

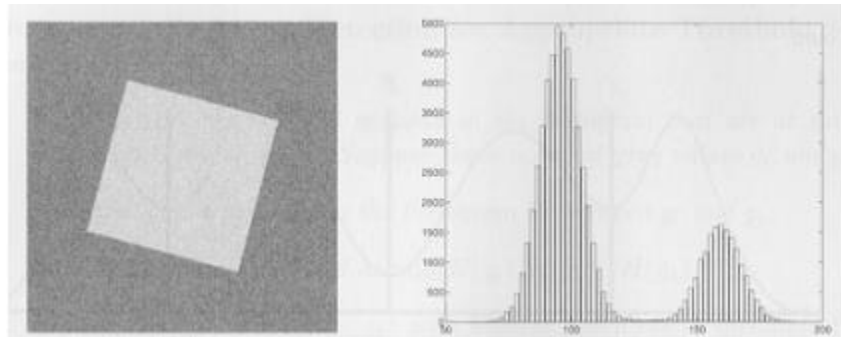
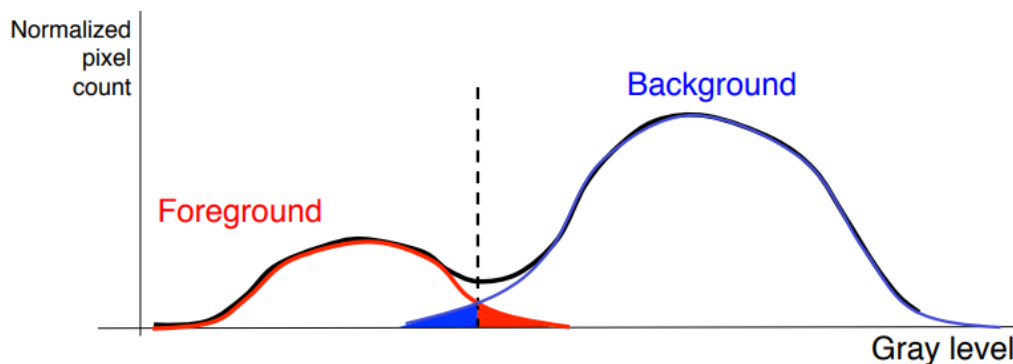
## LAB 6: SEGMENTATION

### I. Single thresholding:

- The simplest approach to segment an image is using thresholding.

$$\text{If } f(x, y) > T \text{ then } f(x, y) = 0 \text{ else } f(x, y) = 255$$

- Choosing the threshold using the image histogram



- Example:

```
% Load test image
img = imread('peter.png');

% Threshold
level = 105;
bwImg = img < level;
holeImg = img .* uint8(bwImg);

% Show images
subplot(1, 3, 1), imshow(img); title('Original Image');
subplot(1, 3, 2), imshow(bwImg); title('Thresholded Image');
```

## Image Processing

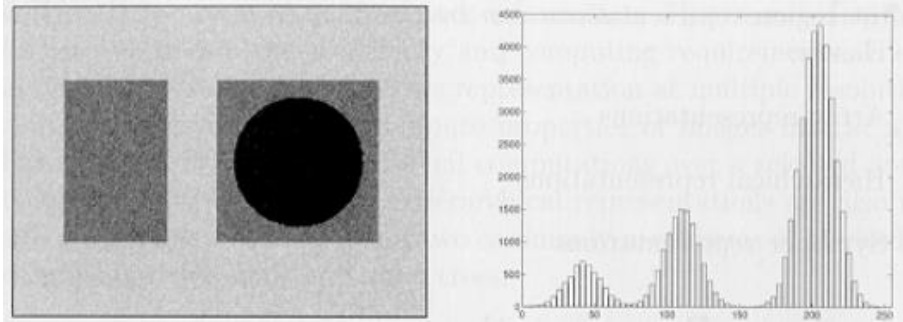
```
subplot(1, 3, 3), imshow(holeImg); title('Binary Map \times  
Original');
```

```
% Save images
```

```
imwrite(bwImg, 'Graylevel_Thresholding_thresholded.png');
```

```
imwrite(holeImg, 'Graylevel_Thresholding_blend.png');
```

