

COMP 551 Kaggle Competition: Classification of Modified MNIST*

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Abstract—This paper provides the report for the Kaggle Competition (assignment 4) of COMP 551 using the provided Modified MNIST dataset. The dataset includes a set of 8-bit grayscale images that include 2 or 3 digits of different sizes that are rotated and scaled from the classic MNIST dataset. The goal is to design Machine Learning algorithms that identify the biggest digit in each image. Several algorithms have been used in the report. First, the logistic regression and linear SVM are used which lead to relatively lower precisions. Second, a forward neural network completely developed by the team was implemented. Finally, a convoluted neural network was trained and tested on the preprocessed dataset which showed the best performance.

I. INTRODUCTION

The MNIST database [1] is a set of handwritten images that is popular for training and testing of Machine Learning algorithms [2].

II. PREPROCESSING

The provided images in the Modified MNIST include 3 numbers that are rotated and scaled from the MNIST dataset and are written on random backgrounds. Some samples of the train dataset with their associated outputs are shown in Figure 1.

The format for the images is 8-bit grayscale image, thus each pixel has 256 shades of gray represented by numbers 0 (black) to 255 (white) as shown in Figure 2.

Before, the data are used for training, the following preprocessing steps are used.

A. Thresholding

Since the numbers in the dataset match the 255 shade, a simple idea for preprocessing is to use *image thresholding*. The idea of thresholding is to compare the pixel values of the input image f with some threshold T and make a binary decision for the output binary image g as below

$$g(i, j) = \begin{cases} 1 & f(i, j) \geq T \\ 0 & f(i, j) < T \end{cases} \quad (1)$$

for all i, j where i, j represent the coordinates of the ij^{th} pixel [3].

The output of this filter is shown in Figure 3

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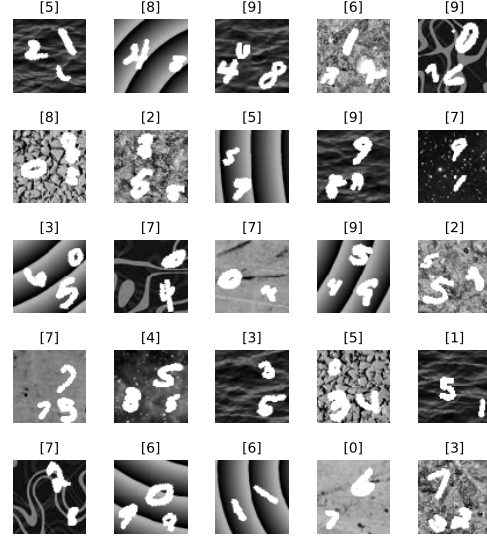


Fig. 1. 25 Random Samples of the original train dataset

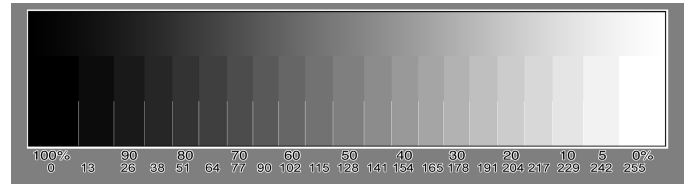


Fig. 2. 8-bit Grayscale Shades of Gray

B. Median Filter

As can be seen in Figure 3, there are some small white areas in some of the images that can act as undesirable noise. Median filtering is one method to remove the noise from the images and smoothen the edges. The main disadvantage of median filter is the damaging of thin lines and sharp corners [3].

The idea of median filter is to choose the median of the pixel values in a neighborhood of the given coordinate. These neighborhoods could be defined as disk, square, or any other shape of interest.

The output of the median filter using a disk of radius 1 applied on thresholded images are shown in Figure 4.

C. Biggest Number

The output of this filter on thresholded images are shown in Figure 5.

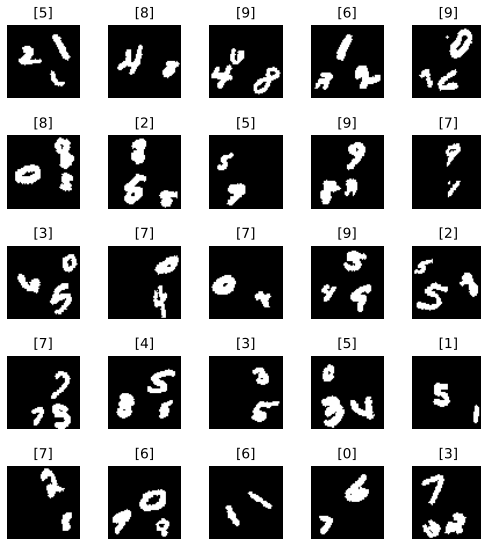


Fig. 3. Output of thresholding on images from Figure 1

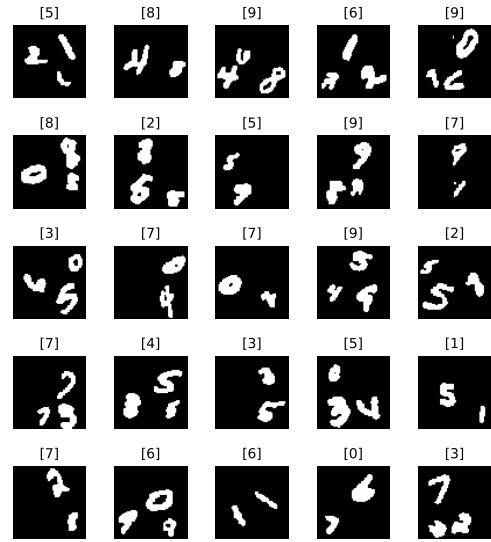


Fig. 4. Output of median filter on thresholded images from Figure 3

III. CONCLUSIONS

APPENDIX

Appendixes should appear before the acknowledgment.

STATEMENT OF CONTRIBUTIONS

Yignan implemented the convolutional neural network. Vincent implemented the fully-connected feedforward neural network and the linear classifiers. Hamed implemented preprocessing and tested the linear classifiers. Yignan and Vincent implemented the algorithms on Amazon AWS. All

three contributed to the report.

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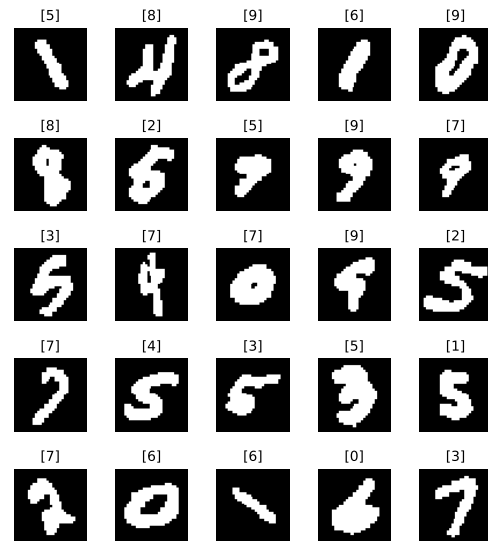


Fig. 5. Output of biggest number filter on thresholded images from Figure 3