

(a) Binary links: 1, 4, 7, 8

Ternary links: 2, 3, 5, 6

Quaternary links: None

Degrees of freedom:

$$\begin{aligned} \text{Dof} &= 3(n_L - 1) - 2n_J - n_H \\ &= 3(8-1) - 2(10) \\ &= 1 \end{aligned}$$

b)  $\frac{\mu N_C}{2} + \frac{\mu N_B}{2} = \frac{\mu N_{\text{outer}}}{2} + \frac{\mu N_A}{2}$

$$\begin{aligned} N_C &= N_{\text{outer}} + N_A - N_B \\ &= 64 + 36 - 60 \\ &= 40 \end{aligned}$$

i)  $N_J + N_H = N_K + N_L$

$$\begin{aligned} N_L &= N_J + N_H - N_K \\ &= 54 + 24 - 40 \\ &= 38 \end{aligned}$$

$$\text{Ibiii)} \quad n_A = n_B$$

$$\frac{n_C}{n_B} = \left( -\frac{N_B}{N_C} \right)$$

$$n_C = \left( -\frac{60}{40} \right) (-100) \quad \therefore n_B = n_A$$

$$= 150 \text{ rpm CCW} = n_5 = n_{\text{arm-1}}$$

$$\text{iv)} \quad \frac{n_0}{n_A} = \left( -\frac{36}{64} \right)$$

$$n_0 = \left( -\frac{36}{64} \right) (-100)$$

$$= 56.25$$

$$= 56.25 \text{ rpm CW}$$

$$\text{v)} \quad n_G = n_{\text{arm-2}}$$

$$\frac{n_G - n_{\text{arm-1}}}{n_0 - n_{\text{arm-1}}} = \left( \frac{N_{\text{inner}}}{N_E} \right) \left( \frac{N_F}{N_G} \right)$$

$$\frac{n_G - 150}{56.25 - 150} = \frac{56}{18} \left( \frac{26}{66} \right)$$

$$n_G = \frac{12275}{396}$$

$$\approx 31 \text{ rpm CCW}$$

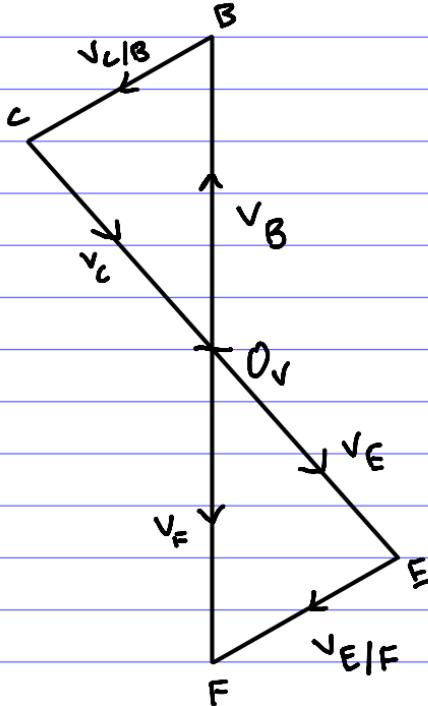
$$lbvi) \frac{n_L - n_{arm-2}}{n_J - n_{arm-2}} = \left(-\frac{N_J}{N_H}\right) \left(-\frac{N_K}{N_L}\right)$$

$$n_L - \frac{12275}{396} = \left(-\frac{54}{24}\right) \left(-\frac{40}{38}\right) \left(150 - \frac{12275}{396}\right)$$

$$\begin{aligned} n_L &= 312.8455609 \\ &\approx 313 \text{ rpm CCW} \end{aligned}$$

$$\therefore n_M = n_L = 313 \text{ rpm CCW}$$

2ai)



$$\begin{aligned} v_B &= r\omega \\ &= 30(2) \\ &= 60 \text{ mm s}^{-1} \end{aligned}$$

