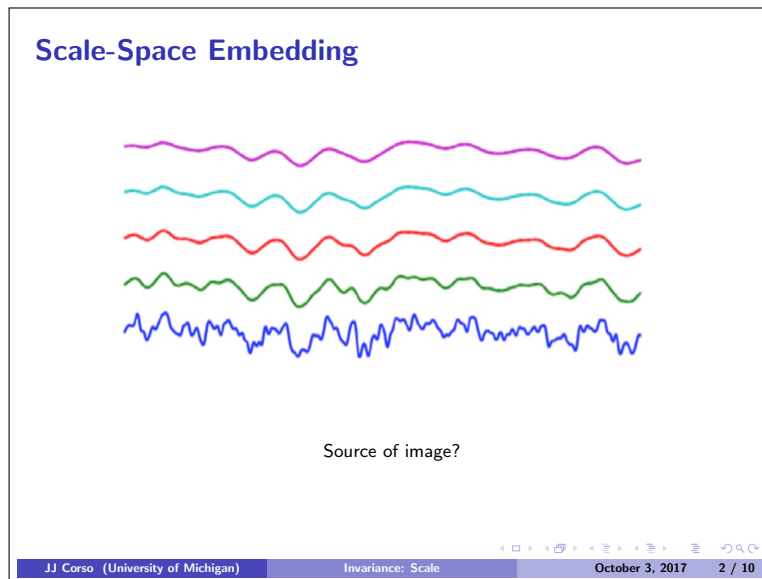


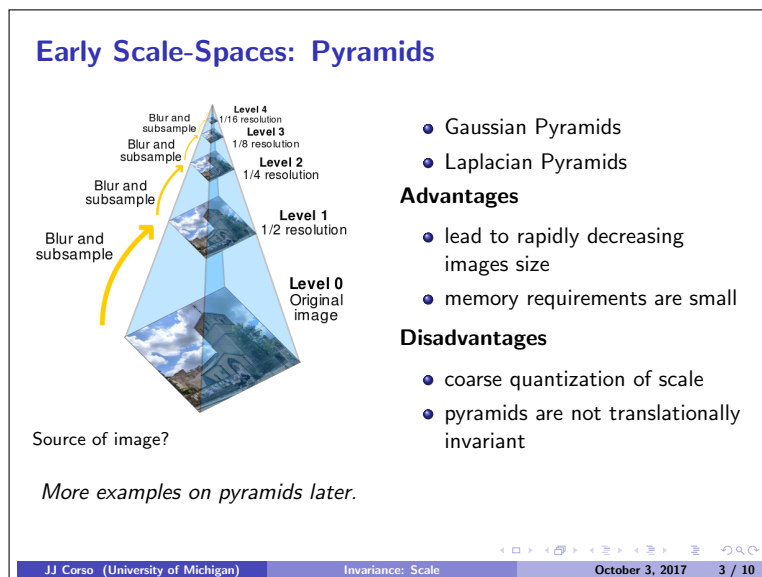
1 Scale Background

Slides begin with motivating examples of scale and scale-selection.

Loosely, scale-space is an embedding of a given signal into a one-parameter family of derived signals, where the family is parameterized by a scale parameter such that fine-scale structures are successively suppressed when the scale parameter is increased.



Goal: Scale-specific structures only occur at their respective scales in the scale-space.



2 Scale-Space Representation

Toward Gaussian Scale-Space

Multi-scale representation comprising a continuous scale parameter and preservation of the same spatial sampling at all scales.

Following Witkin(1983) and Lindeberg(1994):

Embedding of original signal into a one-parameter family of derived signals constructed by convolution with a one-parameter family of Gaussian kernels of increasing width. Gaussian kernel is a unique choice.

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Toward Gaussian Scale-Space

Let $f : \mathbb{R}^N \rightarrow \mathbb{R}$ represent any given signal, e.g., our image.

Then, the scale-space representation $L : \mathbb{R}^N \times \mathbb{R}_+ \rightarrow \mathbb{R}$ is defined by:

$$\begin{aligned} L(\cdot; 0) &= f \\ L(\cdot; t) &= g(\cdot; t) \otimes f \end{aligned}$$

where $t \in \mathbb{R}_+$ is the scale parameter and $g : \mathbb{R}^N \times \mathbb{R}_+ \setminus \{0\} \rightarrow \mathbb{R}$ is the Gaussian kernel of dimension N :

$$g(\mathbf{x}; t) = \frac{1}{(2\pi t)^{\frac{N}{2}}} \exp \left[-\frac{\mathbf{x}^T \mathbf{x}}{2t} \right],$$

where $\mathbf{x} \in \mathbb{R}^N$ and $\sigma = \sqrt{t}$, standard deviation of the Gaussian.

