

$$\begin{aligned}
 \text{1a) } \operatorname{div} \vec{F} &= \nabla \cdot \vec{F} \\
 &= \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) \cdot \left(\frac{x}{\sqrt{x^2+y^2}}, \frac{y}{\sqrt{x^2+y^2}}, 0 \right) \\
 &= \frac{\sqrt{x^2+y^2} - x \left(\frac{2x}{2\sqrt{x^2+y^2}} \right)}{x^2+y^2} + \\
 &\quad \frac{\sqrt{x^2+y^2} - y \left(\frac{2y}{2\sqrt{x^2+y^2}} \right)}{x^2+y^2} \\
 &= \frac{x^2+y^2 - \cancel{x^2} \mp \cancel{x^2+y^2} - y^2}{(x^2+y^2)^{\frac{3}{2}}} \\
 &= \frac{1}{\sqrt{x^2+y^2}}
 \end{aligned}$$

(b) A horizontal surface will have unit normal vector $(0, 0, 1)$ or $(0, 0, -1)$.

In either case, we get $\vec{F} \cdot \vec{U} = 0$ and the flux through S is

$$\iint_S \vec{F} \cdot \vec{U} dS = 0$$

(c) A unit normal vector on the surface S_1 is $\vec{U} = (x, y, 0)$

\therefore the flux through S_1 is

$$\iint_{S_1} \vec{F} \cdot \vec{U} dS = \iint_{S_1} \left(\frac{x}{\sqrt{x^2+y^2}}, \frac{y}{\sqrt{x^2+y^2}}, 0 \right) \cdot (x, y, 0) dS$$

$$= \iint_{S_1} \frac{x^2 + y^2}{\sqrt{x^2 + y^2}} dS$$

$$= \iint_{S_1} \sqrt{x^2 + y^2} dS$$

$$= \iint_{S_1} 1 dS \quad \because x^2 + y^2 = 1$$

$$= \text{Area of } S_1 \quad \because \sqrt{x^2 + y^2} = \sqrt{1} = 1$$

$$= 2\pi(2) = 4\pi$$

(d) Let S_3 be the horizontal surface

$$1 \leq \sqrt{x^2 + y^2} \leq 2, \quad z = 1,$$

with unit normal $\underline{u} = (0, 0, 1)$

and S_4 the surface

$$1 \leq \sqrt{x^2 + y^2} \leq 2, \quad z = -1,$$

with unit normal $\underline{u} = (0, 0, -1)$

Consider the region $Q \subset \mathbb{R}^3$ whose outward oriented boundary consists of $-S_1, S_2, S_3$ and S_4 . By the divergence theorem we have

$$\iint_{-S_1 + S_2 + S_3 + S_4} \underline{F} \cdot \underline{u} \, dS = \iiint_Q \operatorname{div} \underline{F} \, dx \, dy \, dz$$

So,

$$\begin{aligned} \iint_{S_2} \underline{F} \cdot \underline{u} \, dS &= \iiint_Q \operatorname{div} \underline{F} \, dx \, dy \, dz + \iint_{S_1} \underline{F} \cdot \underline{u} \, dS \\ &\quad - \iint_{S_3 + S_4} \underline{F} \cdot \underline{u} \, dS \quad - (1) \end{aligned}$$

1d) By the result of part (b), the flux through S_3 and S_4 is 0, and by part (c), the flux through S_1 is 4π . From the result from (a):

$$\iiint_Q \operatorname{div} \underline{F} \, dx \, dy \, dz = \iiint_Q \frac{1}{\sqrt{x^2 + y^2}} \, dx \, dy \, dz$$

Using cylindrical coordinates,

$$x = r \cos \theta, \quad y = r \sin \theta, \quad z = z,$$

$$dx \, dy \, dz = r \, dr \, d\theta \, dz,$$

$$\int_{\theta=0}^{2\pi} \left(\int_{z=-1}^1 \left(\int_{r=1}^{3-z^2} \frac{1}{r} \cdot r \, dr \right) dz \right) d\theta$$

$$= 2\pi \int_{-1}^1 (3 - z^2 - 1) \, dz$$

$$= 2\pi \int_{-1}^1 (2 - z^2) \, dz$$

$$= 2\pi \left[2z - \frac{z^3}{3} \right]_{-1}^1$$

$$= 2\pi \left(\frac{10}{3} \right) = \frac{20\pi}{3}$$

ld) Putting it all together in (1)

$$\begin{aligned}\iint_{S_2} \vec{F} \cdot \vec{u} \, dS &= \frac{20\pi}{3} + 4\pi - 0 \\ &= \frac{32\pi}{3}\end{aligned}$$

$$2a) \det A = \begin{vmatrix} 0 & 1 & a & 1 \\ 0 & a & 1 & a \\ 1 & 1 & 1 & a \end{vmatrix} = 1 - a^2$$

$$2b) A \underline{x} = \underline{b}$$

A is invertible if and only if $\det A \neq 0$

\therefore For $a \in \mathbb{R}, a \neq \pm 1$, the equation $A \underline{x} = \underline{b}$ has exactly one solution as A is invertible.

For $a = 1$,

$$\begin{bmatrix} 0 & 1 & a & a \\ 0 & a & 1 & a \\ 1 & 1 & 1 & a \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$\therefore A \underline{x} = \underline{b}$ when $a = 1$ has infinitely many solutions.

2b) For $a = -1$,

$$\begin{bmatrix} 0 & 1 & -1 & -1 \\ 0 & -1 & 1 & -1 \\ 1 & 1 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

$\therefore A_{\sim} \vec{x} = \vec{b}_{\sim}$ when $a = -1$ has no solutions.

3a) S being linearly independent means that the only solution to the equation

$$k_1 \underline{x}_1 + k_2 \underline{x}_2 + \dots + k_r \underline{x}_r = 0$$

$$\text{is } k_1 = k_2 = \dots = k_r = 0$$

b) Suppose S is linearly independent,

$$c_1(\underline{x}_1 - \underline{x}_2) + c_2(\underline{x}_2 - \underline{x}_3) + \dots + c_{r-1}(\underline{x}_{r-1} - \underline{x}_r) = 0$$

$$c_1 \underline{x}_1 + (c_2 - c_1) \underline{x}_2 + (c_3 - c_2) \underline{x}_3 + \dots + (c_{r-1} - c_{r-2}) \underline{x}_{r-1} - c_{r-1} \underline{x}_r = 0$$

Since S is linearly independent,

$$c_1 = c_2 - c_1 = c_3 - c_2 = \dots = c_{r-1} - c_{r-2} = c_{r-1} = 0$$

$$\therefore c_1 = c_2 = c_3 = \dots = c_{r-1} = 0$$

$\therefore \{ \underline{x}_1 - \underline{x}_2, \underline{x}_2 - \underline{x}_3, \dots, \underline{x}_{r-1} - \underline{x}_r \}$ is
linearly independent.