

$$1) A^2 - 3A + I = \underset{\sim}{0}_{n \times n}$$

$$A(3I - A) = I$$

$\therefore A$  is invertible as  $A^{-1} = 3I - A$  (shown)

2a) Since  $A$  is invertible,  $A^{-1}$  exists.

$$A^{-1}A = A^0 = I \text{ (shown)}$$

$$(A^{-1})^{-1} = A^{-1(-1)} = A^1 = A \text{ (shown)}$$

$$b) A^n(A^{-1})^n = A^n A^{-n} = A^0 = I \text{ (shown)}$$

$$(A^n)^{-1} = (AA^{n-1})^{-1}$$

$$= (A^{n-1})^{-1} A^{-1}$$

$$= (A^{-1})^{n-1} A^{-1} \quad \therefore (AB)^{-1} = B^{-1}A^{-1}$$

$$= (A^{-1})^n \text{ (shown)}$$

$$2c) kA \cdot \frac{1}{k} A^{-1} = A^0 = I \text{ (shown)}$$

Since  $\frac{1}{k} A^{-1}$  is the inverse of  $kA$ ,

$$(kA)^{-1} = \frac{1}{k} A^{-1} \text{ (shown)}$$

$$3a) (7A)^{-1} = \begin{bmatrix} -3 & 7 \\ 1 & -2 \end{bmatrix}$$

$$7A = \frac{1}{6-7} \begin{bmatrix} -2 & -7 \\ -1 & -3 \end{bmatrix}$$

$$7A = \begin{bmatrix} 2 & 7 \\ 1 & 3 \end{bmatrix}$$

$$A = \frac{1}{7} \begin{bmatrix} 2 & 7 \\ 1 & 3 \end{bmatrix}$$

$$b) (I + 2A)^{-1} = \begin{bmatrix} 3 & 1 \\ -1 & 2 \end{bmatrix}$$

$$I + 2A = \frac{1}{6+1} \begin{bmatrix} 2 & -1 \\ 1 & 3 \end{bmatrix}$$

$$2A = \frac{1}{7} \left( \begin{bmatrix} 2 & -1 \\ 1 & 3 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right)$$

$$A = \frac{1}{14} \begin{bmatrix} -5 & -1 \\ 1 & -4 \end{bmatrix}$$

$$4a) \begin{bmatrix} 0 & 1 & -1 & | & 1 & 0 & 0 \\ 5 & -1 & 2 & | & 0 & 1 & 0 \\ 1 & 0 & 0 & | & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & -1 & | & 1 & 0 & 0 \\ 0 & -1 & 2 & | & 0 & 1 & -5 \\ 1 & 0 & 0 & | & 0 & 0 & 1 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & | & 0 & 0 & 1 \\ 0 & 1 & -1 & | & 1 & 0 & 0 \\ 0 & 0 & 1 & | & 1 & 1 & -5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & | & 0 & 0 & 1 \\ 0 & 1 & 0 & | & 2 & 1 & -5 \\ 0 & 0 & 1 & | & 1 & 1 & -5 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} 0 & 0 & 1 \\ 2 & 1 & -5 \\ 1 & 1 & -5 \end{bmatrix}$$

$$b) \begin{bmatrix} 1 & 5 & 2 & | & 1 & 0 & 0 \\ -1 & 0 & 1 & | & 0 & 1 & 0 \\ 1 & 15 & 8 & | & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 5 & 2 & | & 1 & 0 & 0 \\ 0 & 5 & 3 & | & 1 & 1 & 0 \\ 0 & 10 & 6 & | & -1 & 0 & 1 \end{bmatrix} \sim$$

$$\begin{bmatrix} 1 & 5 & 2 & | & 1 & 0 & 0 \\ 0 & 5 & 3 & | & 1 & 1 & 0 \\ 0 & 0 & 0 & | & -3 & -2 & 1 \end{bmatrix}$$

$A$  is singular.