As t increases, the signal becomes gradually smoother. (See earlier figure)

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Then, the scale-space representation $L : \mathbb{R}^N \times \mathbb{R}_+ \rightarrow \mathbb{R}$ is defined by:

$$L(\cdot; 0) = f \quad (1)$$

$$L(\cdot; t) = g(\cdot; t) \otimes f \quad (2)$$

where $t \in \mathbb{R}_+$ is the scale parameter and $g : \mathbb{R}^N \times \mathbb{R}_+ \setminus \{0\} \rightarrow \mathbb{R}$ is the Gaussian kernel of dimension N :

$$g(\mathbf{x}; t) = \frac{1}{(2\pi t)^{\frac{N}{2}}} \exp \left[-\frac{\mathbf{x}^T \mathbf{x}}{2t} \right], \quad (3)$$

where $\mathbf{x} \in \mathbb{R}^N$ and $\sigma = \sqrt{t}$, standard deviation of the Gaussian.

Remark 1.1. As t increases, the signal becomes gradually smoother. (See earlier figure)

The scale-space family L can equivalently be defined as the solution to the diffusion equation:

$$\partial_t L = \frac{1}{2} \nabla^T \nabla L = \frac{1}{2} \sum_{i=1}^N \partial_{x_i}^2 L$$

with the initial condition $L(\cdot; 0) = f$. This equation explains how a heat distribution L evolves in time in a homogeneous medium with uniform conductivity.

Toward Gaussian Scale-Space
Multiscale Spatial Derivatives

Multiscale spatial derivatives can be defined by:

$$L_{x^n}(\cdot; t) = \partial_{x^n} L(\cdot; t) = g_{x^n}(\cdot; t) \otimes f \quad (*)$$

When g_{x^n} denotes a (possibly mixed) Gaussian derivative of some order $n = (n_1, \dots, n_N)^T \in \mathbb{Z}^N$, each $n_i \in \mathbb{Z}$ and $\partial_{x^n} = \partial_{x_1}^{n_1} \partial_{x_2}^{n_2} \dots \partial_{x_N}^{n_N}$ where $x = (x_1, \dots, x_N)^T \in \mathbb{R}^N$ and $x_i \in \mathbb{R}$.

Note that (*) creates a way of computing derivatives of f to any order even though f may not be differentiable of any order.

JJ Corso (University of Michigan)
Invariance: Scale
October 3, 2017 6 / 10

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Toward Gaussian Scale-Space

Discussion

Scale-space leads to suppressions at fine scale structures. Intuitively, when convolving a signal by a Gaussian kernel with standard deviation $\sigma = \sqrt{t}$, this leads to suppressing most of the structures in the signal with characteristic length less than σ . (not an exact property)

- 1 New local extrema const be created with increasing scale in 1D
- 2 The property that new local extrema can be created with increasing scale is inherit in two and higher dimensions.
- 3 Gaussian kernel is the unique kernel for generating the scale space (Koendeink 1994).
(SSR must satisfy $\partial_t L = \frac{1}{2} \nabla^2 L$ and, since, Gaussian is the Green's function of the diffusion equation at an infinite domain.) *Beyond scope for this course; you are not responsible for this point.*
- 4 Have semigroup property: $h(\cdot; t_1) \otimes h(\cdot; t_2) = (\cdot; t_1 + t_2)$

Remark 2.1. Scale-space leads to suppressions at fine scale structures. Intuitively, when convolving a signal by a Gaussian kernel with standard deviation $\sigma = \sqrt{t}$, this leads to suppressing most of the structures in the signal with characteristic length less than σ . (not an exact property)

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Normalization in Gaussian Scale-Space

Amplitude of scale-space spatial derivatives decreases with scale due to non-enhancement property of local extrema.

Normalize by multiplying by \sqrt{t} or σ of Gaussian:

$$\hat{\partial} = \sqrt{t} \partial$$

See other slides for discussion on this scale normalization.

Remark 2.2. Amplitude of scale-space spatial derivatives decreases with scale due to non-enhancement property of local extrema.