$$v_C = v_B + v_{C/B}$$

$$v_{C/B} = 27 \text{ mm s}^{-1}$$

$$\omega_3 = \frac{27}{44.70}$$

$$\begin{aligned} &= \frac{0.0}{149} \\ &\approx 0.604 \text{ rad s}^{-1} \end{aligned}$$

$$v_C = 54 \text{ mm s}^{-1}$$

$$\omega_4 = \frac{54}{45}$$

$$= 1.2 \text{ rad s}^{-1}$$

$$2a) V_E = V_F + V_{E/F}$$

$$V_{E/F} = 35 \text{ mms}^{-1}$$

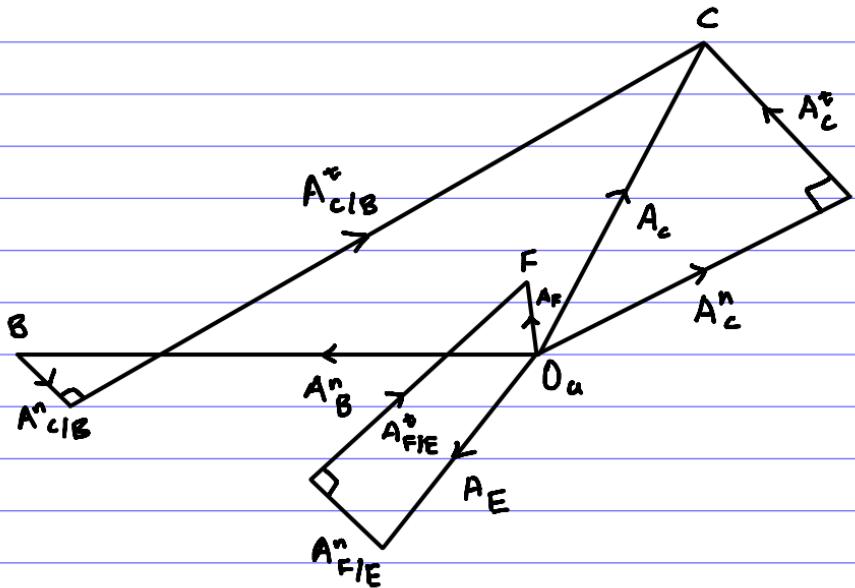
$$\omega_5 = \frac{35}{42.3}$$

$$= \frac{350}{423}$$

$$\approx 0.827 \text{ rad s}^{-1}$$

$$V_F = 72 \text{ mms}^{-1}$$

2aiii)



$$2a:i) \quad \begin{array}{cccccc} \checkmark & \times\checkmark & \checkmark\checkmark & \checkmark\checkmark & \times\checkmark \\ A_c^n + A_c^t = A_B^n + A_{c1B}^n + A_{c1B}^t \\ \text{---} & \text{---} & \text{---} & \text{---} & \text{---} \\ \omega_4^2 CD & \omega_2^2 AB & \omega_3^2 BC \\ = 64.8 & = 120 & = 16.31 \end{array}$$

$$A_F = A_E + A_{F/E}^n + A_{F/E}^t$$



$$\omega_5^2 EF$$

$$= 28.93$$

$$A_{cB}^t = 143 \times 1.2 = 171.6 \text{ mm s}^{-2}$$

$$\alpha_3 = \frac{A_{cB}^t}{BC} = 3.84 \text{ rad s}^{-2}$$

$$A_C^t = 31 \times 1.2 = 37.2 \text{ mm s}^{-2}$$

$$\alpha_4 = \frac{A_C^t}{CD} = 0.83 \text{ rad s}^{-1}$$

$$A_{F/E}^n = 71 \times 1.2 = 85.2 \text{ mm s}^{-2}$$

$$\alpha_5 = \frac{A_{F/E}^n}{EF} = 2.01 \text{ rad s}^{-1}$$

$$A_F = 15 \times 1.2 = 18 \text{ mm s}^{-2}$$

2bi) Crank rocker  $\rightarrow$  shortest link next to fixed link

$O_2A$  must be  $L_{\min}$ .

