

Bridgeland Stability

so: π -stability for D-branes in
String theory

aka : The hardwavey part.

[Douglas 2001]

$N=2$ Superconformal field theory
SCFT

SCFT + topological twist
 $\underbrace{\qquad\qquad\qquad}_{\text{}} \qquad \qquad \qquad \text{(TCFT)}$

A_∞ -category

SCFT + \mathcal{D}

$\mathcal{L} \rightsquigarrow$ same \mathcal{D}

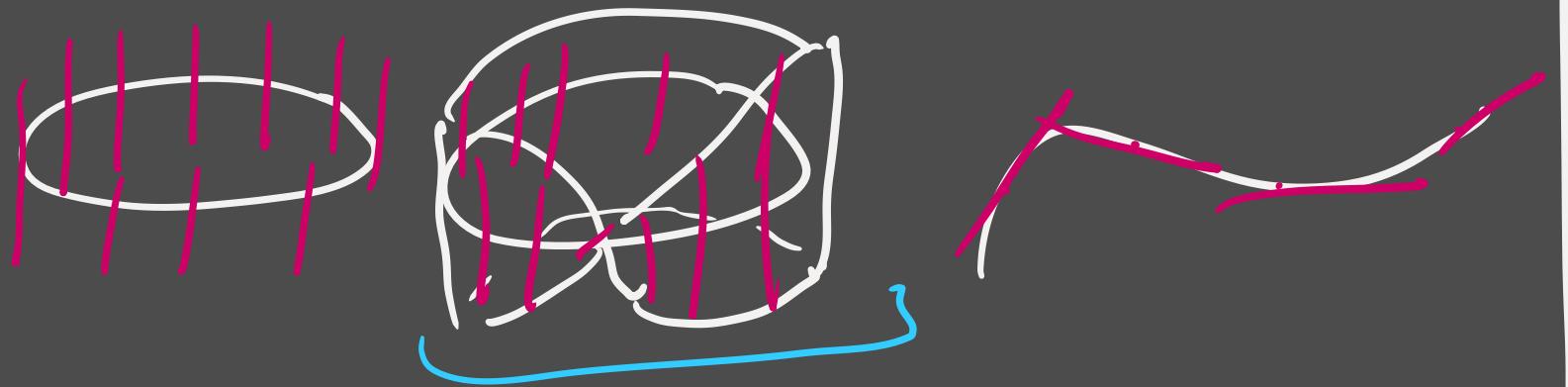
R-stability \leftrightarrow Q: Why is \mathcal{D} special

$\rightsquigarrow \chi(E), \phi(\epsilon)$
 $E \in \mathcal{D}$

gl Stability

Mumford '62: slope stability for vector bundles on curves.

E : vector bundle on a smooth curve C



$$\text{Slope : } \mu(E) = \frac{\deg(E)}{\text{rank}(E)}$$

E is M -stable if $0 \neq F \subseteq E$,
 $\mu(F) < \mu(E)$

$$\leq$$

e.g. L line bundle (rank=1)

$$\mu(L) = \deg(L)$$

$0 \neq F \subseteq L$ must have rank=1

but $\deg(F) < \deg(L)$

$\therefore L$ is stable

IN FACT: Stable bundles are the building
blocks for all vector bundles over C

M : moduli space of vector bds \mathcal{M}

$M_{r,d}$: E : vector bds, rank = r
degree = d

$\hookrightarrow M_{r,d}^{\text{st}}$ is "nice"

Also: (oh (C) similar thing:

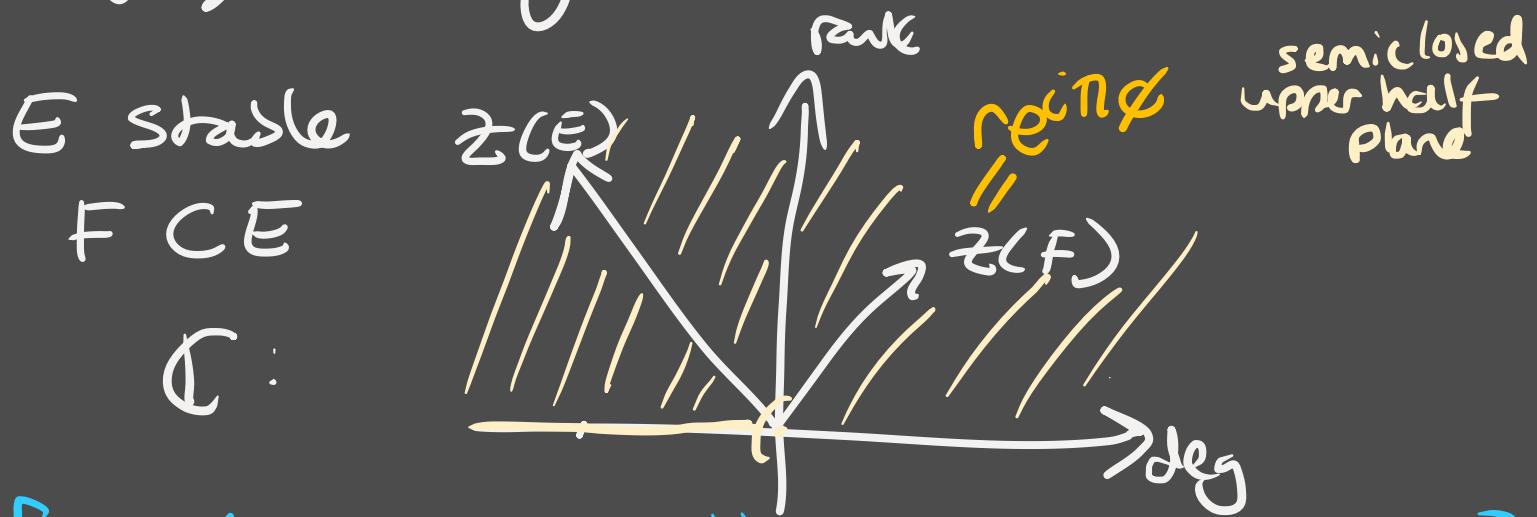
e.g. \mathbb{P}^1 : $\text{Coh}(\mathbb{P}^1)$ generated by line bds

