mark[to[e]])q.push(to[e]), mark[to[e]] = true;
            }
        }
    }

    int curr = sink;
    if(dis[curr] == INF)return make_pair(0, 0);

    ld res = 0;

    int flow = INF;

    while(curr != source)
    {
        flow = min(flow, cap[par[curr]]);
        curr = from[par[curr]];
    }

    curr = sink;
    while(curr != source)
    {
        res += cost[par[curr]];
        cap[par[curr]] -= flow;
        cap[par[curr] ^ 1] += flow;
        curr = from[par[curr]];
    }

    return make_pair(flow, res);
}

pair<int, ld> MinCostMaxFlow(int sink, int source)
{
    int flow = 0;
    pair<int, ld> f = {INF, 0};
    ld Cost = 0;

    while(f.F)
    {

```

```

    f = spfa(sink, source);
    flow += f.F;
    Cost += f.F * f.S;
}

return make_pair(flow, Cost);
}

```

## 5 Number Theory

### 5.1 Chinese Remainder Theorem

```

#define lcm LLLCCM

ll GCD(ll a, ll b) { return (b == 0) ? a : GCD(b, a % b); }
inline ll LCM(ll a, ll b) { return a / GCD(a, b) * b; }
inline ll normalize(ll x, ll mod) { x %= mod; if (x < 0) x
    += mod; return x; }

struct GCD_type { ll x, y, d; };
GCD_type ex_GCD(ll a, ll b){
    if (b == 0) return {1, 0, a};
    GCD_type pom = ex_GCD(b, a % b);
    return {pom.y, pom.x - a / b * pom.y, pom.d};
}

const int N = 2;
ll r[N], n[N], ans, lcm;
// t: number of equations,
// r: reminder array, n: mod array
// returns {remainder, lcm}

pair <ll, ll> CRT(ll* r, ll *n, int t) {
    for(int i = 0; i < t; i++)
        normalize(r[i], n[i]);
    ans = r[0];
    lcm = n[0];

    for(int i = 1; i < t; i++){
        auto pom = ex_GCD(lcm, n[i]);
        ll x1 = pom.x;
        ll d = pom.d;
        if((r[i] - ans) % d != 0) {
            return {-1, -1}; //No Solution
        }
        ans = normalize(ans + x1 * (r[i] - ans) / d % (n[i] / d) *
            lcm, lcm * n[i] / d);
    }
}

```

```

    lcm = LCM(lcm, n[i]); // you can save time by replacing
        above lcm * n[i] /d by lcm = lcm * n[i] / d
}
return {ans, lcm};
}

```

### 5.2 Miller Robin

```

//with probability (1/4) iter, we might make mistake in our
    guess.
//we have false positive here.
using u64 = uint64_t;
using u128 = __uint128_t;

using namespace std;

u64 binpower(u64 base, u64 e, u64 mod) {
    u64 result = 1;
    base %= mod;
    while (e) {
        if (e & 1)
            result = (u128)result * base % mod;
        base = (u128)base * base % mod;
        e >>= 1;
    }
    return result;
}

bool check_composite(u64 n, u64 a, u64 d, int s) {
    u64 x = binpower(a, d, n);
    if (x == 1 || x == n - 1)
        return false;
    for (int r = 1; r < s; r++) {
        x = (u128)x * x % n;
        if (x == n - 1)
            return false;
    }
    return true;
};

```

```

bool MillerRabin(u64 n, int iter=5) { // returns true if n
    is probably prime, else returns false.
    if (n < 4)
        return n == 2 || n == 3;

    int s = 0;
    u64 d = n - 1;
    while ((d & 1) == 0) {
        d >>= 1;
    }
}

```

```

    s++;
}

for (int i = 0; i < iter; i++) {
    int a = 2 + rand() % (n - 3);
    if (check_composite(n, a, d, s))
        return false;
}
return true;
}

```

### 5.3 Most Divisors

```

<= 1e2: 60 with 12 divisors
<= 1e3: 840 with 32 divisors
<= 1e4: 7560 with 64 divisors
<= 1e5: 83160 with 128 divisors
<= 1e6: 720720 with 240 divisors
<= 1e7: 8648640 with 448 divisors
<= 1e8: 73513440 with 768 divisors
<= 1e9: 735134400 with 1344 divisors
<= 1e10: 6983776800 with 2304 divisors
<= 1e11: 97772875200 with 4032 divisors
<= 1e12: 963761198400 with 6720 divisors
<= 1e13: 9316358251200 with 10752 divisors
<= 1e14: 97821761637600 with 17280 divisors
<= 1e15: 866421317361600 with 26880 divisors
<= 1e16: 8086598962041600 with 41472 divisors
<= 1e17: 74801040398884800 with 64512 divisors
<= 1e18: 897612484786617600 with 103680 divisors

```

### 5.4 Number of Primes

