ECE437/CS481

M02A: PROCESSES & THREADS PROCESSES CONCEPTS

Chapter 3.1-3.2

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Programs & Processes

- ☐ What is a program?
 - > "A program contains code & static data stored in a file" (von Neumann architecture)
 - ✓ Source code before compilation
 - ✓ Binary code ready to be loaded
- ☐ What is a process?
 - > "A process is a program that is being executed"
 - ✓ A program can execute many times, so corresponding to many processes
 - ✓ Different process have their own address spaces & process context

Process Context

□Process context includes

- > Execution information
 - ✓ CPU register set image (e.g., Program Counter (PC), Stack Pointer (SP), Instruction Register (IR), Program Status Word (PSW) and other general processor registers)
 - ✓ Process stack containing temporary data (e.g. subroutine parameters, temporary variables, return addresses)

Register	Accu	mulator	Co	unter		ı	Data			Base			Stack F	ointe	r	Stack Bas	e Pointer	So	urce	D	estina	tion
64-bit		RAX		RCX			RDX			RBX			RS	P		RE	Р	R	ISI		RD	
32-bit		EAX		EC)	(EDX			EBX			ESI	0		EBP		ESI			EDI
16-bit		AX			CX			DX			B	X			SP		BP		SI			DI
8-bit		AH AL		CH	CL			DH D	-		ВН	BL										

General-Purpose Registers

Process Context

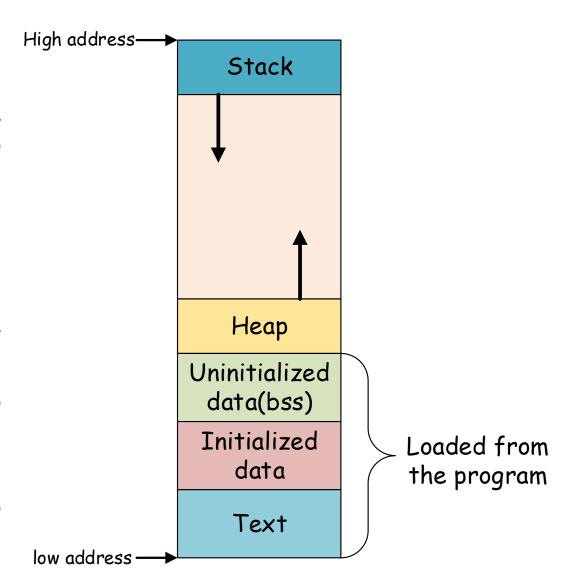
☐ Process context includes

- > Environment information
 - ✓ Memory address space or memory map, which is the various regions of memory that have been allocated to the process
 - ✓ Resources, e.g., Open file table and Communication channels & I/O devises
- > System attributes
 - ✓ process identification or Process ID (PID)
 - ✓ process state information, e.g., waiting, ready, etc.
 - ✓ process control information

Process Memory Map

□ Process's memory map in Unix/Linux

- Text (code): the machine instructions to be executed. Usually, it stays unmodified over the lifecycle of the process.
- > Initialized data
- > Uninitialized data
- > Heap: dynamically allocated memory
 - ✓ grow via a system call to request more memory
- > Stack: memory space to manage function calls, returns, parameter passing, and local variables.
 - ✓ grow and shrink as the depth of function calls varies



Process Memory Map

☐ Initialized data vs Uninitialized data

```
#include <stdio.h>
int main(void)
  return 0;
#include <stdio.h>
int global; /* Uninitialized variable stored in bss*/
int main(void)
```

text	data	bss	dec	hex
960	248	8	1216	4c0

text	data	bss	dec	hex
960	248	12	1220	4c4

return 0;

Process Memory Map

☐ Initialized data vs Uninitialized data

```
#include <stdio.h>
int global; /* Uninitialized variable stored in bss*/
int main(void)
{
    static int i; /* Uninitialized static variable stored in bss */
    return 0;
}
```

text	data	bss	dec	hex
960	248	16	1224	4c8

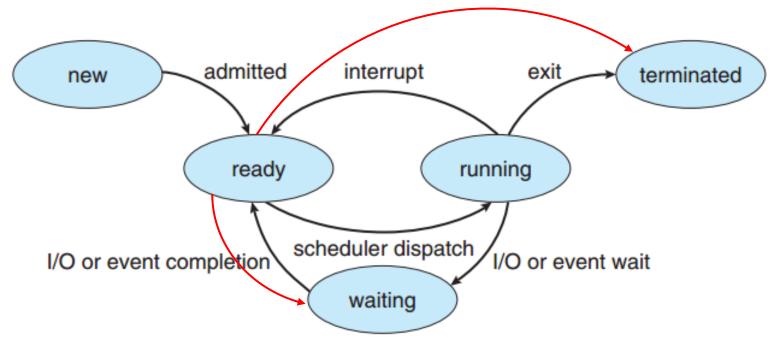
```
int global; /* Uninitialized variable stored in bss*/
int main(void)
{
    static int i = 100; /* Initialized static variable stored in DS*/
    return 0;
}
```

text	data	bss	dec	hex
960	252	12	1224	4c8

#include <stdio.h>

- □ New (Start)
 - > The process is being created but has not yet admitted to the pool of executable processes
 - ✓ Admit --- go to Ready state: The OS will move a process to the Ready state when it can take an additional process.
- ☐ Terminated (Exit):
 - > The process has finished execution.
- □ Ready
 - > The process is waiting to be assigned to a processor.
- □ Running
 - > The process is currently being executed.
 - > If we assume a single processor computer, at most one process can be in this state at a time. But not true for today's multicore system.
- Waiting (Blocked)
 - > The process is waiting for some event to occur.

