# **Fully connected networks**

In the previous notebook, you implemented a simple two-layer neural network class. However, this class is not modular. If you wanted to change the number of layers, you would need to write a new loss and gradient function. If you wanted to optimize the network with different optimizers, you'd need to write new training functions. If you wanted to incorporate regularizations, you'd have to modify the loss and gradient function.

Instead of having to modify functions each time, for the rest of the class, we'll work in a more modular framework where we define forward and backward layers that calculate losses and gradients respectively. Since the forward and backward layers share intermediate values that are useful for calculating both the loss and the gradient, we'll also have these function return "caches" which store useful intermediate values.

The goal is that through this modular design, we can build different sized neural networks for various applications.

In this HW #3, we'll define the basic architecture, and in HW #4, we'll build on this framework to implement different optimizers and regularizations (like BatchNorm and Dropout).

CS231n has built a solid API for building these modular frameworks and training them, and we will use their very well implemented framework as opposed to "reinventing the wheel." This includes using their Solver, various utility functions, and their layer structure. This also includes nndl.fc\_net, nndl.layers, and nndl.layer\_utils. As in prior assignments, we thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu).

## **Modular layers**

This notebook will build modular layers in the following manner. First, there will be a forward pass for a given layer with inputs (x) and return the output of that layer (x) as well as cached variables (x) that will be used to calculate the gradient in the backward pass.

```
def layer_forward(x, w):
    """ Receive inputs x and weights w """

# Do some computations ...

z = # ... some intermediate value

# Do some more computations ...

out = # the output

cache = (x, w, z, out) # Values we need to compute gradients

return out, cache
```

The backward pass will receive upstream derivatives and the cache object, and will return gradients with respect to the inputs and weights, like this:

```
def layer_backward(dout, cache):
    """

Receive derivative of loss with respect to outputs and cache,
    and compute derivative with respect to inputs.
    """

# Unpack cache values
    x, w, z, out = cache

# Use values in cache to compute derivatives
    dx = # Derivative of loss with respect to x
    dw = # Derivative of loss with respect to w
```

```
## Import and setups
import time
import numpy as np
import matplotlib.pyplot as plt
from nndl.fc_net import *
from cs231n.data utils import get CIFAR10 data
from cs231n.gradient_check import eval_numerical_gradient,
eval numerical gradient array
from cs231n.solver import Solver
%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'
# for auto-reloading external modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-
ipython
%load ext autoreload
%autoreload 2
def rel error(x, y):
  """ returns relative error """
 return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + np.abs(y))))
```

```
# Load the (preprocessed) CIFAR10 data.

data = get_CIFAR10_data()
for k in data.keys():
    print('{}: {} '.format(k, data[k].shape))
```

```
X_val: (1000, 3, 32, 32)
y_test: (1000,)
y_train: (49000,)
X_test: (1000, 3, 32, 32)
y_val: (1000,)
X_train: (49000, 3, 32, 32)
```

# **Linear layers**

In this section, we'll implement the forward and backward pass for the linear layers.

The linear layer forward pass is the function <code>affine\_forward</code> in <code>nndl/layers.py</code> and the backward pass is <code>affine\_backward</code>.

After you have implemented these, test your implementation by running the cell below.

## **Affine layer forward pass**

Implement affine\_forward and then test your code by running the following cell.

```
# Test the affine_forward function
num_inputs = 2
input\_shape = (4, 5, 6)
output dim = 3
input_size = num_inputs * np.prod(input_shape)
weight_size = output_dim * np.prod(input_shape)
x = np.linspace(-0.1, 0.5, num=input_size).reshape(num_inputs, *input_shape)
w = np.linspace(-0.2, 0.3, num=weight_size).reshape(np.prod(input_shape),
output_dim)
b = np.linspace(-0.3, 0.1, num=output dim)
out, _ = affine_forward(x, w, b)
correct_out = np.array([[ 1.49834967, 1.70660132, 1.91485297],
                        [ 3.25553199, 3.5141327, 3.77273342]])
# Compare your output with ours. The error should be around 1e-9.
print('Testing affine forward function:')
print('difference: {}'.format(rel_error(out, correct_out)))
```

```
Testing affine_forward function:
difference: 9.7698500479884e-10
```