$$5a) \begin{vmatrix} 3 & 5 \\ -2 & 4 \end{vmatrix} = 3 \times 4 - 5 \times -2 = 22$$

$$b) \begin{vmatrix} -2 & 1 & 4 & -2 & 1 \\ 3 & 5 & -7 & 3 & 5 \\ 1 & 6 & 2 & 1 & 6 \end{vmatrix} = -20 - 7 + 72 - 20 - 84 - 6 = -65$$

$$6a) \begin{vmatrix} 3 & -17 & -3 \\ 0 & 5 & 1 \\ 0 & 0 & -2 \end{vmatrix} = -30$$

$$b) \begin{vmatrix} \sqrt{2} & 0 & 0 & 0 \\ -8 & \sqrt{2} & 0 & 0 \\ 7 & 0 & -1 & 0 \\ 9 & 5 & 1 & 6 \end{vmatrix} = -12$$

$$c) \begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = - \begin{vmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{vmatrix} = -1$$

$$7a) \begin{vmatrix} g & h & i \\ a & b & c \\ d & e & f \end{vmatrix} = - \begin{vmatrix} a & b & c \\ g & h & i \\ d & e & f \end{vmatrix} = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = -5$$

$$b) \begin{vmatrix} a & b & c \\ d & e & f \\ a+g & b+h & c+i \end{vmatrix} = -5$$

$$c) \begin{vmatrix} 2a & 2b & 2c \\ -d & -e & -f \\ 3g & 3h & 3i \end{vmatrix} = 2(-1)(3) \times -5 = 30$$

$$d) \begin{vmatrix} a & d & g & a & d \\ b & e & h & b & e \\ c & f & i & c & f \end{vmatrix} = aei + dhc + gbf - ceg - fha - ibd$$

$$\begin{vmatrix} a & b & c & a & b \\ d & e & f & d & e \\ g & h & i & g & h \end{vmatrix} = aei + bfg + cdh - gec - hfa - idb$$

$$= -5$$

$$= \begin{vmatrix} a & d & g \\ b & e & h \\ c & f & i \end{vmatrix}$$

$$8a) \begin{vmatrix} 2 & 1 & 3 & 3 \\ 1 & 0 & 1 & 1 \\ 0 & 2 & 2 & 0 \\ 0 & 1 & 2 & 3 \end{vmatrix} = - \begin{vmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 2 & 2 & 0 \\ 0 & 1 & 2 & 3 \end{vmatrix} = - \begin{vmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & -2 \\ 0 & 0 & 1 & 2 \end{vmatrix}$$

$$= \begin{vmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & -2 \end{vmatrix} = -2 \begin{vmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 1 \end{vmatrix} = -2$$

$$b) \begin{vmatrix} 1 & 3 & 1 & 5 & 3 \\ -2 & -7 & 0 & -4 & 2 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 2 & 1 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{vmatrix} = \begin{vmatrix} 1 & 3 & 1 & 5 & 3 \\ 0 & -1 & 2 & 6 & 8 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{vmatrix}$$

$$= \begin{vmatrix} 1 & 3 & 1 & 5 & 3 \\ 0 & 1 & -2 & -6 & 8 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{vmatrix} = 0$$

$$9.i) \begin{vmatrix} 2 & 1 & 3 & 3 \\ 1 & 0 & 1 & 1 \\ 0 & 2 & 2 & 0 \\ 0 & 1 & 2 & 3 \end{vmatrix} = 2 \begin{vmatrix} 0 & 1 & 1 & 0 \\ 2 & 2 & 0 & 2 \\ 1 & 2 & 3 & 1 \\ 1 & 2 & 3 & 1 \end{vmatrix} - \begin{vmatrix} 1 & 3 & 3 & 1 \\ 2 & 2 & 0 & 2 \\ 1 & 2 & 3 & 1 \\ 1 & 2 & 3 & 1 \end{vmatrix}$$

