

Optimal Control and Estimation

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2023-06-05

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Preface

This is the textbook for Harvard ES/AM 158: Introduction to Optimal Control and Estimation. Information about the offerings of the class is listed below.

2023 Fall

Time: Mon/Wed 2:15 - 3:30pm

Location: Science and Engineering Complex, Room TBD

Instructor: Heng Yang

Teaching Fellow: Weiyu Li

Syllabus

Acknowledgment

Chapter 1

The Optimal Control Formulation

Chapter 2

Literature

Here is a review of existing methods.

Chapter 3

Methods

We describe our methods in this chapter.

Math can be added in body using usual syntax like this

3.1 math example

p is unknown but expected to be around $1/3$. Standard error will be approximated

$$SE = \sqrt{\left(\frac{p(1-p)}{n}\right)} \approx \sqrt{\frac{1/3(1-1/3)}{300}} = 0.027$$

You can also use math in footnotes like this¹.

We will approximate standard error to 0.027^2

¹where we mention $p = \frac{a}{b}$

² p is unknown but expected to be around $1/3$. Standard error will be approximated

$$SE = \sqrt{\left(\frac{p(1-p)}{n}\right)} \approx \sqrt{\frac{1/3(1-1/3)}{300}} = 0.027$$

Chapter 4

Applications

Some *significant* applications are demonstrated in this chapter.

4.1 Example one

4.2 Example two

Chapter 5

Final Words

We have finished a nice book.