

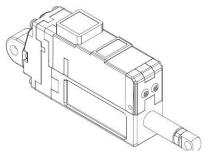
L12-12PT-3

L12-20PT-3 L12-40PT-3

L12-64PT-3 L12-100PT-3

Features / 주요 특장점

- Micro size / 마이크로 사이즈
- Precise position control/ 정밀위치제어
- Strong force comparing to the size / 체적대비 강한 힘
- Built-in Drive Circuitry / 드라이브 회로 내장
- TTL/PWM communication / TTL/PWM 통신 지원
- Parameter programmable on the Manager software / 매니 져 소프트웨어를 통한 파라메터셋팅가능



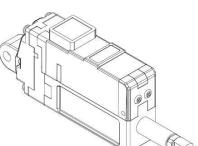
Common Specifications / 공통 사양

- Stroke / 스트로크: 27mm (Extendable to 30mm on Manager software) (프로그램통해 30mm까지 확대 가능)
- Force / 정격 힘: 12N~100N according to gear ratio(See appendix.) / 기어비에 따라 12~100N(별첨 참조)
- Micro controller: 32 bit ARM Core, 4960 resolution (A/D converter)
- Input Voltage / 입력전압: 12.0V(Rated/정격),7V~13V(Operating)
- Motor Type / Watt: coreless DC Motor / 26W
- Recommended duty cycle / 권장 듀티사이클: under 50% (50% 이하)
- Current consumption / 소모전류 :30mA(Idle), 380mA(Rated), 2.3A(Stall)
- Position accuracy / 위치정밀도: less than 0.05mm(50um)
- Position sensor / 위치센서: 10kΩ linearity potentiometer
- Size / Weight /크기,무게: 57.4(L)x29.9(W)x15(H)mm / 49~52g (to be varied according to gear ratio)
- Communication/ 통신:TTL/ PWM(Automatic signal recognition / 신호자동인식)
 - → TTL Level voltage: 3.3~5.0V
 - → PWM Pulse range: 900us(retracted/최대수축)-1500us(center)-2100us(extended/최대확장)
 - → TTL Communication range / TTL 통신 통달 거리 :Max. 4m
- Operating Temperatures / 동작온도 :-10℃ ~ 60℃
- Ingress protection / 방수방진: IP-54
- Mechanical Backlash / 기구백래쉬: 0.03mm(30um)
- Audible Noise / 가청소음: Approx. 50db at 1m
- Gear ratio / 기어비 :10:1(12PT,20PT,40PT) /30:1(64PT) /50:1(100PT)
- Gear type / 기어타입:Engineering plastic gears(12PT,20PT,40PT)

4metal & 2engineering plastic gears(64PT,100PT)

(Alluminum and stainless steel combination)

- Rod type / Rod 타입: Stainless steel rod / 스테인레스 스틸
- Standard Accessory / 표준악세서리 :1xHinge base, 1x Hinge, 1xHinge shaft, 1xRod end tip, 2x M3 NUT, 3 x M2.5x6 screws, 1x Molex wire harness (200mm)
- Wire Harness: Molex(50-37-5033) to Molex(50-37-5033)/ 200mm / 0.08x60(22AWG)



Parameter	Symbol	Limit \	Limit Values / 한계값			Remarks
	심 볼	Min. Typ.	Max.	단위	비고	
(TIO						
/oltages / 전압	111	7.0	12.0	12.0	11/	-
Supply voltage/ 공급전압	V	7.0	12.0	13.0	V	TT 11
Logic input voltage / 로직인가전압	V	2.0	3.3	5.5	V	TTL Level
Currents / 전류						
Maximum peak Current /	1	2.1	2.2	2.3	Α	StallCurrent
최대 피크 전류						
No Load Current / 무부하전류	1	180	200	220	mA	No Load
Full LoadCurrent /	I	420	450	480	mA	12N,20N,40N
정격 부하 전류	I	280	300	320	mA	64N,100N
Idle Current	I	25	30	35	mA	
						•
「emperatures / 온도						
StorageTemp. / 보관온도	Т	-20	-	70	${\mathfrak C}$	
Operating Temp. / 동작온도	Т	-10	-	60	${\mathfrak C}$	
Strokes / 스트로크			T-			
MIN Position / 최소수축위치	L	-	3.8	-	mm	
MAX Position / 최대확장위치	L	-	30.8	-	mm	
Stroke length/ 스트로크	L	-	27.0	_	mm	
PWM (27mm stroke)	T		T	T	1	
MIN Pulse (0mm)	sec	-	900	-	us	Period is
Neutral Pulse (13.5mm)	sec	-	1440	-	us	4ms over /
MAX Pulse (27mm)	sec	-	1980	-	us	4ms이상 주기
PWM (30mm stroke)						
	500	_	900	-	us	Period is
MIN Pulse (0mm)	sec			1	1	
MIN Pulse (0mm) Neutral Pulse (15mm)	sec	-	1500	-	us	4ms over /

