HANLIN "ASHER" MAI

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EDUCATION

University of Illinois at Urbana-Champaign (UIUC)

Aug 2023 - May 2028 (Current)

GPA: 4.0/4.0

M.S. / PhD. in Electrical and Computer Engineering

Aug 2019 - May 2023

University of Illinois at Urbana-Champaign (UIUC)

GPA: 3.93/4.0

Bachelor of Science in Computer Engineering with Highest Honor James Scholar Honors Program, Dean's List

SKILLS

Programming

C++, Python, CUDA, Swift

Pytorch, Scikit-Learn, OpenCV, Pandas, ROS Deep Learning

Web and Design Git, HTML, CSS, JavaScript, React, CI/CD, Docker, Blender 3D

Coursework:

Artificial Intelligence, Principles of Safe Autonomy, Applied Parallel Programming, Computer Vision,

Machine Learning, Applied Linear Algebra, Computational Photography. Digital Signal Processing

EXPERIENCE

Rivian Automotive, Inc.

Jan - Aug 2023, May - Aug 2024

Machine Learning Intern Champaign, IL • Added new capabilities to optimize real-time image processing in Advanced Driver-Assistance System (ADAS) models

• Generated random neural network test cases with respective inputs and outputs using PyTorch

• Built end-to-end testing pipeline with Gitlab CI/CD on various deep-learning Models for Rivian hardware platform

Synchrony Financial

May 2021 - Dec 2021

Emerging Technology Intern — Credit Innovation Team

Champaign, IL

• Analyzed Proactive Credit Line Increase Strategy and migrate strategy to Enterprise DataLake using Python

• Verified the strategy performs identically on databases before and after migration by running simulations and tests

PUBLICATIONS

Shadows Don't Lie and Lines Can't Bend! Generative Models don't know Projective Geometry...for now

A. Sarkar*, H. Mai*, A. Mahapatra*, S. Lazebnik, D. A. Forsyth, A. Bhattad

(* for equal contribution)

CVPR 2024

RESEARCH PROJECTS

Occlusion Aware Crowd Navigation

May 2022 - Aug 2023

Prof. Katie Driggs-Campbell | Human-Centered Autonomy Lab

- Implement ConvLSTM-based Variational Autoencoder to predict human positions in Occupancy Grid Map (OGM)
- Evaluate accuracy of generated OGM with blob detection to access the network's ability to "see" occluded pedestrians
- Integrate baseline A-star planner with occlusion inference module on UCY pedestrian dataset.

Convolutional Neural Network Pruning and Ouantization for FPGA

May 2022 - Sep 2022

Prof. Volodymyr Kindratenko | National Center for Supercomputing Applications

- Train VGG16 image classification CNN using PyTorch and CIFAR10 dataset with team of three
- Reduce model size by more than 4x using pruning and PyTorch's Post Training Quantization framework
- Collaborate with FPGA team to integrate quantized 8 bit convolutional kernels for image classification on hardware

COURSE PROJECTS

Digital Notes With Any Pen on Any Surface

Aug 2022 - Dec 2022

CS 445: Computational Photography

- Designed vision-based system to allow a user to take notes digitally using only a webcam in real-time
- Developed calibration method that translates detected stylus locations on the table to drawings on screen
- Received Donald L. Bitzer and H. Gene Slottow Creativity Award. Presented project at UIUC Engineering Open House

Autonomous Parking Navigation

May 2022

ECE 484: Principle of Safe Autonomy

- Collaborated with team and used A-star search planning algorithm for autonomous parking on Gazebo simulator
- Integrated planning algorithm with on-board system of Polaris GEM Vehicle for real world parking test
- Verified and improved success of parking by adjusting parameters (e.g. braking condition, planning frequency)