

# Deep Learning Technology and Application

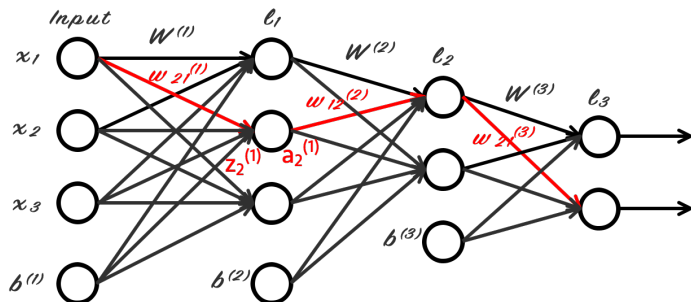
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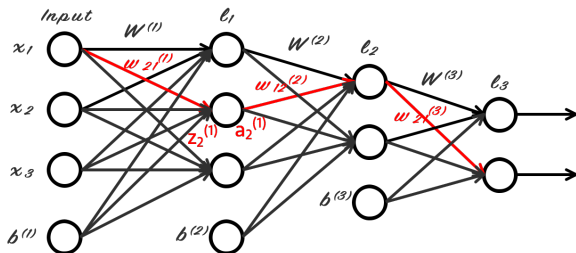
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# 前向传播的符号体系



## 前向传播计算



$$z_1^{(1)} = w_{11}^{(1)} x_1 + w_{12}^{(1)} x_2 + w_{13}^{(1)} x_3 + b_1^{(1)}$$

$$z_2^{(1)} = w_{21}^{(1)} x_1 + w_{22}^{(1)} x_2 + w_{23}^{(1)} x_3 + b_2^{(1)}$$

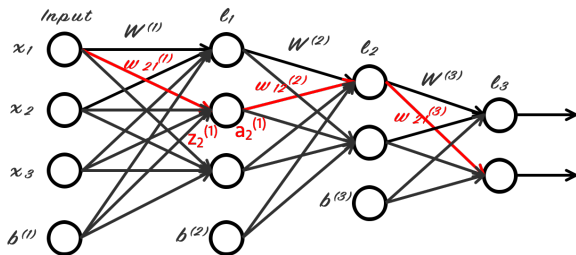
$$z_3^{(1)} = w_{31}^{(1)} x_1 + w_{32}^{(1)} x_2 + w_{33}^{(1)} x_3 + b_3^{(1)}$$

$$a_1^{(1)} = f(z_1^{(1)})$$

$$a_2^{(1)} = f(z_2^{(1)})$$

$$a_3^{(1)} = f(z_3^{(1)})$$

## 前向传播计算

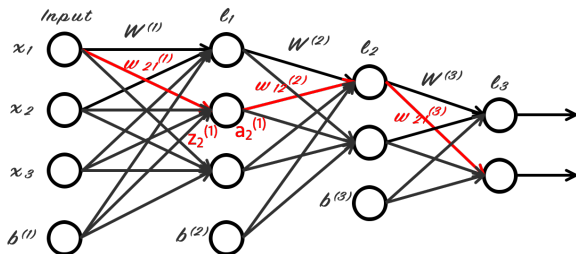


$$z^{(1)} = \begin{bmatrix} z_1^{(1)} \\ z_2^{(1)} \\ z_3^{(1)} \end{bmatrix} = \begin{bmatrix} w_{11}^{(1)} & w_{12}^{(1)} & w_{13}^{(1)} \\ w_{21}^{(1)} & w_{22}^{(1)} & w_{23}^{(1)} \\ w_{31}^{(1)} & w_{32}^{(1)} & w_{33}^{(1)} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1^{(1)} \\ b_2^{(1)} \\ b_3^{(1)} \end{bmatrix} = W^{(1)}X + b^{(1)}$$