^{*}매니저 소프트웨어와 IR-USB01 PC USB interface를 통해 30mm로 확장 가능

No Load Speed / 무부하 속도

Maximum Speed at 12.0V	S	119	120.0	121	mm/s	L12-12PT-3
최대 속도 at 12.0V	S	79.5	80.0	80.5	mm/s	L12-20PT-3
	S	27.5	28.0	28.5	mm/s	L12-40PT-3
	S	10.0	10.5	11.0	mm/s	L12-64PT-3
	S	7.3	7.7	8.1	mm/s	L12-100PT-3

Force / 힘

Parameter	Symbol	Limit Values / 한계값			Unit	Remarks
	심 볼	Min.	Тур.	Max.	단위	비고
Rated Force / 정격 힘		T=	T		Τ	T
Rated Force at 12.0V 정격 힘 at 12.0V	F	11.5	12.0	12.5	N	L12-12PT-3
		2.58	2.69	2.81	lbf	
		1.17	1.22	1.27	kgf	
	F	19.0	20.0	21.0	N	L12-20PT-3
		4.27	4.49	4.72	lbf	
		1.93	2.04	2.14	kgf	
	F	38.0	40.0	42.0	N	L12-40PT-3
		8.54	8.99	9.44	lbf	
		3.87	4.07	4.28	kgf	
	F	61.0	64.0	67.0	N	L12-64PT-3
		13.71	14.38	15.06	lbf	
		6.22	6.52	6.83	kgf	
	F	95.0	100.0	105.0	N	L12-100PT-3
		21.35	22.48	23.60	lbf	
		9.68	10.19	10.70	kgf	
	1		•	I.	* 1 kgf = 9	9.8N , 1lbf = 4.45N
Self Lock Force / 셀프-락 :	포스					
	Fl	_	N/A	_	N	L12-12PT-3
	FI	_	7.0	-	N	L12-20PT-3
	Fl	-	40.0	-	N	L12-40PT-3

- Self-lock force: The force which actuator maintains its position by mechanical friction without motor power.
- · 셀프-락포스 :액츄에이터가 전원을 통한 모터의 힘 없이, 기구마찰력만으로 위치를 고수할 수 있는 힘

Z Axis Force / Z축 포스

Fz	-	N/A	-	N	L12-12PT-3
Fz	-	7.0	-	N	L12-20PT-3
Fz	-	30.0	-	N	L12-40PT-3
Fz	-	48.0	-	N	L12-64PT-3
Fz	-	75.0	-	N	L12-100PT-3

64.0

100.0

L12-64PT-3

L12-100PT-3

Ν

· Z axis force: Actuator force when it is installed vertically.

FI

• Z축 포스 : 수직 중력방향 설치 시 액츄에이터의힘

Figure 1.
Figure1-1. CURRENT VS FORCE (12 VDC)

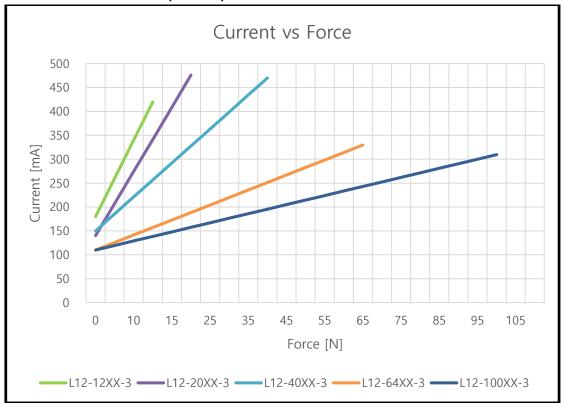


Figure 1-2 . SPEED VS LOAD (12 VDC)

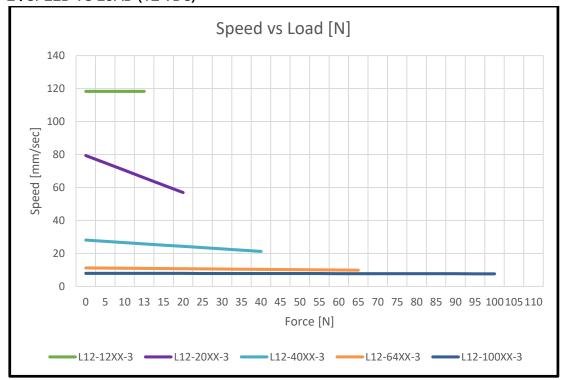


Figure 2. Figure 2-1 . Voltage /Speed[m/s] (12V / 27mm Products)