$$= 2(4 - 2 - 6) - (6 + 12 - 6 - 18)$$

$$= -2$$

$$ii) \begin{vmatrix} 2 & 1 & 3 & 3 \\ 1 & 0 & 1 & 1 \\ 0 & 2 & 2 & 0 \\ 0 & 1 & 2 & 3 \end{vmatrix} = -2 \begin{vmatrix} 2 & 3 & 3 & 2 \\ 1 & 1 & 1 & 1 \\ 0 & 2 & 3 & 0 \\ 0 & 2 & 3 & 0 \end{vmatrix}$$

$$+ 2 \begin{vmatrix} 2 & 1 & 3 & 2 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 1 & 3 & 0 \end{vmatrix}$$

$$= -2(6 + 6 - 4 - 9) + 2(3 - 2 - 3)$$

$$= -2$$

$$(10) \begin{vmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix} \begin{vmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{vmatrix} = \cos^2 \theta + \sin^2 \theta$$

$$= \cos^2 \theta + \sin^2 \theta$$

$$= 1$$

Since  $\det A \neq 0$ ,  $A$  is invertible for all values of  $\theta$ .

$$(11a) \begin{vmatrix} 1 & 1 & 1 \\ x_1 & x_2 & x_3 \\ x_1^2 & x_2^2 & x_3^2 \end{vmatrix} = x_2 x_3^2 + x_3 x_1^2 + x_1 x_2^2 - x_1^2 x_2 - x_2^2 x_3 - x_3^2 x_1$$

$$= x_3^2(x_2 - x_1) + x_1 x_2(x_2 - x_1) + x_3(x_1^2 - x_2^2)$$

$$= (x_3^2 + x_1 x_2)(x_2 - x_1) - x_3(x_2 + x_1)(x_2 - x_1)$$

$$= (x_3^2 + x_1 x_2 - x_3(x_2 + x_1))(x_2 - x_1)$$

$$= (x_3^2 + x_1 x_2 - x_3 x_2 - x_3 x_1)(x_2 - x_1)$$

$$= (x_3(x_3 - x_1) - x_2(x_3 - x_1))(x_2 - x_1)$$

$$= (x_2 - x_1)(x_3 - x_1)(x_3 - x_2) \text{ (shown)}$$



$$11b) \text{ Let } B = \begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \end{bmatrix} \begin{bmatrix} c \\ b \\ a \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

For the equation above to have a unique solution,  $B$  must be invertible.

$$B \text{ is invertible} \Leftrightarrow \det B \neq 0$$

$$\begin{aligned} \det(B^T) &= (x_2 - x_1)(x_3 - x_1)(x_3 - x_2) \\ &= \det B \end{aligned}$$

$$\det B = (x_2 - x_1)(x_3 - x_1)(x_3 - x_2) \neq 0$$

$\therefore$  All  $x_1, x_2$  and  $x_3$  are distinct.

$$(2) \det(AA^{-1}) = \det A \det(A^{-1})$$

$$\det(I) = \det A \det(A^{-1})$$

$$1 = \det A \det(A^{-1})$$

$$\det(A^{-1}) = \frac{1}{\det A} \text{ (shown)}$$

$$(3) \text{ Let } A = \begin{bmatrix} 3 & 0 \\ 0 & 4 \end{bmatrix}, B = \begin{bmatrix} 5 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\det(A+B) = \det\left(\begin{bmatrix} 3 & 0 \\ 0 & 4 \end{bmatrix} + \begin{bmatrix} 5 & 0 \\ 0 & 2 \end{bmatrix}\right)$$

$$= \begin{vmatrix} 8 & 0 \\ 0 & 6 \end{vmatrix}$$

$$= 48$$

$$\det A + \det B = \begin{vmatrix} 3 & 0 \\ 0 & 4 \end{vmatrix} + \begin{vmatrix} 5 & 0 \\ 0 & 2 \end{vmatrix}$$

