

$$1a) \operatorname{curl} \vec{F} = \nabla \times \vec{F}$$

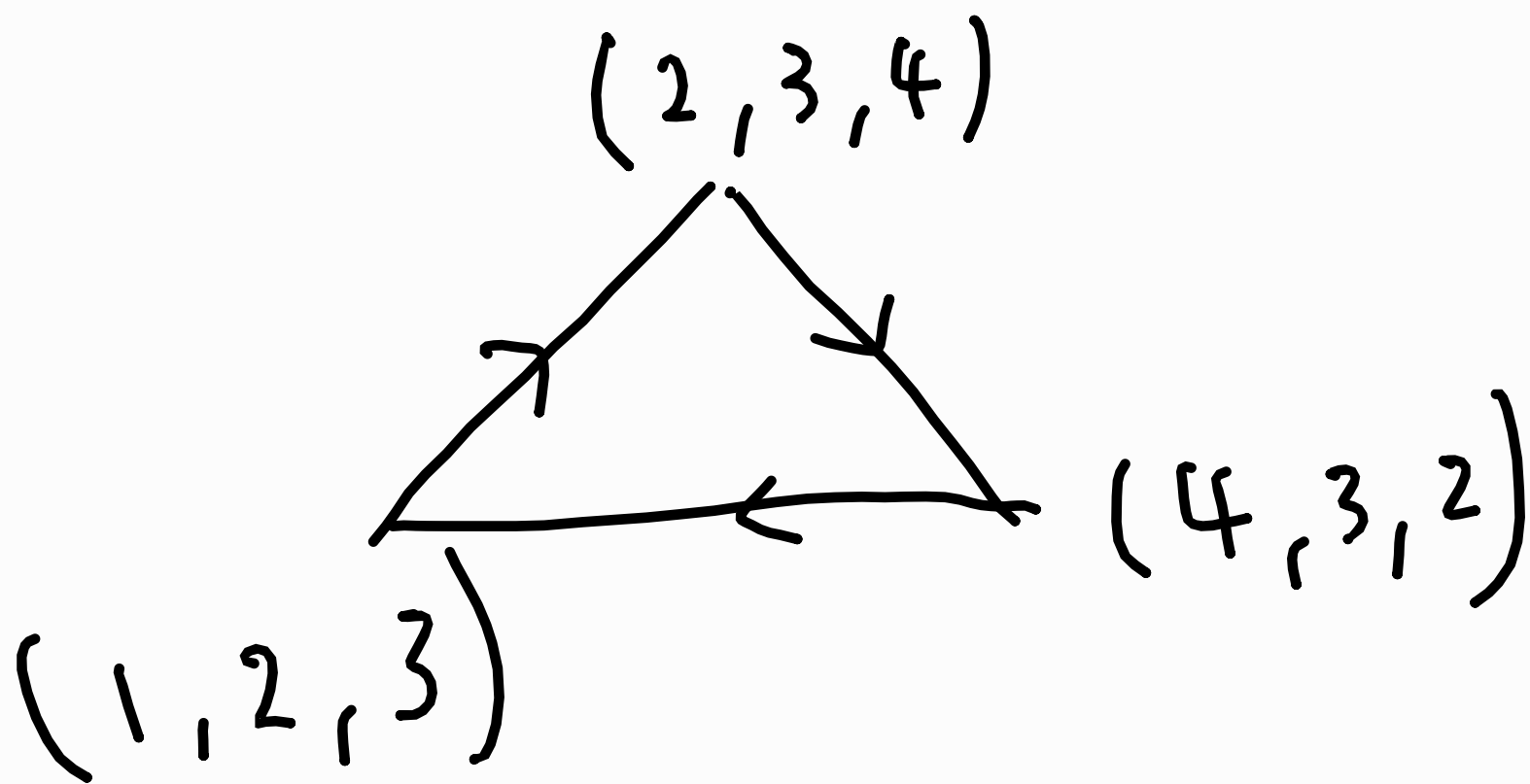
$$= \left( \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \times (2z, -x, -2y)$$

~~$$\begin{array}{ccccc}
 \vec{i} & \vec{j} & \vec{k} & \vec{i} & \vec{j} \\
 \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} & \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\
 2z & -x & -2y & 2z & -x
 \end{array}$$~~

$$= -2\vec{i} + 2\vec{j} - \vec{k} - 0 - 0 - 0$$

$$= (-2, 2, -1)$$

16)



