

ECE437/CS481

# M05A: DEADLOCKS

CHAPTER 7

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A decorative blue wavy line that spans the width of the slide, starting with a small upward curve on the left, dipping into a V-shape in the center, and then curving back up on the right before continuing as a straight line to the edge.

# Deadlock Problem

## □ Deadlock problem

- A set of blocked processes, each of which holds a resource and waits to acquire another resource held by another process.

## □ Example of deadlock

- System has 2 disk drives;  $P_1$  and  $P_2$  each hold one disk drive and each needs another one.
- Semaphores  $A$  and  $B$ , initialized to 1

$P_0$	$P_1$
wait (A);	wait(B)
wait (B);	wait(A)

# Deadlock Problem

## ❑ Deadlock problem

- A set of blocked processes, each of which holds a resource and waits to acquire another resource held by another process.

## ❑ Example of deadlock

- Space is available for allocation of 200K bytes, and the following sequence of events occur.
- Deadlock occurs if both processes progress to their second requests.



# Deadlock & Starvation

## Deadlock

A deadlock occurs when a set of processes in a system is blocked waiting on requirements that can **NEVER** be satisfied.



## Starvation

Starvation occurs when a process waits for a resource that continually available but is never assigned to that process because of priority or a flaw in the design of the scheduler.

## □ Difference:

- In starvation, it's not certain that a process will ever get the requested resource, whereas a deadlock process is permanently blocked.
- In starvation, the resource under contention is in continuous use, whereas this is not true in a deadlock.

# Deadlock Characterization

□ Four conditions are **necessary** for deadlocks to occur:

➤ **Mutual exclusive**

- ✓ at least 1 resource is held in a non-sharable mode. Other requesting processes must wait until the resource is released

➤ **Wait while hold**

- ✓ processes hold previously acquired resources while waiting for additional resources

➤ **No preemption**

- ✓ A resource cannot be preempted from a process without aborting the process

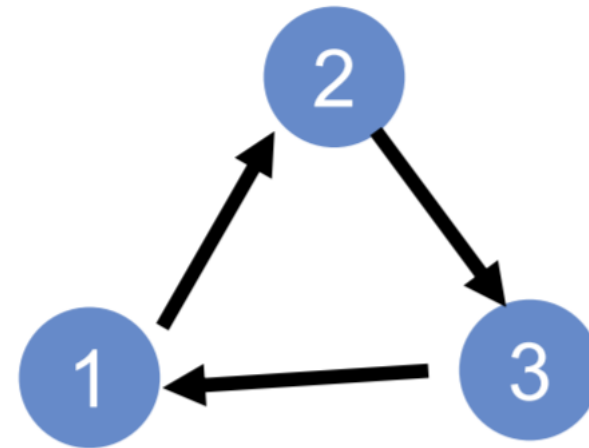
➤ **Circular wait**

- ✓  $\exists$  a set of processes  $\{P_1, P_2, \dots, P_N\}$ , such that  $P_1$  is waiting for  $P_2$ ,  $P_2$  for  $P_3$ , ..., and  $P_N$  for  $P_1$

# Deadlock Detection based on WFG

## □ Create a Wait-For Graph (WFG):

- **Node:** process
- **Edge with direction:** the blocking/waiting relation between processes, e.g.,  $e(p_i, p_j)$  means that  $p_i$  needs a resource currently held by  $p_j$ , or  $p_i$  is waiting for  $p_j$ .
- **Cycle:** indication of deadlock



