Image Processing and Computer Vision (IPCV)



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Example Solutions for Homework Assignment 3 (H3)

Problem 1 (Discrete Fourier Transform)

We show that it holds for all $p, q \in \{0, ..., M - 1\}$:

$$\langle \boldsymbol{b}_p, \boldsymbol{b}_q \rangle = \begin{cases} 1, & \text{if } p = q \\ 0, & \text{else} \end{cases}$$

First we consider $p, q \in \{0, ..., M-1\}, q = p$. We have

$$\langle \boldsymbol{b}_{p}, \boldsymbol{b}_{q} \rangle = \sum_{m=0}^{M-1} \frac{1}{\sqrt{M}} \exp\left(\frac{2\pi i p m}{M}\right) \overline{\frac{1}{\sqrt{M}}} \exp\left(\frac{2\pi i q m}{M}\right)$$

$$= \frac{1}{M} \sum_{m=0}^{M-1} \exp\left(\frac{2\pi i p m}{M}\right) \exp\left(-\frac{2\pi i q m}{M}\right)$$

$$= \frac{1}{M} \sum_{m=0}^{M-1} \exp\left(\frac{2\pi i (p-q)m}{M}\right)$$

$$= \frac{1}{M} \sum_{m=0}^{M-1} \exp\left(0\right)$$

$$= \frac{M}{M} = 1$$

Now we consider $p, q \in \{0, ..., M-1\}, q \neq p$. It holds that

$$\langle \boldsymbol{b}_{p}, \boldsymbol{b}_{q} \rangle = \frac{1}{M} \sum_{m=0}^{M-1} \exp\left(\frac{2\pi i(p-q)m}{M}\right)$$

$$= \frac{1}{M} \sum_{m=0}^{M-1} \left(\exp\left(\frac{2\pi i(p-q)}{M}\right)\right)^{m}$$

$$\stackrel{(1)}{=} \frac{1}{M} \frac{1 - \left(\exp\left(\frac{2\pi i(p-q)}{M}\right)\right)^{M}}{1 - \exp\left(\frac{2\pi i(p-q)M}{M}\right)}$$

$$= \frac{1}{M} \frac{1 - \exp\left(\frac{2\pi i(p-q)M}{M}\right)}{1 - \exp\left(\frac{2\pi i(p-q)M}{M}\right)}$$

$$\stackrel{(2)}{=} \frac{1}{M} \frac{1 - \exp\left(2\pi i(p-q)\right)}{1 - \exp\left(\frac{2\pi i(p-q)}{M}\right)}$$

$$= \frac{1}{M} \frac{1 - 1}{1 - \exp\left(\frac{2\pi i(p-q)}{M}\right)}$$

$$= 0$$

with

(1) For $r \neq 1$, the sum of the first n terms of a geometric series is

$$\sum_{k=0}^{n-1} r^k = \frac{1 - r^n}{1 - r}$$

We have

$$0 \le p, q < M \Rightarrow \frac{p-q}{M} \notin \mathbb{Z} \Rightarrow \exp\left(\frac{2\pi i (p-q)}{M}\right) \ne 1.$$

(2)
$$(p-q) \in \mathbb{Z} \Rightarrow \exp(2\pi i (p-q)) = 1$$

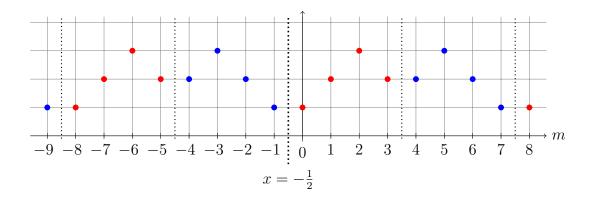
As the set $\{\boldsymbol{b}_0,...,\boldsymbol{b}_{M-1}\}$ has cardinality M, it follows that it forms an orthonormal basis of the M-dimensional vector space \mathbb{C}^M with respect to $\langle\cdot,\cdot\rangle$.

Problem 2: (Relation between DFT and DCT)

We have the discrete signal g defined as:

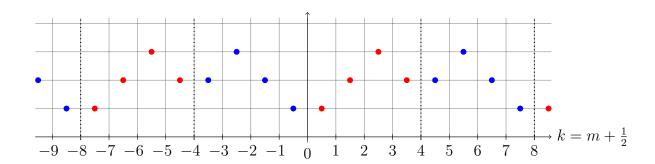
$$g_m := \begin{cases} f_m, & \text{if } 0 \le m \le M - 1\\ f_{2M - m - 1}, & \text{if } M \le m \le 2M - 1 \end{cases}$$
 (1)

This signal is identical to f for $0 \le i \le M-1$ and identical to a mirrored version of f for $M \le i \le 2M-1$. We now assume this signal to be extended periodically with period 2M over \mathbb{Z} . Below you can see a sample sketch of the function g with M=4.



