

Grashof condition:

$$L_{\max} + L_{\min} \leq L_a + L_b$$

4-bar linkage condition:

$$L_{\max} \leq L_{\min} + L_a + L_b$$

Crank-rocker  $\Rightarrow$  shortest link next to fixed link

Drag-link  $\longrightarrow$  shortest link is fixed link

Double-rocker  $\rightarrow$  shortest link is opposite the fixed link

Actual no. of joints = number of links attached to joint - 1

$$\text{Circular pitch: } p_c = \frac{\pi d_p}{N} = \pi m$$

$$\text{Module: } m = \frac{d_p}{N}$$

$$\text{Diametral pitch } P: \frac{m}{25.4} = \frac{1}{P}$$

$$\text{Pitch circle radius: } r = \frac{mN}{2}$$

$$\text{Tooth thickness: } t = \frac{\pi}{2} m$$

$$\text{Addendum: } a = m$$

$$\text{Velocity ratio: } r_v = \frac{\omega_2}{\omega_1} = \frac{\text{RPM}_2}{\text{RPM}_1} = \frac{r_1}{r_2} = \frac{N_1}{N_2}$$

$$\text{Centre distance: } c = \frac{d_{p_1} + d_{p_2}}{2} = \frac{m(N_1 + N_2)}{2} = \frac{N_1 + N_2}{2Pd}$$

Base circle radius:  $r_b = r_1 \cos \phi$   
 $\uparrow$   
 pitch circle radius

Base pitch:  $P_b = m\pi \cos \phi = \frac{\pi}{P} \cos \phi$

Gear chains:  $\frac{\text{Target gear}}{\text{Driving gear}} = \frac{\text{Driving gear}}{\text{Driven gear}}$

Planetary gear chains:  $\frac{n_T - n_c}{n_D - n_c} = \left(-\frac{N_1}{N_2}\right) \left(-\frac{N_3}{N_4}\right) \dots$

For gear chains, - for external gear  
+ for internal gear