Let  $S$  be the oriented surface whose oriented boundary is the triangle  $C$ . By Stokes's Theorem, the circulation of  $\vec{F}$  along  $C$  is:

$$\oint_C P dx + Q dy + R dz = \iint_S \text{curl } \vec{F} \cdot \vec{u} dS$$

Finding the normal vector of the surface,

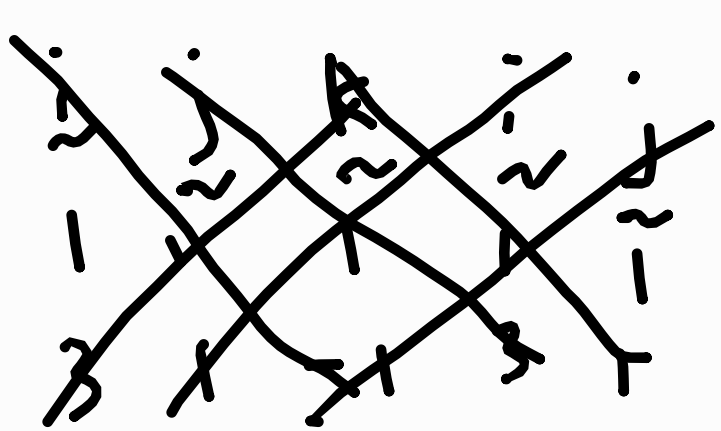
$$\vec{n} = \vec{P_1 P_2} \times \vec{P_1 P_3}$$

$$= \left( \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \right) \times \left( \begin{bmatrix} 4 \\ 3 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \right)$$

$$= (1, 1, 1) \times (3, 1, -1)$$

$$= -\vec{i} + 3\vec{j} + \vec{k} - 3\vec{k} - \vec{i} + \vec{j}$$

$$= (-2, 4, -2)$$



$$1b) \underline{u} = \frac{\underline{n}}{\|\underline{n}\|}$$

$$\text{Area of } S = \frac{1}{2} ab \sin C$$

$$= \frac{1}{2} \|\vec{P_1 P_2} \times \vec{P_1 P_3}\|$$

$$= \frac{1}{2} \|\underline{n}\|$$

$$\iint_S \text{curl } F \cdot \underline{u} \, dS = \iint_S (-2, 2, -1) \cdot \frac{(-2, 4, -2)}{\|\underline{n}\|} \, dS$$

$$= \frac{14}{\|\underline{n}\|} \iint_S dS$$

$$= \frac{14}{\cancel{\|\underline{n}\|}} \times \frac{1}{2} \cancel{\|\underline{n}\|}$$

$$= 7$$

$$2a) \det A = \begin{vmatrix} 0 & 1 & a \\ 0 & a & 1 \\ 1 & 1 & 1 \end{vmatrix} \begin{vmatrix} 0 & 1 \\ 0 & a \\ 1 & 1 \end{vmatrix}$$

$$= 1 - a^2$$

b)  $A$  is invertible if and only if  $\det A \neq 0$   
 When  $A$  is invertible, i.e.  $a \neq \pm 1$ ,  $A\vec{x} = \vec{b}$   
 will have exactly one solution.

For  $a = 1$ ,

$$\begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$\therefore$  there are infinitely many solutions when  
 $a = 1$ .

For  $a = -1$ ,

$$\begin{bmatrix} 0 & 1 & -1 & -1 \\ 0 & -1 & 1 & -1 \\ 1 & 1 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & -2 \end{bmatrix}$$

$\therefore$  the system is inconsistent, which means there  
 are no solutions when  $a = -1$ .

3a)  $\text{span } S$  is defined to be the set:

$$\text{span } S = \left\{ k_1 \underline{x}_1 + k_2 \underline{x}_2 + \dots + k_r \underline{x}_r : k_1, k_2, \dots, k_r \in \mathbb{R} \right\}$$

3b) Let  $\underline{x} = c_1 \underline{x}_1 + c_2 \underline{x}_2 + \dots + c_r \underline{x}_r$ ,  $c_1, c_2, \dots, c_r \in \mathbb{R}$

as  $\underline{x} \in \text{span } S$

For  $\underline{u} \in \text{span}(S \cup \{\underline{x}\})$

$\Downarrow$

$$\underline{u} = k_1 \underline{x}_1 + k_2 \underline{x}_2 + \dots + k_r \underline{x}_r + k \underline{x}, k_1, k_2, \dots, k_r, k \in \mathbb{R}$$

$$= k_1 \underline{x}_1 + \dots + k_r \underline{x}_r + k(c_1 \underline{x}_1 + c_2 \underline{x}_2 + \dots + c_r \underline{x}_r)$$

$$= (k_1 + kc_1) \underline{x}_1 + (k_2 + kc_2) \underline{x}_2 + \dots + (k_r + kc_r) \underline{x}_r$$

$\Downarrow$

$$\underline{u} \in \text{span } S$$

For  $\underline{u} \in \text{span } S$

$\Downarrow$

$$\underline{u} = k_1 \underline{x}_1 + k_2 \underline{x}_2 + \dots + k_r \underline{x}_r + 0 \underline{x}, k_1, k_2, \dots, k_r, k \in \mathbb{R}$$

$\Downarrow$

$$\underline{u} \in \text{span}(S \cup \{\underline{x}\}) \therefore \text{span } S = \text{span}(S \cup \{\underline{x}\})$$