$$a^{(1)} = f(z^{(1)}) = f(W^{(1)}X + b^{(1)})$$

$$a^{(2)} = f(z^{(2)}) = f(W^{(2)}a^{(1)} + b^{(2)})$$

# 前向传播计算



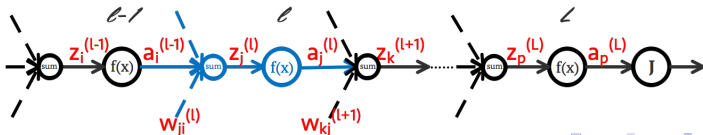
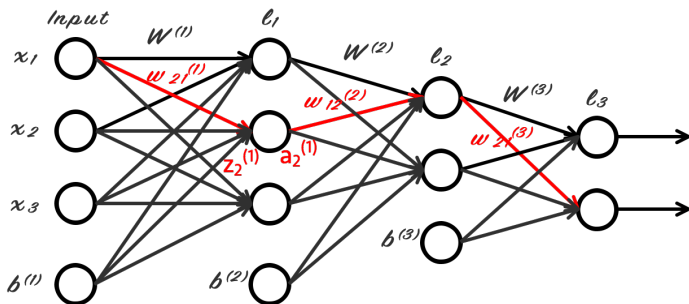
$$z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \end{bmatrix} = \begin{bmatrix} w_{11}^{(2)} & w_{12}^{(2)} & w_{13}^{(2)} \\ w_{21}^{(2)} & w_{22}^{(2)} & w_{23}^{(2)} \end{bmatrix} \begin{bmatrix} a_1^{(1)} \\ a_2^{(1)} \\ a_3^{(1)} \end{bmatrix} + \begin{bmatrix} b_1^{(2)} \\ b_2^{(2)} \\ b_3^{(2)} \end{bmatrix} = W^{(2)} a^{(1)} + b^{(2)}$$

总之：

$$z^l = W^{(l)} a^{(l-1)} + b^{(l)}$$

$$a^{(l)} = f(z^{(l)})$$

## 反向传播符号体系



# 预备知识-多元复合函数求导

由于接下来的计算中要用到多元符合函数的求导，下面我们先来回顾一下“多元复合函数的求导”的方法：



# 多元复合函数求导-1

设:  $z = f(y_1, y_2, \dots, y_m)$ , 其中:  $(y_1, y_2, \dots, y_m) \in D_f$  为区域  $D_f \subset R^m$  上的  $m$  元函数。又设:

$$\begin{aligned} g : D_g &\rightarrow R^m, \\ (x_1, x_2, \dots, x_n) &\mapsto (y_1, y_2, \dots, y_m) \end{aligned} \tag{1}$$

为区域  $D_g \subset R^n$  上的  $n$  元  $m$  维向量值函数, 那么, 对于复合函数:

$$\begin{aligned} z = f \circ g &= f[y_1(x_1, x_2, \dots, x_n), y_2(x_1, x_2, \dots, x_n), \dots, y_m(x_1, x_2, \dots, x_n)] \\ &\text{其中: } (x_1, x_2, \dots, x_n) \in D_g \end{aligned}$$

若  $g$  在  $x^0 \in D_g$  点可导, 即  $y_1, y_2, \dots, y_m$  在  $x^0$  点可偏导, 且  $f$  在  $y^0 = g(x^0)$  点可微, 则:

# 多元复合函数求导-2

$$\frac{\partial z}{\partial x}(x^0) = \left( \frac{\partial z}{\partial x_1}, \frac{\partial z}{\partial x_2}, \dots, \frac{\partial z}{\partial x_i}, \dots, \frac{\partial z}{\partial x_n} \right)_{x=x^0}$$

其中：

$$\frac{\partial z}{\partial x_i}(x^0) = \sum_{j=1}^m \frac{\partial z}{\partial y_j}(y^0) \frac{\partial y_j}{\partial x_i}(x^0)$$