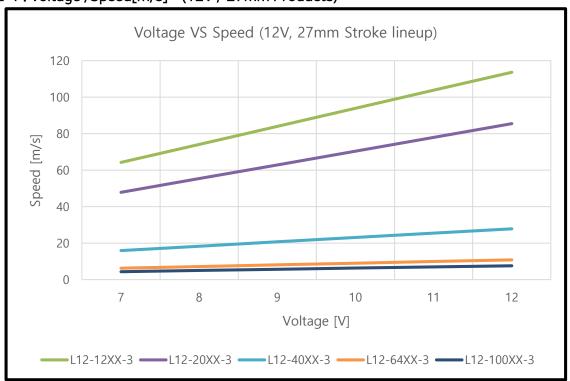
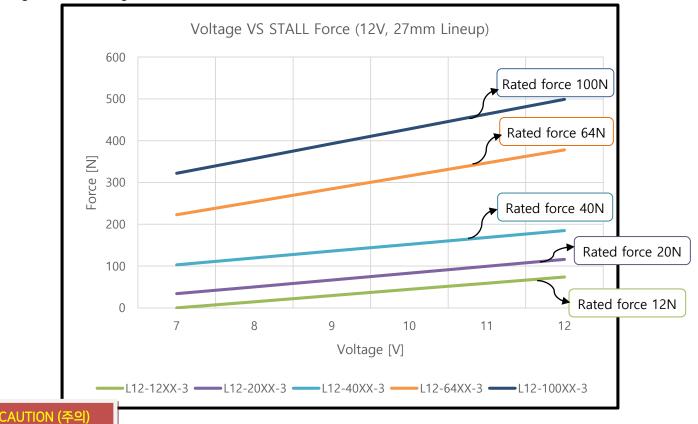


Figure 2-2. Voltage / Stall Force [N] (12V / 27mm Products)



- Stall force는 참고용으로, 제품의 파손을 방지하기 위해 실제 application에서의 사용시에는 Rated force에 맞추어 사용하여 주십시오.
 - Stall force is for reference only. In order to prevent damage of the product, please use it according to the Rated force when using in actual application.

Figure 3. Figure 3-1 Speed/Motor Operating Rate[mm/sec]

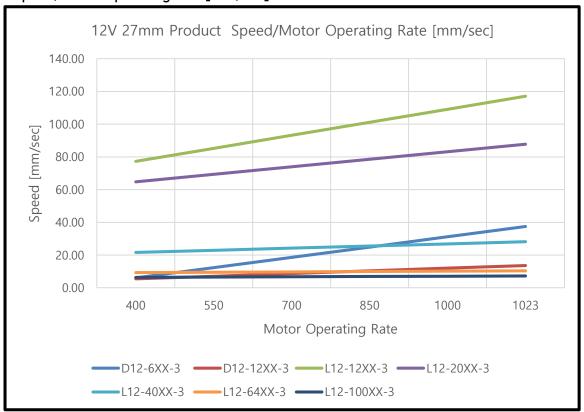


Figure 3-2 Speed/Motor Operating Rate (30:1, 50:1 gear) [mm/sec]

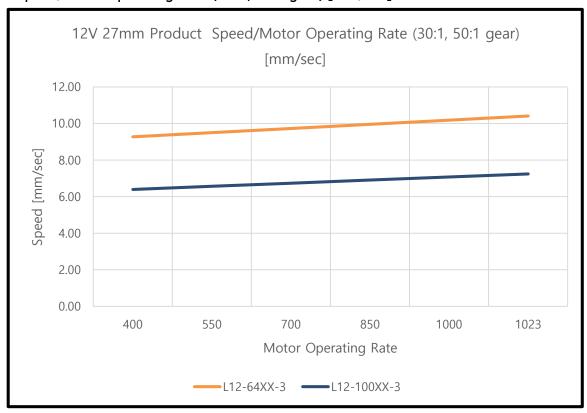


Figure 4.PIN Map

PIN NUMBER(COLOR)	PIN NAME	FUNCTION
1(WHITE)	DATA	통신
2(RED)	VCC	전원 +
3(BLACK)	GND	전원 -

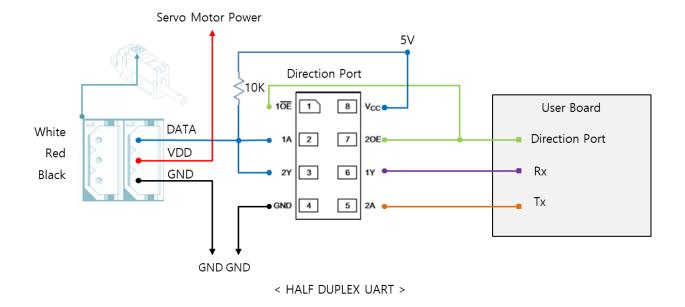


Figure 5. Dimension

