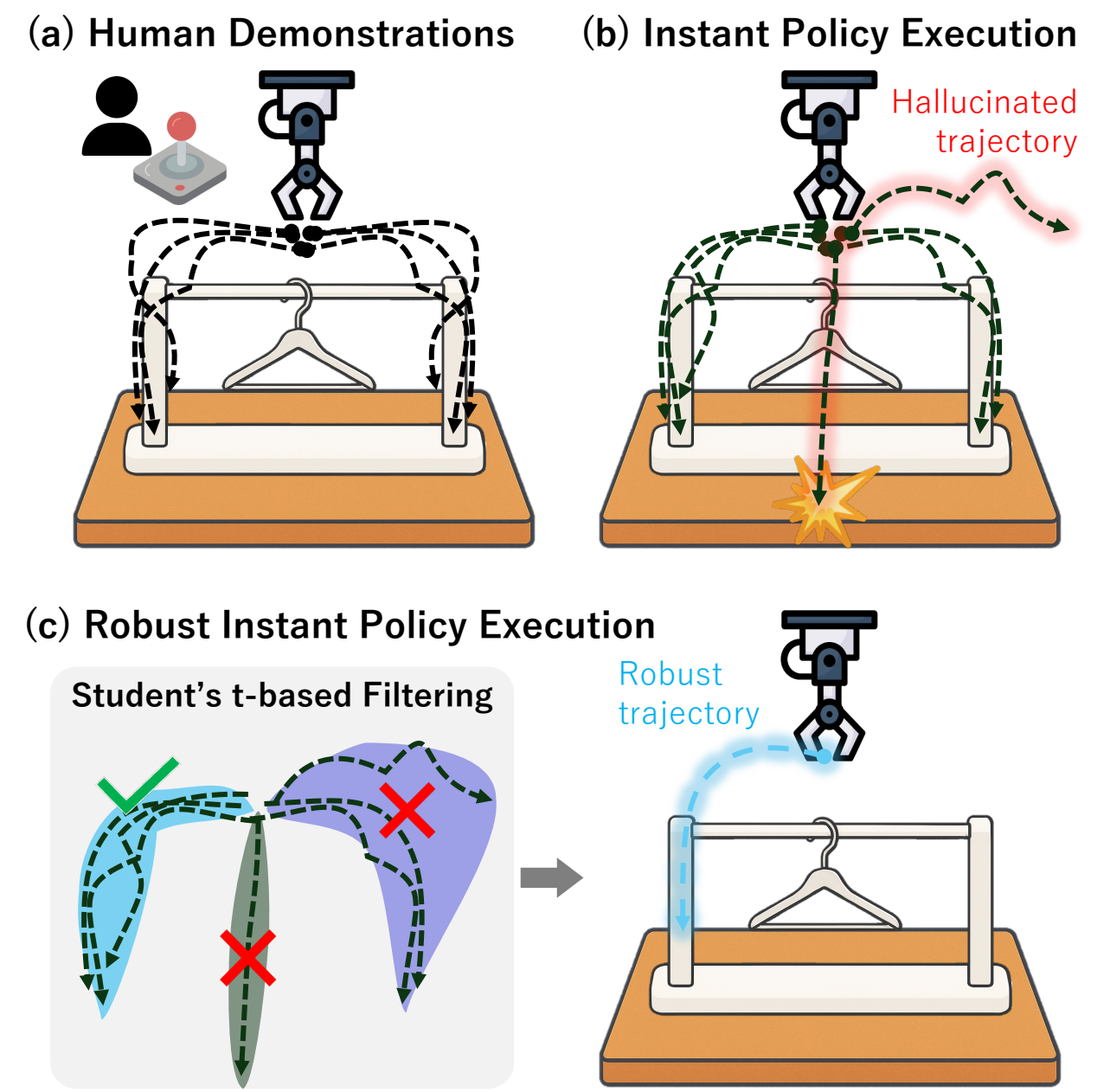
(a) Human Demonstrations
(b) Instant Policy Execution
Hallucinated trajectory
(c) Robust Instant Policy Execution
Student's t-based Filtering
Robust trajectory