

<b>Practical Assignment No. 2</b>	
<b>Title:</b>	Continuous Probability Distribution and Naive Bayes
<b>Problem Statement:</b>	Generate data that follows continuous probability distributions. Implement a Naive Bayes classifier for continuous data using any programming language.
<b>Objective:</b>	To apply mathematical concepts in computer science for solving the problems.
<b>Outcome:</b>	CO505.1: Implement the program to solve the problems using probability.
<b>Software or Hardware Requirements:</b>	Anaconda/Java/GCC
<b>Theory:</b>	<p><b>Naive Bayes Classifier</b></p> <p><b>(Bayes' Rule)</b> If the events <math>B_1, B_2, \dots, B_k</math> constitute a partition of the sample space <math>S</math> such that <math>P(B_i) \neq 0</math> for <math>i = 1, 2, \dots, k</math>, then for any event <math>A</math> in <math>S</math> such that <math>P(A) \neq 0</math>,</p> $P(B_r A) = \frac{P(B_r \cap A)}{\sum_{i=1}^k P(B_i \cap A)} = \frac{P(B_r)P(A B_r)}{\sum_{i=1}^k P(B_i)P(A B_i)} \quad \text{for } r = 1, 2, \dots, k.$ <p>Using the chain rule, the likelihood <math>P(X   C_k)</math> can be decomposed as:</p> $P(X   C_k) = P(x_1, \dots, x_n   C_k) = P(x_1   x_2, \dots, x_n, C_k)P(x_2   x_3, \dots, x_n, C_k) \cdots P(x_{n-1}   x_n, C_k)P(x_n   C_k)$ <p><b>Naive independence assumption</b></p> <p>The above sets of probabilities can be hard and expensive to calculate. Fortunately, with the naive conditional independence assumption, which is stated as:</p> $P(x_i   x_{i+1}, \dots, x_n   C_k) = P(x_i   C_k)$ <p>We can get:</p> $P(X   C_k) = P(x_1, \dots, x_n   C_k) = \prod_{i=1}^n P(x_i   C_k)$ <p>And the posterior probability can then be written as:</p> $P(C_k   X) = \frac{P(C_k) \prod_{i=1}^n P(x_i   C_k)}{P(X)}$

## Naive Bayes model

Since the prior probability of predictor  $P(X)$  is constant given the input, we can get:

$$P(C_k|X) \propto P(C_k) \prod_{i=1}^n P(x_i | C_k)$$

where  $\propto$  means positive proportional to.

The Naive Bayes classification problem then becomes: for different class values of  $C_k$ , find the maximum of  $P(C_k) \prod_{i=1}^n P(x_i | C_k)$ . This can be formulated as:

$$\hat{C} = \arg \max_{C_k} P(C_k) \prod_{i=1}^n P(x_i | C_k)$$

The prior probability of class  $P(C_k)$  could be calculated as the relative frequency of class  $C_k$  in the training data.

The fundamental Naive Bayes assumption is that each feature makes an:

- Feature independence
- Continuous features are normally distributed
- Discrete features have multinomial distributions
- Features are equally important
- No missing data

### Types of Naive Bayes Model

There are three common types of Naive Bayes Model:

- 1) Gaussian Naive Bayes classifier
- 2) Multinomial Naive Bayes
- 3) Bernoulli Naive Bayes

### Applications of Naive Bayes Algorithms

- Real-time Prediction
- Multi-class Prediction
- Text classification/ Spam Filtering/ Sentiment Analysis
- Recommendation System

### Important Concepts-

A **random variable** is a function that associates a real number with each element in the sample space.

If a sample space contains an infinite number of possibilities equal to the number of points on a line segment, it is called a **continuous sample space**.

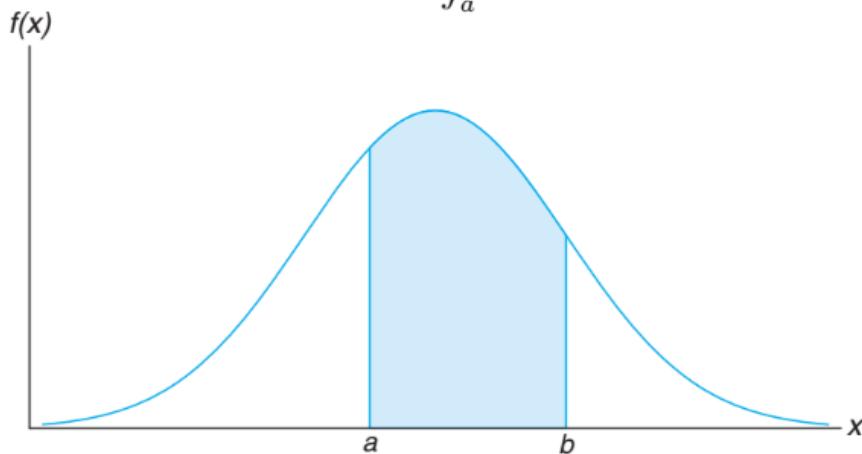
When a random variable can take on values on a continuous scale, it is called a **continuous random variable**.