$$L_{\max} + O_2A \leq L_a + L_b$$

$$O_2A \leq 98 + 58 - 100$$

$$0 \leq O_2A \leq 56$$

ii) Non-Grashof linkage:  $L_{\max} + L_{\min} > L_a + L_b$

① If  $O_6D$  is  $L_{\max}$ :

$$O_6D + 33 > 42 + 58$$

$$O_6D > 67$$

For 4-bar linkage:

$$L_{\max} \leq L_{\min} + L_a + L_b$$

$$O_6D \leq 33 + 42 + 58$$

$$O_6D \leq 133$$

$$67 < O_6D \leq 133$$

② If  $O_6D$  is  $L_{\min}$ :

$$58 + O_6D > 42 + 33$$

$$O_6D > 17$$

$$17 < O_6D \leq 133$$

③ If  $O_6D$  is  $L_a$  or  $L_b$ :

$$58 + 33 > O_6D + 42$$

$$O_6D < 49$$

$$0 < O_6D < 49$$

$$\therefore 0 < O_6D < 49$$

$$3a) \omega = 2 \text{ rad s}^{-1}$$

$30^\circ < \theta < 130^\circ$  (cycloidal motion rise):

$$s = L \left( \frac{\theta - \theta_i}{\pi} - \frac{1}{2\pi} \sin \frac{2\pi(\theta - \theta_i)}{\beta} \right)$$

$$= 40 \left( \frac{\theta - 30}{100} - \frac{1}{2\pi} \sin 360 \left( \frac{\theta - 30}{100} \right) \right)$$

$$s(\theta = 90^\circ) = 40 \left( \frac{90 - 30}{100} - \frac{1}{2\pi} \sin 360 \left( \frac{90 - 30}{100} \right) \right)$$

$$\approx 27.74 \text{ mm}$$

b)  $180^\circ < \theta < 360^\circ$  (simple harmonic motion return):

$$s = \frac{L}{2} \left( 1 - \cos \left( \frac{\pi \theta}{\beta} \right) \right)$$

$$= \frac{40}{2} \left( 1 - \cos \left( \frac{\pi \theta}{20} \right) \right)$$

$$= 20(1 - \cos \theta)$$

$$\dot{s} = 20 \dot{\theta} \sin \theta$$

$$\dot{s}(\theta = 200^\circ) = 20 \dot{\theta} \sin(\theta_e - \theta)$$

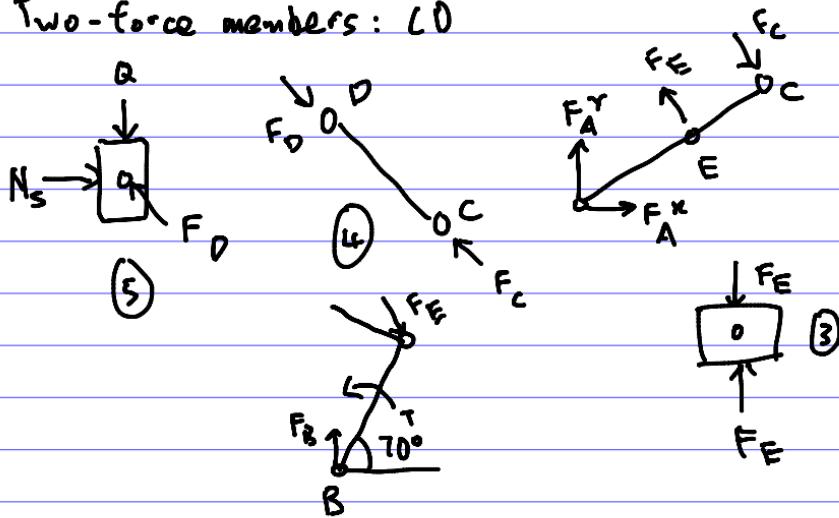
$$= 20(2) \sin(360 - 200^\circ)$$

$$= 13.68 \text{ mm s}^{-1}$$

$$3c) \ddot{s} = 20\ddot{\theta}\sin\theta + 20\dot{\theta}^2\cos\theta \\ = 20\omega^2\sin\theta \quad \because \dot{\theta} = 0, \ddot{\theta} = \omega$$

$$\ddot{s}(\theta = 330^\circ) = 20(2)^2\cos(360 - 330) \\ = 20(4)\cos(30) \\ = 69.28 \text{ mm s}^{-2}$$

