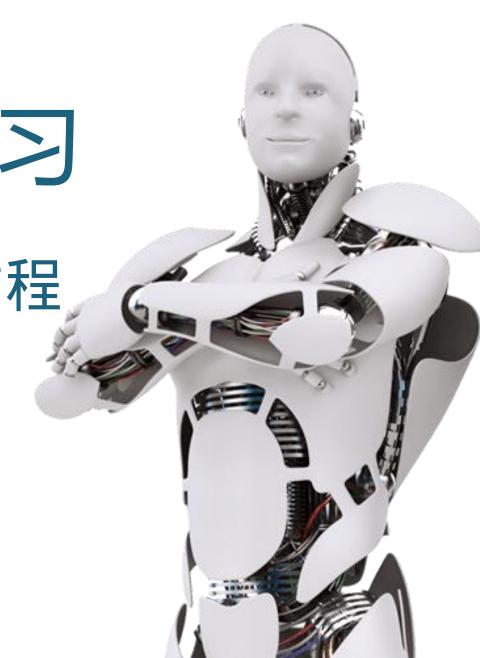
彪哥带你学强化学习

5、彻底理解贝尔曼方程

DEEPLY UNDERSTAND REINFORCEMENT LEARNING

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意义:可以在后面步骤没走完的情况下 计算前面步骤的价值,为时序差分、动 态规划等算法提供了理论指导

是什么

- 1. 用后一步的价值表示前一步的价值
- 2. 类似递推公式
- 3. 有多种不同表达形式

$$V^{\pi}(s_t) = R_t + \gamma \mathbb{E}_{S_{t+1}}[V^{\pi}(S_{t+1})|S_t = s_t]$$

为什么学

- 1. 是后面算法的基础
- 2. 可以加深对模型的理解

怎么学 以理解含义为主,要会数学公式推导

比如:

Vt+1 -> Qt

Qt+1 -> Vt

 $Vt+1 \rightarrow Vt$

Qt+1 -> Qt

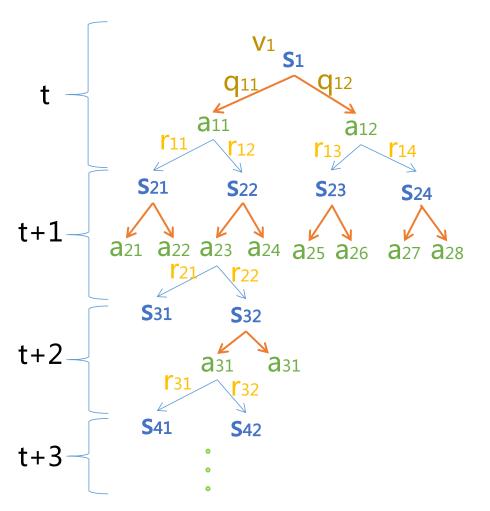
Q*t+1 -> Q*t

V*t+1 -> V*t

贝尔曼方程 Vt+1到Qt

$$Q^{\pi}(s_t, a_t) = \mathbb{E}_{S_{t+1} \sim p(\cdot | s_t, a_t)}[R_t + \gamma V^{\pi}(S_{t+1})]$$

$$egin{aligned} Q^{\pi}(s_t, a_t) &\stackrel{ riangle}{=} \mathbb{E}^{\pi}(G_t | S_t = s_t, A_t = a_t) \ &= \mathbb{E}^{\pi}(R_t + \gamma R_{t+1} + \gamma^2 R_{t+2} + \dots | S_t = s_t, A_t = a_t) \ &= \mathbb{E}^{\pi}(R_t + \gamma (R_{t+1} + \gamma R_{t+2} + \dots) | S_t = s_t, A_t = a_t) \ &= \mathbb{E}^{\pi}(R_t + \gamma V^{\pi}(S_{t+1}) | S_t = s_t, A_t = a_t) \ &= \mathbb{E}_{S_{t+1} \sim p(\cdot | s_t, a_t)} [R_t + \gamma V^{\pi}(S_{t+1})] \end{aligned}$$



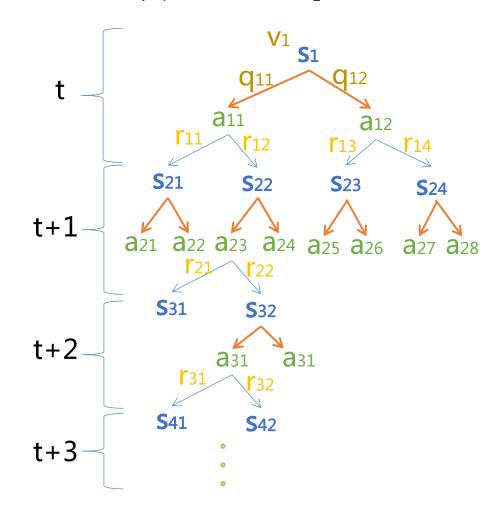
$$Q^{\pi}(s_t, a_t) = \mathbb{E}_{S_{t+1} \sim p(\cdot | s_t, a_t)}[R_t + \gamma V^{\pi}(S_{t+1})]$$

$$Q^{\pi}(s_t, a_t) = \mathbb{E}_{S_{t+1} \sim p(\cdot | s_t, a_t)}[R(s_t, a_t, S_{t+1}) + \gamma V^{\pi}(S_{t+1})]$$

$$Q^{\pi}(s_t, a_t) = \mathbb{E}_{S_{t+1}}[R(s_t, a_t, S_{t+1}) + \gamma V^{\pi}(S_{t+1}) | S_t = s_t, A_t = a_t]$$

