Requirements Analysis:

the humanoid robot with coffee serving feature

This is requirements analysis for adding a new feature (coffee serving) to our humanoid robot. It includes all the departments that work on the robot: Mechanical Engineering Department, Electronics and Power Department, Robotics and AI Department and IOT and software development. The goal of this requirements analysis is to distinguish between functional requirements and non-functional requirements in each department.

The Requirements For Mechanical Engineering Department:

functional requirements:	Non-functional requirements:
1- Balanced humanoid robot.	1- Designing white covers for the arms + hand structures.
2- Floyd dynamic force analysis for a small amount of liquid in humanoid robot to make it able to serve coffee.	
3- Designing structures of the robot arms and making them suitable for serving coffee.	

The Requirements For Electronics and Power Department:

functional requirement:	Non-functional requirements:
 Power circuit design and implementation. Motor drive design and implementation for the robot arms. The motor rotates "the dalah" to carry out the pouring process of the coffee. 	 The rotation angle that the motor causes should be more than 50 degrees with considering the wights for a cultural purpose of how to pour the Saudi coffee. Control circuit design "using ARM controller".
3- Control circuit design.	
4- Power tolerance examination and improvement process.	

The Requirements for Robotics and AI Department:

functional requirement:	Non-functional requirements:
1- Robot Navigation, the ability to determine its own position in its frame of reference and then to plan a path towards some goal location.	 face recognition feature to help in serving the coffee. Robot motion system for "ten" degrees of freedom.
2- Robot operating system installation and configuration.	

The Requirements For IOT and software development:

function	onal requirement:	Non-functional requirements:
1.	stop button on an application for the humanoid robot.	1- Arabic & Chinese natural languages recognition design and testing for robotic
2.	Text to speech design and testing for robotic communication system.	communication system.
3.	Database analysis and design for robotic control system on cloud-based computing.	
4.	User experience testing and improvement for robot control system.	