Normalize by multiplying by \sqrt{t} or σ of Gaussian:

$$\hat{\partial} = \sqrt{t}\partial$$

See other slides for discussion on this scale normalization.

3 Example in scale selection: Normalization

Consider a sinusoidal input signal of frequency ω_0 :

$$f(x) = \sin \omega_0 x$$

Solution of Diffusion Equation for scale space:

$$L(x; t) = e^{-\frac{\omega_0^2 t}{2}} \sin \omega_0 x$$

Amplitude of scale-space L_{\max} , and amplitude of m^{th} order derivative

$$L_{x^m, \max}(t) = \omega_0^m e^{-\omega_0^2 t/2}$$

γ – normalized derivative:

$$\partial_{\zeta, \gamma-norm} = t^{\gamma/2} \partial_x, \quad \zeta = \frac{x}{t^{\gamma/2}}$$

Amplitude of an m^{th} order normalized derivative as a function of scale is given by:

$$L_{\zeta^m, \max}(t) = t^{m\gamma/2} \cdot \omega_0^m \cdot e^{-\omega_0^2 t/2}, \text{ unique max at : } t_{\max, L\zeta^m} = \frac{\gamma m}{\omega_0^2}$$

Scale $\sigma = \sqrt{t}$, wavelength $\lambda_0 = \frac{2\pi}{\omega_0}$, then scale at which amplitude of γ – norm derivative assumes its maximum over scale is proportional to the wavelength λ_0 of the signal

$$\sigma_{\max, L\zeta^m} = \frac{\sqrt{\gamma m}}{2\pi} \lambda_0$$

4 Scale Selection Principle

With the γ – normalized derivative, we achieve a one-to-one correspondence between the matching response at the Gaussian derivative kernels and the wavelength of the signal.

Lindeberg's Scale Selection Principle

In the absence of other evidence, assume that a scale level, at which some (possibly non-linear) combination of normalized derivatives, assumes a local maximum over scales, can be treated as reflecting a characteristic length of a corresponding structure in the data.

4.1 Lindeberg's Principle of automatic scale selection

In the absence of other evidence, assume that a scale level, at which some (possibly non-linear) combination of normalized derivatives, assumes a local maximum over scales, can be treated as reflecting a characteristic length of a corresponding structure in the data.

5 Scale Invariance of Local Scale-Space Maxima

Scale Invariance of Local Scale-Space Maxima

Let $f(x) = f'(sx)$ and $L(\cdot; t) = g(\cdot; t) \otimes f$, $L'(\cdot; t) = g(\cdot; t') \otimes f'$
 $x' = sx$ \Rightarrow if input image is rescaled by factors, then scale of
 $t' = s^2 t$ local maxima assumed to be multiplied by same
 factor. (measured in units of $\sigma = \sqrt{t}$).

Then

$$L(x; t) = L'(x'; t')$$

and for m^{th} order derivatives:

$$\partial_{x^m} L(x; t) = s^m \partial_{x'^m} L'(x'; t')$$

For γ – normalized derivatives:

$$\partial_{\zeta} = t^{\gamma/2} \partial_x, \partial_{\zeta'} = t'^{\gamma/2} \partial_{x'}$$

We have:

$$\partial_{\zeta^m} L(x; t) = s^{m(1-\gamma)} \partial_{\zeta'^m} L'(x'; t')$$

When $\gamma = 1$, we have perfect scale invariance

Consider $f(x) = f'(sx)$ and $L(\cdot; t) = g(\cdot; t) \otimes f$, $L'(\cdot; t) = g(\cdot; t') \otimes f'$

$$x' = sx, t' = s^2 t$$

\Rightarrow if input image is rescaled by factors, then scale of local maxima assumed to be multiplied by same factor.(measured in units of $\sigma = \sqrt{t}$). Then

$$L(x'; t) = L'(x'; t')$$

and for m^{th} order derivatives:

$$\partial_{x^m} L(x; t) = s^m \partial_{x'^m} L'(x'; t')$$

For γ – *normalized* derivatives:

$$\partial_{\zeta} = t^{\gamma/2} \partial_x, \partial_{\zeta'} = t'^{\gamma/2} \partial_{x'}$$

We have:

$$\partial_{\zeta^m} L(x; t) = s^{m(1-\gamma)} \partial_{\zeta'^m} L'(x'; t')$$

When $\gamma = 1$, we have perfect scale invariance

6 Scale Invariant Natural Image Statistics

Add examples; Invariance of gradient statistics.