# Deadlock Detection based on WFG

## □ Testing for cycle in WFG:

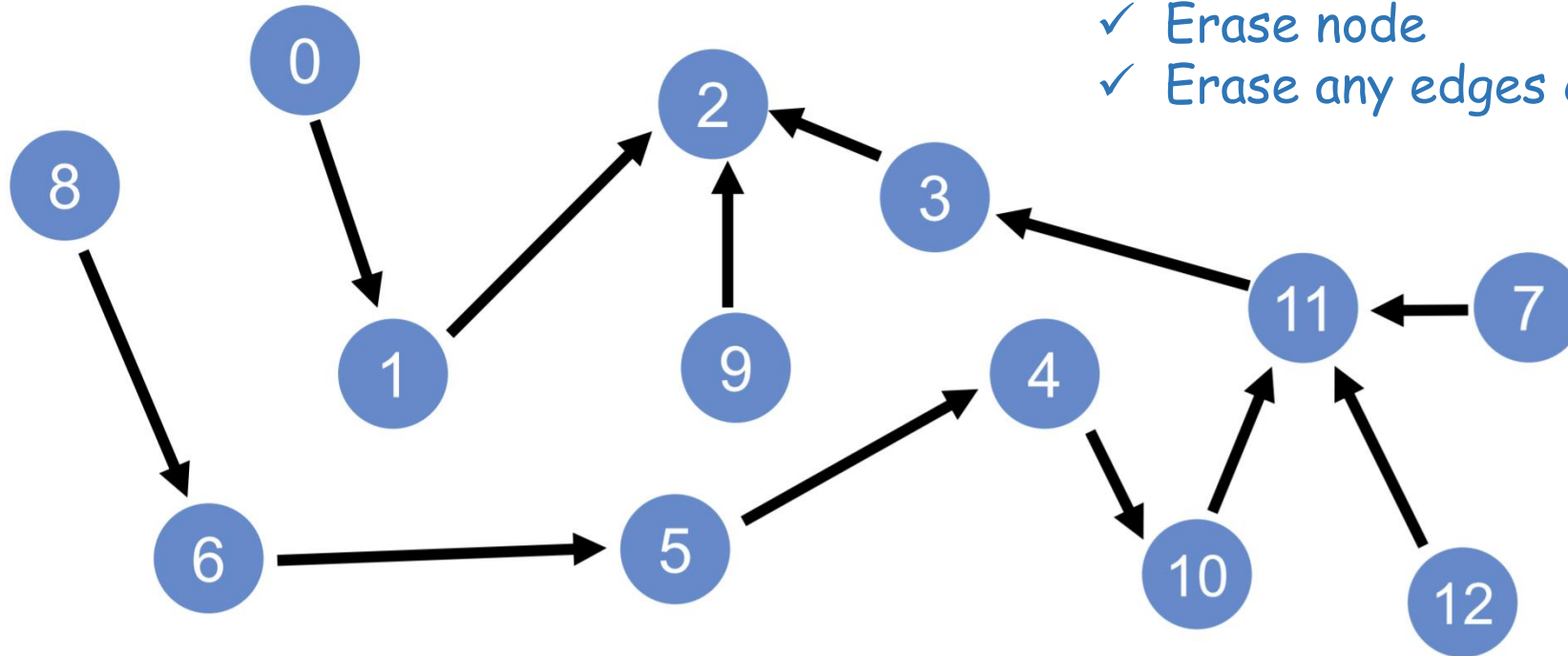
- Find a node with no outgoing edges
  - ✓ Erase node
  - ✓ Erase any edges coming into it
- **Intuition:** this was a process waiting on nothing. It will eventually finish, and anyone waiting on it will no longer be waiting.
- **Results:**
  - ✓ Erase whole graph  $\leftrightarrow$  graph has no cycles
  - ✓ Graph remains  $\leftrightarrow$  deadlock

Graph reduction algorithm

# Deadlock Detection based on WFG

## □ Graph Reduction in WFG: Example 1

- Find a node with no outgoing edges
  - ✓ Erase node
  - ✓ Erase any edges coming into it

