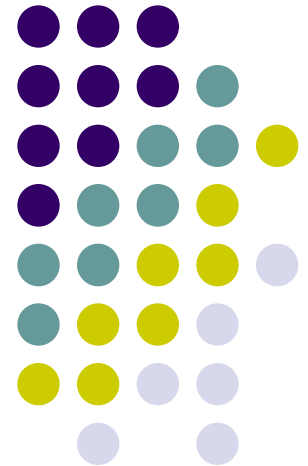


Approximation Algorithms

Analysis of Algorithms



Motivation: Getting around NP-completeness



- Exponential time may be acceptable for small inputs [Brute Force]
- Isolate special cases that can run in polynomial time [Divide-and-Conquer]
- Near-optimal solutions may be acceptable [Approximation Algorithms]



Performance Ratios

- C^* is the cost of the optimal solution
- C is the cost of the solution produced by an approximation algorithm
- An algorithm has an approximation ratio of $\rho(n)$ if for an input of size n , C is within a factor of C^*



Performance Ratios [cont.]

- **Maximization problem**
 - $0 < C \leq C^*$
 - C^* / C factor by which the cost of the optimal solution is larger than the cost of the approximate solution
- **Minimization problem**
 - $0 < C^* \leq C$
 - C / C^* factor by which the cost of the approximate solution is larger than the cost of the optimal solution



Definitions

- *Approximation Algorithm*
 - produces “near-optimal” solution
- Algorithm has *approximation ratio* $\rho(n)$ if:

$$\max\left(\frac{C}{C^*}, \frac{C^*}{C}\right) \leq \rho(n)$$

C = cost of algorithm's solution

C^* = cost of optimal solution

n = number of inputs = size of instance

- *Approximation Scheme*
 - $(1+\varepsilon)$ -approximation algorithm for fixed ε
 - $\varepsilon > 0$ is an input
 - *Polynomial-Time Approximation Scheme*
 - time is polynomial in n

How do approximations algorithms work?



- Exploit the nature of the problem
- Use greedy techniques
- Use linear programming
- Use dynamic programming
- Use random assignments

Overview



- **VERTEX-COVER**
 - Polynomial-time 2-approximation algorithm
- **TSP**
 - TSP with triangle inequality
 - Polynomial-time 2-approximation algorithm
 - TSP without triangle inequality
 - Negative result on polynomial-time $\rho(n)$ -approximation algorithm
- **SET-COVER**
 - polynomial-time $\rho(n)$ -approximation algorithm
 - $\rho(n)$ is a logarithmic function of set size
- **SUBSET-SUM**
 - Fully polynomial-time approximation scheme
- **MAX-3-CNF Satisfiability**
 - Randomized $\rho(n)$ -approximation algorithm



The vertex-cover problem

- Let $G=(V,E)$ be an undirected graph
- A vertex cover
 - subset V' of V
 - such that if (u,v) is an edge of G , then either u belongs in V' or v belongs in V' (or both)
- The **size of a vertex cover** is the number of vertices in it