即：

$$\frac{\partial z}{\partial x}(x^0) = \left( \frac{\partial z}{\partial y_1}, \frac{\partial z}{\partial y_2}, \dots, \frac{\partial z}{\partial y_m} \right)_{y=y^0} \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} & \cdots & \frac{\partial y_1}{\partial x_n} \\ \frac{\partial y_2}{\partial x_1} & \frac{\partial y_2}{\partial x_2} & \cdots & \frac{\partial y_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial y_m}{\partial x_1} & \frac{\partial y_m}{\partial x_2} & \cdots & \frac{\partial y_m}{\partial x_n} \end{bmatrix}_{x=x^0}$$

## 多元复合函数求导-3

若  $g$  处处可导，即  $y_1, y_2, \dots, y_n$  处处可偏导，且  $f$  处处可微，则：

$$\frac{\partial z}{\partial x} = \left( \frac{\partial z}{\partial x_1}, \frac{\partial z}{\partial x_2}, \dots, \frac{\partial z}{\partial x_i}, \dots, \frac{\partial z}{\partial x_n} \right)$$

其中：

$$\frac{\partial z}{\partial x_i} = \sum_{j=1}^m \frac{\partial z}{\partial y_j} \frac{\partial y_j}{\partial x_i}$$

即：

$$\frac{\partial z}{\partial x} = \left( \frac{\partial z}{\partial y_1}, \frac{\partial z}{\partial y_2}, \dots, \frac{\partial z}{\partial y_m} \right) \begin{bmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} & \cdots & \frac{\partial y_1}{\partial x_n} \\ \frac{\partial y_2}{\partial x_1} & \frac{\partial y_2}{\partial x_2} & \cdots & \frac{\partial y_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial y_m}{\partial x_1} & \frac{\partial y_m}{\partial x_2} & \cdots & \frac{\partial y_m}{\partial x_n} \end{bmatrix} \quad (\text{此矩阵即 Jacobian 矩阵})$$

# 一介全微分的形式不变性

对于多元函数  $z = f(y)$ , 其中  $y = (y_1, y_2, \dots, y_m)^\top$ 。当  $y$  为自变量时, 一介全微分形式为:

$$dz = f'(y) dy$$

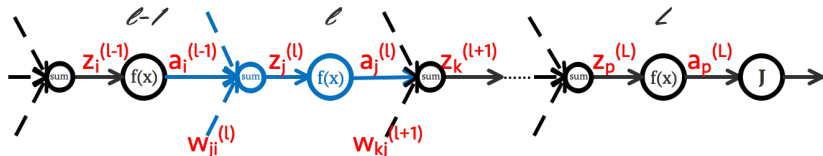
而当  $y$  为中间变量  $y = g(x) (x = (x_1, x_2, \dots, x_n)^\top)$  时,  $dy = g'(x) dx$ 。由链式规则, 得:

$$dz = (f \circ g)'(x) dx = f'(y) g'(x) dx = f'(y) (g'(x) dx) = f'(y) dy$$

注意符号:

$$\frac{dz}{dy} = f'(y); \quad \frac{dz}{dx} = (f \circ g)'(x) = f'(y) g'(x)$$

# 反向传播算法



$$z^l = W^{(l)} a^{(l-1)} + b^{(l)}$$

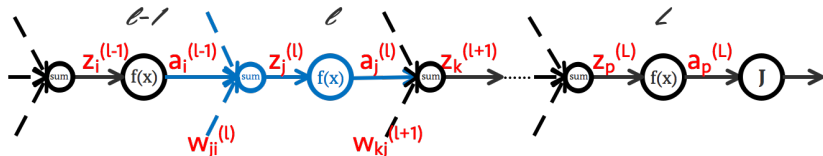
$$a^{(l)} = f(z^{(l)})$$

由梯度下降方法，可知，需要对每个权重权值  $w_{ij}^{(l)}$ ，求取：

$$w_{ji}^{(l)} = w_{ji}^{(l)} - \alpha \frac{\partial J(W, b)}{\partial w_{ji}^{(l)}} \quad b_i^{(l)} = b_i^{(l)} - \alpha \frac{\partial J(W, b)}{\partial b_i^{(l)}}$$

