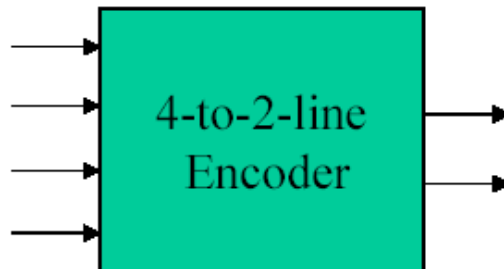


# **Encoder, Priority Encoder**

**By Engr. Rimsha**

# Encoders

- An **encoder** is a digital circuit that performs the **inverse operation** of a **decoder**.
- An encoder has  $2^n$  (or fewer) **input** lines and **n** **output** lines.
- The output lines generate the **binary code** corresponding to the input value



# Truth Table: Octal to Binary Encoder

Inputs								Outputs		
$D_0$	$D_1$	$D_2$	$D_3$	$D_4$	$D_5$	$D_6$	$D_7$	$x$	$y$	$z$
1	0	0	0	0	0	0	0	0	0	0
0	1	0	0	0	0	0	0	0	0	1
0	0	1	0	0	0	0	0	0	1	0
0	0	0	1	0	0	0	0	0	1	1
0	0	0	0	1	0	0	0	1	0	0
0	0	0	0	0	1	0	0	1	0	1
0	0	0	0	0	0	1	0	1	1	0
0	0	0	0	0	0	0	1	1	1	1

$$z = D_1 + D_3 + D_5 + D_7$$

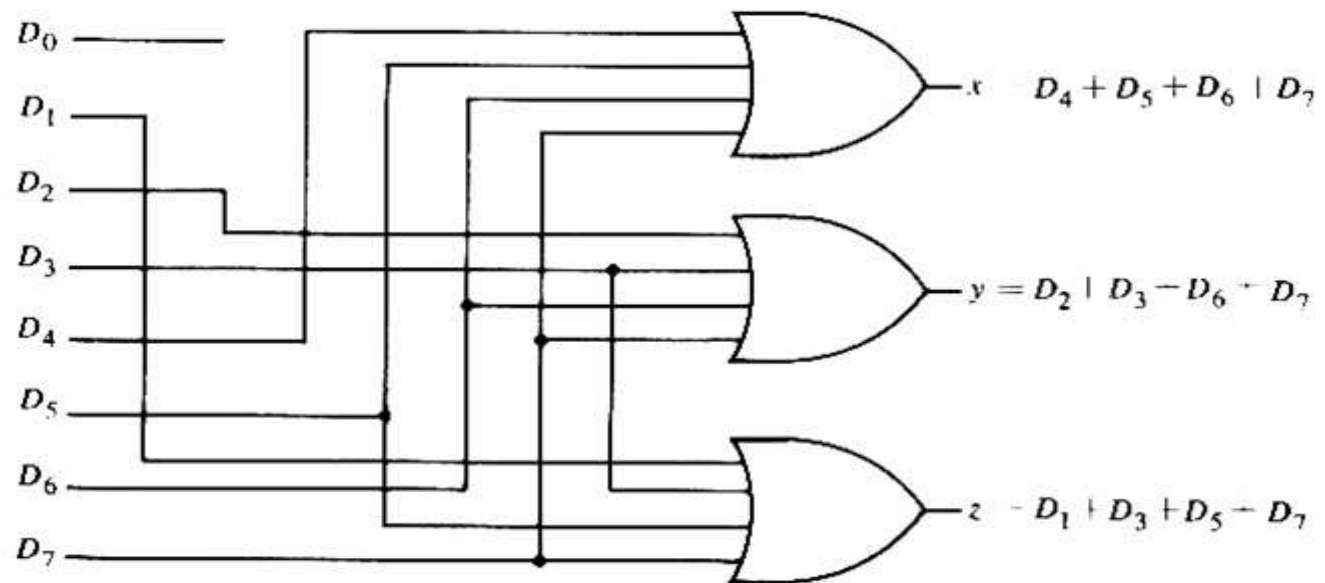
$$y = D_2 + D_3 + D_6 + D_7$$

$$x = D_4 + D_5 + D_6 + D_7$$

# Encoder: Example

- An example of encoder is octal-to-binary encoder
- It has eight inputs (one for each octal digit) and three outputs that generate the corresponding binary number
- It is assumed that only one input has a value of 1 at any given time
- The encoder can be implemented with OR gates whose inputs are determined directly from the truth table
- Output z is equal to 1 when the input octal digit is 1,3,5 or 7. Output y is 1 for octal digits 2,3,6 or 7 and output x is 1 for digits 4,5,6 or 7. These conditions can be expressed as by the Boolean functions as shown in the previous slide

