

Example 2.9b. To illustrate Theorem 2.9c, let

$$\mathbf{A} = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \quad \text{and} \quad \mathbf{B} = \begin{pmatrix} 3 & -2 \\ 1 & 2 \end{pmatrix}.$$

Then

$$\begin{aligned} \mathbf{AB} &= \begin{pmatrix} 5 & 2 \\ 13 & 2 \end{pmatrix}, & |\mathbf{AB}| &= -16, \\ |\mathbf{A}| &= -2, & |\mathbf{B}| &= 8, & |\mathbf{A}| |\mathbf{B}| &= -16. \end{aligned}$$



2.10 ORTHOGONAL VECTORS AND MATRICES

Two $n \times 1$ vectors \mathbf{a} and \mathbf{b} are said to be *orthogonal* if

직교한다.

$$\mathbf{a}'\mathbf{b} = a_1b_1 + a_2b_2 + \cdots + a_nb_n = 0. \quad (2.80)$$

Note that the term *orthogonal* applies to *two* vectors, not to a single vector.

Geometrically, two orthogonal vectors are perpendicular to each other. This is illustrated in Figure 2.3 for the vectors $\mathbf{x}_1 = (4, 2)'$ and $\mathbf{x}_2 = (-1, 2)'$. Note that $\mathbf{x}_1'\mathbf{x}_2 = (4)(-1) + (2)(2) = 0$.

수직

To show that two orthogonal vectors are perpendicular, let θ be the angle between vectors \mathbf{a} and \mathbf{b} in Figure 2.4. The vector from the terminal point of \mathbf{a} to the terminal point of \mathbf{b} can be represented as $\mathbf{c} = \mathbf{b} - \mathbf{a}$. The law of cosines for the relationship of

$\mathbf{b} - \mathbf{a}$: a와 b사이의 벡터

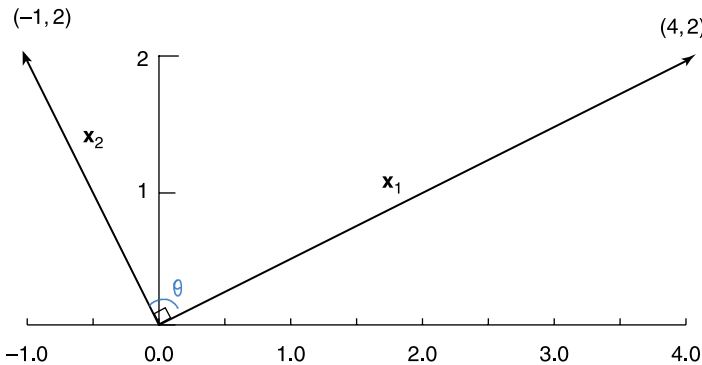
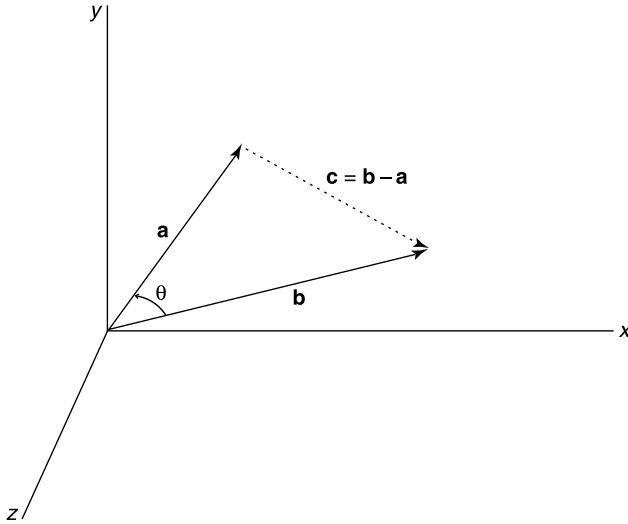


Figure 2.3 Two orthogonal (perpendicular) vectors.

Figure 2.4 Vectors \mathbf{a} and \mathbf{b} in 3-space.

3차원 공간

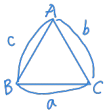
θ to the sides of the triangle can be stated in vector form as

$$\begin{aligned}
 \cos \theta &= \frac{\mathbf{a}'\mathbf{a} + \mathbf{b}'\mathbf{b} - (\mathbf{b} - \mathbf{a})'(\mathbf{b} - \mathbf{a})}{2\sqrt{(\mathbf{a}'\mathbf{a})(\mathbf{b}'\mathbf{b})}} \\
 &= \frac{\mathbf{a}'\mathbf{a} + \mathbf{b}'\mathbf{b} - (\mathbf{b}'\mathbf{b} + \mathbf{a}'\mathbf{a} - 2\mathbf{a}'\mathbf{b})}{2\sqrt{(\mathbf{a}'\mathbf{a})(\mathbf{b}'\mathbf{b})}} \\
 &= \frac{\mathbf{a}'\mathbf{b}}{\sqrt{(\mathbf{a}'\mathbf{a})(\mathbf{b}'\mathbf{b})}}. \quad (2.81)
 \end{aligned}$$

When $\theta = 90^\circ$, $\mathbf{a}'\mathbf{b} = 0$ since $\cos(90^\circ) = 0$. Thus \mathbf{a} and \mathbf{b} are *perpendicular* when $\mathbf{a}'\mathbf{b} = 0$.

