```
import numpy as np
import scipy.io

import matplotlib
import matplotlib.pyplot as plt
import matplotlib.gridspec as gridspec
from IPython import display

%matplotlib inline

import importlib
#importLib.reload(driftDiffusionSimulator)
import driftDiffusionSimulator_periodicBC
importlib.reload(driftDiffusionSimulator_periodicBC)
from driftDiffusionSimulator_periodicBC import driftDiffusionSimulator
```

```
In [3]: def getLengths(Xpos,Ypos):
    Lpos = np.sqrt((Xpos[1:]-Xpos[:-1])**2+(Ypos[1:]-Ypos[:-1])**2)
    return Lpos

def getR_EndToEnd(Xpos,Ypos,L):
    Lpos = np.insert(np.cumsum(np.sqrt((Xpos[1:]-Xpos[:-1])**2+(Ypos[1:]-Ypos
[:-1])**2)),0,0)
    Xout = np.interp(L,Lpos,Xpos)
    Yout = np.interp(L,Lpos,Ypos)
    Rout = np.sqrt(Xout**2+Yout**2)
    return Rout

def p_rGauss(r,t,D):
    return r/4/D/t*np.exp(-r**2/4/D/t)
```

# Analysis of sim. files

#### Load in files and initialize functions

```
In [4]:
        Emins = list(np.ones(20)*.9)
        Emins+= list(np.ones(20)*.9)
        Emins+= list(np.ones(20)*.9)
        Emins+= list(np.ones(20)*.9)
        Emins+= list(np.ones(20)*.95)
        Emins+= list(np.ones(20)*.975)
        Emins+= list(np.ones(20)*.9875)
        Emins+= list(np.ones(20)*.99375)
        N particles = list(np.ones(20)*100)
        N particles+= list(np.ones(20)*200)
        N particles+= list(np.ones(20)*400)
        N particles+= list(np.ones(100)*800)
        N particles = [int(x) for x in N particles]
        mainPath = "E:\Arthur's Stanford Simulations\Hydrodynamics\Periodic Boundary C
        onditions"
        fnames = []
        for i in range(20):
            fnames.append(mainPath+'/periodicBC 0p9E 100N/periodicBC 0p9E 100N '+'%03d
         ' % i +'.npz')
        for i in range(20):
            fnames.append(mainPath+'/periodicBC 0p9E 200N/periodicBC 0p9E 200N '+'%03d
         ' % i +'.npz')
        for i in range(20):
            fnames.append(mainPath+'/periodicBC 0p9E 400N/periodicBC 0p9E 400N '+'%03d
         ' % i +'.npz')
        for i in range(20):
            fnames.append(mainPath+'/periodicBC 0p9E 800N/periodicBC 0p9E 800N '+'%03d
         ' % i +'.npz')
        for i in range(20):
            fnames.append(mainPath+'/periodicBC 0p95E 800N/periodicBC 0p95E 800N '+'%0
        3d' % i +'.npz')
        for i in range(20):
            fnames.append(mainPath+'/periodicBC_0p975E_800N/periodicBC_0p975E_800N_'+'
        %03d' % i +'.npz')
        for i in range(20):
            fnames.append(mainPath+'/periodicBC 0p9875E 800N/periodicBC 0p9875E 800N '
        +'%03d' % i +'.npz')
        for i in range(20):
            fnames.append(mainPath+'/periodicBC_0p99375E_800N/periodicBC_0p99375E_800N
         '+'%03d' % i +'.npz')
        rDiffs = []
        XposMultSims = []
        YposMultSims = []
        Lfinals = np.zeros(len(fnames))
        Lees = np.zeros(len(fnames))
        diffusionConsts = np.zeros(len(fnames))
        N pathlength = 10
        sample_diff_const = np.arange(0,5,.01)
```

```
In [5]: for i,fname in enumerate(fnames):
            if N particles[i] == 400:
                mat = np.load(fname)
                Lfinal = mat['timeCount']/100.
                Lfinals[i] = Lfinal
                traces = mat['traces']
                vX = mat['vX']
                vY = mat['vY']
                 rDiff = np.zeros(N_particles[i])
                XposInSim = []
                 YposInSim = []
                for j in range(N particles[i]):
                     Nscatter = round(len(traces[j]))
                     Xpos = np.zeros(Nscatter+2)
                     Ypos = np.zeros(Nscatter+2)
                     Ltot = 0