```

30: 10
60: 17
100: 25
1000: 168
10000: 1229
100000: 9592
1000000: 78498
10000000: 664579

```

## 6 Numerical

### 6.1 Base Vector Z2

```
const int maxL = 61;

struct Base{
    ll a[maxL] = {};
    ll eliminate(ll x){
        for(int i=maxL-1; i>=0; --i) if(x >> i & 1) x ^= a[i];
        return x;
    }
    void add(ll x){
        x = eliminate(x);
        if(x == 0) return ;
        for(int i=maxL-1; i>=0; --i) if(x >> i & 1) {
            a[i] = x;
            return ;
        }
    }
    int size(){
        int cnt = 0;
        for(int i=0; i<maxL; ++i) if(a[i]) ++cnt;
        return cnt;
    }
    ll get_mx() {
        ll x = 0;
        for (int i=maxL-1; i>=0; i--) {
            if(x & (1LL << i)) continue ;
            else x ^= a[i];
        }
        return x;
    }
};
```

### 6.2 Extended Catalan

number of ways for going from 0 to A with k moves without going to -B:

$$\binom{k}{\frac{A+k}{2}} - \binom{k}{\frac{2B+A+k}{2}}$$

### 6.3 FFT

```
const int LG = 20; // IF YOU WANT TO CONVOLVE TWO ARRAYS OF
                    // LENGTH N AND M CHOOSE LG IN SUCH A WAY THAT 2LG > n + m
const int MAX = 1 << LG;
```

```
#define M_PI acos(-1)

struct point{
    double real, imag;
    point(double _real = 0.0, double _imag = 0.0){
        real = _real;
        imag = _imag;
    }
};

point operator + (point a, point b){
    return point(a.real + b.real, a.imag + b.imag);
}

point operator - (point a, point b){
    return point(a.real - b.real, a.imag - b.imag);
}

point operator * (point a, point b){
    return point(a.real * b.real - a.imag * b.imag, a.real * b.
        imag + a.imag * b.real);
}

void fft(point *a, bool inv){
    for (int mask = 0; mask < MAX; mask++){
        int rev = 0;
        for (int i = 0; i < LG; i++){
            if ((1 << i) & mask)
                rev |= (1 << (LG - 1 - i));
            if (mask < rev)
                swap(a[mask], a[rev]);
        }
        for (int len = 2; len <= MAX; len *= 2){
            double ang = 2.0 * M_PI / len;
            if (inv)
                ang *= -1.0;
            point wn(cos(ang), sin(ang));
            for (int i = 0; i < MAX; i += len){
                point w(1.0, 0.0);
                for (int j = 0; j < len / 2; j++){
                    point t1 = a[i + j] + w * a[i + j +
                        len / 2];
                    point t2 = a[i + j] - w * a[i + j +
                        len / 2];
                    a[i + j] = t1;
                    a[i + j + len / 2] = t2;
                    w = w * wn;
                }
            }
        }
    }
    if (inv)
        for (int i = 0; i < MAX; i++){
            a[i].real /= MAX;
```

```
        a[i].imag /= MAX;
    }
}
```

### 6.4 Gaussian Elimination Xor

```
const int maxN = 105;
typedef vector <int> vec;

bitset<maxN> matrix[maxN];
bitset<maxN> ans;

vec solve(int n, int m) {
    vec ptr;
    ptr.resize(n);

    int i = 0, j = 0;
    while(i < n and j < m) {
        int ind = -1;
        for(int row = i; row < n; row++){
            if(matrix[row][j])
                ind = row;
        }
        if(ind == -1) {
            j++;
            continue ;
        }

        bitset<maxN> b;
        b = matrix[i];
        matrix[i] = matrix[ind];
        matrix[ind] = b;

        bool f = ans[i];
        ans[i] = ans[ind];
        ans[ind] = f;

        for(int row = i + 1; row < n; row++) {
            if(matrix[row][j]) {
                matrix[row] ^= matrix[i];
                ans[row] = ans[row] ^ ans[i];
            }
        }

        ptr[i] = j;
        i++;
        j++;
    }
}
```

```

vec sol;

if(i != n) {
    for (int row=i; row<n; row++)
        if(ans[row])
            return sol; //without answer;
}
sol.resize(m);

for (int j=0; j<m; j++)
    sol[j] = 0;

for (int row=i-1; row>=0; row--){
    int j = ptr[row];
    sol[j] = ans[row];
    for (int c=row-1; c>=0; c--)
        if(matrix[c][j]) ans[c] = ans[c] ^ sol[j];
}
return sol;
}

```

## 6.5 Gaussian Elimination