If $\mathbf{a}'\mathbf{a} = 1$, the vector \mathbf{a} is said to be *normalized*. A vector \mathbf{b} can be normalized by dividing by its length, $\sqrt{\mathbf{b}'\mathbf{b}}$. Thus

코사인 법칙



$$\cos A = \frac{b^2 + c^2 - a^2}{2bc}$$

벡터의 길이가 1이면,

$$\mathbf{c} = \frac{\mathbf{b}}{\sqrt{\mathbf{b}'\mathbf{b}}}$$

b의 정규화된 벡터 c

$$(2.82)$$

is normalized so that $\mathbf{c}'\mathbf{c} = 1$.

A set of $p \times 1$ vectors $\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_p$ that are normalized ($\mathbf{c}_i'\mathbf{c}_i = 1$ for all i) and mutually orthogonal ($\mathbf{c}_i'\mathbf{c}_j = 0$ for all $i \neq j$) is said to be an *orthonormal set* of vectors. If the $p \times p$ matrix $\mathbf{C} = (\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_p)$ has *orthonormal columns*, \mathbf{C} is called an *orthogonal matrix*. Since the elements of $\mathbf{C}'\mathbf{C}$ are products of columns of

\mathbf{C} [see Theorem 2.2c(i)], an orthogonal matrix \mathbf{C} has the property

$$\mathbf{C}'\mathbf{C} = \mathbf{I}. \quad \text{C의 열 벡터들이 서로 직교하기 때문} \quad (2.83)$$

It can be shown that an orthogonal matrix \mathbf{C} also satisfies

$$\mathbf{C}\mathbf{C}' = \mathbf{I}. \quad \text{C의 행 벡터들도 서로 직교함} \quad (2.84)$$


Thus an orthogonal matrix \mathbf{C} has orthonormal rows as well as orthonormal columns. It is also clear from (2.83) and (2.84) that $\mathbf{C}' = \mathbf{C}^{-1}$ if \mathbf{C} is orthogonal.

Example 2.10. To illustrate an orthogonal matrix, we start with

$$\mathbf{A} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -2 & 0 \\ 1 & 1 & -1 \end{pmatrix},$$

whose columns are mutually orthogonal but not orthonormal. To normalize the three columns, we divide by their respective lengths, $\sqrt{3}$, $\sqrt{6}$, and $\sqrt{2}$, to obtain the matrix $\text{각 열 벡터의 길이가 1이 되도록 하면}$

$$\mathbf{C} = \begin{pmatrix} 1/\sqrt{3} & 1/\sqrt{6} & 1/\sqrt{2} \\ 1/\sqrt{3} & -2/\sqrt{6} & 0 \\ 1/\sqrt{3} & 1/\sqrt{6} & -1/\sqrt{2} \end{pmatrix},$$

whose columns are orthonormal. Note that the rows of \mathbf{C} are also orthonormal, so that \mathbf{C} satisfies (2.84) as well as (2.83). 

Multiplication of a vector by an orthogonal matrix 벡터를 직교 행렬로 곱하면 has the effect of rotating axes; 축이 회전하는 것 that is, if a point \mathbf{x} is transformed to $\mathbf{z} = \mathbf{C}\mathbf{x}$, where \mathbf{C} is orthogonal, then the distance from the origin to \mathbf{z} is the same as the distance to \mathbf{x} : $\text{원점} \sim \mathbf{z} = \text{원점} \sim \mathbf{x}$

$$\mathbf{z}'\mathbf{z} = (\mathbf{C}\mathbf{x})'(\mathbf{C}\mathbf{x}) = \mathbf{x}'\mathbf{C}'\mathbf{C}\mathbf{x} = \mathbf{x}'\mathbf{I}\mathbf{x} = \mathbf{x}'\mathbf{x}. \quad (2.85)$$

Hence, the transformation from \mathbf{x} to \mathbf{z} is a rotation.

Some properties of orthogonal matrices are given in the following theorem.

Theorem 2.10. If the $p \times p$ matrix \mathbf{C} is orthogonal and if \mathbf{A} is any $p \times p$ matrix, then

$$\begin{aligned} \text{(i) } |\mathbf{C}| &= +1 \text{ or } -1. & \mathbf{C}'\mathbf{C} &= \mathbf{I} \text{ 이므로} \\ & \text{행렬식} & |\mathbf{C}\mathbf{C}'| &= |\mathbf{I}| = 1 \\ & & |\mathbf{C}'||\mathbf{C}| &= |\mathbf{C}|^2 = 1. \\ & & \therefore |\mathbf{C}| &= \pm 1 \end{aligned}$$

\downarrow 행렬식의 곱셈 성질

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$$\rightarrow |C'| |A| |C| = |C|^2 |A| = |A|$$

$$(ii) |C'AC| = |A|.$$

$$(iii) -1 \leq c_{ij} \leq 1, \text{ where } c_{ij} \text{ is any element of } C.$$

\therefore 정규화된 벡터들의 집합

2.11 TRACE

The *trace* of an $n \times n$ matrix $\mathbf{A} = (a_{ij})$ is a scalar function defined as the sum of the diagonal elements of \mathbf{A} ; that is, $\text{tr}(\mathbf{A}) = \sum_{i=1}^n a_{ii}$. For example, suppose

$$\mathbf{A} = \begin{pmatrix} 8 & 4 & 2 \\ 2 & -3 & 6 \\ 3 & 5 & 9 \end{pmatrix}.$$

Then

$$\text{tr}(\mathbf{A}) = 8 - 3 + 9 = 14.$$

Some properties of the trace are given in the following theorem.