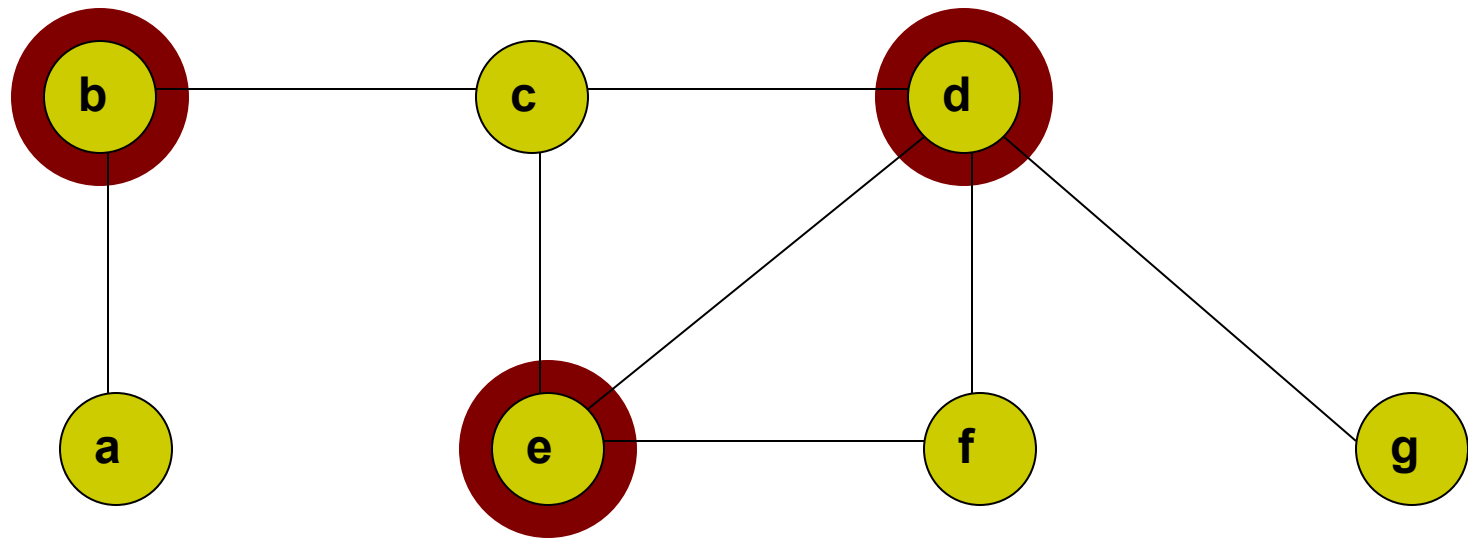
The vertex-cover problem

[cont.]



- The vertex-cover problem is to find a vertex cover of **minimum size**
- Such a vertex-cover is called an **optimal vertex cover**
- **This problem is NP-complete**

Consider the graph:



By inspection, optimal vertex cover is $\{b,d,e\}$

$C^* = \text{size of optimal solution} = 3$

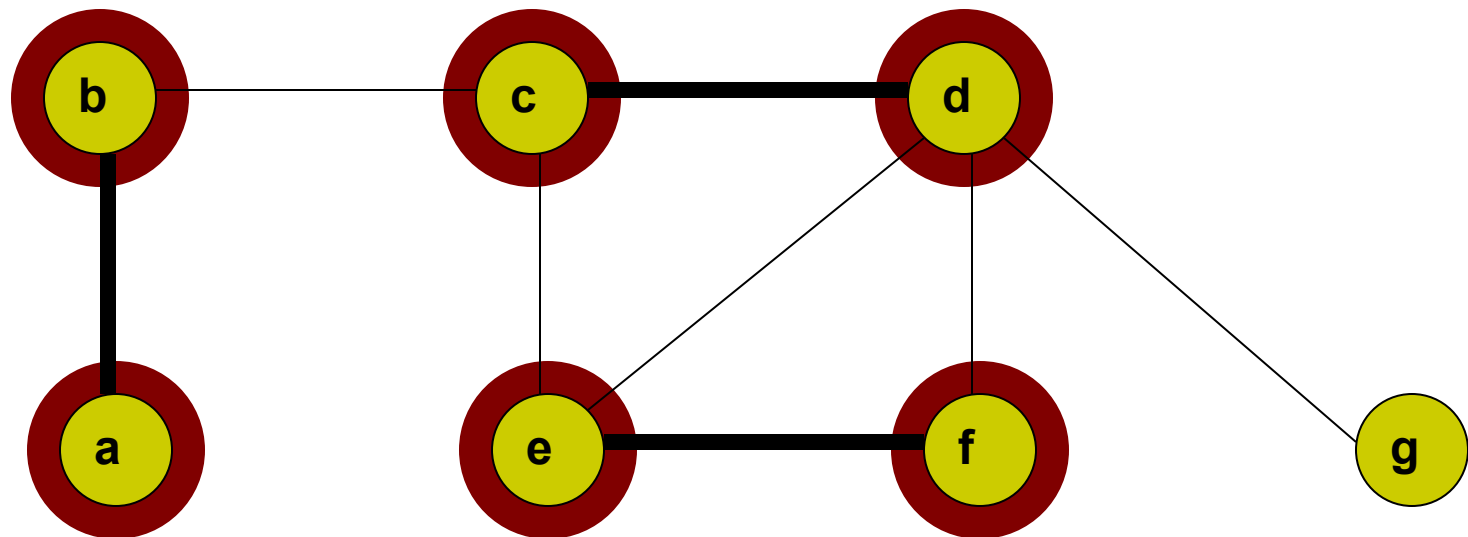


Approx-Vertex-Cover (G)