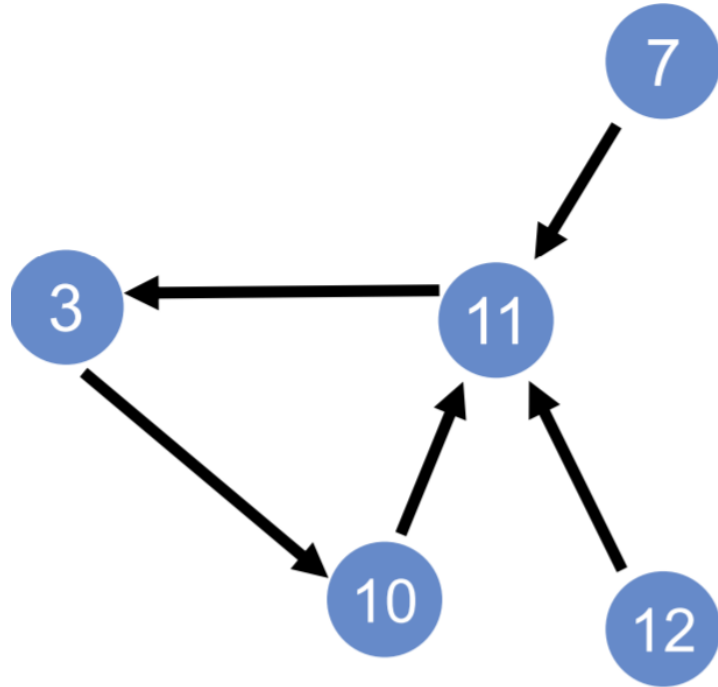


- ✓ Graph can be fully reduced, hence there was no deadlock at the time the graph was drawn. (Obviously, things could change later!)



# Deadlock Detection based on WFG

## □ Graph Reduction in WFG: Example 2



- Find a node with no outgoing edges
  - ✓ Erase node
  - ✓ Erase any edges coming into it

- ✓ No node with no outgoing edges... Irreducible graph, contains a cycle ↔ deadlock.

# Deadlock Detection based on RAG

## □ Create a Resource Allocation Graph (RAG):

### ➤ Two types of Nodes



**node circles:**

$P = \{P_1, P_2, \dots, P_n\}$

- the set consisting of all the processes in the system



**node squares:**

$R = \{R_1, R_2, \dots, R_m\}$

- the set consisting of all resource types in the system
- (dots within a square --- resource instances)

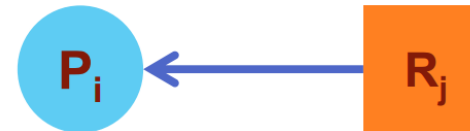
### ➤ Two types of edges



**request edge:**

directed edge  $P_i \rightarrow R_j$

- ❖ edge from a process node to a resource node



**assignment edge (granting edge):**

directed edge  $R_j \rightarrow P_i$

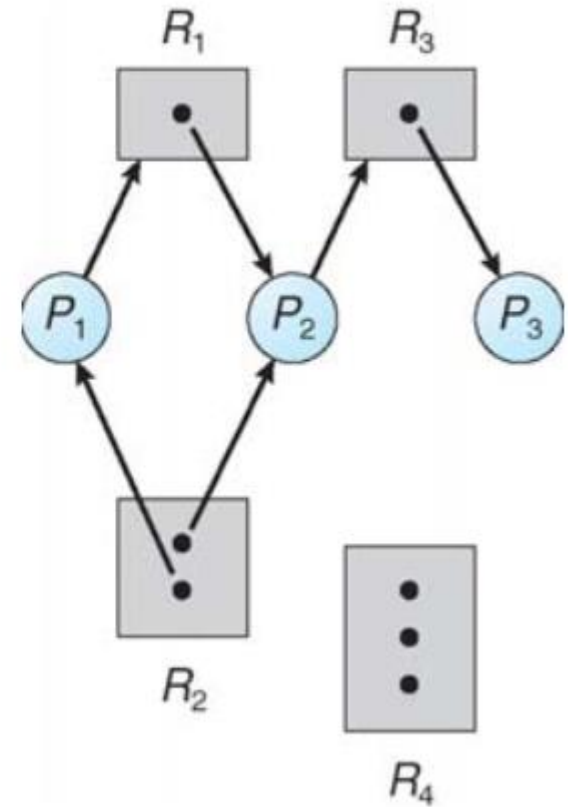
- ❖ edge from a resource instance to a process node