其中，关键是如何求取：  $\frac{\partial J(W, b)}{\partial w_{ji}^{(l)}}$  和  $\frac{\partial J(W, b)}{\partial b_i^{(l)}}$

# 反向传播算法



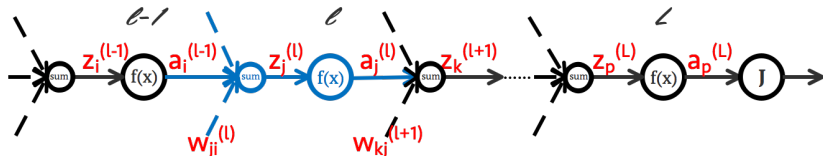
由前向传播过程可知:  $z_j^{(l)} = \sum_{i=1}^{n_l} w_{ji}^{(l)} a_i^{(l-1)} + b_i^{(l)}$  可知:

$$\frac{\partial J(W, b)}{\partial w_{ji}^{(l)}} = \frac{\partial J(W, b)}{\partial z_j^{(l)}} \frac{\partial z_j^{(l)}}{\partial w_{ji}^{(l)}} = \frac{\partial J(W, b)}{\partial z_j^{(l)}} a_i^{(l-1)}$$

$$\frac{\partial J(W, b)}{\partial b_i^{(l)}} = \frac{\partial J(W, b)}{\partial z_j^{(l)}} \frac{\partial z_j^{(l)}}{\partial b_i^{(l)}} = \frac{\partial J(W, b)}{\partial z_j^{(l)}}$$

到此为止, 关键是如何求取  $\frac{\partial J(W, b)}{\partial z_j^{(l)}}$

# 反向传播算法

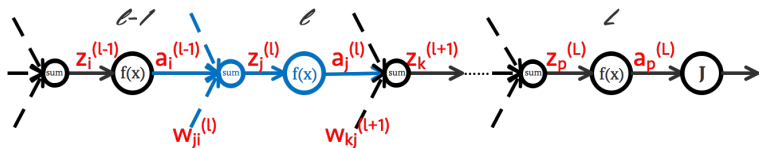


设:  $\delta_j^{(l)} = \frac{\partial J(W,b)}{\partial z_j^{(l)}}$

因为:  $z_k^{(l+1)} = \sum_{j=1}^{n_{l+1}} w_{kj}^{(l+1)} a_j^{(l)} + b^{(l+1)}$

所以, 可以选择从  $z_k^{(l+1)}$  开始进行对  $z_j^{(l)}$  进行求导计算:

## 反向传播算法推导



$$\begin{aligned}
 \delta_j^{(l)} &= \frac{\partial J(W, b)}{\partial z_j^{(l)}} = \sum_{k=1}^{n_{l+1}} \frac{\partial J(W, b)}{\partial z_k^{(l+1)}} \frac{\partial z_k^{(l+1)}}{\partial a_j^{(l)}} \frac{\partial a_j^{(l)}}{\partial z_j^{(l)}} \\
 &= \sum_{k=1}^{n_{l+1}} \frac{\partial J(W, b)}{\partial z_k^{(l+1)}} w_{kj}^{(l+1)} f'(z_j^{(l)}) \\
 &= \sum_{k=1}^{n_{l+1}} \delta_k^{(l+1)} w_{kj}^{(l+1)} f'(z_j^{(l)})
 \end{aligned}$$

(2)



# 反向传播算法推导

对于最后一层：

$$\delta_p^{(L)} = \frac{\partial J(W, b)}{\partial z_p^{(L)}} = \frac{\partial J(W, b)}{\partial a_p^{(L)}} * \frac{\partial a_p^{(L)}}{\partial z_p^{(L)}} = \frac{\partial J(W, b)}{\partial a_p^{(L)}} * f'(z_p^{(L)})$$

