

Object Centric Abnormality Detection by Attribute Based Reasoning

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How do you describe this object? What class is this object?

Car Boat Sofa Airplane Independent of its object category, it looks **Abnormal!**

We Argue that **Abnormalities** are among most important components that form what worth mentioning.
We are Proposing a method that **Recognize Abnormalities** in images and **Reports Weird Visual Attributes**.

Research Questions

- I) What is Abnormality? A: There is NO clear answer for it!
- II) What can make an image look weird? A: Large variety of sources!
- III) Is it a simple Two-way classification (Normal vs. Abnormal)?

A: It is not a straightforward classification problem.

We can not use abnormal images for training the classifier mainly because:

- 1) Imbalanced number of Abnormal objects comparing to Normal objects.
- 2) People are able to judge Normality while they have not seen any Abnormal.

We only use Normal objects for learning a “Typicality Model” and represents Abnormality as meaningful deviation from Normality.

Dataset

- Cause of Abnormality: I) Abnormalities rooted in Object by itself (**Our Focus**)
- II) Context related Abnormality

We present the **First Dataset on Abnormal Objects**. Along with a **Novel Human Subject Experiment** to acquire Ground truth annotation.

Data acquisition**Human Subject Experiment**

- ❖ Ten human subject for each image
- ❖ Outlier responders are removed
- ❖ Averaging responses across users

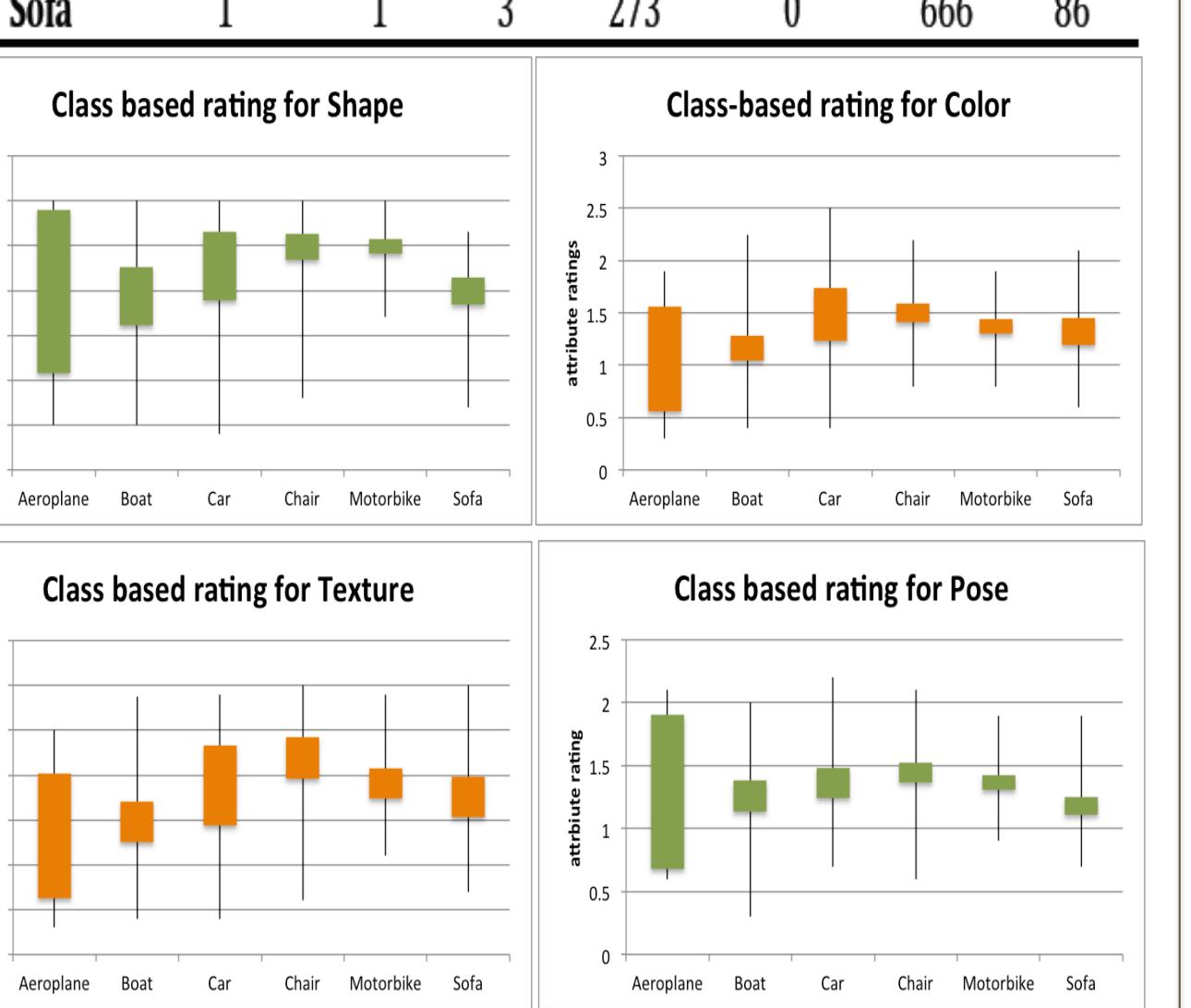
Here are some insights:

