

# CS 577 - Graphs

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TopHat Section 001 Join Code: 275653



# GRAPHS

## Graphs

A graph  $G$  is a pair  $G = (V, E)$ , where  $V$  is a set of vertices/nodes and  $E$  is a set of edges/arcs connecting a pair of vertices. That is,  $E \subseteq V \times V$ .

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- Directed Acyclic Graph (DAG)
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- Forests

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## Definition

- A connected graph without cycles.
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## Properties of a tree $T$

- 1 If  $|V| \geq 2$ , (unrooted)  $T$  has at least 2 leaves.
- 2 For all nodes  $u$  and  $v$ , there exists one path between them in  $T$ .
- 3  $|V| = |E| + 1$  for  $|V| \geq 1$ .

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## TopHat 1

Is  $P_{10}$  a tree?

# WHAT CAN BE REPRESENTED BY GRAPHS?

- Transportation networks
- Communication networks
- Information networks
- Social networks
- Dependency networks

# CONNECTIVITY

# GRAPH CONNECTIVITY

## Problem: $s$ - $t$ connectivity

Given a graph  $G = (V, E)$ , and the vertices  $s$  and  $t$ , is there a path from  $s$  to  $t$  in  $G$ ?



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## Connected Components

Let  $H \subset G$  be a subgraph of  $G$ . If  $H$  is connected and there are no edges between  $H$  and  $G \setminus H$ . Then,  $H$  is a connected component of  $G$ .

# GRAPH EXPLORATION/TRAVERSAL

## Determining $s$ - $t$ Connectivity

Requires an algorithm that explores or traverses the graph by considering the edges of the graph to find all nodes connected to  $s$ .

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**Algorithm:** Generalized Exploration

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$R = \{s\}$

**while**  $\exists$  an edge  $(u, v)$  where  $u \in R$  and  $v \notin R$  **do**

    | Add  $v$  to  $R$

**end**

**return**  $R$

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# GRAPH ENCODINGS AND IMPLEMENTATION

## Representations

- **Adjacency matrix:**  $|V|$  by  $|V|$  matrix with a 1 if nodes are adjacent.
- **Adjacency list:** For each node, list adjacent nodes.
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Find  $(u, v)$

List of neighbours

Adjacency matrix

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**while**  $\exists$  an edge  $(u, v)$  where  $u \in R$  and  $v \notin R$  **do**

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**end**

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**TopHat 2**

Which graph representation would be best suited?

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## Rough Running Time

- At step  $i$ :  $O(|E_i| \cdot (\log |R_i| + \log |R_i|) + \log |R_i|)$ , assuming  $R$  is a self-balancing BST.

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What is this algorithm lacking?

## BREADTH-FIRST SEARCH (BFS)

### Process

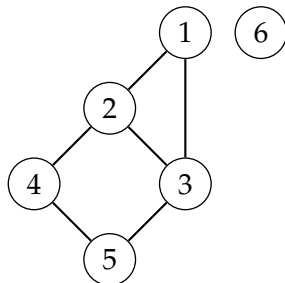
- Also referred to as graph flooding.
- Let  $L_i$  be all the neighbours at a distance  $i$  from  $s$ .
- Starting from  $i = 0$ , visit all the nodes (not previously visited) in  $L_i$ . Increment  $i$  and repeat.

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TopHat 3: This process engenders a BFS tree. Start at 1 and draw such a tree for the following.





# DEPTH-FIRST SEARCH (DFS)

## Recursive Process starting at $s$

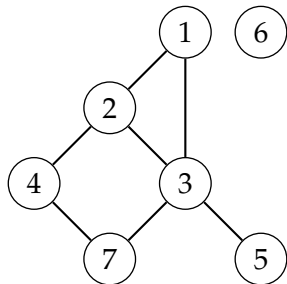
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TopHat 4: This process engenders a DFS tree. Start at 1 and draw such a tree for the following.



# IMPLEMENTING BFS AND DFS

## TopHat 5

Which graph representation would be best for BFS and DFS?

# IMPLEMENTING BFS AND DFS

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Which graph representation would be best for BFS and DFS?  
Why?

# IMPLEMENTING BFS AND DFS

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## DFS Recursive Process starting at $s$

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# IMPLEMENTING BFS AND DFS

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**Algorithm:** BFS( $S$ )

---

Initialize  $v[u] = \text{false}$  for all  
nodes

Set  $v[s] = \text{true}$

Add  $s$  to tree  $T$

Add  $s$  to queue  $Q$

**while**  $Q$  is not empty **do**

$u = \text{dequeue}(Q)$

**foreach** neighbour  $r$  of  $u$

**do**

**if**  $\neg v[r]$  **then**

                Add  $(u, r)$  to  $T$

                Set  $v[r] = \text{true}$

                Enqueue  $v$

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**return**  $T$

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**Algorithm: DFS(S)**

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Initialize  $v[u] = \text{false}$  and

$p[u] = \text{null}$  for all nodes

Push  $s$  to stack  $S$

**while**  $S$  is not empty **do**

$u = \text{pop}(S)$

**if**  $!v[u]$  **then**

        Add  $(p[u], u)$  to  $T$

        Set  $v[u] = \text{true}$

**foreach** neighbour  $r$   
            of  $u$  **do**

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Runtime:  $O(|E| + |V|)$

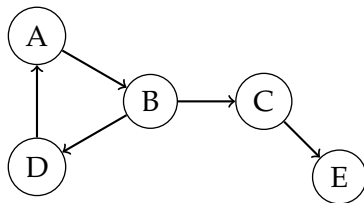


# STRONGLY CONNECTED COMPONENTS

# DIRECTED GRAPHS

## Directed Graph

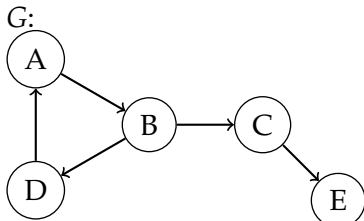
- In a directed graph, the edges have a direction and are often called *arcs*.
- I.e.  $(u, v)$  is different than  $(v, u)$ .



