

# ERIC SOLOMON

FULLSTACK ENGINEER & TECHNOLOGY GENERALIST



## EXPERIENCES

2020

### Senior Fullstack Engineer

Upstack

📍 (remote)

- Work dynamically and autonomously with independent clients to create fullstack applications in NodeJS, ReactJS, Go, Python, SQL, and NoSQL
- Maintain ownership of and accountability for continuous integration pipeline

2019

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2018

### Fullstack Engineer

Boid: Social Supercomputer

📍 (remote)

- Design, implement, and manage blockchain-based system to run a medium-scale distributed computing cluster using Python, Javascript, C++ and SQL
- Participate in startup funding proposal and business outreach processes

2018

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2016

### Graduate Research Assistant

Alfred Gessow Rotorcraft Center

📍 College Park, Maryland

- Create state-of-art, resource-constrained aerial robotics systems, including computer vision, controls, and artificial intelligence using Python and C++
- Manage engineering pipeline for undergraduate, graduate, and third-party collaborators including the U.S. military
- Publish papers, write contract proposals, and speak at technical conferences



## SELECTED PROJECTS

2020

### GatsbyJS

GatsbyJS

- Contribute to the GatsbyJS static-site generator using NodeJS and ReactJS
- Document & demonstrate asynchronous plugin usage
- Update to image components to maintain HTML validation

2020

### Linkerd

Linkerd

- Contribute to the Linkerd service mesh using Go and Rust
- Incorporate RSA-based PKI certifications
- Validate compatibility of Kubernetes service accounts

2020

### Personal projects

Personal

- Create serverless and microservice-based projects with modern techniques using ReactJS, Typescript, NodeJS, Go, Python, SQL, NoSQL, and containers
- Fractalooze: Compress images up to 15x compression rate using fractals. Integrate with JAMstack-based display and API.
- Graphtools: Create a general purpose graph for visualizing and testing algorithms using Go, websockets, and ReactJS
- AAAB: Create a serverless webapp for dataset source validation to experiment with quantum computing using IBM Qiskit, Python, and ReactJS

2019

|

2018

### BOLD-EOS

Boid

- Manage the effectiveness of BOLD teams, which sell personal computing power and compete for prizes using EOSIO and World Community Grid platforms for secure, distributed, redundant cluster computing
- Create API endpoints based on the EOSIO public blockchain and Boid-run, customer-facing NodeJS servers

2018

### Metaltail Hybrid VTOL Vehicle

Alfred Gessow Rotorcraft Center

- Design and analyze avionics and controls systems for a hybrid hover & forward-flight vehicle for use in urban environments
- Collaborate with a team of aerospace engineers to analyze budget, weight, and technology-readiness of the entire vehicle

## SOCIAL INFO

🌐 [errcsool.com](https://errcsool.com)  
🐙 [github.com/han-solomon](https://github.com/han-solomon)  
📄 [stackoverflow.com/users/3271700/errolflynn](https://stackoverflow.com/users/3271700/errolflynn)  
✉ [errcsool@engineer.com](mailto:errcsool@engineer.com)  
in [linkedin.com/in/eric-solomon-35a22490](https://linkedin.com/in/eric-solomon-35a22490)

## SKILLS

Web design  
Serverless  
Microservices  
Javascript & Typescript  
Go  
NodeJS & ReactJS  
HTML5 & CSS3  
SQL & NoSQL  
GraphQL & REST  
  
Container orchestration  
Docker & Kubernetes  
Service mesh (incl Linkerd)  
Blockchain (incl EOSIO)  
  
Data science  
Machine learning & AI  
Vehicle control  
Computer vision  
Python  
C++  
Tensorflow  
  
Git  
CI/CD  
Linux  
Bash



## EDUCATION

2018  
|  
2016

### **M.Sc. in Aerospace Engineering**

University of Maryland

📍 College Park, Maryland

- Focus in aerial robotics
- GPA: 3.47

2016  
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2012

### **B.Sc. in Aerospace Engineering**

University of Maryland

📍 College Park, Maryland

- Minor in Computer Science
- GPA: 3.40



## PUBLICATIONS

2019

"Reinforcement Learning Control for Quadrotors using Snapdragon Flight". E. Solomon, A. Shastry, V. Hrishikeshvan, I. Chopra. 8th Biennial Technical Meeting on VTOL Unmanned Aircraft Systems and Autonomy. Mesa, AZ. Jan 2019

2018

"Autonomous Quadrotor Control and Navigation with Snapdragon Flight". E. Solomon, V. Hrishikeshvan, I. Chopra. 74th American Helicopter Society International Forum. Phoenix, AZ. May 2018

2017

"Visual Odometry Onboard a Micro Air Vehicle Using Snapdragon Flight". E. Solomon, C. Vorwald, V. Hrishikeshvan, I. Chopra. 7th American Helicopter Society Technical Meeting on VTOL Unmanned Aircraft Systems and Autonomy. Mesa, AZ. Jan 2017.



## AWARDS

2018

2018 American Helicopter Society Graduate Design Prize