# Octal to Binary Encoder Implementation



$$z = D_1 + D_3 + D_5 + D_7$$

$$y = D_2 + D_3 + D_6 + D_7$$

$$x = D_4 + D_5 + D_6 + D_7$$



# Priority Encoder

- A **priority encoder** is an encoder circuit that includes the **priority function**.
- The operation of the **priority encoder** is such that if two or more inputs are equal to 1 at the same time, the **input** having the **highest priority** will take **precedence**
  - $D_3$  has the highest priority
  - $D_0$  has the lowest priority
- **Valid bit indicator** (V) is set to 1 when one or more inputs are equal to 1. If all inputs are 0, there is no valid inputs and V is equal to 0. The other two outputs are **not inspected** when **V equals 0** and are specified as don't care conditions

# Priority Encoder: Expanded Truth Table

$D_0$	$D_1$	$D_2$	$D_3$	$x$	$y$	$V$
0	0	0	0	X	X	0
0	0	0	1	1	1	1
0	0	1	0	1	0	1
0	0	1	1	1	1	1
0	1	0	0	0	1	1
0	1	0	1	1	1	1
0	1	1	0	1	0	1
0	1	1	1	1	1	1
1	0	0	0	0	0	1
1	0	0	1	1	1	1
1	0	1	0	1	0	1
1	0	1	1	1	1	1
1	1	0	0	0	1	1
1	1	0	1	1	1	1
1	1	1	0	1	0	1
1	1	1	1	1	1	1

**Truth Table of a Priority Encoder**

Inputs				Outputs		
$D_0$	$D_1$	$D_2$	$D_3$	$x$	$y$	$V$
0	0	0	0	X	X	0
1	0	0	0	0	0	1
X	1	0	0	0	1	1
X	X	1	0	1	0	1
X	X	X	1	1	1	1

# Priority Encoder: Truth Table

Input				Output		
$D_0$	$D_1$	$D_2$	$D_3$	x	y	v
0	0	0	0	X	X	0
1	0	0	0	0	0	1
X	1	0	0	0	1	1
X	X	1	0	1	0	1
X	X	X	1	1	1	1

–X: don't-care conditions in the output, used in the inputs to condense truth table, replaced by both 0 and then 1