1. $C \leftarrow \text{NULL}$ //C contains results of vertex cover
2. $E' \leftarrow E[G]$ //Initially all edges are stored here
3. while $E' \neq \text{NULL}$ //all edges that are not considered yet
4. do let (u,v) be an edge of E' //select an edge from E'
5. $C \leftarrow C \cup \{u,v\}$ //add vertices to C of the selected edge
6. remove from E' all edges incident on u or v
 //delete all edges related to the vertices “u” and “v”
7. return C



Back to our graph:

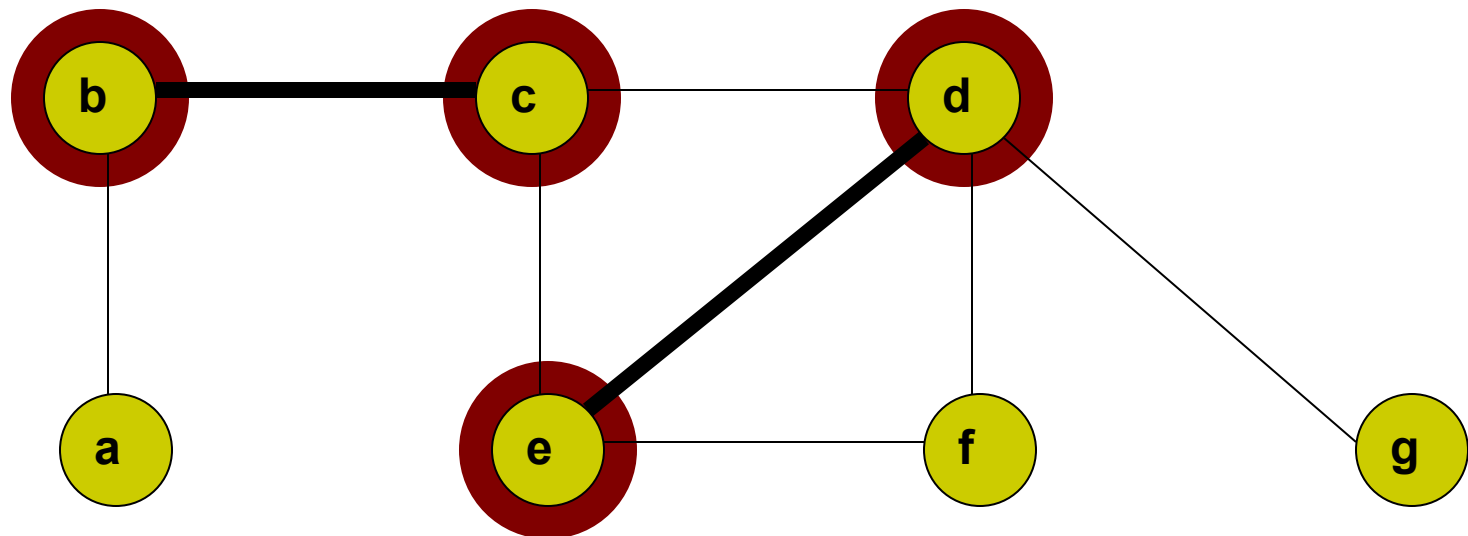


C : a b c d e f Approximate vertex cover. C=6

E' : ~~(a,b)~~ ~~(b,c)~~ ~~(c,d)~~ ~~(c,e)~~ ~~(d,e)~~ ~~(d,f)~~ ~~(d,g)~~ ~~(e,f)~~