```

const int N = 505, MOD = 1e9 + 7;
typedef vector<ll> vec;

ll pw(ll a, ll b) {
    if(!b)
        return 1;
    ll x = pw(a, b/2);
    return x * x % MOD * (b % 2 ? a : 1) % MOD;
}
ll inv(ll x) { return pw(x, MOD - 2); }

//matrix * x = ans
vec solve(vector<vec> matrix, vec ans) {
    int n = matrix.size(), m = matrix[0].size();
    for (int i=0; i<n; i++)
        matrix[i].pb(ans[i]);

    vector<int> ptr;
    ptr.resize(n);

    int i = 0, j = 0;
    while(i < n and j < m) {
        int ind = -1;
        for(int row = i; row < n; row++)
            if(matrix[row][j])

```

```

                ind = row;
        if(ind == -1) {
            j++;
            continue;
        }
        matrix[i].swap(matrix[ind]);
        ll inverse = inv(matrix[i][j]);
        for(int row = i + 1; row < n; row++) {
            ll z = matrix[row][j] * inverse % MOD;
            for(int k = 0; k <= m; k++)
                matrix[row][k] = (matrix[row][k] % MOD - matrix[i][k]*z %
                    MOD + MOD) % MOD;
        }
        ptr[i] = j;
        i++;
        j++;
    }

    vector<ll> sol;

    if(i != n) {
        for (int row=i; row<n; row++)
            if(matrix[row][m] != 0)
                return sol; //without answer;
    }
    sol.resize(m);
    for (int j=0; j<m; j++)
        sol[j] = 0;

    for (int row=i-1; row>=0; row--){
        int j = ptr[row];
        sol[j] = matrix[row][m] * inv(matrix[row][j]) % MOD;
        for (int c=row-1; c>=0; c--)
            matrix[c][m] += (MOD - sol[j] * matrix[c][j] % MOD),
                matrix[c][m] %= MOD;
    }
    return sol;
}

int main() {
    int n, m; cin >> n >> m;
    vector<vec> A;
    for (int i=0; i<n; i++)
    {
        vec B;
        for (int j=0; j<m; j++)
        {
            ll x; cin >> x;

```

```

        B.push_back(x);
    }
    A.push_back(B);
}

vec ans;
for (int i=0; i<n; i++)
{
    ll y; cin >> y;
    ans.pb(y);
}

vec sol = solve(A, ans);
for (auto X : sol)
    cout << X << ' ';
cout << endl;
}

```

## 6.6 General Linear Recursion

```

const int maxL = 20; // IF YOU WANT TO CONVOLVE TWO ARRAYS
    OF LENGTH N AND M CHOOSE LG IN SUCH A WAY THAT 2LG > n
    + m
const int maxN = 1 << maxL, MOD = 998244353;

#define M_PI acos(-1)

int root[maxL + 2] = {0,998244352,86583718,372528824,
    69212480,87557064,15053575,57475946,15032460,
    4097924,1762757,752127,299814,730033,227806,
    42058,44759,8996,2192,1847,646,42};

int bpow(int a, int b){
    int ans = 1;
    while (b){
        if (b & 1)
            ans = 1LL * ans * a % MOD;
        b >>= 1;
        a = 1LL * a * a % MOD;
    }
    return ans;
}

void ntt(vector<int> &a, bool inv){
    int LG = 0, z = 1, MAX = a.size();
    while(z != MAX) z *= 2, LG++;
    int ROOT = root[LG];