                     for k in range(Nscatter):
                         P=np.array(traces[j][k][0:2])
                         L=traces[j][k][2]
                         E=np.sqrt(np.sum(P**2))
                         vhat=P/E
                         Xpos[k+1]=Xpos[k]+vhat[0]*L
                         Ypos[k+1]=Ypos[k]+vhat[1]*L
                         Ltot+=L
                     Xpos[-1] = Xpos[-2] + vX[j]*(Lfinal-Ltot)
                     Ypos[-1] = Ypos[-2] + vY[j]*(Lfinal-Ltot)
                     #XposInSim and YposInSim are the sets of coordinates
                     XposInSim.append(Xpos)
                     YposInSim.append(Ypos)
                     rDiff[j] = np.sqrt(Xpos[-1]**2+Ypos[-1]**2)
                 rDiffs.append(rDiff)
                XposMultSims.append(XposInSim)
                 YposMultSims.append(YposInSim)
                 RvsL = np.zeros((N particles[i],N pathlength))
                 total travel = np.floor(Lfinals[i])
                 pathlengths = np.linspace(total travel/2.,total travel,N pathlength+1)
        [1:]
                for k in range(N_particles[i]):
                     for j,path len in enumerate(pathlengths):
                         RvsL[k,j] = getR EndToEnd(XposInSim[k],YposInSim[k],path len)
                mu tests = sample diff const
                 logProb = np.zeros(np.shape(mu tests))
                #np.log(p_rGauss(rDiff,mu))
                 for k,mu in enumerate(mu tests):
                     #logProbs = np.log(p rGauss(rDiff,mu))
```

```
logProb[k]=0
            for j,path_len in enumerate(pathlengths):
                logProb[k]+=np.sum(np.log(p_rGauss(RvsL[:,j],path_len,mu)))
        logProb[np.where(np.isnan(logProb))]=-np.inf
        logProb-=np.max(logProb)
        plt.plot(mu tests,np.exp(logProb))
        plt.show()
        display.clear_output(wait=True);
        diffusionConsts[i] = mu tests[np.argmax(logProb)]
       L = np.array([])
        for k in range(N particles[i]):
            L = np.append(L,getLengths(XposInSim[k],YposInSim[k]))
        Lees[i] = np.mean(np.array(L))
       fname save = fname[:-4]+' analysis.npz'
        np.savez(fname_save, RvsL = RvsL, Lee = Lees[i], diffusionConst = diff
usionConsts[i],
                mu tests = mu tests, prob = np.exp(logProb),total travel = tot
al_travel,pathlengths = pathlengths,
                N particles = N particles)
```

```
FileNotFoundError
                                          Traceback (most recent call last)
<ipython-input-5-8783a4c42ed1> in <module>()
      2
            if N particles[i] == 400:
                mat = np.load(fname)
---> 4
                Lfinal = mat['timeCount']/100.
                Lfinals[i] = Lfinal
C:\ProgramData\Anaconda3\lib\site-packages\numpy\lib\npyio.py in load(file, m
map_mode, allow_pickle, fix_imports, encoding)
            own fid = False
    370
            if isinstance(file, basestring):
    371
--> 372
                fid = open(file, "rb")
    373
                own fid = True
    374
            elif is pathlib path(file):
FileNotFoundError: [Errno 2] No such file or directory: "E:\\Arthur's Stanfor
d Simulations\\Hydrodynamics\\Periodic Boundary Conditions/periodicBC 0p9E 40
0N/periodicBC_0p9E_400N_000.npz"
```

#### Calculate diffusion const

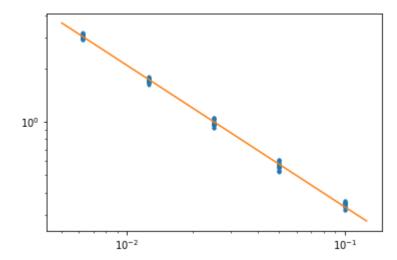
### Emperical fit of diffusion const. vs. temperature

```
In [142]: diffusionConsts = np.zeros(np.shape(fnames))
  Lees = np.zeros(np.shape(fnames))

for i,fname in enumerate(fnames):
    mat = np.load(fname[:-4]+'_analysis.npz')
    diffusionConsts[i] = mat['diffusionConst']
    Lees[i] = mat['Lee']
```