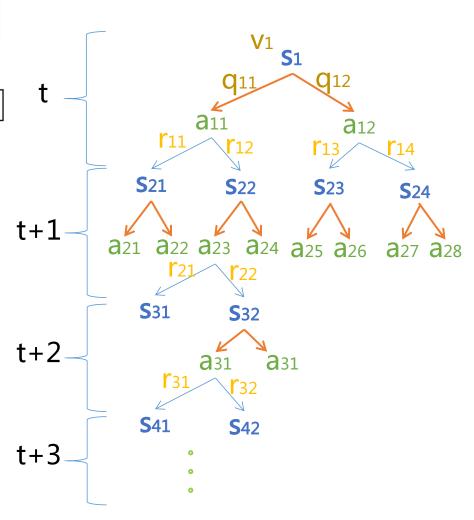
$$Q^{\pi}(s_t, a_t) = \sum_{S_{t+1} \sim p(\cdot | s_t, a_t)} p(S_{t+1} | s_t, a_t) [R(s_t, a_t, S_{t+1}) + \gamma V^{\pi}(S_{t+1})]$$

$$V^{\pi}(s_t) = R_t + \gamma \mathbb{E}_{S_{t+1},A_{t+1}}[Q^{\pi}(S_{t+1},A_{t+1})|S_t = s_t]$$



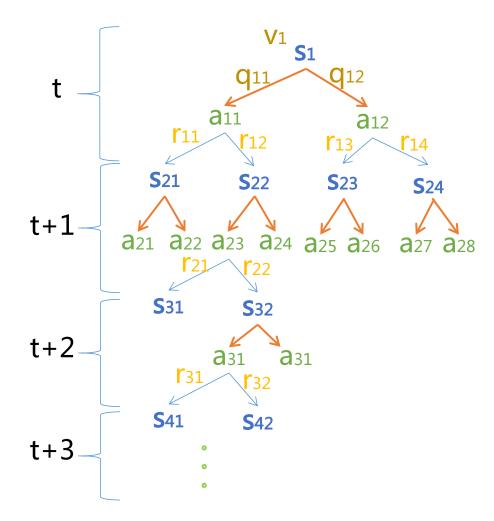
$$V^{\pi}(s_t) = R_t + \gamma \mathbb{E}_{S_{t+1}}[V^{\pi}(S_{t+1})|S_t = s_t]$$

$$V^{\pi}(s_t) = \mathbb{E}_{A_t,S_{t+1}}[R(s_t,A_t,S_{t+1}) + \gamma V^{\pi}(S_{t+1})|S_t = s_t]$$
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贝尔曼方程 Qt+1到Qt

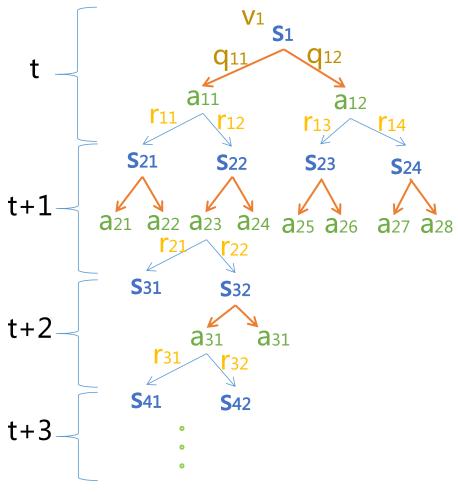
$$Q^{\pi}(s_t, a_t) = \mathbb{E}^{\pi}_{S_{t+1}, A_{t+1}}[R(s_t, a_t, S_{t+1}) + \gamma Q^{\pi}(S_{t+1}, A_{t+1}) | S_t = s_t, A_t = a_t]$$



贝尔曼最优方程 Q*t+1到Q*t

$$Q^{\star}(s_t, a_t) = \mathbb{E}_{S_{t+1} \sim p(\cdot | s_t, a_t)}[R(s_t, a_t, S_{t+1}) + \gamma \max_{A_{t+1} \in \mathcal{A}} Q^{\star}(S_{t+1}, A_{t+1})]$$

$$Q^{\star}(s_t, a_t) = \sum_{S_{t+1} \sim p(\cdot | s_t, a_t)} p(S_{t+1} | s_t, a_t) [R(s_t, a_t, S_{t+1}) + \gamma \max_{A_{t+1} \in \mathcal{A}} Q^{\star}(S_{t+1}, A_{t+1})] \quad \mathsf{t}$$



贝尔曼最优方程 V*t+1到V*t

$$V^{\star}(s_t) = \max_{A_t \in \mathcal{A}} (\sum_{S_{t+1} \sim p(\cdot | s_t, A_t)} p(S_{t+1} | s_t, A_t) [R(s_t, A_t, S_{t+1}) + \gamma V^{\star}(S_{t+1})])$$