Theorem 2.11

(i) If \mathbf{A} and \mathbf{B} are $n \times n$, then

$$\text{tr}(\mathbf{A} \pm \mathbf{B}) = \text{tr}(\mathbf{A}) \pm \text{tr}(\mathbf{B}). \quad (2.86)$$

(ii) If \mathbf{A} is $n \times p$ and \mathbf{B} is $p \times n$, then

$$\text{tr}(\mathbf{AB}) = \text{tr}(\mathbf{BA}). \quad (2.87)$$

Note that in (2.87) n can be less than, equal to, or greater than p .

(iii) If \mathbf{A} is $n \times p$, then

$$\text{tr}(\mathbf{A}'\mathbf{A}) = \sum_{i=1}^p \mathbf{a}'_i \mathbf{a}_i, \quad (2.88)$$

$$\begin{pmatrix} a_{1.} \\ a_{2.} \end{pmatrix} (a_{.1} \ a_{.2}) = \begin{pmatrix} \underbrace{a_{1.} a_{.1}} & \underbrace{a_{1.} a_{.2}} \\ \underbrace{a_{2.} a_{.1}} & \underbrace{a_{2.} a_{.2}} \end{pmatrix}$$

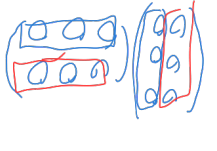
where \mathbf{a}_i is the i th column of \mathbf{A} .

(iv) If \mathbf{A} is $n \times p$, then

$$\text{tr}(\mathbf{AA}') = \sum_{i=1}^n \mathbf{a}'_i \mathbf{a}_i, \quad (2.89)$$

where \mathbf{a}'_i is the i th row of \mathbf{A} .

(v) If $\mathbf{A} = (a_{ij})$ is an $n \times p$ matrix with representative element a_{ij} , then



$$\text{tr}(\mathbf{A}'\mathbf{A}) = \text{tr}(\mathbf{A}\mathbf{A}') = \sum_{i=1}^n \sum_{j=1}^p a_{ij}^2. \quad (2.90)$$

(vi) If \mathbf{A} is any $n \times n$ matrix and \mathbf{P} is any $n \times n$ nonsingular matrix, then

$$\text{tr}(\mathbf{P}^{-1}\mathbf{A}\mathbf{P}) = \text{tr}(\mathbf{A}). \quad (2.91)$$

(vii) If \mathbf{A} is any $n \times n$ matrix and \mathbf{C} is any $n \times n$ orthogonal matrix, then

$$\text{tr}(\mathbf{C}'\mathbf{A}\mathbf{C}) = \text{tr}(\mathbf{A}). \quad (2.92)$$

(viii) If \mathbf{A} is $n \times p$ of rank r and \mathbf{A}^- is a generalized inverse of \mathbf{A} , then

$$\text{tr}(\mathbf{A}^-\mathbf{A}) = \text{tr}(\mathbf{A}\mathbf{A}^-) = r. \quad (2.93)$$

PROOF. We prove parts (ii), (iii), and (vi).

(ii) By (2.13), the i th diagonal element of $\mathbf{E} = \mathbf{A}\mathbf{B}$ is $e_{ii} = \sum_k a_{ik}b_{ki}$. Then

$$\text{tr}(\mathbf{A}\mathbf{B}) = \text{tr}(\mathbf{E}) = \sum_i e_{ii} = \sum_i \sum_k a_{ik}b_{ki}.$$

Similarly, the i th diagonal element of $\mathbf{F} = \mathbf{B}\mathbf{A}$ is $f_{ii} = \sum_k b_{ik}a_{ki}$, and

$$\begin{aligned} \text{tr}(\mathbf{B}\mathbf{A}) &= \text{tr}(\mathbf{F}) = \sum_i f_{ii} = \sum_i \sum_k b_{ik}a_{ki} \\ &= \sum_k \sum_i a_{ki}b_{ik} = \text{tr}(\mathbf{E}) = \text{tr}(\mathbf{A}\mathbf{B}). \end{aligned}$$

(iii) By Theorem 2.2c(i), $\mathbf{A}'\mathbf{A}$ is obtained as products of columns of \mathbf{A} . If \mathbf{a}_i is the i th column of \mathbf{A} , then the i th diagonal element of $\mathbf{A}'\mathbf{A}$ is $\mathbf{a}_i'\mathbf{a}_i$.

(vi) By (2.87) we obtain



$$\text{tr}(\mathbf{P}^{-1}\mathbf{A}\mathbf{P}) = \text{tr}(\mathbf{A}\mathbf{P}\mathbf{P}^{-1}) = \text{tr}(\mathbf{A}).$$

Example 2.11. We illustrate parts (ii) and (viii) of Theorem 2.11.