Improved version:

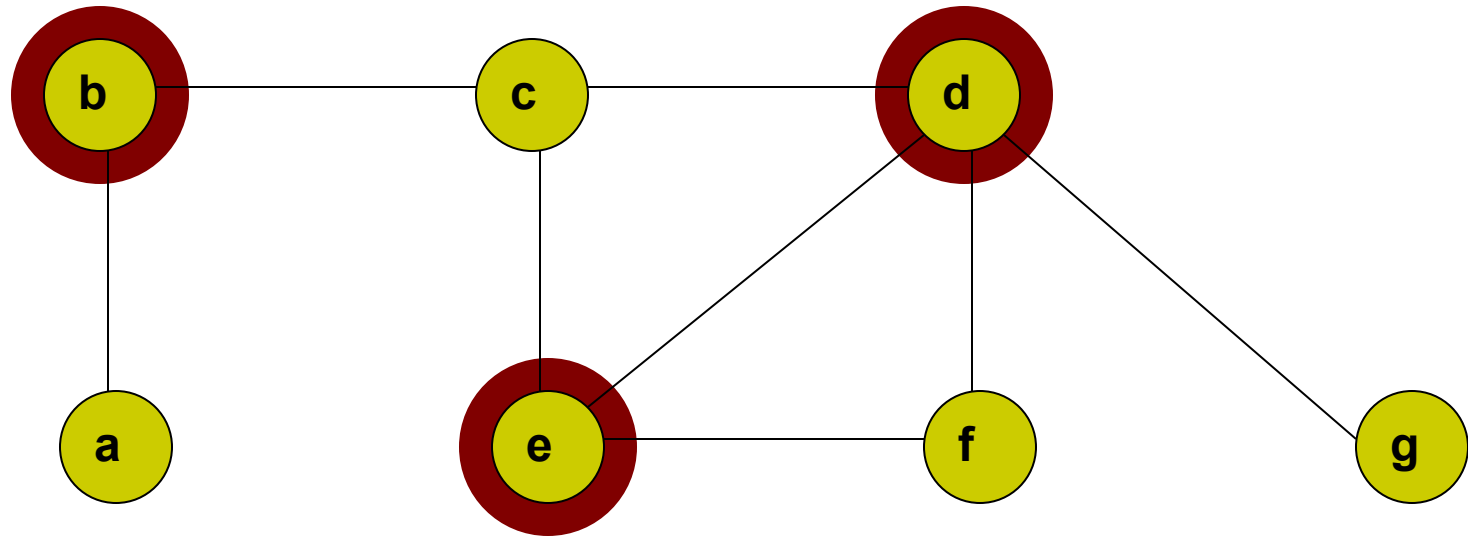
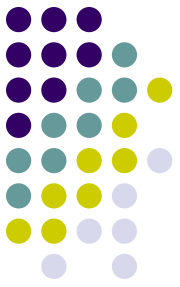


C : d e b c

Approximate vertex cover. $C=4$

E' : (d,e) (c,d) (c,e) (d,f) (d,g) (e,f) (b,c) (a,b)

Is it possible to approximate the optimal solution?



In this case, and with our algorithm, **NO!**



Analysis of Algorithm

- Running time:
 - $O(V+E)$: if we use adjacency list.
- 2-Approximation Algorithm
 - Minimization problem $C^* = 3$; $C = 6$
 - Factor = $C/C^* = 2$

Theorem: APPROX-VERTEX-COVER is a polynomial-time 2-approximation algorithm



- Proof:
 - Polynomial time algorithm because : Complexity = $O(V+E)$
 - Let, A = set of edges picked by approximation algorithm
 - No 2 edges in A share an endpoint.
 - Thus no 2 edges in A are covered by the same vertex in C^*
 - **So, Lower bound: $|C^*| \geq |A|$**
 - We pick an edge for which neither of its endpoints are already in C
 - **So, Upper bound: $|C| = 2|A|$**
 - **Therefore: $|C| = 2|A| \leq 2|C^*|$**