## II. Multilevel thresholding

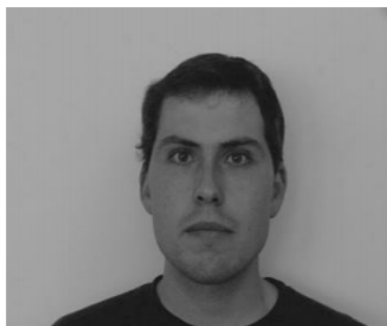


If  $f(x, y) < T_1$  then  $f(x, y) = 255$

else if  $T_1 \leq f(x, y) < T_2$  then  $f(x, y) = 128$

else  $f(x, y) = 0$

**Exercise:** Thực hiện phân đoạn cho các image sau:



Original image  
 $Peter\ f[x, y]$



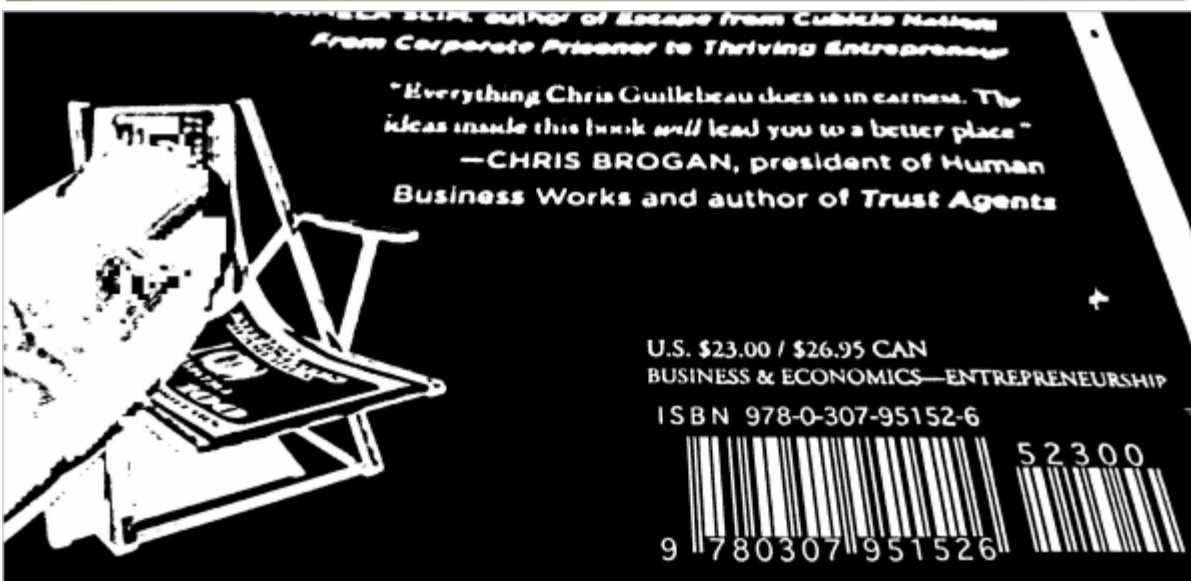
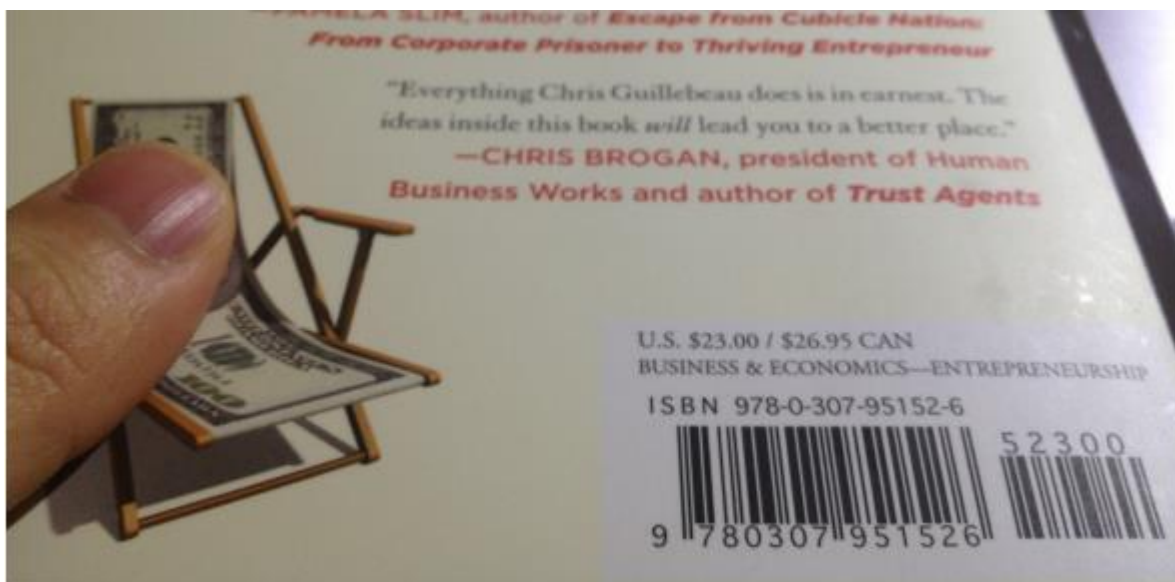
Thresholded  
 $Peter\ m[x, y]$

How can holes be filled?