(ii) Let

$$\mathbf{A} = \begin{pmatrix} 1 & 3 \\ 2 & -1 \\ 4 & 6 \end{pmatrix} \quad \text{and} \quad \mathbf{B} = \begin{pmatrix} 3 & -2 & 1 \\ 2 & 4 & 5 \end{pmatrix}.$$

Then

$$\mathbf{AB} = \begin{pmatrix} 9 & 10 & 16 \\ 4 & -8 & -3 \\ 24 & 16 & 34 \end{pmatrix}, \quad \mathbf{BA} = \begin{pmatrix} 3 & 17 \\ 30 & 32 \end{pmatrix},$$

$$\text{tr}(\mathbf{AB}) = 9 - 8 + 34 = 35, \quad \text{tr}(\mathbf{BA}) = 3 + 32 = 35.$$

(viii) Using \mathbf{A} in (2.59) and \mathbf{A}_1^- in (2.60), we obtain

$$\mathbf{A}^- \mathbf{A} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{pmatrix}, \quad \mathbf{AA}^- = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \end{pmatrix},$$

$$\text{tr}(\mathbf{A}^- \mathbf{A}) = 1 + 1 + 0 = 2 = \text{rank}(\mathbf{A}),$$

$$\text{tr}(\mathbf{AA}^-) = 1 + 1 + 0 = 2 = \text{rank}(\mathbf{A}).$$



2.12 EIGENVALUES AND EIGENVECTORS

2.12.1 Definition

For every square matrix \mathbf{A} , a scalar λ and a nonzero vector \mathbf{x} can be found such that

$$\mathbf{Ax} = \lambda \mathbf{x}, \quad (2.94)$$

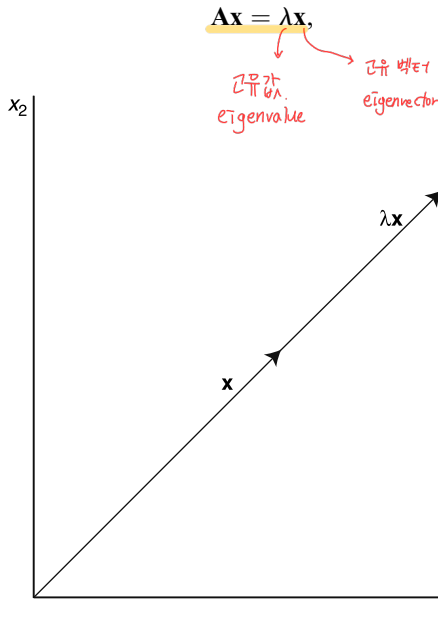


Figure 2.5 An eigenvector \mathbf{x} is transformed to $\lambda \mathbf{x}$.

where λ is an *eigenvalue* of \mathbf{A} and \mathbf{x} is an *eigenvector*. (These terms are sometimes referred to as characteristic root and characteristic vector, respectively.) Note that in (2.94), the vector \mathbf{x} is transformed by \mathbf{A} onto a multiple of itself, so that the point \mathbf{Ax} is on the line passing through \mathbf{x} and the origin. This is illustrated in Figure 2.5.

To find λ and \mathbf{x} for a matrix \mathbf{A} , we write (2.94) as

$$(\mathbf{A} - \lambda \mathbf{I})\mathbf{x} = \mathbf{0}. \quad (2.95)$$

By (2.37), $(\mathbf{A} - \lambda \mathbf{I})\mathbf{x}$ is a linear combination of the columns of $\mathbf{A} - \lambda \mathbf{I}$, and by (2.40) and (2.95), these columns are linearly dependent. Thus the square matrix $(\mathbf{A} - \lambda \mathbf{I})$ is singular, and by Theorem 2.9a(iii), we can solve for λ using

If \mathbf{A} is singular,
 $|\mathbf{A}| = 0$

$$|\mathbf{A} - \lambda \mathbf{I}| = 0, \quad (2.96)$$

특성 방정식.

which is known as the *characteristic equation*.

If \mathbf{A} is $n \times n$, the characteristic equation (2.96) will have n roots; that is, \mathbf{A} will have n eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$. The λ 's will not necessarily all be distinct, or all nonzero, or even all real. (However, the eigenvalues of a symmetric matrix are real; see Theorem 2.12c.) After finding $\lambda_1, \lambda_2, \dots, \lambda_n$ using (2.96), the accompanying eigenvectors $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ can be found using (2.95). → 실수

If an eigenvalue is 0, the corresponding eigenvector is not $\mathbf{0}$. To see this, note that if $\lambda = 0$, then $(\mathbf{A} - \lambda \mathbf{I})\mathbf{x} = \mathbf{0}$ becomes $\mathbf{Ax} = \mathbf{0}$, which has solutions for \mathbf{x} because \mathbf{A} is singular, and the columns are therefore linearly dependent. [The matrix \mathbf{A} is singular because it has a zero eigenvalue; see (63) and (2.107).]