    for (int mask = 0; mask < MAX; mask++){

```

```

int rev = 0;
for (int i = 0; i < LG; i++)
    if ((1 << i) & mask)
        rev |= (1 << (LG - 1 - i));
if (mask < rev)
    swap(a[mask], a[rev]);
}
for (int len = 2; len <= MAX; len *= 2){
    int wn = bpow(ROOT, MAX / len);
    if (inv)
        wn = bpow(wn, MOD - 2);
    for (int i = 0; i < MAX; i += len){
        int w = 1;
        for (int j = 0; j < len / 2; j++){
            int l = a[i + j];
            int r = 1LL * w * a[i + j + len / 2] %
                MOD;
            a[i + j] = (l + r);
            a[i + j + len / 2] = l - r + MOD;
            if (a[i + j] >= MOD)
                a[i + j] -= MOD;
            if (a[i + j + len / 2] >= MOD)
                a[i + j + len / 2] -= MOD;
            w = 1LL * w * wn % MOD;
        }
    }
}
if (inv){
    int x = bpow(MAX, MOD - 2);
    for (int i = 0; i < MAX; i++)
        a[i] = 1LL * a[i] * x % MOD;
}

int ans[maxN], bb[maxN];

//ans[i] = sum_j=1~i b_j * ans[i - j], ans[0] = 1;
void solve(int l, int r) {
    if(r - 1 == 1) return ;
    int mid = (l + r)/2;

    solve(l, mid);

    vector<int> a, b;
    for (int i=1; i<r; i++) {
        if(i < mid) a.pb(ans[i]);
        else a.pb(0);

        b.pb(bb[i-1+1]);
    }
}

```

```

}

for (int i=1; i<r; i++) {
    a.pb(0);
    b.pb(0);
}

ntt(a, false);
ntt(b, false);

vector<int> c;
c.resize(a.size());

for (int i=0; i<2*r-2*1; i++)
    c[i] = 1LL * a[i] * b[i] % MOD;

ntt(c, true);
for (int i=0; i<r-mid; i++)
    ans[mid + i] += c[mid - 1 - 1 + i], ans[mid + i] %= MOD;

solve(mid, r);
}

int main() {
    int n, m; cin >> n >> m;
    for (int i=1; i<=m; i++)
        cin >> bb[i];
    int k = 1;
    while(k < n) k = 2 * k;

    ans[0] = 1;
    solve(0, k);
    for (int i=0; i<n; i++)
        cout << ans[i] << ' ';
    cout << endl;
}

```

## 6.7 LP Duality

primal: Maximize  $c^T x$  subject to  $Ax \leq b, x \geq 0$

dual: Minimize  $b^T y$  subject to  $A^T y \geq c, y \geq 0$

## 6.8 NTT

```
const int MOD = 998244353;
```

```

const int LG = 16; // IF YOU WANT TO CONVOLVE TWO ARRAYS OF
    LENGTH N AND M CHOOSE LG IN SUCH A WAY THAT 2LG > n + m
const int MAX = (1 << LG);
const int ROOT = 44759; // ENSURE THAT ROOT2(LG - 1) = MOD -
    1
int bpow(int a, int b){
    int ans = 1;
    while (b){
        if (b & 1)
            ans = 1LL * ans * a % MOD;
        b >>= 1;
        a = 1LL * a * a % MOD;
    }
    return ans;
}

void ntt(int *a, bool inv){
    for (int mask = 0; mask < MAX; mask++){
        int rev = 0;
        for (int i = 0; i < LG; i++){
            if ((1 << i) & mask)
                rev |= (1 << (LG - 1 - i));
            if (mask < rev)
                swap(a[mask], a[rev]);
        }
        for (int len = 2; len <= MAX; len *= 2){
            int wn = bpow(ROOT, MAX / len);
            if (inv)
                wn = bpow(wn, MOD - 2);
            for (int i = 0; i < MAX; i += len){
                int w = 1;
                for (int j = 0; j < len / 2; j++){
                    int l = a[i + j];
                    int r = 1LL * w * a[i + j + len / 2] %
                        MOD;
                    a[i + j] = (l + r);
                    a[i + j + len / 2] = l - r + MOD;
                    if (a[i + j] >= MOD)
                        a[i + j] -= MOD;
                    if (a[i + j + len / 2] >= MOD)
                        a[i + j + len / 2] -= MOD;
                    w = 1LL * w * wn % MOD;
                }
            }
        }
        if (inv){
            int x = bpow(MAX, MOD - 2);
            for (int i = 0; i < MAX; i++)
                a[i] = 1LL * a[i] * x % MOD;
        }
    }
}

```

## 6.9 Popular LP

### BellmanFord:

maximize  $X_n$

$X_1 = 0$

and for each edge ( $v \rightarrow u$  and weight  $w$ ):

$X_u - X_v \leq w$

### Flow:

maximize  $\Sigma f_{out}$  (where *out* is output edges of vertex 1)

for each vertex (except 1 and n):

$\Sigma f_{in} - \Sigma f_{out} = 0$  (where *in* is input edges of  $v$  and *out* is output edges of  $v$ )

### Dijkstra(IP):

minimize  $\Sigma z_i * w_i$

for each edge ( $v \rightarrow u$  and weight  $w$ ):

$0 \leq z_i \leq 1$

and for each ST-cut which vertex 1 is in S and vertex n is in T:

$\Sigma z_e \geq 1$  (for each edge  $e$  from S to T)

## 6.10 Simplex