# STRONG CONNECTIVITY

## Mutually Reachable

- A pair of nodes  $(u, v)$  in a directed graph are *mutually reachable* if there is a path from  $u$  to  $v$ , and from  $v$  to  $u$ .
- Note: This property is transitive: if  $(u, v)$  and  $(v, w)$  are both mutually reachable, then  $u, w$  is mutually reachable.



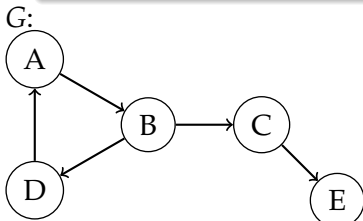
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## Strongly Connected

A directed graph is *strongly connected* if, for every pair of nodes  $(u, v)$ ,  $u$  and  $v$  are mutually reachable.



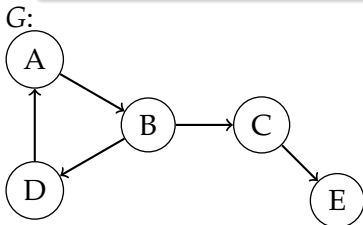
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## Testing for Mutually Reachable

How might we check if  $(u, v)$  is mutually reachable?



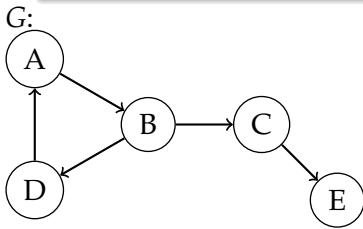
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Check if DFS/BFS from  $u$  reach  $v$ , and DFS/BFS from  $v$  reaches  $u$ .



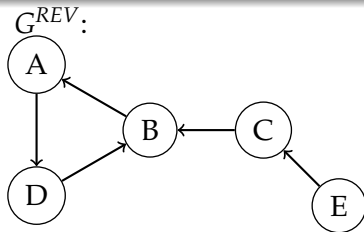
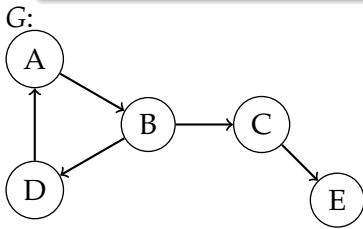
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Check if DFS/BFS from  $u$  in  $G$  reaches  $v$ , and DFS/BFS from  $u$  in  $G^{REV}$  reaches  $v$ .



# STRONGLY CONNECTED COMPONENTS

## Strongly Connected Component (SCC)

A maximal strongly connected subgraph.

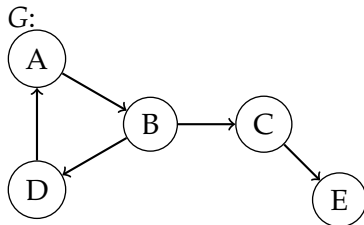


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TopHat 6: How many SCC in  $G$ ?

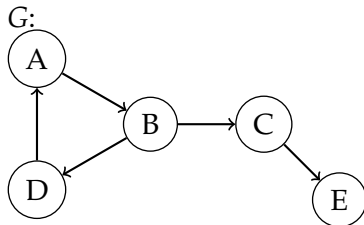


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- ❸ While  $S$  is not empty:
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  - ❷ If  $v$  is unvisited, run DFS on  $G^{REV}$  from  $v$  to extract an SCC.

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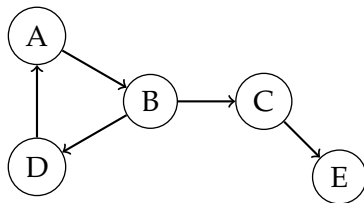
TopHat 7: What is the time complexity of Kosaraju's Algorithm?  $O(|E| + |V|)$

# TOPOLOGICAL ORDERING

# DIRECTED GRAPHS

## Directed Graph

- In a directed graph, the edges have a direction and are often called *arcs*.
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# DIRECTED GRAPHS

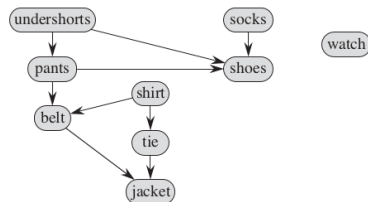
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## Directed Acyclic Graph (DAG)

- A directed graph with no directed cycles.
- Precedence relationships.

Getting dressed:



# TOPOLOGICAL ORDERING

## Definition

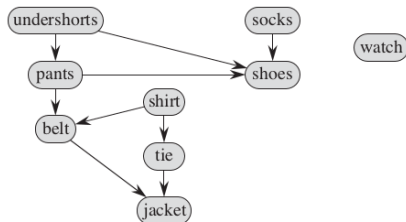
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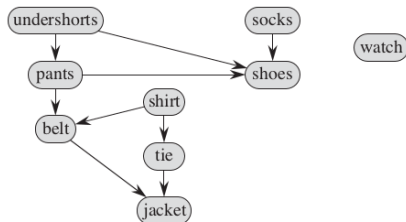


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- After visiting  $|V| + 1$  nodes, by the Pigeon Hole principle, we have visited some node  $w$  twice  $\implies G$  contains a cycle.

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- Prove it by induction.
- Does the inductive proof imply an algorithm to build a topological ordering from a DAG? If so, what is it?

# APPENDIX

# REFERENCES

# IMAGE SOURCES I



<https://brand.wisc.edu/web/logos/>