并且：

$$\frac{\partial J(W, b)}{\partial w_{pq}^{(L)}} = \frac{\partial J(W, b)}{\partial z_p^{(L)}} a_p^{(L-1)} = \delta_p^{(L)} a_p^{(L-1)}$$

$$\frac{\partial J(W, b)}{\partial b_q^{(L)}} = \frac{\partial J(W, b)}{\partial z_p^{(L)}} = \delta_p^{(L)}$$

# 反向传播算法推导

小结一下，因为：

$$\frac{\partial J(W, b)}{\partial w_{ji}^{(l)}} = \frac{\partial J(W, b)}{\partial z_j^{(l)}} a_i^{(l-1)} \quad \frac{\partial J(W, b)}{\partial b_i^{(l)}} = \frac{\partial J(W, b)}{\partial z_j^{(l)}}$$

又因为 (上文推导结果)：

$$\frac{\partial J(W, b)}{\partial z_j^{(l)}} = \delta_j^{(l)} = \sum_{k=1}^{n_{l+1}} \delta_k^{(l+1)} w_{kj}^{(l+1)} f'(z_j^{(l)})$$

从而得到：

$$\frac{\partial J(W, b)}{\partial w_{ji}^{(l)}} = \delta_j^{(l)} a_i^{(l-1)} \quad \frac{\partial J(W, b)}{\partial b_i^{(l)}} = \delta_j^{(l)}$$

# 反向传播算法总结

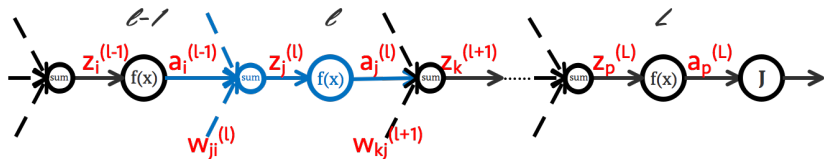
总结一下：

$$\frac{\partial J(W, b)}{\partial w_{ji}^{(l)}} = \delta_j^{(l)} a_i^{(l-1)} = \left( \sum_{k=1}^{n_{l+1}} \delta_k^{(l+1)} w_{kj}^{(l+1)} f'(z_j^{(l)}) \right) a_i^{(l-1)}$$

$$\frac{\partial J(W, b)}{\partial b_i^{(l)}} = \delta_j^{(l)} = \sum_{k=1}^{n_{l+1}} \delta_k^{(l+1)} w_{kj}^{(l+1)} f'(z_j^{(l)})$$

# 反向传播计算流程

Step-1: 依据前向传播算法求解每一层的激活值:

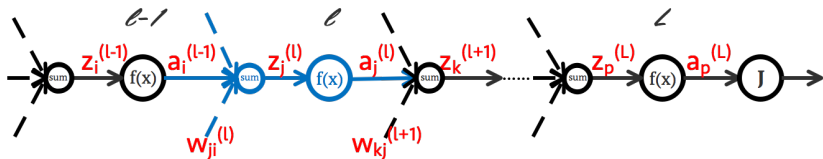


$$z^l = W^{(l)} a^{(l-1)} + b^{(l)}$$

$$a^{(l)} = f(z^{(l)})$$

# 反向传播计算流程

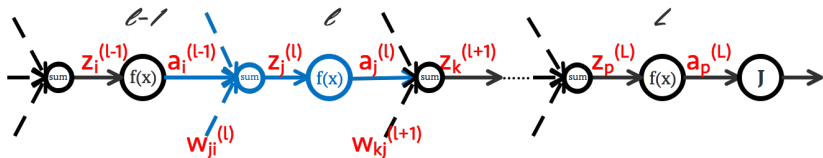
Step-2: 计算出最后一层 (L 层) 的每个神经元的  $\delta_p^{(L)}$ :