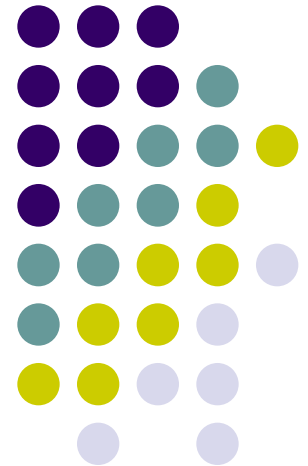
Traveling Salesman

TSP with triangle inequality

Polynomial-time 2-approximation
algorithm

TSP without triangle inequality

Negative result on
polynomial-time ρ
(n)-approximation algorithm



The traveling-salesperson problem.



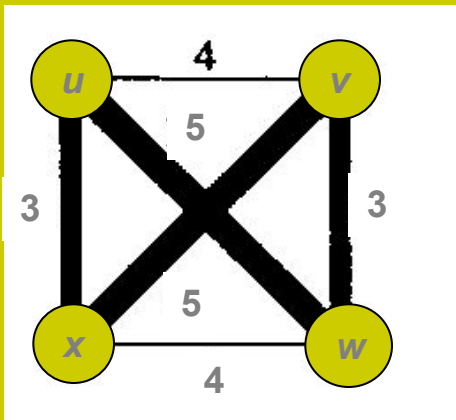
- Given a complete undirected graph $G=(V,E)$
- Each edge has a nonnegative integer cost $c(u,v)$
- Find a Hamiltonian cycle of G with minimum cost.
- This is a NP complete problem



Triangle Inequality

- The cost function satisfies the **triangle inequality** for all vertices u, v, w in V
 - $c(u,w) \leq c(u,v) + c(v,w)$

TSP with Triangle Inequality



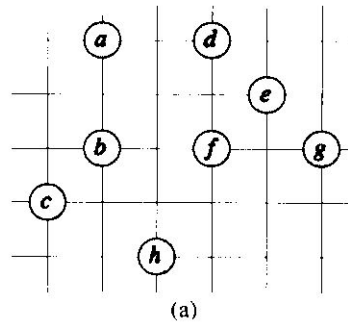
Cost Function Satisfies
Triangle Inequality

$$\forall u, v, w \in V$$

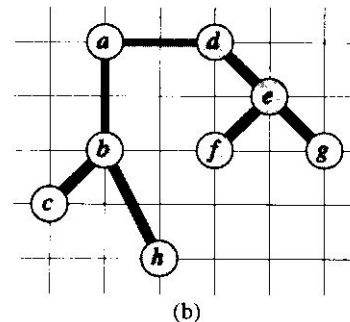
$$c(u, w) \leq c(u, v) + c(v, w)$$

APPROX-TSP-TOUR(G, c)

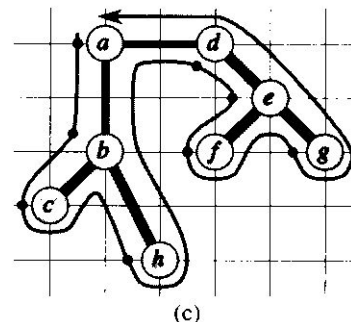
- 1 select a vertex $r \in V[G]$ to be a “root” vertex
- 2 compute a minimum spanning tree T for G from root r
using MST-PRIM(G, c, r)
- 3 let L be the list of vertices visited in a preorder tree walk of T
- 4 **return** the hamiltonian cycle H that visits the vertices in the order L



(a)

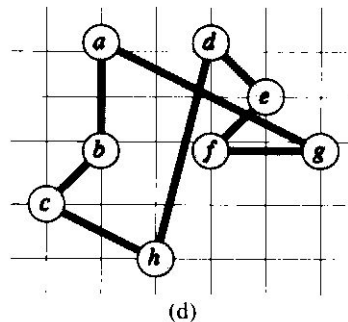


(b)

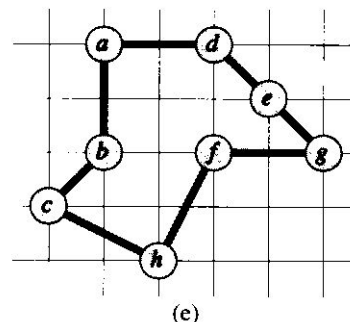


(c)

