Maple Precision – Software Developer Intern

February 2020 - Present

- Developing 3D geospatial topography maps and models through quantized meshing of databases of lidar point clouds, satellite imaging, and maps, using PostgreSQL
- Building a mobile application version of the Maple Precision Web App, using Objective-C on Swift for IOS development and Java on Android Studio for Android OS development
- Utilizing GraphQL, React, Git, Bash, MongoDB, Amazon Web Services, Django, Java, Python

Reach – Internet Access Through SMS

September 2019 - January 2020

- Built an automated program using Javascript with Node.js that allows users to access internet features through text messaging, including: Directions, Weather, News, Wikipedia Articles, Unit and Currency Conversion. Used Google Maps and News API and Fixer API
- Used Google Firebase to host my program on cloud servers to process and compute user request and Twilio to automatically send and receive SMS

Axel - Autonomous Chess Playing Robot

September 2019 - December 2019

- Programmed event-driven embedded software for chess robot using RobotC along with mechanical movement, HMI, and integrated Stockfish Artificial Intelligence API using C++
- Designed with AutoCAD, SolidWorks and built robot using a combination of 3D printing, Laser cutting, Lego EV3 and Tetrix robotics components, MDF, and aluminum extrusions

Stamp – Microphone Audio Amplifier

October 2019 – November 2019

Designed and built a functional audio amplifier using KiCad. Integrated both inverting and difference opamps in circuit design to amplify the audio input signal for a microphone

Inception – Mechanical Timeclock

December 2018 – March 2019

Modelled and Constructed a mechanical timeclock using AutoCAD, SolidWorks, 3D printing, Maya, and hobby materials. Achieving top 3 out of over 70 teams at UBC Physics Olympics

Train μ – Machine Learning Sports Trainer

February 2020 - Present

- Building and training a machine learning model to analyze sports footage and help users improve athletic form, achieving top 3 out of over 100 teams at Hack the Valley 4
- Using TensorFlow and Openpos for machine learning and dataset. Using Python, Google Cloud Servers, and Docker for backend, and Javascript, HTML, and React for frontend

Waterloop - SpaceX Hyperloop Team

September 2019 - Present

Linear Induction Motor Team Lead

- Leading a team of over 25 students prototyping, designing, and building a linear induction motor, creating a new method of transportation to compete in the Hyperloop Competition
- Coordinating and working with software and electrical team to integrate electro-mechanical subsystems and create a full-sized functioning linear induction motor (LIM)
- Programming, configuring, and wiring embedded systems with Magnetometer, Hall Effect sensor, Digital Temperature sensor, and Accelerometer to collect data through trial runs
- Creating computer simulations of the LIM using ANSYS to apply Maxwell's equations

UWAFT - General Motors EcoCAR Team

September 2019 - Present

Autonomous Vehicle Software Team Member

- Utilizing C++ in ROS (Robot Operating System) to program path finding algorithms and to perform sensor diagnostics and sensor fusion to compete in the EcoCAR Competition
- Using MATLAB and Simulink to create simulations in order to test vehicle's autonomous capabilities and performance across possible scenarios and edge cases
- Processing CAN bus (Controller Area Network) data using C++ data structures and algorithms in ROS to detect and counteract failures within microcontrollers, devices, and communication between control units in the vehicle system



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Website Link §: bit.ly/hank-website

1st Place

Waterloo Engineering Competition (Senior Design 2019)

1st Place

Kwantlen Senior Science Challenge 2019

1st Place

Vancouver Math Olympiad 2018

Top 3/70 Teams

UBC Physics Olympics Timeclock 2019

Top 3/100 Teams

Hack the Valley 4 Hackathon 2020

B1 DELF Certificate

French Professional Working Proficiency

Software:

Java, Python, Javascript, C, C#, C++ Google Cloud Servers, TensorFlow, Git, ROS, Twilio, NodeJS, SQL, Keras, Django, Docker, Spark, PyTorch, React, Linux

Hardware:

CAN bus, Arduino, PLC, IGBT, KiCAD inverting and difference opamps, HMI, linear induction motor, electromagnetism high and low pass filters, microcontrollers

Mechanical:

SolidWorks, AutoCAD, Matlab, Simulink, Inventor, Maya, 3D printing and design, laser cutting and engraving, CNC mill, lathe, drill press, band saw, disk sander

Agile and Waterfall Development Process, Microsoft Word, Excel, Publisher, and PowerPoint, Adobe Photoshop, Fireworks, and After Effects

Education

University of Waterloo Mechatronics Engineering, Honours.

Sept. 2019 - Present

Intended Minors: Artificial Intelligence and Robotics