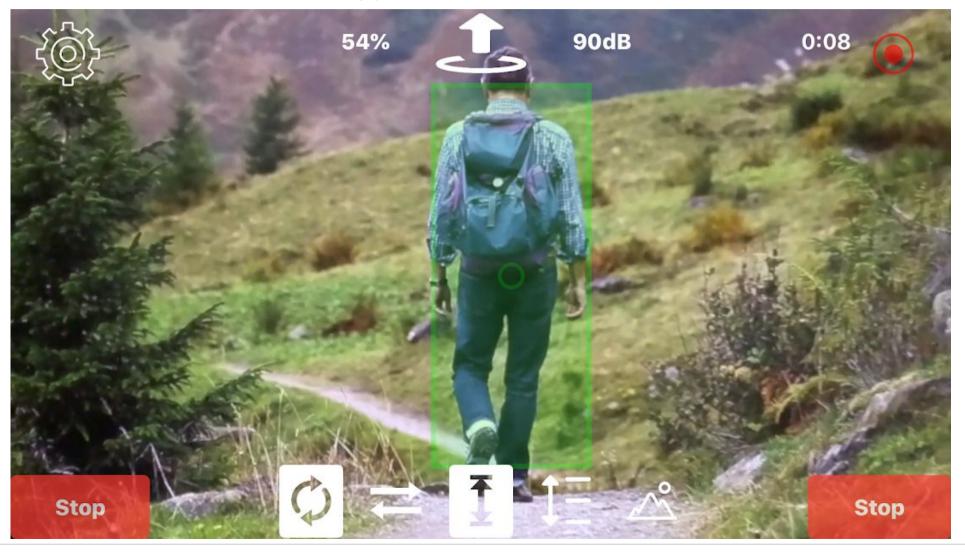
# **Drone**

https://tello.oneoffcoder.com/index.html

저녁이 있는 프로젝트 오상훈 6 Hours, 1 Month

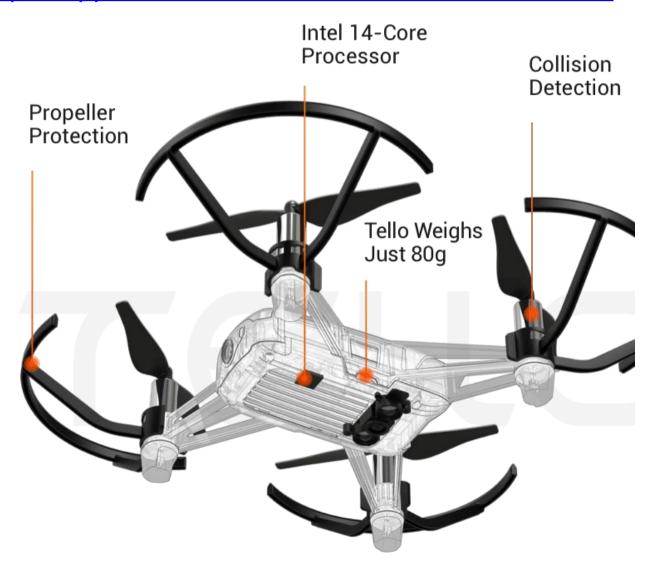
# Goal

- Refer: <a href="https://github.com/Matthias84/awesome-tello">https://github.com/Matthias84/awesome-tello</a>
- See : <a href="https://youtu.be/8WXEkjuXiUE">https://youtu.be/8WXEkjuXiUE</a>
- ❖ 해보기
  - with Tello and Tellome App