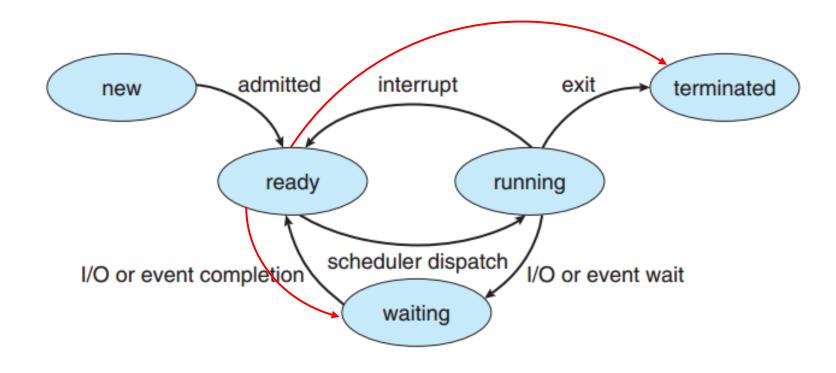
- □ Ready→Running/Waiting/Terminated
 - > Scheduler dispatch --- go to the Running state
 - > Suspend --- go to the Waiting state
 - > Kill --- go to the Terminated state



□ Running→Read/Waiting/Terminated

- > Yield (i.e., the running process voluntarily release control of the processor) --- go to the Ready state
- Time slice is up (i.e., the running process has reached the maximum allowable time) go to the Ready state
- > Arrival of high priority process (i.e., the running process will be preempted due to its lower priority) --- go to the Ready state
- > I/O request --- go to the Waiting state
- > Suspend --- go to the Waiting state
- > Terminate --- go to the Terminated state

- Waiting→Ready/Terminated
 - > I/O complete, wakeup --- go to the Ready state
 - > Kill --- go to the Exit /terminated state



☐ Process Control Block (PCB)

- > Each process is represented in the OS by a PCB
- > An important data structure to keep the context of a process
 - ✓ PID: a unique integer as process ID
 - ✓ UID: user ID who is executing this process
 - ✓ Process state: the current process state
 - ✓ Event: any event for which the process may be waiting
 - ✓ Memory management info: information of page table, memory limits, segment table, etc.
 - ✓ CPU registers: CPU registers where process need to be stored for execution.
 - ✓ Scheduling priority: parameters for the process scheduling
 - ✓ Program counter: a pointer to the address of the next instruction to be executed for this process.
 - ✓ Accounting into: timing, usage, ...
 - ✓ IO status information: a list of I/O devices allocated to the process.
- > In linux:
 - ✓ defined in task_struct (include/linux/sched.h)---over 95 fields!!!

Process list

- > Each existing process has one entry, the entry itself is PCB
- Given a process ID to find its PCB through the process table, needed by kill, wakeup, suspend...

