

ClassPurePursuit

- + ClassPurePursuit()
- + ~ClassPurePursuit()
- + setVehicleWheelbaseMeter()
- + setTargetLinearSpeedMps()
- + setLookAheadCoefficient()
- + setPathSegment()
- + setRobotPose()
- + findTargetPoint()
- + getTargetPoint()
- + solveForSpeedCommand()
- + findPreciseTargetPoint()