If we multiply both sides of (2.95) by a scalar k , we obtain

$$k(\mathbf{A} - \lambda \mathbf{I})\mathbf{x} = k\mathbf{0} = \mathbf{0},$$

which can be rewritten as

$$(\mathbf{A} - \lambda \mathbf{I})k\mathbf{x} = \mathbf{0} \quad [\text{by (2.12)}].$$

Thus if \mathbf{x} is an eigenvector of \mathbf{A} , $k\mathbf{x}$ is also an eigenvector. Eigenvectors are therefore unique only up to multiplication by a scalar. (There are many solution vectors \mathbf{x} because $\mathbf{A} - \lambda \mathbf{I}$ is singular; see Section 2.8) Hence, the length of \mathbf{x} is arbitrary, but its direction from the origin is unique; that is, the relative values of (ratios of) the elements of $\mathbf{x} = (x_1, x_2, \dots, x_n)'$ are unique. Typically, an eigenvector \mathbf{x} is scaled to normalized form as in (2.82), $\mathbf{x}'\mathbf{x} = 1$.

일정한 크기로 나타낼 수 있다.
← 정규화

Example 2.12.1. To illustrate eigenvalues and eigenvectors, consider the matrix

$$\mathbf{A} = \begin{pmatrix} 1 & 2 \\ -1 & 4 \end{pmatrix}.$$

By (2.96), the characteristic equation is

$$|\mathbf{A} - \lambda \mathbf{I}| = \begin{vmatrix} 1 - \lambda & 2 \\ -1 & 4 - \lambda \end{vmatrix} = (1 - \lambda)(4 - \lambda) + 2 = 0,$$

which becomes

$$\lambda^2 - 5\lambda + 6 = (\lambda - 3)(\lambda - 2) = 0,$$

with roots $\lambda_1 = 3$ and $\lambda_2 = 2$.

To find the eigenvector \mathbf{x}_1 corresponding to $\lambda_1 = 3$, we use (2.95)

$$\begin{aligned} (\mathbf{A} - \lambda_1 \mathbf{I})\mathbf{x}_1 &= \mathbf{0}, \\ \begin{pmatrix} 1 - 3 & 2 \\ -1 & 4 - 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} &= \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \end{aligned}$$

which can be written as

$$\begin{aligned} -2x_1 + 2x_2 &= 0 \\ -x_1 + x_2 &= 0. \end{aligned}$$

The second equation is a multiple of the first, and either equation yields $x_1 = x_2$. The solution vector can be written with $x_1 = x_2 = c$ as an arbitrary constant:

$$\mathbf{x}_1 = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_1 \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} = c \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

If c is set equal to $1/\sqrt{2}$ to normalize the eigenvector, we obtain

$$\mathbf{x}_1 = \begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix}.$$

Similarly, corresponding to $\lambda_2 = 2$, we obtain

$$\mathbf{x}_2 = \begin{pmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \end{pmatrix}.$$



2.12.2 Functions of a Matrix

If λ is an eigenvalue of \mathbf{A} with corresponding eigenvector \mathbf{x} , then for certain functions $g(\mathbf{A})$, an eigenvalue is given by $g(\lambda)$ and \mathbf{x} is the corresponding eigenvector of $g(\mathbf{A})$ as well as of \mathbf{A} . We illustrate some of these cases:

1. If λ is an eigenvalue of \mathbf{A} , then $c\lambda$ is an eigenvalue of $c\mathbf{A}$, where c is an arbitrary constant such that $c \neq 0$. This is easily demonstrated by multiplying the defining relationship $\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$ by c :

$$c\mathbf{A}\mathbf{x} = c\lambda\mathbf{x}. \quad (2.97)$$

Note that \mathbf{x} is an eigenvector of \mathbf{A} corresponding to λ , and \mathbf{x} is also an eigenvector of $c\mathbf{A}$ corresponding to $c\lambda$.

2. If λ is an eigenvalue of the \mathbf{A} and \mathbf{x} is the corresponding eigenvector of \mathbf{A} , then $c\lambda + k$ is an eigenvalue of the matrix $c\mathbf{A} + k\mathbf{I}$ and \mathbf{x} is an eigenvector of $c\mathbf{A} + k\mathbf{I}$, where c and k are scalars. To show this, we add $k\mathbf{x}$ to (2.97):

$$\begin{aligned} c\mathbf{A}\mathbf{x} + k\mathbf{x} &= c\lambda\mathbf{x} + k\mathbf{x}, \\ (c\mathbf{A} + k\mathbf{I})\mathbf{x} &= (c\lambda + k)\mathbf{x}. \end{aligned} \quad (2.98)$$

Thus $c\lambda + k$ is an eigenvalue of $c\mathbf{A} + k\mathbf{I}$ and \mathbf{x} is the corresponding eigenvector of $c\mathbf{A} + k\mathbf{I}$. Note that (2.98) does not extend to $\mathbf{A} + \mathbf{B}$ for arbitrary $n \times n$ matrices \mathbf{A} and \mathbf{B} ; that is, $\mathbf{A} + \mathbf{B}$ does not have $\lambda_A + \lambda_B$ for an eigenvalue, where λ_A is an eigenvalue of \mathbf{A} and λ_B is an eigenvalue of \mathbf{B} .