```
typedef vector<ld> vd;
typedef vector<int> vi;
const ld Eps = 1e-9;
```

```
// ax <= b, max(cTx), x >= 0
// 0(nm^2)
```

```
vd simplex(vector<vd> a, vd b, vd c) {
    int n = a.size(), m = a[0].size() + 1, r = n, s = m - 1;
    vector<vd> d(n + 2, vd(m + 1, 0)); vd x(m - 1);
    vi ix(n + m); iota(ix.begin(), ix.end(), 0);
    for(int i = 0; i < n; i++) {
        for(int j = 0; j < m - 1; j++) d[i][j] = -a[i][j];
        d[i][m - 1] = 1;
        d[i][m] = b[i];
        if(d[r][m] > d[i][m])
            r = i;
    }
}
```

```
for(int j = 0; j < m - 1; j++) d[n][j] = c[j];
d[n + 1][m - 1] = -1;
while(true) {
    if(r < n) {
        vd su;
        swap(ix[s], ix[r + m]); d[r][s] = 1 / d[r][s];
        for(int j = 0; j <= m; j++) if(j != s) {
            d[r][j] *= -d[r][s]; if(d[r][j]) su.pb(j);
        }
        for(int i = 0; i <= n + 1; i++) if(i != r) {
            for(int j = 0; j < su.size(); j++)
                d[i][su[j]] += d[r][su[j]] * d[i][s];
            d[i][s] *= d[r][s];
        }
    }
    r = s = -1;
    for(int j = 0; j < m; j++) if(s < 0 || ix[s] > ix[j])
        if(d[n + 1][j] > Eps || d[n + 1][j] > -Eps &&
            d[n][j] > Eps) s = j; if(s < 0) break;
    for(int i = 0; i < n; i++) if(d[i][s] < -Eps) {
        if(r < 0) {
            r = i;
            continue;
        }
        double e = d[r][m] / d[r][s] - d[i][m] / d[i][s];
        if(e < -Eps || e < Eps && ix[r + m] > ix[i + m]) r = i;
    }
    if(r < 0)
        {return vd();} // Unbounded
}
if(d[n + 1][m] < -Eps) {return vd();} // No solution
for(int i = m; i < n + m; i++)
    if(ix[i] < m - 1) x[ix[i]] = d[i - m][m];
return x;
}
```

## 6.11 Stirling Cycle

```
const int mod = 998244353;
const int root = 15311432;
const int root_1 = 469870224;
const int root_pw = 1 << 23;
const int N = 400004;
vector<int> v[N];

ll modInv(ll a, ll mod = mod){
    ll x0 = 0, x1 = 1, r0 = mod, r1 = a;
    while(r1){
        ll q = r0 / r1;
```

```
x0 -= q * x1; swap(x0, x1);
r0 -= q * r1; swap(r0, r1);
}
return x0 < 0 ? x0 + mod : x0;
}
```

```
void fft(vector<int> &a, bool inv) {
    int n = (int) a.size();
    for (int i=1, j=0; i<n; ++i) {
        int bit = n >> 1;
        for (; j>=bit; bit>>=1)
            j -= bit;
        j += bit;
        if (i < j)
            swap (a[i], a[j]);
    }
    for (int len=2; len<=n; len<=1) {
        int wlen = inv ? root_1 : root;
        for (int i=len; i<root_pw; i<=1)
            wlen = int (wlen * 1ll * wlen % mod);
        for (int i=0; i<n; i+=len) {
            int w = 1;
            for (int j=0; j<len/2; ++j) {
                int u = a[i+j], v = int (a[i+j+len/2] * 1ll * w % mod);
                a[i+j] = u+v < mod ? u+v : u+v-mod;
                a[i+j+len/2] = u-v >= 0 ? u-v : u-v+mod;
                w = int (w * 1ll * wlen % mod);
            }
        }
    }
    if(inv) {
        int nrev = modInv(n, mod);
        for (int i=0; i<n; ++i)
            a[i] = int (a[i] * 1ll * nrev % mod);
    }
}