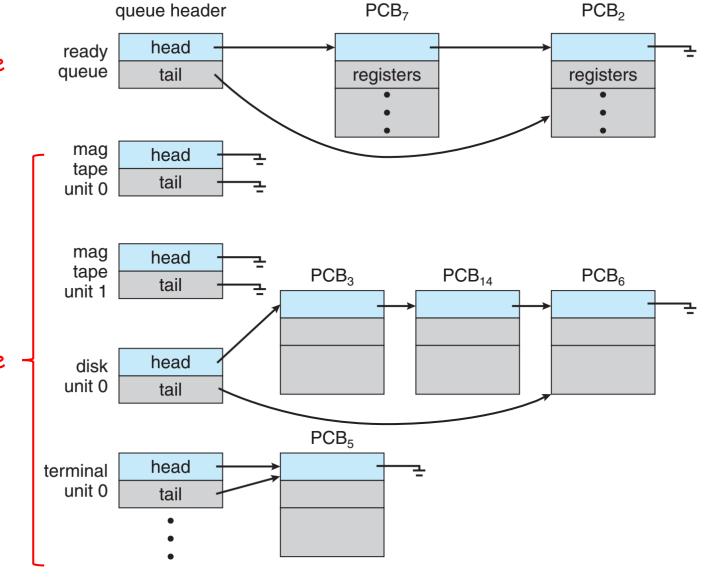
```
TASKS 227 (578 thr), 1 run, 225 slp, 1 oth sorted automatically by cpu percent
       MEM% VIRT RES PID USER
                                         NI S
                                                 TIME+ IOR/s IOW/s Command
                                                                 0 /home/nicolargo/virtualenvs/glances-develop/bin,
        0.2 79.0M 15.2M 27889 nicolargo
                                          0 R
                                               0:03.24
                                                                0 /usr/bin/X:0 -background none -verbose -auth /
        3.6 676M 284M 1107 root
                                          0 S 5:09.56
                                                                0 /usr/lib/firefox/plugin-container /usr/lib/flas
        0.9 717M 70.8M 22440 nicolargo
                                          0 S 1:16.40
                                                                0 /usr/bin/gnome-shell
        4.7 2.10G 371M 22870 nicolargo
                                          0 S 35:31.50
        0.6 1.02G 47.2M 4089 nicolargo
                                          0 5 0:49.50
                                                                0 /usr/bin/python /usr/bin/terminator
        0.3 386M 27.5M 1982 nicolargo
                                                                0 /usr/bin/ibus-daemon --daemonize --xim
                                          0 5 8:37.84
       2.2 1.64G 176M 7042 nicolargo
                                          0 S 23:44.30
                                                                 0 vlc
        6.5 1.98G 515M 8411 nicolargo
                                                                0 /usr/bin/perl /usr/bin/shutter
                                          0 S 2:30.55
        0.0
                                              0:01.75
                                                                0 kworker/0:0
                      0 19741 root
        0.0
                      0 26267 root
                                          0 5 0:00.47
                                                                0 kworker/2:1
        0.0
                                                                0 kworker/u16:0
                Θ
                      0 27127 root
                                              0:00.11
        0.1 36.5M 6.45M
                            1 root
                                          0 S 0:07.73
                                                                0 /sbin/init
        0.0
                                                                0 kthreadd
                            2 root
                                          0 5 0:00.80
                                                                0 ksoftirgd/0
       0.0
                            3 root
                                              0:01.32
        0.0
                                                                0 kworker/0:0H
                            5 root
                                         -20 S 0:00.00
        0.0
                            7 root
                                           0 S 1:05.30
                                                                 0 rcu sched
```

State Queues

- ☐ The OS maintains a collection of queues that represent the state of all processes in the system
 - > Typically, one queue stands for a state, e.g., ready, waiting, ...
 - > Each PCB is queued onto a specific state queue based on its status.
 - > Once a process changes state, its PCB is unlinked from one queue, and linked onto another.

State Queues

- There may be many Ready queue waiting queues, one for each type of wait (particular device, timer, message, ...)
- Running queue?
 Terminated queue?



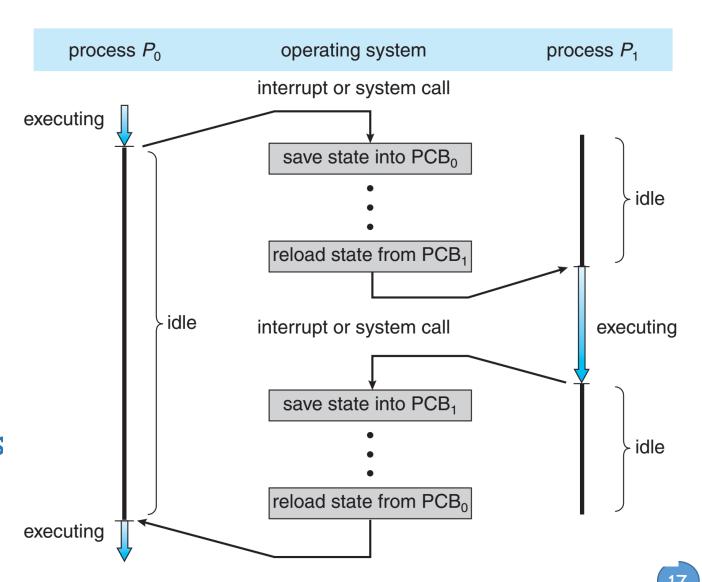
Waiting queue

Process Context Switch

- ☐ Process context switch
 - ---Switching of the CPU from process A to another, requiring storing the state of process A such that it can be restored and execution resumed from the same point later.
 - > Why need context switch
 - --- improve CPU utilization
 - > How to switch the process context --- Dispatch
 - 1. stopping the current process's computation
 - 2. saving enough information about its execution context
 - 3. changing process state and putting it back to corresponding queues
 - 4. selecting another process from the ready queue
 - 5. changing the newly selected process' state
 - 6. restarting computation of the new process

Process Context Switch

- ☐ Switching between processes
- □ Context of a process represented in the process's PCB
- □ Context-switch time is the overhead; the system does no useful work while switching
- Tricky: context switch can improve the CPU utilization; however, context switch may incur overheads which may reduce CPU utilization.



Process Context Switch

- ☐ When to do context switch
 - > I/O request
 - > CPU time slice is up
 - > Arrival of higher priority process
 - > Yield by process itself
 - > Termination of process
 - √ processes may terminate itself by using an exit() system call
 - ✓ one process may terminate another, if given appropriate permissions
- □ Scheduler specifies the policy used to select a process from the ready queue to run next