

$\vec{F}$  is conservative means  $\vec{F} = \text{grad } f$

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## Line Integrals

Arc length:

$$\int_C ds = \int_a^b \|\vec{r}'(t)\| dt$$

Line integral of real valued function  $f$ :

$$\int_C f(x) ds = \int_a^b f(\vec{r}(t)) \|\vec{r}'(t)\| dt$$

Line integral (work) of vector field  $\vec{F}$ :

↖ unit tangent to the vector field

$$\int_C \vec{F} \cdot \vec{U} ds = \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$$

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$$\text{curl } \vec{F} = \nabla \times \vec{F}$$

$$\text{div } \vec{F} = \nabla \cdot \vec{F}$$

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# Surface integrals

Surface area:

$$\iint_S dS = \iint_R \|\underline{r}_u \times \underline{r}_v\| du dv$$

Surface integral of real valued function  $f$ :

$$\iint_S f(x) dS = \iint_R f(\underline{r}(t)) \|\underline{r}_u \times \underline{r}_v\| du dv$$

Surface integral (flux) of vector field  $\underline{F}$ :

$$\iint_S \underline{F} \cdot \overset{\substack{\uparrow \\ \text{unit normal vector to the surface}}}{\underline{u}} dS = \iint_R \underline{F}(\underline{r}(u,v)) \cdot \underline{r}_u \times \underline{r}_v du dv$$

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Common unit normal vectors

Cylinder:  $(x, y, 0)$

Sphere:  $(x, y, z)$

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## Green's Theorem

Positively oriented boundary  $\partial D$

$\vec{F}$  has continuous partial derivatives on both  $D$  and  $\partial D$ , then

$$\oint_{\partial D} P dx + Q dy = \iint_D (Q_x - P_y) dx dy$$

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## Stoke's Theorem

Positively oriented boundary  $\partial S$

$\vec{F}$  has continuous partial derivatives on both  $S$  and  $\partial S$ , then

$$\oint_{\partial S} P dx + Q dy + R dz = \iint_S \text{curl } \vec{F} \cdot d\vec{S}$$

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## Gauss' Divergence Theorem

Surface oriented with normal vector pointing away from  $Q$ .

$\vec{F}$  has continuous partial derivatives on both  $Q$  and  $\partial Q$ , then:

$$\iint_{\partial Q} \vec{F} \cdot d\vec{S} = \iiint_Q \text{div } \vec{F} dx dy dz$$

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# Triangular and diagonal matrices

Upper triangular matrix:

$$A = \begin{bmatrix} 1 & 3 & 5 & 0 \\ 0 & 3 & -2 & a \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

Lower triangular matrix:

$$B = \begin{bmatrix} 5 & 3 & 0 & 0 & 0 & 0 \\ -4 & 3 & 0 & 0 & 0 \\ 1 & 0 & \pi & 0 & 0 \\ 0 & -1 & 2 & \sqrt{2} & 0 \\ 1 & 3 & 5 & 7 & a \end{bmatrix}$$

Diagonal matrix:

$$C = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & a & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$$

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Matrix transpose

$$(A^T)_{ij} = (A)_{ji}$$

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# Symmetric matrices

$$A^T = A$$

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Matrix arithmetic involving transposes

1.  $(A^T)^T = A$

2.  $(A \pm B)^T = A^T \pm B^T$

3.  $(\alpha A^T) = \alpha(A^T)$

4.  $(AB)^T = B^T A^T$

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## Invertible matrices

A matrix  $A$  being invertible means there exists a matrix  $B$  such that:

$$AB = BA = I$$

$A$  being invertible also means

1.  $A\underline{x} = \underline{0}$  has only the trivial solution  
(the solution  $\underline{x} = \underline{0}$ )
  2. For any  $\underline{b} \in \mathbb{R}^n$ ,  $A\underline{x} = \underline{b}$  has exactly one solution
  3.  $\det A \neq 0$
- 

## Subspace check

$W$  is a subspace if

1.  $W \neq \emptyset$
  2.  $W$  is closed under addition, i.e.  
 $\underline{u} + \underline{v} \in W, \underline{u}, \underline{v} \in W$
  3.  $W$  is closed under multiplication, i.e.  
 $k\underline{u} \in W, \underline{u} \in W$
-

# Span

$$\text{Let } S = \{\underline{x}_1, \underline{x}_2, \dots, \underline{x}_n\}$$

$$\text{Span } S = \{k_1 \underline{x}_1 + k_2 \underline{x}_2 + \dots + k_n \underline{x}_n, k_1, \dots, k_n \in \mathbb{R}\}$$

$$\text{Span } \emptyset = \{\underline{0}\}$$

## Linear independence

$$k_1 \underline{x}_1 + k_2 \underline{x}_2 + \dots + k_n \underline{x}_n = \underline{0}$$

$$k_1 = k_2 = \dots = k_n = 0$$