“full walk” = $abcbhbadeefegeda$



(d)



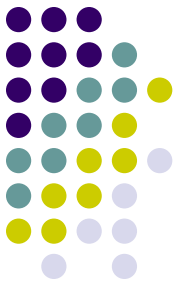
(e)

final approximate tour

optimal tour

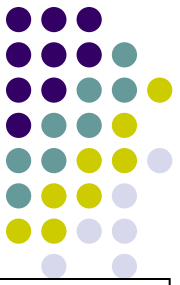
source: 91.503 textbook Cormen et al.

TSP with Triangle Inequality



- Time Complexity:
 - MST-Prim()'s running time: $O(V^2)$
 - So, APPROX-TSP-TOUR's running time: $O(V^2)$

TSP with Triangle Inequality



Theorem: APPROX-TSP-TOUR is a polynomial-time 2-approximation algorithm for TSP with triangle inequality.

Proof:

Algorithm runs in time polynomial in n .

Let H^* be an optimal tour and T be MST

$$c(T) \leq c(H^*) \quad (\text{since deleting 1 edge from a tour creates a spanning tree})$$

Let W be a full walk of T (lists vertices when they are first visited and when returned to after visiting subtree)

$$c(W) = 2c(T) \quad (\text{since full walk traverses each edge of } T \text{ twice})$$

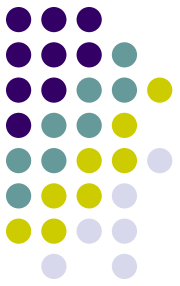
$$c(W) \leq 2c(H^*)$$

Now make W into a tour H using triangle inequality.

$$c(H) \leq c(W) \quad (\text{New inequality holds since } H \text{ is formed by deleting duplicate vertices from } W.)$$

$$c(H) \leq 2c(H^*)$$

TSP without Triangle Inequality



- If $P \neq NP$, then for any constant $\rho \geq 1$, there is no polynomial time approximation algorithm with approximation ratio ρ for the general traveling-salesman problem
- Prove: try yourself

TSP without Triangle Inequality



Theorem: If $P \neq NP$, then for any constant $\rho \geq 1$
~~polynomial-time approximation algorithm with ratio ρ~~
~~for TSP without triangle inequality.~~

Proof: (by contradiction) Suppose there is one --- call it A

Showing how to use A to solve NP-complete Hamiltonian Cycle problem  contradiction!

Convert instance G of Hamiltonian Cycle into instance of TSP (in polynomial time):

$$E' = \{(u, v) : u, v \in V, u \neq v\} \quad (G' = (V, E') \text{ is complete graph on } V)$$

$$c(u, v) = \begin{cases} 1 & (u, v) \in E \\ \rho|V| + 1 & \text{otherwise} \end{cases} \quad (\text{assign integer cost to each edge in } E')$$

For TSP problem (G', c) :

G has Hamiltonian Cycle  (G', c) contains tour of cost $|V|$

G does not have Hamiltonian Cycle  Tour of G' must use some edge not in E

$$\text{Cost of that tour of } G' \geq (\rho|V| + 1) + (|V| - 1) = \rho|V| + |V| > \rho|V|$$

Can use A on (G', c) ! A finds tour of cost at most $\rho(\text{length of optimal tour})$

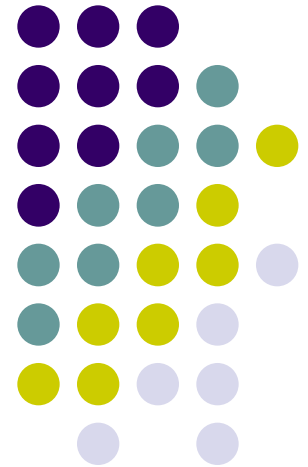
G has Hamiltonian Cycle  A finds tour of cost at most $\rho|V|$  cost = $|V|$