# Deadlock Detection based on RAG

## □ RAG

- If each resource type has exactly one instance
  - ✓ a cycle in the graph is both a **necessary and a sufficient condition** for the existence of deadlock
- If each resource type has several instances
  - ✓ a cycle in a graph is a **necessary but not a sufficient condition** for the existence of deadlock

$P_1$ hold $R_2$ request $R_1$	$R_1$ --- $m=1$
$P_2$ hold $R_1$ & $R_2$ request $R_3$	$R_2$ --- $m=1$
$P_3$ hold $R_3$	$R_3$ --- $m=2$
	$R_4$ --- $m=3$

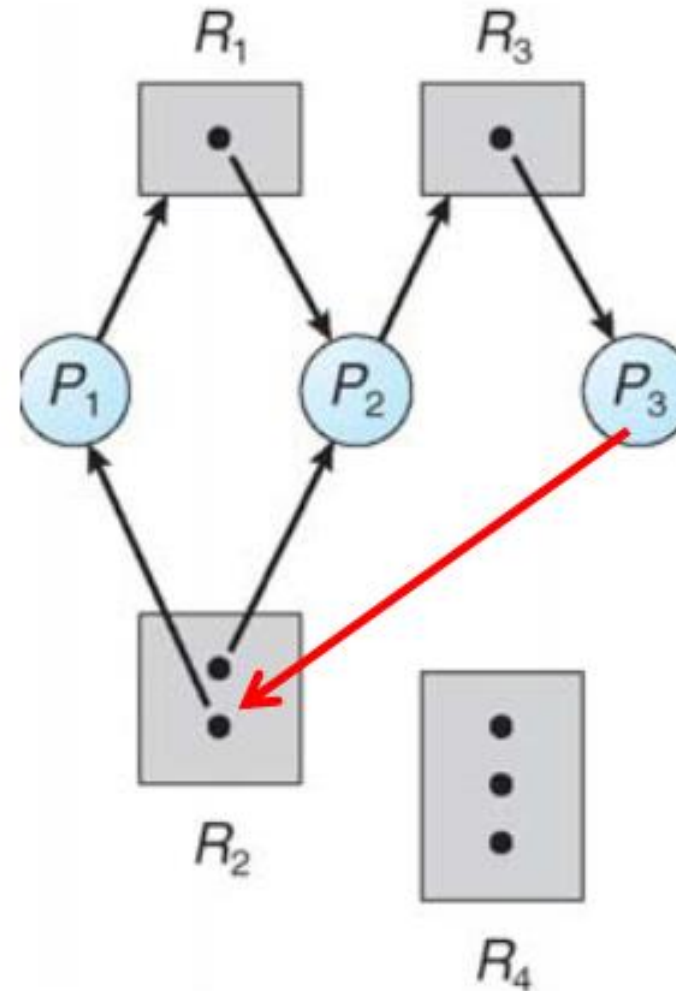


# Deadlock Detection based on RAG

□ RAG: a circle incurs a deadlock

$P_1$ hold $R_2$ request $R_1$	$R_1$ --- $m=1$
$P_2$ hold $R_1$ & $R_2$ request $R_3$	$R_2$ --- $m=1$
$P_3$ hold $R_3$	$R_3$ --- $m=2$
	$R_4$ --- $m=3$

$P_3$  request  $R_2$   
**Deadlock!**



# Deadlock Detection based on RAG

- RAG: a circle does not incur a deadlock

<b><math>P_1</math> hold <math>R_2</math> request <math>R_1</math> <math>P_2</math> hold <math>R_1</math> <math>R_3</math> hold <math>R_1</math> request <math>R_2</math> <math>P_4</math> hold <math>R_2</math></b>	<b><math>R_1</math> --- <math>m=2</math> <math>R_2</math> --- <math>m=2</math></b>
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**With a cycle,  
But no deadlock!**