3. If λ is an eigenvalue of \mathbf{A} , then λ^2 is an eigenvalue of \mathbf{A}^2 . This can be demonstrated by multiplying the defining relationship $\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$ by \mathbf{A} :

$$\begin{aligned} \mathbf{A}(\mathbf{A}\mathbf{x}) &= \mathbf{A}(\lambda\mathbf{x}), \\ \mathbf{A}^2\mathbf{x} &= \lambda\mathbf{A}\mathbf{x} = \lambda(\lambda\mathbf{x}) = \lambda^2\mathbf{x}. \end{aligned} \quad (2.99)$$

Thus λ^2 is an eigenvalue of \mathbf{A}^2 , and \mathbf{x} is the corresponding eigenvector of \mathbf{A}^2 . This can be extended to any power of \mathbf{A} :

$$\mathbf{A}^k\mathbf{x} = \lambda^k\mathbf{x}; \quad (2.100)$$

that is, λ^k is an eigenvalue of \mathbf{A}^k , and \mathbf{x} is the corresponding eigenvector.

4. If λ is an eigenvalue of the nonsingular matrix \mathbf{A} , then $1/\lambda$ is an eigenvalue of \mathbf{A}^{-1} . To demonstrate this, we multiply $\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$ by \mathbf{A}^{-1} to obtain

$$\begin{aligned}\mathbf{A}^{-1}\mathbf{A}\mathbf{x} &= \mathbf{A}^{-1}\lambda\mathbf{x}, \\ \mathbf{x} &= \lambda\mathbf{A}^{-1}\mathbf{x}, \\ \mathbf{A}^{-1}\mathbf{x} &= \frac{1}{\lambda}\mathbf{x}.\end{aligned}\tag{2.101}$$

Thus $1/\lambda$ is an eigenvalue of \mathbf{A}^{-1} , and \mathbf{x} is an eigenvector of both \mathbf{A} and \mathbf{A}^{-1} .

5. The results in (2.97) and (2.100) can be used to obtain eigenvalues and eigenvectors of a polynomial in \mathbf{A} . For example, if λ is an eigenvalue of \mathbf{A} , then

$$\begin{aligned}(\mathbf{A}^3 + 4\mathbf{A}^2 - 3\mathbf{A} + 5\mathbf{I})\mathbf{x} &= \mathbf{A}^3\mathbf{x} + 4\mathbf{A}^2\mathbf{x} - 3\mathbf{A}\mathbf{x} + 5\mathbf{x} \\ &= \lambda^3\mathbf{x} + 4\lambda^2\mathbf{x} - 3\lambda\mathbf{x} + 5\mathbf{x} \\ &= (\lambda^3 + 4\lambda^2 - 3\lambda + 5)\mathbf{x}.\end{aligned}$$

Thus $\lambda^3 + 4\lambda^2 - 3\lambda + 5$ is an eigenvalue of $\mathbf{A}^3 + 4\mathbf{A}^2 - 3\mathbf{A} + 5\mathbf{I}$, and \mathbf{x} is the corresponding eigenvector.

For certain matrices, property 5 can be extended to an infinite series. For example, if λ is an eigenvalue of \mathbf{A} , then, by (2.98), $1 - \lambda$ is an eigenvalue of $\mathbf{I} - \mathbf{A}$. If $\mathbf{I} - \mathbf{A}$ is nonsingular, then, by (2.101), $1/(1 - \lambda)$ is an eigenvalue of $(\mathbf{I} - \mathbf{A})^{-1}$. If $-1 < \lambda < 1$, then $1/(1 - \lambda)$ can be represented by the series

$$\frac{1}{1 - \lambda} = 1 + \lambda + \lambda^2 + \lambda^3 + \cdots.$$

Correspondingly, if all eigenvalues of \mathbf{A} satisfy $-1 < \lambda < 1$, then

$$(\mathbf{I} - \mathbf{A})^{-1} = \mathbf{I} + \mathbf{A} + \mathbf{A}^2 + \mathbf{A}^3 + \cdots.\tag{2.102}$$

2.12.3 Products

It was noted in a comment following (2.98) that the eigenvalues of $\mathbf{A} + \mathbf{B}$ are not of the form $\lambda_A + \lambda_B$, where λ_A is an eigenvalue of \mathbf{A} and λ_B is an eigenvalue of \mathbf{B} . Similarly, the eigenvalues of \mathbf{AB} are not products of the form $\lambda_A\lambda_B$. However, the eigenvalues of \mathbf{AB} are the same as those of \mathbf{BA} .

Theorem 2.12a. If \mathbf{A} and \mathbf{B} are $n \times n$ or if \mathbf{A} is $n \times p$ and \mathbf{B} is $p \times n$, then the (nonzero) eigenvalues of \mathbf{AB} are the same as those of \mathbf{BA} . If \mathbf{x} is an eigenvector of \mathbf{AB} , then \mathbf{Bx} is an eigenvector of \mathbf{BA} .

$$\begin{aligned}\mathbf{ABx} &= \lambda\mathbf{x} \\ \mathbf{B}(\mathbf{ABx}) &= \lambda\mathbf{Bx} \\ \mathbf{BA}(\mathbf{Bx}) &= \lambda(\mathbf{Bx})\end{aligned}$$

Two additional results involving eigenvalues of products are given in the following theorem.

Theorem 2.12b. Let \mathbf{A} be any $n \times n$ matrix.