### Affine layer backward pass

Implement affine\_backward and then test your code by running the following cell.

```
# Test the affine_backward function
x = np.random.randn(10, 2, 3)
w = np.random.randn(6, 5)
b = np.random.randn(5)
dout = np.random.randn(10, 5)
dx_num = eval_numerical_gradient_array(lambda x: affine_forward(x, w, b)[0],
x, dout)
dw num = eval numerical gradient array(lambda w: affine forward(x, w, b)[0],
w, dout)
db_num = eval_numerical_gradient_array(lambda b: affine_forward(x, w, b)[0],
b, dout)
_, cache = affine_forward(x, w, b)
dx, dw, db = affine_backward(dout, cache)
# The error should be around 1e-10
print('Testing affine_backward function:')
print('dx error: {}'.format(rel error(dx num, dx)))
print('dw error: {}'.format(rel_error(dw_num, dw)))
print('db error: {}'.format(rel_error(db_num, db)))
```

```
Testing affine_backward function:
dx error: 1.7792258869473942e-10
dw error: 1.7504796033291886e-10
db error: 1.7519769156660496e-11
```

# **Activation layers**

In this section you'll implement the ReLU activation.

#### **ReLU forward pass**

Implement the relu\_forward function in nndl/layers.py and then test your code by running the following cell.

```
Testing relu_forward function:
difference: 4.999999798022158e-08
```

### **ReLU backward pass**

Implement the relu\_backward function in nndl/layers.py and then test your code by running the following cell.

```
x = np.random.randn(10, 10)
dout = np.random.randn(*x.shape)

dx_num = eval_numerical_gradient_array(lambda x: relu_forward(x)[0], x, dout)

_, cache = relu_forward(x)
dx = relu_backward(dout, cache)

# The error should be around 1e-12
print('Testing relu_backward function:')
print('dx error: {}'.format(rel_error(dx_num, dx)))
```

```
Testing relu_backward function:
dx error: 3.2756113236027615e-12
```

# **Combining the affine and ReLU layers**

Often times, an affine layer will be followed by a ReLU layer. So let's make one that puts them together. Layers that are combined are stored in <code>nndl/layer\_utils.py</code>.

#### **Affine-ReLU layers**

We've implemented affine\_relu\_forward() and affine\_relu\_backward in nndl/layer\_utils.py. Take a look at them to make sure you understand what's going on. Then run the following cell to ensure its implemented correctly.

```
from nndl.layer utils import affine relu forward, affine relu backward
x = np.random.randn(2, 3, 4)
w = np.random.randn(12, 10)
b = np.random.randn(10)
dout = np.random.randn(2, 10)
out, cache = affine_relu_forward(x, w, b)
dx, dw, db = affine_relu_backward(dout, cache)
dx_num = eval_numerical_gradient_array(lambda x: affine_relu_forward(x, w, b)
[0], x, dout)
dw num = eval numerical gradient array(lambda w: affine relu forward(x, w, b)
[0], w, dout)
db_num = eval_numerical_gradient_array(lambda b: affine_relu_forward(x, w, b)
[0], b, dout)
print('Testing affine relu forward and affine relu backward:')
print('dx error: {}'.format(rel_error(dx_num, dx)))
print('dw error: {}'.format(rel_error(dw_num, dw)))
print('db error: {}'.format(rel error(db num, db)))
```

```
Testing affine_relu_forward and affine_relu_backward:
dx error: 2.261033893905029e-09
dw error: 6.051708743538486e-09
db error: 7.55627367037208e-11
```

#### **Softmax and SVM losses**

You've already implemented these, so we have written these in layers.py. The following code will ensure they are working correctly.

```
num_classes, num_inputs = 10, 50
x = 0.001 * np.random.randn(num inputs, num classes)
y = np.random.randint(num_classes, size=num_inputs)
dx num = eval numerical gradient(lambda x: svm loss(x, y)[0], x,
verbose=False)
loss, dx = svm_loss(x, y)
# Test svm loss function. Loss should be around 9 and dx error should be 1e-9
print('Testing svm loss:')
print('loss: {}'.format(loss))
print('dx error: {}'.format(rel_error(dx_num, dx)))
dx num = eval numerical gradient(lambda x: softmax loss(x, y)[0], x,
verbose=False)
loss, dx = softmax_loss(x, y)
# Test softmax_loss function. Loss should be 2.3 and dx error should be 1e-8
print('\nTesting softmax_loss:')
print('loss: {}'.format(loss))
print('dx error: {}'.format(rel error(dx num, dx)))
```

```
Testing svm_loss:
loss: 8.998306995796787
dx error: 1.4021566006651672e-09

Testing softmax_loss:
loss: 2.3024162325284747
dx error: 7.635214473842447e-09
```