$$\delta_p^{(L)} = \frac{\partial J(W, b)}{\partial a_p^{(L)}} * f'(z_p^{(L)})$$

# 反向传播计算流程

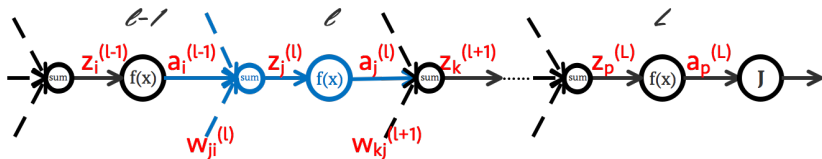
Step-3: 由后向前, 依次计算出各层 ( $l$  层) 各个神经元的  $\delta_j^{(l)}$



$$\delta_j^{(l)} = \sum_{k=1}^{n_{l+1}} \delta_k^{(l+1)} w_{kj}^{(l+1)} f'(z_j^{(l)})$$

# 反向传播计算流程

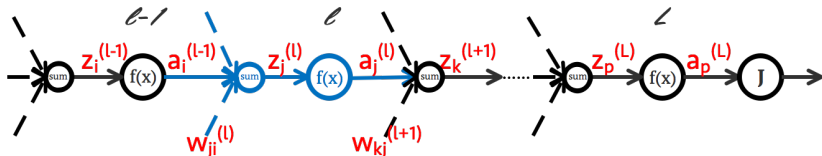
Step-4: 计算出各层 ( $l$  层) 的各个权重 ( $w_{ji}^{(l)}$ ) 的梯度  $\frac{\partial J(W,b)}{\partial w_{ji}^{(l)}}$  及各个偏置 ( $b_i^{(l)}$ ) 的梯度  $\frac{\partial J(W,b)}{\partial b_i^{(l)}}$ :



$$\frac{\partial J(W,b)}{\partial w_{ji}^{(l)}} = \delta_j^{(l)} a_i^{(l-1)} \quad \frac{\partial J(W,b)}{\partial b_i^{(l)}} = \delta_j^{(l)}$$

# 反向传播计算流程

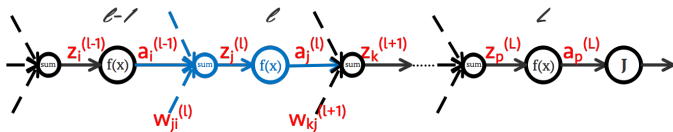
Step-5: 对各层 ( $l$  层) 的各个权重 ( $w_{ji}^{(l)}$ ) 及各个偏置 ( $b_i^{(l)}$ ) 进行更新, 直到代价函数  $J(W, b)$  足够小:



$$w_{ji}^{(l)} = w_{ji}^{(l)} - \alpha \frac{\partial J(W, b)}{\partial w_{ji}^{(l)}} \quad b_i^{(l)} = b_i^{(l)} - \alpha \frac{\partial J(W, b)}{\partial b_i^{(l)}}$$



# 反向传播核心算式



$$\begin{aligned}
 w_{ji}^{(l)} &= w_{ji}^{(l)} - \alpha \frac{\partial J(W, b)}{\partial w_{ji}^{(l)}} \\
 &= w_{ji}^{(l)} - \alpha \frac{\partial J(W, b)}{\partial z_j^{(l)}} \frac{\partial z_j^{(l)}}{\partial w_{ji}^{(l)}} = w_{ji}^{(l)} - \alpha \frac{\partial J(W, b)}{\partial z_j^{(l)}} a_i^{(l-1)} \\
 &= w_{ji}^{(l)} - \alpha \delta_j^{(l)} a_i^{(l-1)} \\
 &= w_{ji}^{(l)} - \alpha \left( \sum_{k=1}^{n_{l+1}} \delta_k^{(l+1)} w_{kj}^{(l+1)} f'(z_j^{(l)}) \right) a_i^{(l-1)}
 \end{aligned}$$

*Thanks.*