$$= 12 + 10$$

$$= 22 \neq 48$$

$$\therefore \det(A+B) \neq \det A + \det B$$

$$14) \det(kA) = \det \left( \begin{bmatrix} k & & 0 \\ & \ddots & \\ 0 & & k \end{bmatrix} A \right)$$

$$= \det \begin{bmatrix} k & & 0 \\ & \ddots & \\ 0 & & k \end{bmatrix} \det A$$

$$= k^n \det A$$

$$15) f(x, y) = (xy + x - y, \cos x + \sin y, \sin x + \cos y)$$

$$f'(x, y) = \begin{bmatrix} y+1 & x-1 \\ -\sin x & \cos y \\ \cos x & -\sin y \end{bmatrix}$$

16) Since the partial derivatives  $f'(x,y)$  are continuous everywhere due to being elementary functions, the linearisation is:

$$L(\underline{x}) = f(0,0) + f'(0,0) (\underline{x} - (0,0))$$

$$L(x,y) = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 & -1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x & y \end{bmatrix}$$

$$L(x,y) = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} x-y \\ y \\ x \end{bmatrix}$$

$$L(x,y) = (x-y, y+1, x+1)$$

$$G_L = L(x,y) = (x-y, y+1, x+1)$$

$$17) (x, y, z) = g(r, \theta, z) = (r \cos \theta, r \sin \theta, z)$$

$$g'(r, \theta, z) = \begin{bmatrix} x_r & x_\theta & x_z \\ y_r & y_\theta & y_z \\ z_r & z_\theta & z_z \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$dx dy dz = \left| \begin{array}{ccc|ccc} \cos \theta & -r \sin \theta & 0 & \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 & \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right| dr d\theta dz$$

$$= |r \cos^2 \theta + r \sin^2 \theta| dr d\theta dz$$

$$= |r| dr d\theta dz$$

$$= r dr d\theta dz$$

$$17) (x, y, z) = g(\rho, \theta, \varphi) = (\rho \cos \theta \sin \varphi, \rho \sin \theta \sin \varphi, \rho \cos \varphi)$$

$$g'(\rho, \theta, \varphi) = \begin{bmatrix} x_\rho & x_\theta & x_\varphi \\ y_\rho & y_\theta & y_\varphi \\ z_\rho & z_\theta & z_\varphi \end{bmatrix}$$

$$= \begin{bmatrix} \cos \theta \sin \varphi & -\rho \sin \theta \sin \varphi & \rho \cos \theta \cos \varphi \\ \sin \theta \sin \varphi & \rho \cos \theta \sin \varphi & \rho \sin \theta \cos \varphi \\ \cos \varphi & 0 & -\rho \sin \varphi \end{bmatrix}$$

$$dx dy dz = \begin{vmatrix} \cos \theta \sin \varphi & -\rho \sin \theta \sin \varphi & \rho \cos \theta \cos \varphi \\ \sin \theta \sin \varphi & \rho \cos \theta \sin \varphi & \rho \sin \theta \cos \varphi \\ \cos \varphi & 0 & -\rho \sin \varphi \end{vmatrix} d\rho d\theta d\varphi$$

$$= \begin{vmatrix} -\rho^2 \cos^2 \theta \sin^3 \varphi - \rho^2 \sin^2 \theta \sin \varphi \cos^2 \varphi \\ -\rho^2 \cos^2 \theta \sin \varphi \cos^2 \varphi - \rho^2 \sin^2 \theta \sin^3 \varphi \end{vmatrix} d\rho d\theta d\varphi$$

$$= \begin{vmatrix} -(\rho^2 \sin^3 \varphi) - (\rho^2 \sin \varphi \cos^2 \varphi) \end{vmatrix} d\rho d\theta d\varphi$$

$$= \begin{vmatrix} -(\rho^2 \sin \varphi (\sin^2 \varphi + \cos^2 \varphi)) \end{vmatrix} d\rho d\theta d\varphi$$