# Implementation of a two-layer NN

In nndl/fc\_net.py, implement the class TwoLayerNet which uses the layers you made here.
When you have finished, the following cell will test your implementation.

```
N, D, H, C = 3, 5, 50, 7
X = np.random.randn(N, D)
y = np.random.randint(C, size=N)

std = 1e-2
model = TwoLayerNet(input_dim=D, hidden_dims=H, num_classes=C, weight_scale=std)

print('Testing initialization ... ')
```

```
W1 std = abs(model.params['W1'].std() - std)
b1 = model.params['b1']
W2 std = abs(model.params['W2'].std() - std)
b2 = model.params['b2']
assert W1 std < std / 10, 'First layer weights do not seem right'
assert np.all(b1 == 0), 'First layer biases do not seem right'
assert W2_std < std / 10, 'Second layer weights do not seem right'
assert np.all(b2 == 0), 'Second layer biases do not seem right'
print('Testing test-time forward pass ...')
model.params['W1'] = np.linspace(-0.7, 0.3, num=D*H).reshape(D, H)
model.params['b1'] = np.linspace(-0.1, 0.9, num=H)
model.params['W2'] = np.linspace(-0.3, 0.4, num=H*C).reshape(H, C)
model.params['b2'] = np.linspace(-0.9, 0.1, num=C)
X = np.linspace(-5.5, 4.5, num=N*D).reshape(D, N).T
scores = model.loss(X)
correct_scores = np.asarray(
 [[11.53165108, 12.2917344, 13.05181771, 13.81190102, 14.57198434,
15.33206765, 16.09215096],
   [12.05769098, 12.74614105, 13.43459113, 14.1230412, 14.81149128,
15.49994135, 16.18839143],
   [12.58373087, 13.20054771, 13.81736455, 14.43418138, 15.05099822,
15.66781506, 16.2846319 ]])
scores_diff = np.abs(scores - correct_scores).sum()
assert scores diff < 1e-6, 'Problem with test-time forward pass'
print('Testing training loss (no regularization)')
y = np.asarray([0, 5, 1])
loss, grads = model.loss(X, y)
correct loss = 3.4702243556
assert abs(loss - correct loss) < 1e-10, 'Problem with training-time loss'
model.reg = 1.0
loss, grads = model.loss(X, y)
correct loss = 26.5948426952
assert abs(loss - correct loss) < 1e-10, 'Problem with regularization loss'
for reg in [0.0, 0.7]:
  print('Running numeric gradient check with reg = {}'.format(reg))
 model.reg = reg
 loss, grads = model.loss(X, y)
 for name in sorted(grads):
   f = lambda _: model.loss(X, y)[0]
    grad_num = eval_numerical_gradient(f, model.params[name], verbose=False)
    print('{} relative error: {}'.format(name, rel error(grad num,
grads[name])))
```

```
Testing initialization ...

Testing test-time forward pass ...

Testing training loss (no regularization)

Running numeric gradient check with reg = 0.0

W1 relative error: 2.131611955458401e-08

W2 relative error: 3.310270199776237e-10

b1 relative error: 8.36819673247588e-09

b2 relative error: 2.530774050159566e-10

Running numeric gradient check with reg = 0.7

W1 relative error: 2.5279153413239097e-07

W2 relative error: 1.367837124985045e-07

b1 relative error: 1.5646802033932055e-08

b2 relative error: 9.089614638133234e-10
```