The function  $f(x)$  is a **probability density function** (pdf) for the continuous random variable  $X$ , defined over the set of real numbers, if

1.  $f(x) \geq 0$ , for all  $x \in R$ .
2.  $\int_{-\infty}^{\infty} f(x) dx = 1$ .
3.  $P(a < X < b) = \int_a^b f(x) dx$ .

In Figure below, the probability that  $X$  assumes a value between  $a$  and  $b$  is equal to the shaded area under the density function between the ordinates at  $x = a$  and  $x = b$ , and from integral calculus is given by

$$P(a < X < b) = \int_a^b f(x) dx.$$



The **cumulative distribution function**  $F(x)$  of a continuous random variable  $X$  with density function  $f(x)$  is

$$F(x) = P(X \leq x) = \int_{-\infty}^x f(t) dt, \quad \text{for } -\infty < x < \infty.$$

As an immediate consequence of Definition above, one can write the two results

$$P(a < X < b) = F(b) - F(a) \text{ and } f(x) = \frac{dF(x)}{dx},$$

if the derivative exists.

The function  $f(x, y)$  is a **joint density function** of the continuous random variables  $X$  and  $Y$  if

1.  $f(x, y) \geq 0$ , for all  $(x, y)$ ,
2.  $\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) dx dy = 1$ ,
3.  $P[(X, Y) \in A] = \int \int_A f(x, y) dx dy$ , for any region  $A$  in the  $xy$  plane.

The **marginal distributions** of  $X$  alone and of  $Y$  alone are

$$g(x) = \sum_y f(x, y) \quad \text{and} \quad h(y) = \sum_x f(x, y)$$

for the discrete case, and

$$g(x) = \int_{-\infty}^{\infty} f(x, y) dy \quad \text{and} \quad h(y) = \int_{-\infty}^{\infty} f(x, y) dx$$

for the continuous case.

Let  $X$  and  $Y$  be two random variables, discrete or continuous. The **conditional distribution** of the random variable  $Y$  given that  $X = x$  is

$$f(y|x) = \frac{f(x, y)}{g(x)}, \quad \text{provided } g(x) > 0.$$

Similarly, the conditional distribution of  $X$  given that  $Y = y$  is

$$f(x|y) = \frac{f(x, y)}{h(y)}, \quad \text{provided } h(y) > 0.$$

Let  $X_1, X_2, \dots, X_n$  be  $n$  random variables, discrete or continuous, with joint probability distribution  $f(x_1, x_2, \dots, x_n)$  and marginal distribution  $f_1(x_1), f_2(x_2), \dots, f_n(x_n)$ , respectively. The random variables  $X_1, X_2, \dots, X_n$  are said to be mutually **statistically independent** if and only if

$$f(x_1, x_2, \dots, x_n) = f_1(x_1)f_2(x_2) \cdots f_n(x_n)$$

for all  $(x_1, x_2, \dots, x_n)$  within their range.

If  $X$  is a random variable with CDF-  $F$ , then  $F(X)$  follows a uniform distribution between 0 and 1. This opens up the possibility of generating artificial data with any desired distribution, given that we know  $F$ . The process is as follows:

1. Generate a random value  $y$  uniformly from the interval  $[0, 1]$ .
2. Compute  $F^{-1}(y)$ , which is the inverse function of  $F$  evaluated at  $y$ .

There are three common probability distributions that can be used to generate data:

- Uniform

	<ul style="list-style-type: none"> <li>● Binomial</li> <li>● Gaussian</li> </ul> <p>(*Data generation using any one of above method followed by Naive Bayes)</p>
<b>Input/Datasets/Test Cases:</b>	Size of data to be generated and range.
<b>Results:</b>	Print histogram of data generated. Write result values in table
<b>Analysis and conclusion:</b>	Write your own analysis of output and conclusion( Minimum 1 statement Analysis, Minimum 1 Statement Conclusion)
<b>References:</b>	Reference Links(Any 2)