



*IEEE Robotics and Automation Society
Japan Joint Chapter Young Award (IROS2024)*

to

Habit Oh

for the paper entitled

*"Leveraging Demonstrator-perceived Precision for Safe
Interactive Imitation Learning of Clearance-limited Tasks"*

A handwritten signature in black ink, appearing to read "Kensuke Harada".

October 16, 2024 Kensuke Harada, Chair, IEEE R&A Society Japan Joint Chapter