void pro(const vector<int> &a, const vector<int> &b, vector<
    int> &res)
{
    vector<int> fa(a.begin(), a.end()), fb(b.begin(), b.end());
    int n = 1;
    while (n < (int) max(a.size(), b.size())) n <= 1;
    n <= 1;
    fa.resize (n), fb.resize (n);
    fft(fa, false), fft (fb, false);
    for (int i = 0; i < n; ++i)
        fa[i] = 1LL * fa[i] * fb[i] % mod;
    fft (fa, true);
    res = fa;
}
```

```

int S(int n, int r) {
    int nn = 1;
    while(nn < n) nn <= 1;
    for(int i = 0; i < n; ++i) {
        v[i].push_back(i);
        v[i].push_back(1);
    }
    for(int i = n; i < nn; ++i) {
        v[i].push_back(1);
    }
    for(int j = nn; j > 1; j >= 1){
        int hn = j >> 1;
        for(int i = 0; i < hn; ++i){
            pro(v[i], v[i + hn], v[i]);
        }
    }
    /*for (int k=0; k<=r; k++)
        cout << v[0][k] << ' '; cout << '\n';*/

    return v[0][r];
}

int fac[N], ifac[N], inv[N];
void prencr(){
    fac[0] = ifac[0] = inv[1] = 1;
    for(int i = 2; i < N; ++i)
        inv[i] = mod - 1LL * (mod / i) * inv[mod % i] % mod;
    for(int i = 1; i < N; ++i){fac[i] = 1LL * i * fac[i - 1] %
        mod;
        ifac[i] = 1LL * inv[i] * ifac[i - 1] % mod;
    }
}

int C(int n, int r){
    return (r >= 0 && n >= r) ? (1LL * fac[n] * ifac[n - r] %
        mod
        * ifac[r] % mod) : 0;
}

int main(){
    prencr();
    int n, k;
    cin >> n >> k;
    cout << S(n, k) << endl; //Also you have S(n, t) for all t.
}

```

## 6.12 Stirling Set

```

const int MOD = 998244353;
const int LG = 16; // IF YOU WANT TO CONVOLVE TWO ARRAYS OF
    LENGTH N AND M CHOOSE LG IN SUCH A WAY THAT 2LG > n + m
const int MAX = (1 << LG);

```

```

const int ROOT = 44759; // ENSURE THAT ROOT2(LG - 1) = MOD -
    1
int bpow(int a, int b){
    int ans = 1;
    while (b){
        if (b & 1)
            ans = 1LL * ans * a % MOD;
        b >>= 1;
        a = 1LL * a * a % MOD;
    }
    return ans;
}

void ntt(int *a, bool inv){
    for (int mask = 0; mask < MAX; mask++){
        int rev = 0;
        for (int i = 0; i < LG; i++){
            if ((1 << i) & mask)
                rev |= (1 << (LG - 1 - i));
            if (mask < rev)
                swap(a[mask], a[rev]);
        }
        for (int len = 2; len <= MAX; len *= 2){
            int wn = bpow(ROOT, MAX / len);
            if (inv)
                wn = bpow(wn, MOD - 2);
            for (int i = 0; i < MAX; i += len){
                int w = 1;
                for (int j = 0; j < len / 2; j++){
                    int l = a[i + j];
                    int r = 1LL * w * a[i + j + len / 2] %
                        MOD;
                    a[i + j] = (l + r);
                    a[i + j + len / 2] = l - r + MOD;
                    if (a[i + j] >= MOD)
                        a[i + j] -= MOD;
                    if (a[i + j + len / 2] >= MOD)
                        a[i + j + len / 2] -= MOD;
                    w = 1LL * w * wn % MOD;
                }
            }
        }
        if (inv){
            int x = bpow(MAX, MOD - 2);
            for (int i = 0; i < MAX; i++)
                a[i] = 1LL * a[i] * x % MOD;
        }
    }
}

```