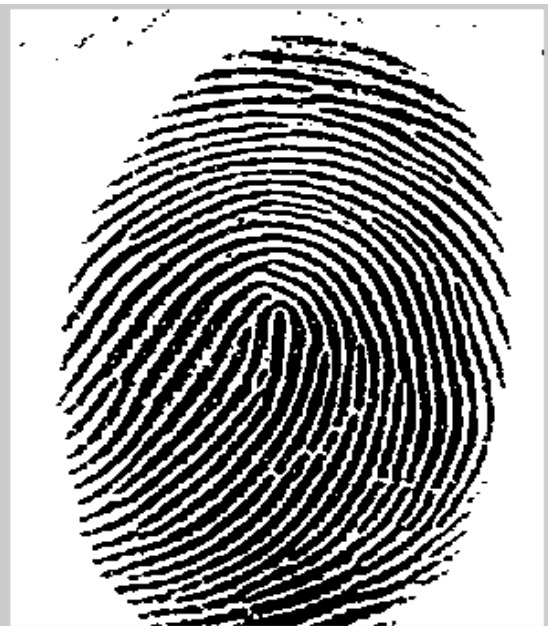


$f[x, y] \cdot m[x, y]$









ponents or broken connection paths. There is no point in going past the level of detail required to identify those components.

Segmentation of nontrivial images is one of the most difficult tasks in image processing. Segmentation accuracy determines the effectiveness of computerized analysis procedures. For this reason, considerable effort can be taken to improve the probability of rugged segmentation. In applications such as industrial inspection applications, at least some degree of automation in the environment is possible at times. The experienced image processing designer invariably pays considerable attention to such



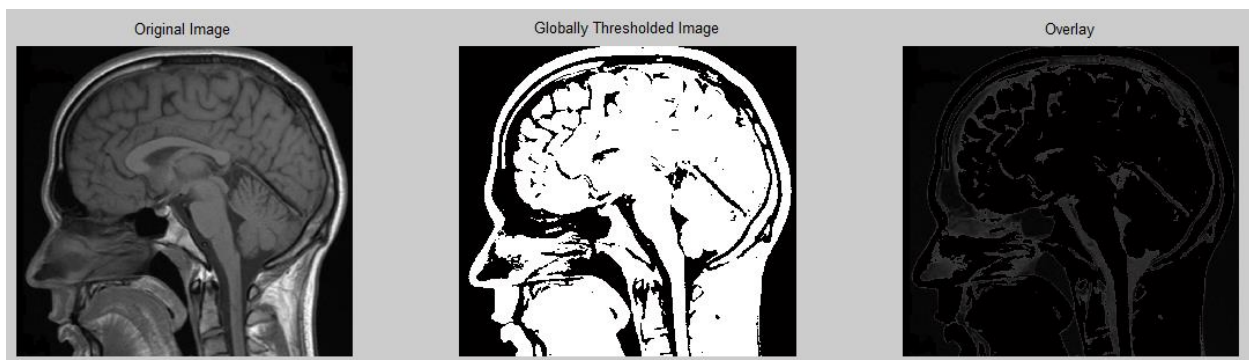
### III. Automatic Thresholding Algorithm - Otsu:

```
% Load test image
img = imread('brain.jpg');

% Perform Otsu thresholding
level = graythresh(img); % chooses Otsu threshold
% otsuThresh = round(level * 255)
bwImg = im2bw(img, level);

% Show images
subplot(1, 3, 1), imshow(img); title('Original Image');
subplot(1, 3, 2), imshow(bwImg); title('Globally Thresholded Image');
subplot(1, 3, 3), imshow((1-bwImg) .* im2double(img)); title('Overlay');

% Save images
imwrite(bwImg, 'Global_Thresholding_bw.png');
saveas(gcf, 'Global_Thresholding_hist.png')
```



- **Thuật toán:**

Thuật toán sau được sử dụng để chọn ngưỡng,  $T$  tự động:

1. Select an initial estimate for  $T$ . A possible initial value is the midpoint between the minimum and maximum intensity values in the image.
2. Segment the image using  $T$ . This will produce two groups of pixels:
  - $G1$  consisting of all pixels with intensity values  $> T$
  - $G2$ , consisting of pixels with values  $< T$ .
3. Compute the average intensity values  $x1$  and  $x2$  for the pixels in regions  $G1$  and  $G2$ .
4. Compute a new threshold value:  $T=1/2(x1+x2)$
5. Repeat steps 2 through 4 until the difference in  $T$  in successive iterations is smaller than a predefined parameter  $T0$ .

Hiện thực hàm **gray\_thresh** như sau:

```
T=0.5*(double(min(f(:)))+double(max(f(:))));
done = false;
while ~done
    g = f >= T;
    Tnext = 0.5*(mean(f(g))+mean(f(~g)));
    done = abs (T-Tnext) < 0.5;
    T = Tnext;
end
```

**Exercise:** So sánh kết quả của hàm **gray\_thresh** và **graythresh** thực hiện trên các ảnh của phần I.

## II. HOLE FILLING AS DUAL TO SMALL REGION REMOVAL

```
% Load test image
img = imread('peter.png');

% Binarize image
level = 105;
bwImg = img < level;
filledBwImg = imfill(bwImg, 'holes');

% Show images
subplot(1, 2, 1), imshow(bwImg); title('Original Binary Image');
subplot(1, 2, 2), imshow(filledBwImg); title('Filled Binary Image');

% Save images
imwrite(bwImg, 'Hole_Filling_bw.png');
imwrite(filledBwImg, 'Hole_Filling_filled.png');
```



**Exercise:** Áp dụng hàm `imfill` cho các ảnh nhị phân có được ở phần I, II trên.