import numpy as np import pdb

""" This code was originally written for CS 231n at Stanford University (cs231n.stanford.edu). It has been modified in various areas for use in the ECE 239AS class at UCLA. This includes the descriptions of what code to implement as well as some slight potential changes in variable names to be consistent with class nomenclature. We thank Justin Johnson & Serena Yeung for permission to use this code. To see the original version, please visit cs231n.stanford.edu.

def affine\_forward(x, w, b): """ Computes the forward pass for an affine (fully-connected) layer.

The input x has shape (N,  $d_1$ , ...,  $d_k$ ) and contains a minibatch of N examples, where each example x[i] has shape ( $d_1$ , ...,  $d_k$ ). We will reshape each input into a vector of dimension D =  $d_1$  \* ... \*  $d_k$ , and then transform it to an output vector of dimension M.

#### Inputs:

- x: A numpy array containing input data, of shape (N, d\_1, ..., d\_k)
- w: A numpy array of weights, of shape (D, M)
- b: A numpy array of biases, of shape (M,)

#### Returns a tuple of:

- out: output, of shape (N, M)
- cache: (x, w, b)

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## **YOUR CODE HERE:**

# Calculate the output of the forward pass. Notice the dimensions

of w are D x M, which is the transpose of what we did in earlier

assignments.

print('minibatch: {}'.format(x.shape))
prod = np.prod(x.shape[1:]) out = x.reshape((x.shape[0], prod)).dot(w) + b
END YOUR CODE HERE
cache = (x, w, b) return out, cache
def affine_backward(dout, cache): """ Computes the backward pass for an affine layer.
Inputs:
• dout: Upstream derivative, of shape (N, M)
• cache: Tuple of:
<ul><li>x: Input data, of shape (N, d_1, d_k)</li><li>w: Weights, of shape (D, M)</li></ul>
Returns a tuple of:
<ul> <li>dx: Gradient with respect to x, of shape (N, d1,, d_k)</li> <li>dw: Gradient with respect to w, of shape (D, M)</li> <li>db: Gradient with respect to b, of shape (M,)</li> </ul>
x, w, b = cache dx, dw, db = None, None
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## **YOUR CODE HERE:**

Calculate the gradients for the backward pass.		
prod = np.prod(x.shape[1:]) db = np.sum(dout, axis = 0) dw = x.reshape((x.shape[0], prod)).T.dot(dout) dx = dout.dot(w.T).reshape(x.shape)		
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return dx, dw, db		
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return dx, dw, db  def relu_forward(x): """ Computes the forward pass for a layer of rectified linear units (ReLUs).		
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return dx, dw, db  def relu_forward(x): """ Computes the forward pass for a layer of rectified linear units (ReLUs).  Input:  • x: Inputs, of any shape		

## YOUR CODE HERE:

Implement the ReLU forward pass.		
out = x * (x > 0)		
END YOUR CODE HERE		
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cache = x return out, cache		
def relu_backward(dout, cache): """ Computes the backward pass for a layer of rectified linear units (ReLUs).		
Input:		
<ul> <li>dout: Upstream derivatives, of any shape</li> <li>cache: Input x, of same shape as dout</li> </ul>		
Returns:		
• dx: Gradient with respect to x		
x = cache		
YOUR CODE HERE:		

# 

return dx

def svm\_loss(x, y): """ Computes the loss and gradient using for multiclass SVM classification.

Inputs:

- x: Input data, of shape (N, C) where x[i, j] is the score for the jth class for the ith input.
- y: Vector of labels, of shape (N,) where y[i] is the label for x[i] and
   0 <= v[i] < C</li>

Returns a tuple of:

- loss: Scalar giving the loss
- dx: Gradient of the loss with respect to x

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N = x.shape[0]
correct_class_scores = x[np.arange(N), y]
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margins = np.maximum(0, x - correct_class_scores[:, np.newaxis] + 1.0)
margins[np.arange(N), y] = 0
loss = np.sum(margins) / N
num_pos = np.sum(margins > 0, axis=1)
dx = np.zeros_like(x)
dx[margins > 0] = 1
dx[np.arange(N), y] -= num_pos
dx /= N
return loss, dx
```

def softmax\_loss(x, y): """ Computes the loss and gradient for softmax classification.

### Inputs:

- x: Input data, of shape (N, C) where x[i, j] is the score for the jth class for the ith input.
- y: Vector of labels, of shape (N,) where y[i] is the label for x[i] and 0 <= y[i] < C</li>

### Returns a tuple of:

- loss: Scalar giving the loss
- dx: Gradient of the loss with respect to x

probs = np.exp(x - np.max(x, axis=1, keepdims=True)) probs /= np.sum(probs, axis=1, keepdims=True) N = x.shape[0] loss = -np.sum(np.log(probs[np.arange(N), y])) / N dx = probs.copy() dx[np.arange(N), y] -= 1 dx /= N return loss, dx