Mengrui Han Email: mengrui.han@connect.polyu.hk

Personal Website: https://hanmirror.github.io/web/index.html

EDUCATION

	EDUCATION
01/2023-now	Hong Kong Polytechnic University
	PhD of Philosophy, Electrical and Electronic Engineering
10/2022-11/2023	Imperial College London
00/2017 07/2021	MSC of Applied Computational Science and Engineering
09/2017-07/2021	Beijing University of Technology
	Bachelor of Engineering in Measurement and Control Technique and Instrument(First Class Honours Degree), Average Mark: 88.16% (Top 5%), GPA: 3.66
	Degree), Average Mark. 88.10 /8 (10p 5 /8), GrA. 3.00
	RESEARCH EXPERIENCE
05/2023-now	C++ HPC MPI project: Solving the Navier Stokes Equation
	> Develop a parallel solver for the Navier-Stokes equation with performance evaluation on IC's High-
	Performance Computing system
03/2023-04/2023	C++ project: Image processing tool for 2D and 3D data
	 Offering features including filter application, color correction, data volume slicing, and projection
	generation
12/2022	DL project: Using cVAE and cGAN to process Fashion MNIST dataset
	Develop a Conditional Variational Autoencoder and a Conditional Generative Adversarial Network
	leveraging the YOLOv5 architecture
12/2019-06/2021	Graduation Thesis: Lightweight Method of Laser Tracing System Mechanical Structure
	Based on 3D Topology Optimization
	Awarded Excellent Graduation Project in Beijing and published a paper in the Journal of Harbin
	Engineering University Created optimised algorithms within MATLAB to improve the performance of this platform
	 Created optimised algorithms within MATLAB to improve the performance of this platform Reduce the weight of the platform by 55%
	 Used Autodesk Inventor to implement modelling, simulation and stress analysis, and finalised vibration
	experiment
04/2018-09/2018	Researcher, Support Vector Machine-Based Gear Defect Detection Software System Design
0 1/2010 05/2010	> Created algorithm with MATLAB and input the sound of gear rotation into support vector machine to
	identify whether gears were good
	Achieved 93% accuracy
05/2018-08/2018	Member, A Smart Mobility Robot for Senior Citizens
	Dobtained the First Prize (twice, national level) respectively in China Robot Competition, Service-Based
	Robot Band and China Robot Competition
	Build an intelligent robot based on a robot operating system (ROS) combining a laser radar, Kinect
	motion sensors and simultaneous localisation and mapping (SLAM) techniques
10/2018-06/2019	Researcher, Rubik's Cube-Based Restoring Robot
	Employed Autodesk Inventor to model and design the structure, visualised main components of this
	structure by 3D printing technology
	Created algorithm based on machine vision to identify Rubik's cube's status with Python and Opency
10/2010 12/2010	Increased the accuracy of this algorithms to above 97% after denoising, image-splitting and recognition
10/2018-12/2018	Team Leader, AVG Car Design based on PID control Design and makes a trailing part in 2018 China Bahat Ability Commetition, and want the First Duige
	 Design and make a trailing car in 2018 China Robot Ability Competition, and won the First Prize Developed a computer programme to capture PID parameters of four wheels of the car
01/2010 05/2010	Member, Four Tracked Lunar Service Robot
01/2019-05/2019	Senerated 3D model of lunar service robot with Autodesk Inventor, awarded the First Prize in the 2019
	National College Students' Mechanical Products Digital Design Competition
09/2019-11/2020	Team Leader, Fall Prevention Walking Aid for Seniors
05.2015 11/2020	Designed and generated a fall prevention device with folding seat, speed limiting device and reverse
	device in 2020 National Undergraduate Mechanical Innovation Competition, and got the First Place (the
	national level)
	INTERNSHIP EXPERIENCE
01/2022-05/2022	Qingqingjieneng Technology Co., Ltd(Tsinghua Automotive Strategy Research Institute, TASRI))
U1/4U44-U3/4U44	Pure hydrogen mileage and data analysis (algorithm of jiaoyanyuan Institute)
	Data platform for search and model conversion (Technology serviced for 2022 Rejijing Winter Olympics

Data platform for search and model conversion (Technology serviced for 2022 Beijing Winter Olympics

Complete the group and Futian enterprise standard

Dr. Jin zhenhuan(Tsinghua University) acted as my supervisor during the internship

FYTDA	CURRICUL	ARA	CTIX	TTIFC
LAIN	CUNNICUL		\mathbf{c}	

09/2018-09/2019 Director, Science and Technology Association of Beijing University of Technology

Planned and organised a wide range of contests, lectures, salons

Volunteer, Volunteer Activities (100 Hours) 02/2018-09/2019

Work as an international volunteer in Sri Lanka and Nepal

SKILLS

- Language Skills: English-good, German-primary, French-basic, Korean-basic, Japanese-basic
- Computer Skills: MATLAB, Inventor, SolidWorks, CAD, ANSYS, Labview, KICAD, Arduino, STM32 (keil), C++, Python
- Hobbies: Mechanical Structure Design, Robot Design, Kendo, Reading, Play Chinese Chess

	PUBLISH
10/2021	Lightweight method of laser tracing system mechanical structure based on topology optimization
	(https://scholar.google.com/scholar?hl=zh-CN&as_sdt=0%2C5&q=激光追踪系统机械结构拓扑优化轻量化
	方法&btnG=)
02/2022	Generative design for self-balancing unicycle robot in additive
	manufacturing(https://doi.org/10.1117/12.2639454)

PATENTS & SOFTWARE COPYRIGHT & CERTIFICATE

Patents:	
08/2020	Utility Model Patent for an Optimisation Method of Mechanical Structure Weight Reduction for Laser
	Tracking Measurement System Based on 3D Topology Optimisation (No.2020108966114)
03/2020	Utility Model of a Device and Interactive Platform Algorithm for Rubik's Cube-Based Restoring
	Teaching and Training (No.202010246767.8)
12/2019	Utility Model Patent for Fall Prevention Walking Aid for Seniors (No. 201911384811.5)
12/2019	Utility Model Patent for A Reduction Device Featuring Slope Reversion (No. 201911384794.5)
04/2019	Utility Model Patent for Four Tracked Device for Lunar Rover to Assist Astronauts in Operations and
	Building Lunar Bases (No. 201910336772.5)

Software Copyrights:

04/2021	CMM Temperature Supplement Secondary Development System Based on Rational DIMS 7.1
05/2020	Measurement Uncertainty Analysis Software for Laser Heterodyne Interference System
11/2019	Stepper Motor Precision Control System Based on STM32 (V1.0)
11/2019	Rubik's Cube-Based Multifunctional Restoring Teaching Platform (V1.0)
11/2018	Support Vector Machine-Based Gear Detection Software System (V1.0)
Certificate:	

Certificate of Trainee Engineer of Instrument, Control and Measurement (awarded by China Instrument and 10/2020 Control Society)

AWARDS		
07/2021	Outstanding Undergraduate Award in Beijing (Top 5%)	
07/2021	Outstanding Undergraduate Graduation Project in Beijing (Top 1%)	
07/2021	A-level Outstanding Bachelor Thesis of Engineering in Measurement and Control Technique and Instrument Major in China	
08/2020	First Prize in the 14th University Computer Games Championship & National Computer Games Tournament	
09/2019	Beijing University of Technology Innovation and Entrepreneurship Scholarship	
09/2019	National Encouragement Scholarship	