```
int a[MAX], b[MAX], c[MAX];
```

```

int main() {
    int n; cin >> n;

    a[0] = 1;
    b[0] = 0;
    int inv_fact = 1;

    for (int i=1; i<=n; i++)
    {
        a[i] = 1LL * a[i - 1] * (MOD - 1) % MOD;
        a[i] = 1LL * a[i] * bpow(i, MOD - 2) % MOD;

        inv_fact = 1LL * inv_fact * bpow(i, MOD - 2) % MOD;
        b[i] = bpow(i, n);
        b[i] = 1LL * b[i] * inv_fact % MOD;
    }

    ntt(a, false);
    ntt(b, false);

    for (int i=0; i<MAX; i++)
        c[i] = 1LL * a[i] * b[i] % MOD;

    ntt(c, true);
    for (int j=0; j<n; j++)
        cout << c[j] << ' ';
    cout << endl;
}

```

## 6.13 Stirling

$$\left\{ \begin{matrix} n \\ k \end{matrix} \right\} = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$$

## 7 String

### 7.1 Aho Corrasick

```

int nxt[N][C];
int f[N], q[N], vcnt;
vector<int> adj[N];

int add(string s)
{
    int cur = 0;

```

```

for(auto ch : s)
{
    ch -= 'a';
    if(!nxt[cur][ch]) nxt[cur][ch] = ++vcnt;
    cur = nxt[cur][ch];
}
return cur;
}

void aho()
{
    int hi = 0, lo = 0;
    for(int i = 0; i < C; i++) if(nxt[0][i]) q[hi++] = nxt[0][i];
    while(hi != lo)
    {
        int x = q[lo++];
        adj[f[x]].pb(x);
        for(int i = 0; i < C; i++)
        {
            if(nxt[x][i])
            {
                q[hi++] = nxt[x][i];
                f[nxt[x][i]] = nxt[f[x]][i];
            }
            else nxt[x][i] = nxt[f[x]][i];
        }
    }
}

```

## 7.2 Palindromic

```

int n, last, sz;
char s[N];
int len[N], link[N], cnt[N];
map<short, int> to[N];
void init() {
    n = 0; last = 0;
    for(int i = 0; i < N; i++) to[i].clear();
    s[n++] = -1;
    link[0] = 1;
    len[1] = -1;
    sz = 2;
}
int get_link(int v) {
    while(s[n - len[v] - 2] != s[n - 1]) v = link[v];
    return v;
}
void add_letter(int c) {

```

```

s[n++] = c;
last = get_link(last);
if(!to[last][c]) {
    len[sz] = len[last] + 2;
    link[sz] = to[get_link(link[last])][c];
    to[last][c] = sz++;
}
last = to[last][c];
cnt[last] = cnt[link[last]] + 1;
}

```

## 7.3 Suffix Array

```

string s;
int rank[LOG][N], n, lg;
pair<pair<int, int>, int> sec[N];
int sa[N];
int lc[N];

int lcp(int a, int b)
{
    int _a = a;
    for(int w = lg - 1; ~w && max(a, b) < n; w--)
        if(max(a, b) + (1 << w) <= n && rank[w][a] == rank[w][b])
            a += 1 << w, b += 1 << w;
    return a - _a;
}

```

```

int cnt[N];
pair<pii, int> gec[N];
void srt()
{
    memset(cnt, 0, sizeof cnt);
    for(int i = 0; i < n; i++) cnt[sec[i].F.S+1]++;
    for(int i = 1; i < N; i++) cnt[i] += cnt[i - 1];
    for(int i = 0; i < n; i++) gec[--cnt[sec[i].F.S+1]] = sec[i];
    memset(cnt, 0, sizeof cnt);
    for(int i = 0; i < n; i++) cnt[gec[i].F.F+1]++;
    for(int i = 1; i < N; i++) cnt[i] += cnt[i - 1];
    for(int i = n - 1; ~i; i--) sec[--cnt[gec[i].F.F+1]] = gec[i];
}

void build()
{
    n = s.size();
    {
        int cur = 1; lg = 0;

```

```

while(cur < n)
{
    lg++;
    cur <= 1;
}
lg++;
}

for(int i = 0; i < n; i++) rank[0][i] = s[i];
for(int w = 1; w < lg; w++)
{
    for(int i = 0; i < n; i++)
        if(i + (1 << w - 1) >= n)
            sec[i] = {{rank[w-1][i], -1}, i};
        else
            sec[i] = {{rank[w-1][i], rank[w-1][i+(1<<w-1)]}, i};
    srt();
    rank[w][sec[0].S] = 0;
    for(int i = 1; i < n; i++)
        if(sec[i].F == sec[i - 1].F)
            rank[w][sec[i].S] = rank[w][sec[i-1].S];
        else
            rank[w][sec[i].S] = i;
}

for(int i = 0; i < n; i++)
    sa[rank[lg-1][i]] = i;
for(int i = 0; i + 1 < n; i++)
    lc[i] = lcp(sa[i], sa[i + 1]);
}

```

## 7.4 Suffix Automata