- (i) If \mathbf{P} is any $n \times n$ nonsingular matrix, then \mathbf{A} and $\mathbf{P}^{-1}\mathbf{A}\mathbf{P}$ have the same eigenvalues.
 $Ax = \lambda x$. 새로운 벡터 y 정의. $y = Px \rightarrow x = P^{-1}y$ 가 된다. $A(P^{-1}y) = \lambda(P^{-1}y)$ 양변에 P 를 곱하면 $PA P^{-1}y = \lambda y$.
- (ii) If \mathbf{C} is any $n \times n$ orthogonal matrix, then \mathbf{A} and $\mathbf{C}'\mathbf{A}\mathbf{C}$ have the same eigenvalues.
 $C'C = I, C^{-1} = C'$ $Ax = \lambda x$. 새로운 벡터 $y = Cx$ 정의. $A(C'y) = \lambda(C'y)$ 양변에 C 를 곱하면 $(C'AC)y = \lambda y$ \square

2.12.4 Symmetric Matrices

Two properties of the eigenvalues and eigenvectors of a symmetric matrix are given in the following theorem.

Theorem 2.12c. Let \mathbf{A} be an $n \times n$ symmetric matrix.

- (i) The eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ of \mathbf{A} are real. $A' = A$
- (ii) The eigenvectors $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k$ of \mathbf{A} corresponding to distinct eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_k$ are mutually orthogonal; the eigenvectors $\mathbf{x}_{k+1}, \mathbf{x}_{k+2}, \dots, \mathbf{x}_n$ corresponding to the nondistinct eigenvalues can be chosen to be mutually orthogonal to each other and to the other eigenvectors; that is, $\mathbf{x}_i' \mathbf{x}_j = 0$ for $i \neq j$. \square

If the eigenvectors of a symmetric matrix \mathbf{A} are normalized and placed as columns of a matrix \mathbf{C} , then by Theorem 2.12c(ii), \mathbf{C} is an orthogonal matrix. This orthogonal matrix can be used to express \mathbf{A} in terms of its eigenvalues and eigenvectors.

Theorem 2.12d. If \mathbf{A} is an $n \times n$ symmetric matrix with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ and normalized eigenvectors $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$, then \mathbf{A} can be expressed as

$$\mathbf{A} = \mathbf{C}\mathbf{D}\mathbf{C}' \quad (2.103)$$

$$= \sum_{i=1}^n \lambda_i \mathbf{x}_i \mathbf{x}_i', \quad (2.104)$$

where $\mathbf{D} = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$ and \mathbf{C} is the orthogonal matrix $\mathbf{C} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)$. The result in either (2.103) or (2.104) is often called the *spectral decomposition of \mathbf{A}* .

PROOF. By Theorem 2.12c(ii), \mathbf{C} is orthogonal. Then by (2.84), $\mathbf{I} = \mathbf{C}\mathbf{C}'$, and multiplication by \mathbf{A} gives

$$\mathbf{A} = \mathbf{A}\mathbf{C}\mathbf{C}'$$

We now substitute $\mathbf{C} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)$ to obtain

$$\begin{aligned}\mathbf{A} &= \mathbf{A}(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)\mathbf{C}' \\ &= (\mathbf{A}\mathbf{x}_1, \mathbf{A}\mathbf{x}_2, \dots, \mathbf{A}\mathbf{x}_n)\mathbf{C}' \quad [\text{by (2.28)}] \\ &= (\lambda_1\mathbf{x}_1, \lambda_2\mathbf{x}_2, \dots, \lambda_n\mathbf{x}_n)\mathbf{C}' \quad [\text{by (2.94)}] \\ &= \mathbf{C}\mathbf{D}\mathbf{C}',\end{aligned}\tag{2.105}$$

since multiplication on the right by $\mathbf{D} = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$ multiplies columns of \mathbf{C} by elements of \mathbf{D} [see (2.30)]. Now writing \mathbf{C}' in the form

$$\mathbf{C}' = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n)' = \begin{pmatrix} \mathbf{x}'_1 \\ \mathbf{x}'_2 \\ \vdots \\ \mathbf{x}'_n \end{pmatrix} \quad [\text{by (2.39)}],$$

(2.105) becomes

$$\begin{aligned}\mathbf{A} &= (\lambda_1\mathbf{x}_1, \lambda_2\mathbf{x}_2, \dots, \lambda_n\mathbf{x}_n) \begin{pmatrix} \mathbf{x}'_1 \\ \mathbf{x}'_2 \\ \vdots \\ \mathbf{x}'_n \end{pmatrix} \\ &= \lambda_1\mathbf{x}_1\mathbf{x}'_1 + \lambda_2\mathbf{x}_2\mathbf{x}'_2 + \dots + \lambda_n\mathbf{x}_n\mathbf{x}'_n.\end{aligned}$$



Corollary 1. If \mathbf{A} is symmetric and \mathbf{C} and \mathbf{D} are defined as in Theorem 2.12d, then \mathbf{C} diagonalizes \mathbf{A} :

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$$\mathbf{C}'\mathbf{A}\mathbf{C} = \mathbf{D}.\tag{2.106}$$



We can express the determinant and trace of a square matrix \mathbf{A} in terms of its eigenvalues. → 이를 통하여 A의 고유값으로 |A|와 tr(A)를 표현 가능.