As we can see, the whole signal g is symmetric with respect to the point $x = -\frac{1}{2}$. Also note that $g_m = g_{-m-1} = g_{2M-m-1}$.

In order to get a symmetry with respect to x'=0, we have to shift the signal by $\frac{1}{2}$ to the right, which means that we define a new, shifted signal \boldsymbol{h} and a (non-integer) index $k \in \{\frac{2l+1}{2}|l \in \mathbb{Z}\}$ such that $h_k = g_{k-\frac{1}{2}}$. The result of this index-shift can be seen in the figure below.



We can now compute the discrete Fourier transform (DFT) of \boldsymbol{g} at a point $p \in \{0,..,2M-1\}$ to obtain a slightly modified discrete cosine transform (DCT) of the original signal \boldsymbol{f} . However, we have only defined the DFT for the grid points at integer points while the samples of the shifted signal are defined on a intermediate positions $k = m + \frac{1}{2}$. Therefore we use the shift theorem to express \boldsymbol{h} in terms of the unshifted signal \boldsymbol{g} which lives on the original discrete grid $m = k - \frac{1}{2}$.

$$\begin{aligned} \operatorname{DFT}\left[h_{k}\right]_{p} &= \operatorname{DFT}\left[g_{k-\frac{1}{2}}\right]_{p} \\ &\stackrel{\text{(1)}}{=} \exp\left(\frac{-i2\pi\frac{1}{2}p}{2M}\right) \operatorname{DFT}\left[g_{m}\right]_{p} \\ &= \exp\left(\frac{-i\pi p}{2M}\right) \operatorname{DFT}\left[g_{m}\right]_{p} \\ &\stackrel{\text{(2)}}{=} \exp\left(\frac{-i\pi p}{2M}\right) \frac{1}{\sqrt{2M}} \sum_{m=0}^{2M-1} g_{m} \exp\left(\frac{-i2\pi pm}{2M}\right) \\ &= \frac{1}{\sqrt{2M}} \sum_{m=0}^{2M-1} g_{m} \exp\left(\frac{-i\pi p(2m+1)}{2M}\right) \\ &\stackrel{\text{(3)}}{=} \frac{1}{\sqrt{2M}} \sum_{m=0}^{2M-1} g_{m} \left(\cos\left(\frac{\pi p(2m+1)}{2M}\right) - i\sin\left(\frac{\pi p(2m+1)}{2M}\right)\right) \\ &= \frac{1}{\sqrt{2M}} \sum_{m=0}^{2M-1} g_{m} \cos\left(\frac{\pi p(2m+1)}{2M}\right) - \underbrace{\frac{1}{\sqrt{2M}}i \sum_{m=0}^{2M-1} g_{m} \sin\left(\frac{\pi p(2m+1)}{2M}\right)}_{=0, \text{ since sine is odd and } g_{m} = g_{2M-(m+1)} \end{aligned}$$

$$&= \frac{1}{\sqrt{2M}} \sum_{m=0}^{2M-1} g_{m} \cos\left(\frac{\pi p(2m+1)}{2M}\right) \\ &\stackrel{\text{(4)}}{=} 2\frac{1}{\sqrt{2M}} \sum_{m=0}^{M-1} f_{m} \cos\left(\frac{\pi p(2m+1)}{2M}\right) \\ &= \sqrt{\frac{2}{M}} \sum_{m=0}^{M-1} f_{m} \cos\left(\frac{\pi p(2m+1)}{2M}\right) \end{aligned}$$

Here, the following properties have been used:

(1) Shift Theorem, rename index to m (completely optional)

- (2) Definition of the Discrete Fourier Transform
- (3) $\exp(\phi) = \cos(\phi) + i\sin(\phi)$
- (4) $g_m = g_{2M-m-1}$, the definition of g in terms of f and the fact that the cosine function is even

As we can see, we are able express our signal in terms of the basis vectors \mathbf{v}_p (p = 0, ..., M - 1) with

$$v_p = \sqrt{\frac{2}{M}} \left(\cos \left(\frac{\pi p(2m+1)}{2M} \right) \right)_{m=0,\dots,M-1}^{\top}$$
$$= \sqrt{\frac{2}{M}} \left(\cos \left(\frac{\pi p}{2M} \right), \cos \left(\frac{\pi p \cdot 3}{2M} \right), \cos \left(\frac{\pi p \cdot 5}{2M} \right), \dots, \cos \left(\frac{\pi p(2M-1)}{2M} \right) \right)^{\top}$$

A simple computation shows that these vectors are orthogonal to each other. Regarding the norm, one can see:

$$||v_p|| = \sqrt{\sum_{m=0}^{M-1} \frac{2}{M} \cos^2\left(\frac{\pi p(2m+1)}{2M}\right)} = \begin{cases} \sqrt{2}, & \text{if } p = 0\\ 1, & \text{if } p = 1, ..., M-1 \end{cases}$$
 (2)

To make the transformation orthonormal we can further use the coefficients

$$c_p := \begin{cases} \sqrt{\frac{1}{M}}, & \text{if } p = 0\\ \sqrt{\frac{2}{M}}, & \text{if } p = 1, .., M - 1 \end{cases}$$

It follows that the DCT can be derived via the Discrete Fourier Transform of a shifted and mirrored signal.