- § It is even hard for Human to categorize Abnormal Objects

§ Across different cues, **Shape** is the most important reason for abnormality.

§ Except for Aeroplane people are sure about the cause of Abnormality.

	Aeroplane	Boat	Car	Chair	Motorbike	Sofa	None
Aeroplane	908	10	7	1	0	0	51
Boat	62	868	57	0	1	1	44
Car	7	9	1072	3	0	1	52
Chair	0	1	11	861	1	166	36
Motorbike	17	0	31	3	540	0	38
Sofa	1	1	3	273	0	666	86

**Proposed Abnormality Model**

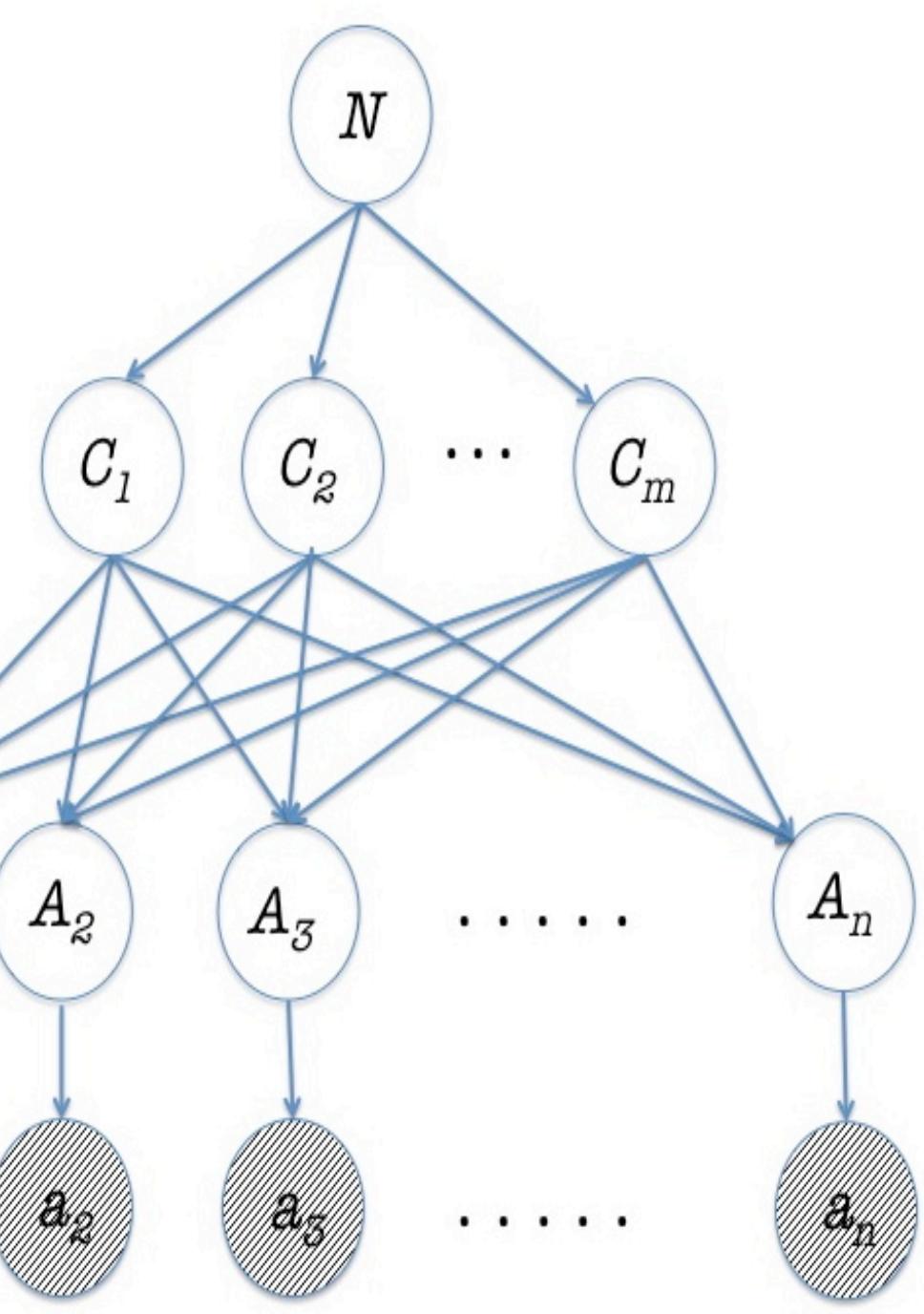
Normality assumption (N) imposes a peaked distribution over Object Classes (C). As a result multimodal and uniform distributions over Categories suggests Abnormality.

