Name:

UNIQNAME#:

2	2	6	10

Directions – The quiz is closed book/notes. You have 15 minutes to complete it; use this paper only.

Problem 1: Recall (2 pts, 0.5 for each) (Write down only T or F)

Harris operator is invariant to ...

- (a) Translation ()
- (b) Rotation (
- (c) Scale ()
- (d) Intensity shift ()

Solution:

| T, T, F, T

Problem 2: Recall (2 pts, 1 for each) (Write down a proper term for each blank)

(a) SIFT descriptor is more robust to pose and intra-class variation than a simple patch or bank of filters thanks to _______. (Hint: It is an estimation of probability distribution)

(b) Scale of traditional SIFT is decided by ______ response.

Solution:

histogram, DoG

Problem 3: Comprehension (6 pts, 1 for each) (Find the proper kernel and fill in the blanks)









(F1)

(F3)

(F4₂

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 12 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
(K1)

$$\begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix}$$

$$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 1 & 1 \end{bmatrix}$$
(K4)

$$\begin{bmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{bmatrix}$$
(K5)

F1 is the Gaussian-filtered image of "cameraman". Here \dots

(a) F2 is the image after applying convolution to F1 with K Edges along x-axis are the	of F2.			
(b) F3 is the image after applying convolution to F1 with K Edges along y-axis are the	of F3.			
(c) F4 is the image after applying convolution to F1 with K Blobs are the				
Solution:				
5, 2, 3. All the following answers are accepted: extrema, maxima,				