#### Solver

We will now use the cs231n Solver class to train these networks. Familiarize yourself with the API in cs231n/solver.py. After you have done so, declare an instance of a TwoLayerNet with 200 units and then train it with the Solver. Choose parameters so that your validation accuracy is at least 50%.

```
model = TwoLayerNet()
solver = None
# YOUR CODE HERE:
 Declare an instance of a TwoLayerNet and then train
# it with the Solver. Choose hyperparameters so that your validation
# accuracy is at least 40%. We won't have you optimize this further
 since you did it in the previous notebook.
model = TwoLayerNet(reg = 0.25)
solver = Solver(model, data = data,
         optim_config = {
            'learning rate': 0.001,
         }, lr_decay = 0.85, num_epochs = 10, batch_size = 200,
print_every = 50)
solver.train()
# END YOUR CODE HERE
```

```
(Iteration 1 / 2450) loss: 2.337337
(Epoch 0 / 10) train acc: 0.176000; val acc: 0.173000
(Iteration 51 / 2450) loss: 1.910711
(Iteration 101 / 2450) loss: 1.802551
(Iteration 151 / 2450) loss: 1.746674
(Iteration 201 / 2450) loss: 1.782862
(Epoch 1 / 10) train acc: 0.446000; val acc: 0.434000
(Iteration 251 / 2450) loss: 1.606931
(Iteration 301 / 2450) loss: 1.609461
(Iteration 351 / 2450) loss: 1.620807
(Iteration 401 / 2450) loss: 1.636927
(Iteration 451 / 2450) loss: 1.644888
(Epoch 2 / 10) train acc: 0.479000; val acc: 0.462000
(Iteration 501 / 2450) loss: 1.590001
(Iteration 551 / 2450) loss: 1.539093
(Iteration 601 / 2450) loss: 1.500296
(Iteration 651 / 2450) loss: 1.633473
(Iteration 701 / 2450) loss: 1.552428
(Epoch 3 / 10) train acc: 0.500000; val acc: 0.474000
(Iteration 751 / 2450) loss: 1.498844
(Iteration 801 / 2450) loss: 1.485141
(Iteration 851 / 2450) loss: 1.401013
(Iteration 901 / 2450) loss: 1.536564
(Iteration 951 / 2450) loss: 1.449009
(Epoch 4 / 10) train acc: 0.553000; val acc: 0.490000
(Iteration 1001 / 2450) loss: 1.289351
(Iteration 1051 / 2450) loss: 1.448503
(Iteration 1101 / 2450) loss: 1.463511
(Iteration 1151 / 2450) loss: 1.381720
(Iteration 1201 / 2450) loss: 1.302922
(Epoch 5 / 10) train acc: 0.535000; val_acc: 0.491000
(Iteration 1251 / 2450) loss: 1.344926
(Iteration 1301 / 2450) loss: 1.369209
(Iteration 1351 / 2450) loss: 1.359285
(Iteration 1401 / 2450) loss: 1.349837
(Iteration 1451 / 2450) loss: 1.398131
(Epoch 6 / 10) train acc: 0.572000; val acc: 0.503000
(Iteration 1501 / 2450) loss: 1.425162
(Iteration 1551 / 2450) loss: 1.299397
(Iteration 1601 / 2450) loss: 1.266481
(Iteration 1651 / 2450) loss: 1.573615
(Iteration 1701 / 2450) loss: 1.410486
(Epoch 7 / 10) train acc: 0.541000; val acc: 0.525000
(Iteration 1751 / 2450) loss: 1.418999
(Iteration 1801 / 2450) loss: 1.258174
(Iteration 1851 / 2450) loss: 1.329931
```

```
(Iteration 1901 / 2450) loss: 1.395133

(Iteration 1951 / 2450) loss: 1.328131

(Epoch 8 / 10) train acc: 0.602000; val_acc: 0.508000

(Iteration 2001 / 2450) loss: 1.254937

(Iteration 2051 / 2450) loss: 1.391966

(Iteration 2101 / 2450) loss: 1.434608

(Iteration 2151 / 2450) loss: 1.311771

(Iteration 2201 / 2450) loss: 1.374558

(Epoch 9 / 10) train acc: 0.552000; val_acc: 0.510000

(Iteration 2251 / 2450) loss: 1.319331

(Iteration 2301 / 2450) loss: 1.273286

(Iteration 2351 / 2450) loss: 1.328836

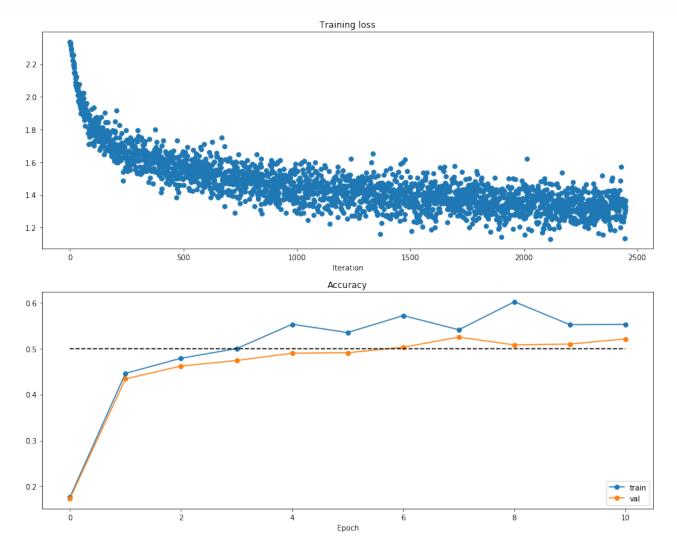
(Iteration 2401 / 2450) loss: 1.327306

(Epoch 10 / 10) train acc: 0.553000; val_acc: 0.521000
```

```
# Run this cell to visualize training loss and train / val accuracy

plt.subplot(2, 1, 1)
plt.title('Training loss')
plt.plot(solver.loss_history, 'o')
plt.xlabel('Iteration')

plt.subplot(2, 1, 2)
plt.title('Accuracy')
plt.plot(solver.train_acc_history, '-o', label='train')
plt.plot(solver.val_acc_history, '-o', label='val')
plt.plot([0.5] * len(solver.val_acc_history), 'k--')
plt.xlabel('Epoch')
plt.legend(loc='lower right')
plt.gcf().set_size_inches(15, 12)
plt.show()
```