Considering this point, Normality Model can be illustrated by this graphical model:

Conditioned on observed visual attributes (A) and without any assumption on the object class, Abnormality is the complement event of Normality:

$$P(\neg N|A) = 1 - P(N|A)$$

$$P(N|A) = P(A|N) * P(N)/P(A)$$



Estimating the joint attribute likelihood by marginalizing over object Classes: $P(A|N) = \sum_j P(A|C_j, N)P(C_j|N)$ and as given

An object class, attributes are independent:

$$P(A|N) = \sum_j \prod_{i=1}^k P(A_i|C_j, N)P(C_j|N)$$

For a given object class, each visual attribute has a different importance factor. We measured it by Conditional Entropy:

$$I(A_i = a|C_j, N) = -\log P(A_i = a|C_j, N)$$

As the learned attribute classifiers are not perfect we consider their accuracy during learning as a measure of their reliability:

$$surprise_{(A_i|C_j)}(a) = reliability(A_i) * I(A_i = a|C_j) * relevance(A_i|C_j)$$

$$signed_surprise_{(A_i|C_j)}(a) = surprise_{(A_i|C_j)}(a) * (2*a - 1)$$

Experimental Results**I) Abnormality Prediction**

* We use Normal images from Pascal dataset and Abnormal images from our dataset.

* Parameters are learned **ONLY** on Normal objects, which are represented by 64 Visual attributes.

* Our model has a better accuracy for Abnormality Detection (we are not using any abnormal images – during training). Second row shows the result for the case of using Abnormal images during training a classifier.

* Using surprise score, we are able to rank images based on how abnormal they look :

**II) Abnormal Attribute Reporting**

* Given an abnormal instance from an object class, we can Determine Missing (M) and Unexpected (U) attributes.

* For quantitative results, we made the baseline based on: Farhadi et al (CVPR 2009) which assumes a Gaussian Distribution over attributes for normal objects.

* To be comparable with human responses we have grouped Visual attributes into disjoint lists, representing : **Shape, Pose, Color and Texture**.

{Numbers are KL-Divergence}							
Method	Airplane	Boat	Car	Chair	Motorbike	Sofa	Average
Baseline I	0.0796	0.0801	0.0775	0.1035	0.0944	0.064	0.0832
Baseline II	0.0826	0.0768	0.0809	0.0956	0.0892	0.0565	0.0803
Our Model	0.0567	0.0369	0.0758	0.0631	0.0635	0.0695	0.0609

Aeroplane: (U):Wheel,Clear
(M):Tail,Jet,Engine,Rov,Wn,Car : (U):Skin,Clear,Propeller,Wing (M):Handlebars

Aeroplane: (M):Label,Taillight (U):
Mast,Boat : (U):Propeller,Glass,Wheel (M):Mast,Wood

Aeroplane: (U):Skin,Engine,Wheel
(M):Most,Text,Label,(M):Label,Clear,Tail (U):Engine,Skin

Boat: (U):Skin,Engine,Wheel
(M):Most,Text,Label,(M):Label,Clear,Tail (U):Engine,Skin

III) Abnormality Detection helps Object Categorization

* By knowing an object is an abnormal instance of a given class, we will have a list of attributes which made this object look weird.

* Adjusting these abnormal attributes with what is expected from a normal instance, will improve the object categorization task.

* We Measure KL-Divergence between Distribution over object categories using TURK vs. our Model

KL-Divergence
SVM classification **before** 47.2502

Abnormality detection

SVM classification **after** 38.5203

Abnormality detection