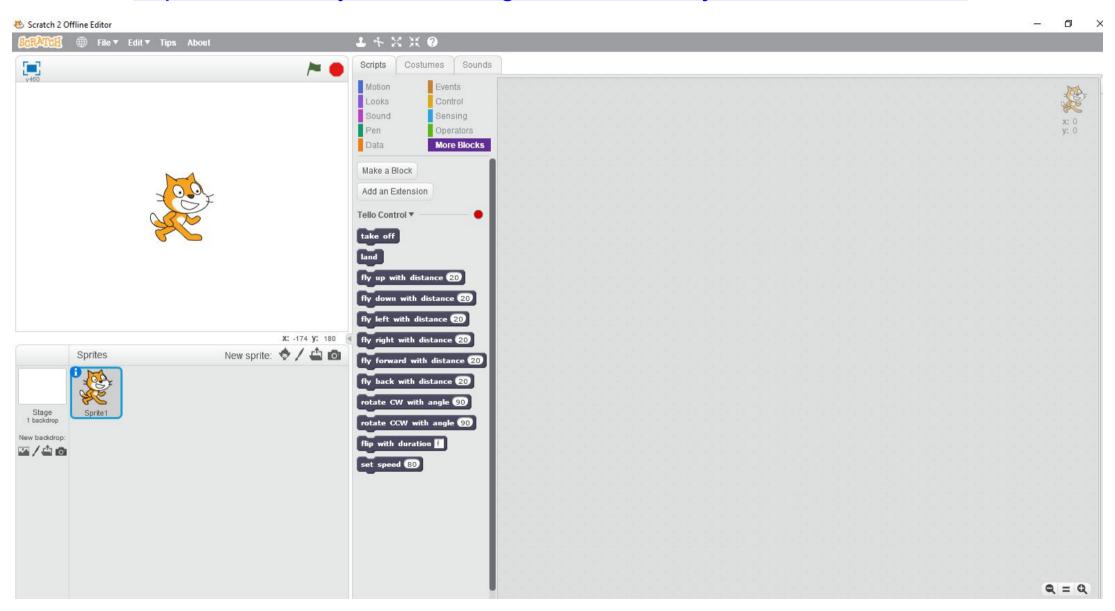
## Tello Edu

- Refer : <a href="https://www.ryzerobotics.com/kr/tello-edu">https://www.ryzerobotics.com/kr/tello-edu</a>
  - Specs(soft): <a href="https://www.ryzerobotics.com/kr/tello-edu/specs">https://www.ryzerobotics.com/kr/tello-edu/specs</a>
  - Specs(hard): <a href="https://tello.oneoffcoder.com/parts.html#">https://tello.oneoffcoder.com/parts.html#</a>
- install Tello Edu with Simulator on windows OS
  - Down: <a href="https://appsonwindows.com/download/4233532/74/">https://appsonwindows.com/download/4233532/74/</a>



## Tello with Scratch

- Refer : <a href="https://www.ryzerobotics.com/kr/tello-edu/downloads">https://www.ryzerobotics.com/kr/tello-edu/downloads</a>
  - https://alfredo-reyes-montero.gitbook.io/tello-dji/frameworks/scratch



#### Tello with Packet

- Refer : <u>Tello EDU SDK</u>
- install APP Packet Sender
- ❖ 해보기
  - > Turn on Tello
  - run Packet Sender And then input parameters And then save
    - Name : tello\_command
    - ASCII: command
    - HEX : auto generating
    - Address: 192.168.0.1 Port: 8889 Protocol: UDP
  - Click tello\_command And then Change ASCII parameter And send
    - command, battery?, emergency, takeoff, land etc
- Python, Auto Flight Path: <a href="https://tello.oneoffcoder.com/python-auto-flight.html">https://tello.oneoffcoder.com/python-auto-flight.html</a>
- Swarm Programming : <a href="https://tello.oneoffcoder.com/swarm.html#">https://tello.oneoffcoder.com/swarm.html#</a>

# Coding with DJITelloPy

- Refer : <a href="https://djitellopy.readthedocs.io/">https://djitellopy.readthedocs.io/</a>
  - > API : <a href="https://djitellopy.readthedocs.io/en/latest/tello/">https://djitellopy.readthedocs.io/en/latest/tello/</a>
- Source python : <a href="https://github.com/damiafuentes/DJITelloPy/tree/master/examples">https://github.com/damiafuentes/DJITelloPy/tree/master/examples</a>
- Read Sequence : <a href="https://youtu.be/LmEcyQnfpDA">https://youtu.be/LmEcyQnfpDA</a>
  - simple.py
  - manual-control-opency.py or manual-control-pygame.py
  - mission-pads.py
  - > take-picture.py
  - > record-video.py
  - simple-swarm.py
- with opency : <a href="https://edimoon777.github.io/junghomoon/Tellopy/">https://edimoon777.github.io/junghomoon/Tellopy/</a>
- Tello edu swarm basic#4 curve command
  - https://youtu.be/89C34JsAKEQ
- Python Code Flies Tello Drone Around Polygon
  - https://youtu.be/zNyvbDGcR9E
- Scratch Programming : <a href="https://tello.oneoffcoder.com/scratch.html">https://tello.oneoffcoder.com/scratch.html</a>
  - https://tello.oneoffcoder.com/blocks.html
  - https://github.com/kebhr/scratch3-tello

#### tello with ROS

- Refer : <a href="http://wiki.ros.org/tello-driver">http://wiki.ros.org/tello-driver</a>
- ❖ Tello, ROS 드라이버 연동
  - https://edimoon777.github.io/junghomoon/Tello-ROS/
- Drone demo in ROS 2/Gazebo/RVIZ 2
  - with TelloPy: <a href="https://alfredo-reyes-montero.gitbook.io/tello-dji/frameworks/ros">https://alfredo-reyes-montero.gitbook.io/tello-dji/frameworks/ros</a>
  - with Pixhawk : <a href="https://github.com/osrf/drone\_demo">https://github.com/osrf/drone\_demo</a>
  - > tello ros is a ROS2 driver : <a href="https://github.com/clydemcqueen/tello">https://github.com/clydemcqueen/tello</a> ros
  - > flock2 can fly a swarm : <a href="https://github.com/clydemcqueen/flock2">https://github.com/clydemcqueen/flock2</a>
  - SLAM with Camera: <a href="https://github.com/tau-adl/Tello-ROS ORBSLAM">https://github.com/tau-adl/Tello-ROS ORBSLAM</a>

### Advance

- Swarm
  - Tello EDU Drone Swarming Tutorial with Packet Sender and Python
    - https://youtu.be/clsddY4SKgA
  - ➤ [텔로에듀군집비행]tello edu swarm basic#1 ~ 5
    - https://youtu.be/Z0Uluimdi2k
- Object Detection
  - Drone-Face-Tracking and openpose
    - https://github.com/murtazahassan/Drone-Face-Tracking
  - Using OpenPose with the Tello Drone to make selfies
    - https://github.com/geaxqx/tello-openpose
  - Tello Drone | Python OpenCV Object Tracking with Code
    - https://youtu.be/vDOkUHNdmKs



Reference