# **Multilayer Neural Network**

Now, we implement a multi-layer neural network.

Read through the FullyConnectedNet class in the file nndl/fc\_net.py.

Implement the initialization, the forward pass, and the backward pass. There will be lines for batchnorm and dropout layers and caches; ignore these all for now. That'll be in assignment #4.

```
Running check with reg = 0
Initial loss: 2.3227094181176984
W1 relative error: 9.473423981398794e-06
W2 relative error: 5.335962923177645e-09
b1 relative error: 6.073247014072795e-09
b2 relative error: 1.328227452893485e-10
Running check with reg = 3.14
Initial loss: 4.3230386136289765
W1 relative error: 3.800613468132099e-08
W2 relative error: 3.117433723741423e-08
b1 relative error: 6.036366525813558e-09
b2 relative error: 1.750006524595143e-10
```

```
# Use the three layer neural network to overfit a small dataset.
num_train = 50
small_data = {
  'X_train': data['X_train'][:num_train],
  'y_train': data['y_train'][:num_train],
 'X_val': data['X_val'],
  'y_val': data['y_val'],
}
#### !!!!!!
# Play around with the weight scale and learning rate so that you can overfit
a small dataset.
# Your training accuracy should be 1.0 to receive full credit on this part.
weight_scale = 1e-2
learning_rate = 1e-4
# i just changed the learning rate to .001.
model = FullyConnectedNet([100, 100],
              weight scale=weight scale, dtype=np.float64)
solver = Solver(model, small data,
                print_every=10, num_epochs=20, batch_size=25,
                update_rule='sgd',
                optim_config={
                  'learning rate': 0.001,
solver.train()
plt.plot(solver.loss_history, 'o')
plt.title('Training loss history')
plt.xlabel('Iteration')
plt.ylabel('Training loss')
plt.show()
```

```
(Iteration 1 / 40) loss: 3.355742
(Epoch 0 / 20) train acc: 0.380000; val acc: 0.114000
(Epoch 1 / 20) train acc: 0.440000; val acc: 0.153000
(Epoch 2 / 20) train acc: 0.720000; val acc: 0.120000
(Epoch 3 / 20) train acc: 0.800000; val acc: 0.146000
(Epoch 4 / 20) train acc: 0.880000; val acc: 0.141000
(Epoch 5 / 20) train acc: 0.960000; val acc: 0.163000
(Iteration 11 / 40) loss: 0.237550
(Epoch 6 / 20) train acc: 0.980000; val acc: 0.152000
(Epoch 7 / 20) train acc: 1.000000; val acc: 0.150000
(Epoch 8 / 20) train acc: 1.000000; val_acc: 0.154000
(Epoch 9 / 20) train acc: 1.000000; val_acc: 0.154000
(Epoch 10 / 20) train acc: 1.000000; val acc: 0.155000
(Iteration 21 / 40) loss: 0.034686
(Epoch 11 / 20) train acc: 1.000000; val_acc: 0.152000
(Epoch 12 / 20) train acc: 1.000000; val_acc: 0.153000
(Epoch 13 / 20) train acc: 1.000000; val acc: 0.151000
(Epoch 14 / 20) train acc: 1.000000; val_acc: 0.154000
(Epoch 15 / 20) train acc: 1.000000; val_acc: 0.158000
(Iteration 31 / 40) loss: 0.018596
(Epoch 16 / 20) train acc: 1.000000; val acc: 0.160000
(Epoch 17 / 20) train acc: 1.000000; val acc: 0.159000
(Epoch 18 / 20) train acc: 1.000000; val_acc: 0.162000
(Epoch 19 / 20) train acc: 1.000000; val acc: 0.159000
(Epoch 20 / 20) train acc: 1.000000; val acc: 0.160000
```