–V: valid output indication, implemented by OR function



# Maps for Priority Encoder

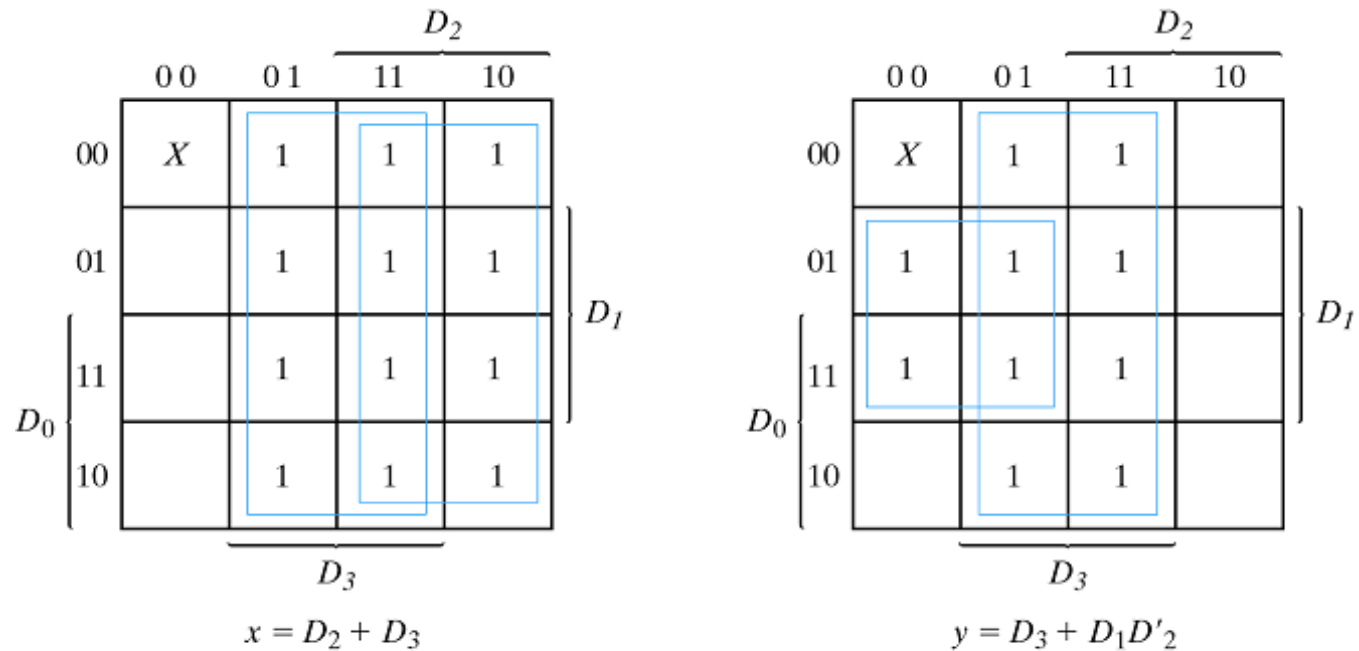
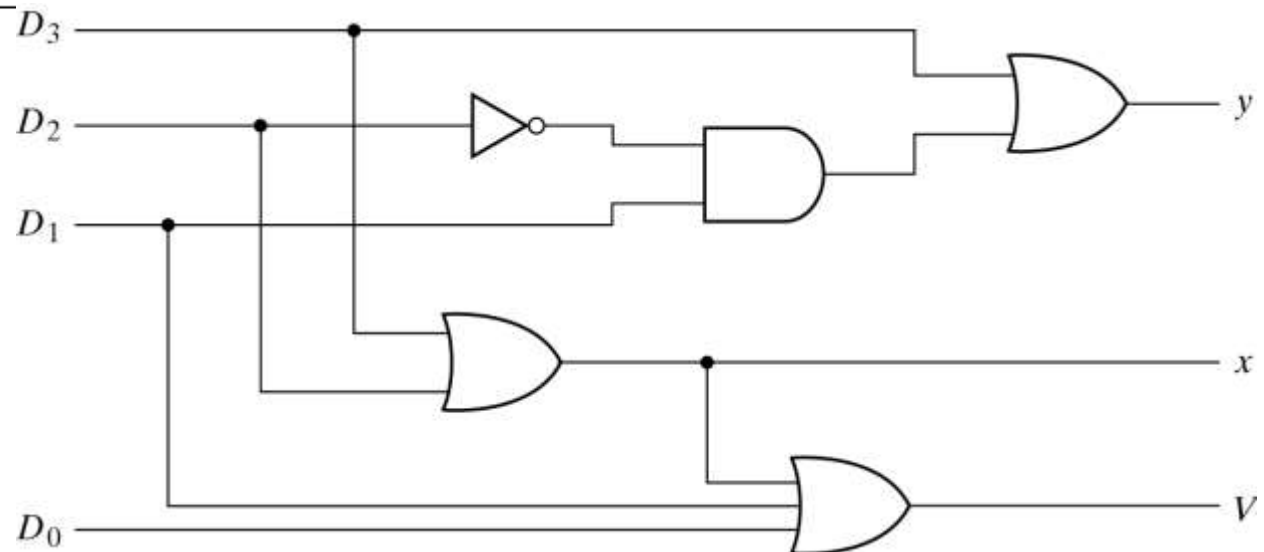


Fig. 4-22 Maps for a Priority Encoder

# Priority Encoder: Logic circuit

**Truth Table of a Priority Encoder**

Inputs				Outputs		
$D_0$	$D_1$	$D_2$	$D_3$	$x$	$y$	$V$
0	0	0	0	X	X	0
1	0	0	0	0	0	1
X	1	0	0	0	1	1
X	X	1	0	1	0	1
X	X	X	1	1	1	1





# Practice Problem

- Design a Priority Encoder with Priority to Lower Subscript

End of Lecture