Hancheng Min | Curriculum Vitae

Ph.D. Candidate, ECE Department Johns Hopkins University, Baltimore, MD, USA

Research interests: Networked Dynamical Systems, Deep Learning Theory, Reinforcement Learning

Education

Johns Hopkins University

Ph.D. Candidate, Electrical and Computer Engineering

GPA: 4.0/4.0

University of Pennsylvania

Master of Science in Engineering, Major: Systems Engineering

GPA: 4.0/4.0

Tongji University Bachelor of Engineering, Major: Automation

GPA: 4.5/5.0

Baltimore, MD, U.S. Sep. 2018—Now

Philadelphia, PA, U.S.

Sep. 2016—May 2018

Shanghai, China Sep. 2012—Jun. 2016

Research Experience

Graduate Research Assistant

NetD-Lab, ECE Dept., Johns Hopkins University (Advisor: Enrique Mallada, Co-advisor: René Vidal)

Graduate Research Assistant

Kod*Lab, Penn Engineering GRASP Lab, University of Pennsylvania (Advisor: Daniel E. Koditschek)

Undergraduate Research Assistant

Yuan's research group, Tongji University

(Advisor: Hongliang Yuan)

Baltimore, MD, U.S.

Sep. 2018—Now

Philadelphia, PA, U.S.

Jun. 2017—May 2018

Shanghai, China

Jun. 2015—Jun. 2016

Research Projects

Convergence and Implicit Bias of Gradient Methods on Linear Networks [4]

2020-Now

- Full characterization of convergence rate of gradient flow on two-layer linear networks
- Understand the convergence and implicit bias for random initialization with large hidden layer width
- Ongoing works extend current result [4] to multi-layer linear networks and nonlinear networks

Learning to Act Safely with Limited Exposure and Almost Sure Certainty [1] 2021-Now

- Safe RL: Constrained reinforcement learning problem that only allows finite exposure to damage/failure
- Assured Q-learning: Learning optimal policy efficiently under safety constraint
- Ongoing works consider more general types of safety constraints

o Coherence and Concentration in tightly-connected networks [2], [3], [5]

2018-Now

- Characterization of coherent dynamics in heterogeneous networked dynamical systems
- Application to model reduction in power networks

Voronoi-based coverage control for mobile sensor networks [6], [7]

2017-2018

- Coverage control of pan-tilt-zoom camera systems
- Developed program for calibrating/control/visualize PTZ cameras in real-world experiments

Publications

- [1] A. Castellano, H. Min, J. Bazerque, and E. Mallada, "Learning to act safely with limited exposure and almost sure certainty," May 2021, under review.
- [2] H. Min and E. Mallada, "Coherence and concentration in tightly-connected networks," 2021, under
- [3] H. Min, F. Paganini, and E. Mallada, "Accurate reduced order models for coherent heterogeneous generators," IEEE Control Systems Letters (L-CSS), vol. 5, no. 5, pp. 1741-1746, Nov. 2021, also in ACC 2021.
- [4] H. Min, S. Tarmoun, R. Vidal, and E. Mallada, "On the explicit role of initialization on the convergence and implicit bias of overparametrized linear networks," in Proceedings of the 38th International Conference on Machine Learning, ser. Proceedings of Machine Learning Research, vol. 139, PMLR, Jul. 2021, pp. 7760-7768.
- [5] **H. Min** and E. Mallada, "Dynamics concentration of tightly-connected large-scale networks," in 58th IEEE Conference on Decision and Control (CDC), Dec. 2019, pp. 758–763.
- [6] O. Arslan, H. Min, and D. E. Koditschek, "Voronoi-based coverage control of pan/tilt/zoom camera networks," in 2018 IEEE International Conference on Robotics and Automation (ICRA), May 2018, pp. 5062-5069.
- [7] H. Min, "On balancing event and area coverage in mobile sensor networks," Master's thesis, University of Pennsylvania, 2018.

Programming Skills

Python(Tensorflow, Gym, Sklearn, OpenCV), Matlab, C/C++

Selected Coursework

University of Pennsylvania

• Graduate Courses

Sep. 2016—May 2018

- Model Predictive Control

Advanced Probability

 Dynamical Systems for Engineering and Biological **Applications**

Johns Hopkins University

Graduate Courses

Sep. 2018—Now

- Nonlinear Optimization
- Networked Dynamical Systems
- Statistical Theory
- Unsupervised Learning

- Control Systems Design

Machine Learning

- Random Signal Analysis
- High-dimensional Probability
- Stochastic Processes

Presentations

- o "On the explicit role of initialization and implicit bias of overparametrized linear networks", 38th International Conference on Machine Learning, Virtual, July 2021
- o "Accurate Reduced Order Models for Coherent Heterogeneous Generators", American Control Conference 2021, Virtual, May 2021
- "Dynamics Concentration of Large-Scale Tightly-Connected Networks", 58th Conference on Decision and Control, Nice, France Dec 2019
- "Accurate Reduced Order Models for Coherent Synchronous Generators", NetD-Lab group meeting, Fall 2019

- "Localize Eigenvalues of Transfer Matrix of Network Dynamical Systems", NetD-Lab group meeting, Spring 2019
- o "Literature Review: A Convex Characterization of Robust Stability for Positive and Positively Dominated Linear Systems", NetD-Lab group meeting, Fall 2018

Professional Service

Technical Reviewer.

Journal: TAC, Control System Letter

Conference: ICML, CVPR, NeurIPS, ICLR, ACC

Teaching Experience

- cardinal Experience	
Teaching Assistant • EN.520.637 Foundation of Reinforcement Learning, Johns Hopkins University	Fall 2021
Teaching Assistant One in the image of the	Fall 2020
Teaching Assistant One of the image of the	Fall 2019
Teaching Assistant of edX Course: Robotics: Locomotion and Engineering, Penn Engineering Online Learning	Spring 2018
Awards and Honors	
MINDS Data Science Spring Fellowship 2021	Jan. 2021
o MINDS Data Science Fellowship 2019/2020	Nov. 2019
Third Prize, Tongji Scholarship of Excellence	Dec. 2015
Third Prize, Tongji Scholarship of Excellence	Dec. 2014
Third Prize, Tongji University Electronic Design Contest	Dec. 2014
Second Prize, Tongji Scholarship of Excellence	Dec. 2013
o First Prize, The Chinese Mathematics Competetion (Shanghai Preliminary)	Nov. 2013