G does not have Hamiltonian Cycle  A finds tour of cost $> \rho|V|$

$P \neq NP$

MAX-3-CNF Satisfiability

3-CNF Satisfiability Background
Randomized Algorithms
Randomized MAX-3-CNF SAT
Approximation Algorithm



MAX-3-CNF Satisfiability

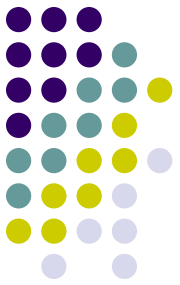


- Background on Boolean Formula Satisfiability
 - Boolean Formula Satisfiability: Instance of language **SAT** is a boolean formula ϕ consisting of:
 - n boolean variables: x_1, x_2, \dots, x_n
 - m boolean connectives: boolean function with 1 or 2 inputs and 1 output
 - e.g. AND, OR, NOT, implication, iff
 - parentheses \vee \wedge \neg \rightarrow \leftrightarrow
 - truth, satisfying assignments notions apply

$$SAT = \{ \langle \phi \rangle : \phi \text{ is a satisfiable boolean formula} \}$$

MAX-3-CNF Satisfiability

(continued)

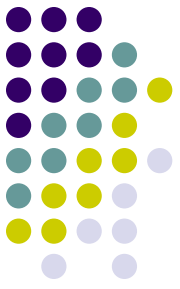


- Background on 3-CNF-Satisfiability
 - Instance of language **SAT** is a boolean formula φ consisting of:
 - *literal*: variable or its negation
 - CNF = conjunctive normal form
 - *conjunction*: AND of clauses
 - *clause*: OR of literal(s)
 - 3-CNF: each clause has **exactly 3** distinct literals

MAX-3-CNF Satisfiability: optimization version of 3-CNF-SAT

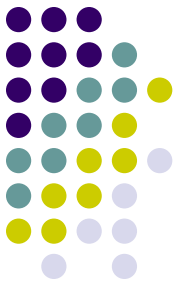
- Maximization: satisfy as many clauses as possible
- Input Restrictions:
 - exactly 3 literals/clause
 - no clause contains both variable and its negation

Randomized approximation algorithm for MAX-3-CNF-SAT



- Each clause has 3 distinct literals. Also assume that no clause contains a variable and its negation.
- **Problem**: Return an assignment of variables which maximizes the number of clauses which evaluate to true.

The random approximation algorithm



- **Randomly assign a 0 or a 1 value to all variables.**



Analysis

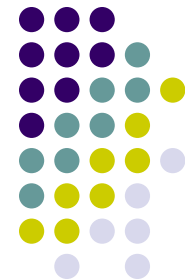
- We have set each variable to 1 with a $\frac{1}{2}$ probability.
- We have set each variable to 0 with a $\frac{1}{2}$ probability.
- We define an indicator random variable
 - $Y_i = I \{\text{clause } i \text{ is satisfied}\}$
- $Y_i = 1$ as long as at least one of the literals in the i^{th} clause has been set to 1.
- A clause is not satisfied iff all its literals are 0.
 - $\Pr \{\text{clause } i \text{ is not satisfied}\} = (\frac{1}{2})^3 = 1/8$



Analysis [cont.]

- So $\Pr \{\text{clause } i \text{ is satisfied}\} = 1 - 1/8 = 7/8$
- Lemma 5.1 (CLRS)
 - Given a sample space S and an event A in the sample space, let $X_A = I\{A\}$. Then $E[X_A] = \Pr\{A\}$
- $E[Y_i] = 7/8$

Analysis [cont.]



- Let Y = number of satisfied clauses.
 - $Y = Y_1 + Y_2 + \dots + Y_m$
- Then we have:

$$\begin{aligned} E[Y] &= E\left[\sum_{i=1}^m Y_i\right] \\ &= \sum_{i=1}^m E[Y_i] \\ &= \sum_{i=1}^m 7/8 \\ &= 7m/8 \end{aligned}$$

- Since m is the upper bound on the number of satisfied clauses, the approximation ratio is $m/(7m/8) = 8/7$
- Therefore this is a $8/7$ approximation algorithm