$$= \begin{vmatrix} -\rho^2 \sin \varphi \end{vmatrix} d\rho d\theta d\varphi$$

$$= \rho^2 \sin \varphi d\rho d\theta d\varphi$$

$$18) (x, y) = g(u, v) = (u^2, v)$$

$$g'(u, v) = \begin{bmatrix} x_u & x_v \\ y_u & y_v \end{bmatrix}$$

$$= \begin{bmatrix} 2u & 0 \\ 0 & 1 \end{bmatrix}$$

$$dx dy = \left| \begin{vmatrix} 2u & 0 \\ 0 & 1 \end{vmatrix} \right| du dv = 2u du dv$$

$$\iint_D ye^{\sqrt{x}} dx dy = \int_{u=0}^1 \int_{v=0}^u ve^u (2u) du dv$$

$$= 2 \int_0^1 ue^u \left[ \frac{v^2}{2} \right]_0^u du$$

$$= \int_0^1 u^3 e^u du$$

$$= 6 - 2e$$

$$19) (x, y, z) = g(\rho, \theta, \varphi) = (a\rho \cos\theta \sin\varphi, b\rho \sin\theta \sin\varphi, c\rho \cos\varphi)$$

$$g'(\rho, \theta, \varphi) = \begin{bmatrix} x_\rho & x_\theta & x_\varphi \\ y_\rho & y_\theta & y_\varphi \\ z_\rho & z_\theta & z_\varphi \end{bmatrix}$$

$$= \begin{bmatrix} a \cos\theta \sin\varphi & -a\rho \sin\theta \sin\varphi & a\rho \cos\theta \cos\varphi \\ b \sin\theta \sin\varphi & b\rho \cos\theta \sin\varphi & b\rho \sin\theta \cos\varphi \\ c \cos\varphi & 0 & -c\rho \sin\varphi \end{bmatrix}$$

$$dx dy dz = \begin{vmatrix} a \cos\theta \sin\varphi & -a\rho \sin\theta \sin\varphi & a\rho \cos\theta \cos\varphi \\ b \sin\theta \sin\varphi & b\rho \cos\theta \sin\varphi & b\rho \sin\theta \cos\varphi \\ c \cos\varphi & 0 & -c\rho \sin\varphi \end{vmatrix} d\rho d\theta d\varphi$$

$$= \begin{vmatrix} -abc\rho^2 \cos^2\theta \sin^3\varphi - abc\rho^2 \sin^2\theta \sin\varphi \cos^2\varphi \\ -abc\rho^2 \cos^2\theta \sin\varphi \cos^2\varphi - abc\rho^2 \sin^2\theta \sin^3\varphi \end{vmatrix} d\rho d\theta d\varphi$$

$$= abc\rho^2 \begin{vmatrix} -(\sin^3\varphi) - (\sin\varphi \cos^2\varphi) \end{vmatrix} d\rho d\theta d\varphi$$

$$= abc\rho^2 \begin{vmatrix} -\sin\varphi (\sin^2\varphi + \cos^2\varphi) \end{vmatrix} d\rho d\theta d\varphi$$

$$= abc\rho^2 \sin\varphi d\rho d\theta d\varphi$$



$$1a) \iiint dx dy dz = \int_{\rho=0}^1 \int_{\theta=0}^{2\pi} \int_{\varphi=0}^{\pi} abc \rho^2 \sin \varphi d\rho d\theta d\varphi$$

$$= abc \int_{\theta=0}^{2\pi} \int_{\varphi=0}^{\pi} \sin \varphi \left[ \frac{\rho^3}{3} \right]_0^1 d\theta d\varphi$$

$$= \frac{abc}{3} \int_{\theta=0}^{2\pi} \int_{\varphi=0}^{\pi} \sin \varphi d\theta d\varphi$$

$$= \frac{abc}{3} \int_0^{2\pi} \left[ -\cos \varphi \right]_0^{\pi} d\theta$$

$$= \frac{2abc}{3} \int_0^{2\pi} 1 d\theta$$

$$= \frac{4\pi abc}{3}$$