4f) Two-force members: (D)



For link S:

$$\sum F_y = 0:$$

$$F_D^Y = Q$$

$$F_D Y = 20N$$

$$F_D \cos 30^\circ = 20$$

$$F_D = 23.09401077$$

$$\approx 23.09N$$

$$F_C = F_D$$

$$\approx 23.09N$$

4ii) For link 2:

$$\sum M = 0$$

$$F_E(105) = F_c(200)$$
$$F_E = \frac{23.09(200)}{105}$$

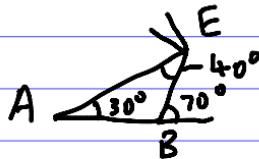
$$= 43.98859194$$
$$\approx 43.99 N$$

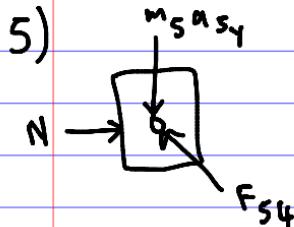
For link 1:

$$\sum M = 0$$

$$F_E \cos 40^\circ (56) = T$$

$$T = 1887.04419$$
$$\approx 1887.04 N$$





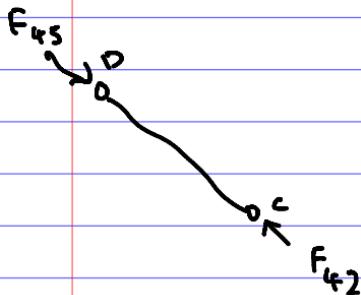
$$\sum F_y = 0:$$

$$m_5 a_{5y} - F_{54} \cos 30^\circ = 0$$

$$F_{54} = \frac{m_5 a_{5y}}{\cos 30^\circ}$$

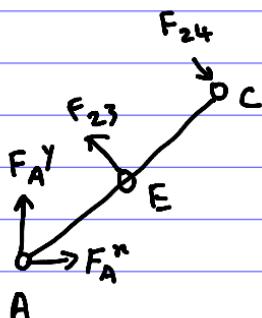
$$\sum F_x = 0:$$

$$N = F_{54} \sin 30^\circ$$



$$\sum F = 0:$$

$$F_{43} = F_{45}$$



$$\sum F_y = 0:$$

$$F_A^Y + F_{23} \cos 30^\circ - F_{24} \cos 30^\circ = 0$$

$$F_A^Y = F_{24} \cos 30^\circ - F_{23} \cos 30^\circ$$

$$\sum F_x = 0:$$

$$F_A^X - F_{23} \sin 30^\circ + F_{24} \sin 30^\circ = 0$$

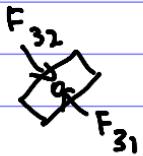
$$F_A^X = F_{23} \sin 30^\circ - F_{24} \sin 30^\circ$$

$$\sum M = 0:$$

$$F_{24} A C = F_{23} \times A E$$

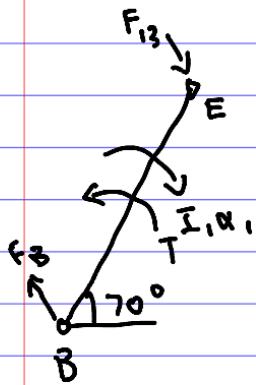
$$F_{23} = \frac{0.46 F_{24}}{0.24} = 1.1917 F_{24}$$

5)



$$\sum F = 0$$

$$F_{32} = F_{31}$$



$$\sum M = 0:$$

$$T - I_{1, \alpha_1} - F_{13} \cos 40^\circ (BE) = 0$$

$$T = 0.1 F_3 + I_{1, \alpha_1}$$

$$\sum F = 0$$

$$F_B = F_{13}$$