Problem 3 (Interpretation of the Fourier Spectrum)

- (a) Cut-off errors. Each of the three Gaussians is cut at the image boundaries, and treated as periodically repeated by the Fourier transform. While for the small kernels gauss1.pgm and gauss2.pgm the values at the image boundaries are close enough to 0 to leave no visible effects in the Fourier spectrum, the cutting off of fairly large values in gauss3.pgm spoils the rotational invariance of the Gaussian itself and therefore of its Fourier spectrum.
- (b) The lines in tile.pgm induce in the Fourier spectrum visible beams starting off in the centre and directed perpendicular to the corresponding lines.

The reason is that a single edge in the spatial domain is represented by a superposition of wave-like patterns of different frequencies but equal direction. The phases and amplitudes of these waves are adjusted such that their slopes add up to give the edge at the specified location but cancel elsewhere.

A close look at the spectrum of tile.pgm reveals that there are beams that do not go out radially from the centre but from the image boundary. These are traces of aliasing effects.

Remembering that images and also Fourier spectra are treated periodically by the DFT we see that some of the radial lines extending from the centre do not end at the image boundaries but are prolongated beyond that boundary, wrapping around to the opposite image boundaries. Translated into frequencies: These lines depict high frequencies which don't fit in our Fourier spectrum but are represented in it by lower frequencies. This is aliasing.

Problem 4 (Filtering in the Fourier Domain)

(a) From C3, Problem 1 and the lecture we know that wave-like patterns generate 3-point spectra which are oriented in the same way as the wave pattern. Vertical line artefacts as the ones smoke.pgm are generated by the superposition of many such wave-patterns. Therefore, the three-point spectra of such wave patterns form a horizontal line of coefficients with a high contribution to the spectrum. Setting the coefficients on this line to zero successfully removes the line artifacts. The overall quality of the image smoke.pgm is affected only slighly, since the removal of these frequencies does not remove too many significant structures of the smoke (see Figure 1).

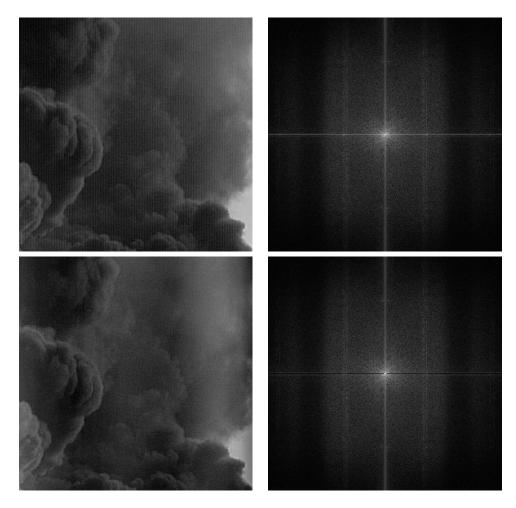


Table 1: Filtering results for smoke.pgm. (a) Top left: original image. (b) Top right: original Fourier spectrum. (c) Bottom left: filtered image. (d) Bottom right: filtered Fourier spectrum.

(b) For the image fire.pgm, a similar approach can be used to remove the artifacts. However, the vertical structures in the corrugated iron sheets of the hut create problems. These vertical structures occupy similar frequencies as the artifacts in the image. Removing the vertical line artifacts by removing the corresponding Fourier coefficients therefore destroys much more of the actual image structure than in the smoke example (see Figure 2).

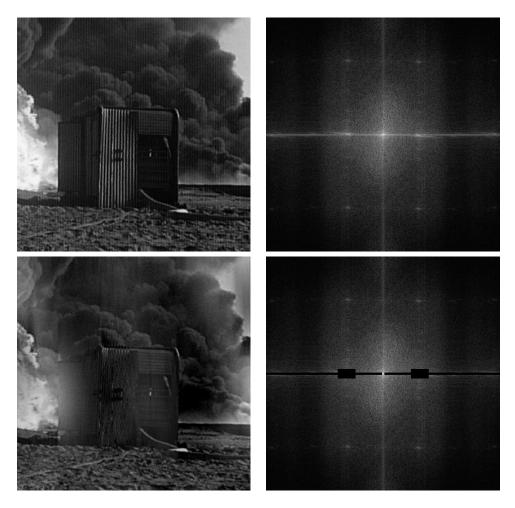


Table 2: Filtering results for fire.pgm. (a) Top left: original image. (b) Top right: original Fourier spectrum. (c) Bottom left: filtered image. (d) Bottom right: filtered Fourier spectrum.