```

const int maxn = 2 e5 + 42; // Maximum amount of states
map < char , int > to [ maxn ]; // Transitions
int link [ maxn ]; // Suffix links
int len [ maxn ]; // Lengthes of largest strings in states
int last = 0; // State corresponding to the whole string
int sz = 1; // Current amount of states
void add_letter ( char c ) { // Adding character to the end
    int p = last ; // State of string s
    last = sz ++; // Create state for string sc
    len [ last ] = len [ p ] + 1;
    for ( ; to [ p ][ c ] == 0; p = link [ p ] ) // (1)
        to [ p ][ c ] = last ; // Jumps which add new suffixes
    if ( to [ p ][ c ] == last ) { // This is the first
        occurrence of
        c if we are here
        link [ last ] = 0;

```



```
    return ;
}
int q = to [ p ][ c ];
if ( len [ q ] == len [ p ] + 1 ) {
    link [ last ] = q ;
    return ;
}
// We split off cl from q here
int cl = sz ++;
to [ cl ] = to [ q ]; // (2)
link [ cl ] = link [ q ];
len [ cl ] = len [ p ] + 1;
link [ last ] = link [ q ] = cl ;
for (; to [ p ][ c ] == q ; p = link [ p ]) // (3)
    to [ p ][ c ] = cl ; // Redirect transitions where needed
}
```

7.5 Suffix Tree

```
#define fpos adla
const int inf = 1e9;
const int maxn = 1e4; //maxn = number of states of suffix
    tree

char s[maxn];
map<int, int> to[maxn]; //edges of tree
int len[maxn], fpos[maxn], link[maxn];
//len[i] is the length of the inner edge of v
//fpos[i] is start position of inner edge in string s
int node, pos;
int sz = 1, n = 0;

int make_node(int _pos, int _len) {
    fpos[sz] = _pos;
    len [sz] = _len;
    return sz++;
}
void go_edge() {
    while(pos > len[to[node][s[n - pos]]]) {
        node = to[node][s[n - pos]];
        pos -= len[node];
    }
}
void add_letter(int c) {
    s[n++] = c;
    pos++;
    int last = 0;
    while(pos > 0) {
        go_edge();
```

```
int edge = s[n - pos];
int &v = to[node][edge];
int t = s[fpos[v] + pos - 1];
if(v == 0) {
    v = make_node(n - pos, inf);
    link[last] = node;
    last = 0;
} else if(t == c) {
    link[last] = node;
    return;
} else {
    int u = make_node(fpos[v], pos - 1);
    to[u][c] = make_node(n - 1, inf);
    to[u][t] = v;
    fpos[v] += pos - 1;
    len [v] -= pos - 1;
    v = u;
    link[last] = u;
    last = u;
}
if(node == 0)
    pos--;
else
    node = link[node];
}
```

8 Useful Fact and Constants

8.1 C(2n,n)

- 1: 2
- 2: 6
- 3: 20
- 4: 70
- 5: 252
- 6: 924
- 7: 3432
- 8: 12870
- 9: 48620
- 10: 184756
- 11: 705432
- 12: 2704156
- 13: 10400600
- 14: 40116600
- 15: 155117520

8.2 Factorials

- 1: 1
- 2: 2
- 3: 6
- 4: 24
- 5: 120
- 6: 720
- 7: 5040
- 8: 40320
- 9: 362880
- 10: 3628800
- 11: 39916800
- 12: 479001600
- 13: 6227020800
- 14: 87178291200
- 15: 1307674368000

8.3 Long Long Long Integer

```
__int128 x;
unsigned __int128 y;
//Cin and Cout must be implemented
//Constants doesn't work
```

8.4 Power of 3

- 1: 3
- 2: 9
- 3: 27
- 4: 81
- 5: 243
- 6: 729
- 7: 2187
- 8: 6561
- 9: 19683
- 10: 59049
- 11: 177147
- 12: 531441
- 13: 1594323
- 14: 4782969
- 15: 14348907
- 16: 43046721
- 17: 129140163
- 18: 387420489
- 19: 1162261467
- 20: 3486784401