Theorem 2.12e. If \mathbf{A} is any $n \times n$ matrix with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$, then

$$(i) \quad \begin{aligned} &\text{A} = \mathbf{C}\mathbf{D}\mathbf{C}' \\ &|\mathbf{A}| = |\mathbf{C}\mathbf{D}\mathbf{C}'| \\ &= |\mathbf{C}| |\mathbf{D}| |\mathbf{C}'| = |\mathbf{D}| \end{aligned} \quad \begin{aligned} &\text{diag}(\lambda_1, \dots, \lambda_n) \\ &|\mathbf{A}| = \prod_{i=1}^n \lambda_i. \end{aligned} \tag{2.107}$$


$$(ii) \quad \begin{aligned} &\text{tr}(\mathbf{A}) = \text{tr}(\mathbf{C}\mathbf{D}\mathbf{C}') = \text{tr}(\mathbf{D}) \\ &\text{tr}(\mathbf{A}) = \sum_{i=1}^n \lambda_i. \end{aligned} \tag{2.108}$$



We have included Theorem 2.12e here because it is easy to prove for a symmetric matrix \mathbf{A} using Theorem 2.12d (see Problem 2.72). However, the theorem is true for any square matrix (Searle 1982, p. 278).

Example 2.12.4. To illustrate Theorem 2.12e, consider the matrix \mathbf{A} in Example 2.12.1

$$\mathbf{A} = \begin{pmatrix} 1 & 2 \\ -1 & 4 \end{pmatrix}, \quad \begin{array}{l} Ax = \lambda x, \\ (A - \lambda I) = 0 \end{array} \quad \begin{array}{l} \left| \begin{array}{cc} 1-\lambda & 2 \\ -1 & 4-\lambda \end{array} \right| = 0, \\ \begin{array}{l} \lambda - 5\lambda + \lambda^2 + 2 = 0 \\ \lambda^2 - 5\lambda + 6 = 0 \\ (\lambda - 2)(\lambda - 3) = 0 \end{array} \end{array}$$

which has eigenvalues $\lambda_1 = 3$ and $\lambda_2 = 2$. The product $\lambda_1 \lambda_2 = 6$ is the same as $|\mathbf{A}| = 4 - (-1)(2) = 6$. The sum $\lambda_1 + \lambda_2 = 3 + 2 = 5$ is the same as $\text{tr}(\mathbf{A}) = 1 + 4 = 5$. 

2.12.5 Positive Definite and Semidefinite Matrices

The eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$ of positive definite and positive semidefinite matrices (Section 2.6) are positive and nonnegative, respectively.

$\lambda_i > 0$ $\lambda_i \geq 0$

Theorem 2.12f. Let \mathbf{A} be $n \times n$ with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$.

- (i) If \mathbf{A} is positive definite, then $\lambda_i > 0$ for $i = 1, 2, \dots, n$.
- (ii) If \mathbf{A} is positive semidefinite, then $\lambda_i \geq 0$ for $i = 1, 2, \dots, n$. The number of eigenvalues λ_i for which $\lambda_i > 0$ is the rank of \mathbf{A} .


$\lambda_i > 0$ 인 고유값의 개수 = $\text{rank}(\mathbf{A})$

PROOF.

- (i) For any λ_i , we have $\mathbf{A}\mathbf{x}_i = \lambda_i\mathbf{x}_i$. Multiplying by \mathbf{x}_i' , we obtain

$$\begin{aligned} \mathbf{x}_i' \mathbf{A} \mathbf{x}_i &= \lambda_i \mathbf{x}_i' \mathbf{x}_i, \\ \lambda_i &= \frac{\mathbf{x}_i' \mathbf{A} \mathbf{x}_i}{\mathbf{x}_i' \mathbf{x}_i} > 0. \end{aligned}$$

\leftarrow 양의 정방행렬의 항상 양수.
 \leftarrow 제2/2.4에서 항상 양수.

In the second expression, $\mathbf{x}_i' \mathbf{A} \mathbf{x}_i$ is positive because \mathbf{A} is positive definite, and $\mathbf{x}_i' \mathbf{x}_i$ is positive because $\mathbf{x}_i \neq \mathbf{0}$. 

If a matrix \mathbf{A} is positive definite, we can find a *square root matrix* $\mathbf{A}^{1/2}$ as follows. Since the eigenvalues of \mathbf{A} are positive, we can substitute the square roots $\sqrt{\lambda_i}$ for λ_i in the spectral decomposition of \mathbf{A} in (2.103), to obtain

$$\mathbf{A}^{1/2} = \mathbf{C} \mathbf{D}^{1/2} \mathbf{C}', \quad (2.109)$$

where $\mathbf{D}^{1/2} = \text{diag}(\sqrt{\lambda_1}, \sqrt{\lambda_2}, \dots, \sqrt{\lambda_n})$. The matrix $\mathbf{A}^{1/2}$ is symmetric and has the property

$$\mathbf{A}^{1/2} \mathbf{A}^{1/2} = (\mathbf{A}^{1/2})^2 = \mathbf{A}. \quad (2.110)$$