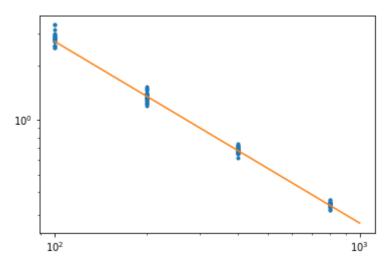
```
In [196]: r1 = [int(i) for i,x in enumerate(N_particles) if x == 800]
Emins1 = [Emins[i] for i in r1]
diffusionConsts1 = [diffusionConsts[i] for i in r1]

plt.loglog(1-np.array(Emins1),np.array(diffusionConsts1),'.')
x = np.logspace(-2.3,-.9,1000)
plt.plot(x,42*x**-.8/800)
plt.show()k
```



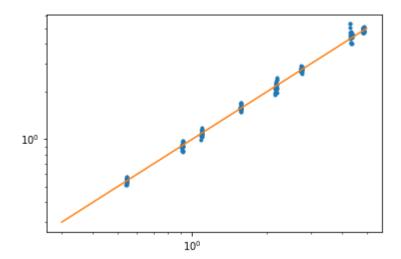
```
In [191]: r1 = [int(i) for i,x in enumerate(Emins) if x == 0.9]
N_particles1 = [N_particles[i] for i in r1]
diffusionConsts1 = [diffusionConsts[i] for i in r1]

plt.loglog(N_particles1,np.array(diffusionConsts1),'.')
x = np.logspace(2,3,1000)
plt.plot(x,270*x**-1)
plt.show()
```



# $\ell_{ee}$ vs. $D/v_f$

```
In [192]: plt.loglog(Lees,np.array(diffusionConsts)*1.6,'.')
   plt.plot([.3,5],[.3,5])
   plt.show()
```



Based on these data, our current understanding is that the diffusion constant goes as:

$$D=rac{42}{N(\Delta E)^{0.8}}$$

Where N is the number of particles (in a  $3\mu m$  square and  $\Delta E$  is the effective temperature  $(1-E_{min})$ . This yields:

$$D=rac{4.7}{n(\Delta E)^{0.8}}$$

where n is the particle density in  $\mu m^{-2}$ . We also find that the  $\ell_{ee} \approx 1.6 D/v_f$ . So, this means that the mean free path goes as:

$$\ell_{ee}=rac{7.5}{n(\Delta E)^{0.8}}$$

in units of microns.

The variables n and  $\Delta E$  are input parameters to the simulation, however in a physical system, these are linked. Both are approximately proportional to temperature. So, we could select them independently, or tie them together based on a simulation condition. Alternatively, we could try to mimic the behavior for a particular quasiparticle density at a particular temperature. For now, we'll go with the former.

Based on particular simulation conditions (N=800 and  $\Delta E=0.1$ ) we get  $\ell_{ee}=0.53~\mu m$ . This scattering length is achieved at a density of  $10^{12}~cm^{-2}$  at roughly 120~K.

So, we could assert that N = 6.67T and  $\Delta E = 8.33 imes 10^{-4} T$ .

One variable not yet tested is the "overlap radius". Based on scaling arguments, I believe the scattering length is inversely related to this variable, as long as the system is still "dilute" in the sense that the thickness in the direction of travel is small compared to  $\ell_{ee}$ . In other words, the volume traversed by a given particle in a given time is proportional to its width, and not its thickness.

Currently, we have an "overlap radius" as  $r_{over}=0.05~\mu m$ . This means the scattering length should actually go as:

$$\ell_{ee} = rac{150}{nr_{over}(\Delta E)^{0.8}}$$

In [198]: 150/(800/42.1)/.05/(.1)\*\*.8

Out[198]: 996.1239075981051

## Theoretical mean free path for bulk scattering

```
In [260]: p_scatter = 0.001
N_test = int(1E8)

A = np.random.rand(N_test)

scatters = np.array([i for i,x in enumerate(A) if x<p_scatter])

print(np.mean(scatters[1:]-scatters[:-1]))</pre>
```

996.4385475417024

This shows that the mean free path with a probability  $p_{scatter}$  of scattering per timestep is:

$$\ell_{scatter} \ = \ rac{v_f \Delta \ t}{p_{scatter}}$$

where  $\Delta$  t is the timestep and  $v_f$  is the Fermi velocity.

Given that the timestep we traditionally use is 0.01 and  $v_f=1$ , This means  $\ell_{scatter}=1~\mu m$  corresponds to  $p_{scatter}=0.01$ 

```
In [ ]:
```