and skyscraper sheaves. $\mathcal{O}(n) \times$

$x \in X \rightsquigarrow \mathcal{O}_x$

\mathcal{O}_x

$$z(E) = -\deg(E) + \text{rank}(E) \in \mathbb{H}$$



[we will see later in "P(ϕ)" def. why we use ϕ not $\text{Arg}(z)$]

Stability for Quivers

- Q finite quiver, $Q_0 = \{0, \dots, n\}$
- Consider $\text{Rep}_k Q$

Example

$$\rho_2: \quad \begin{matrix} \circ & \xrightarrow{x} & | \\ & \downarrow y & \\ & | & \end{matrix}$$

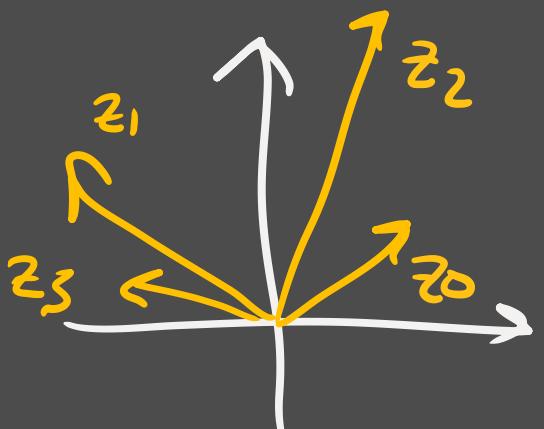
$$\underline{V} \in \text{Rep}_k Q : (V_0, V_1, \phi_x, \phi_y : V_0 \rightarrow V_1)$$

e.g.:

$$\begin{matrix} \mathbb{C} & \xrightarrow{\lambda^e} & \mathbb{C} \\ & \xrightarrow{\mu} & \end{matrix}$$

and more
generally:

$$\underline{V}: \quad \mathbb{C}^n \xrightarrow{\phi_x} \mathbb{C}^m$$



Prk $z_0, \dots, z_n \in \mathbb{H}$

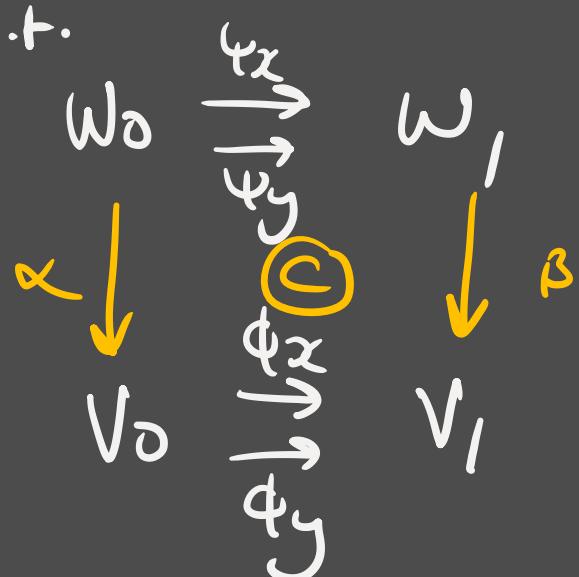
$$\begin{aligned} Z(\underline{V}) &= \sum_{i=0}^n \dim V_i \cdot z_i \\ &= r e^{i \pi \phi} \end{aligned}$$

\underline{V} is stable if $\underline{w} \subset \underline{v} \Rightarrow \phi(\underline{w}) \leq \phi(\underline{v})$

* 0

e.g. P_2 : Pick $z_0, z_1 \in H$

RECALL: $\underline{W} = (w_0, w_1, \Psi_x, \Psi_y)$ is a subrep. of $\underline{V} = (V_0, V_1, \Phi_x, \Phi_y)$ if $w_0 \subset V_0$ and $w_1 \subset V_1$ as subvector spaces, and $\exists \alpha, \beta$ linear maps s.t.

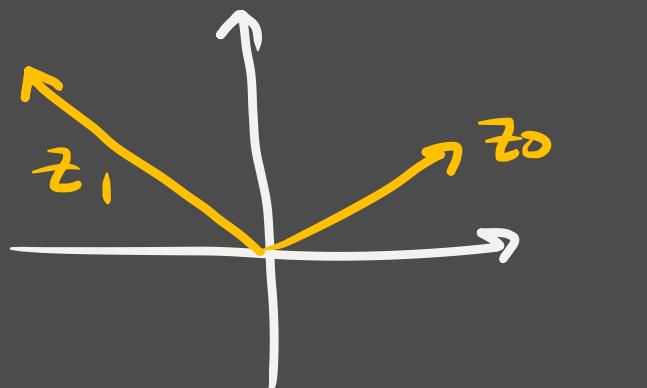


HENCE If \underline{V} is a subrep of P_2 then:

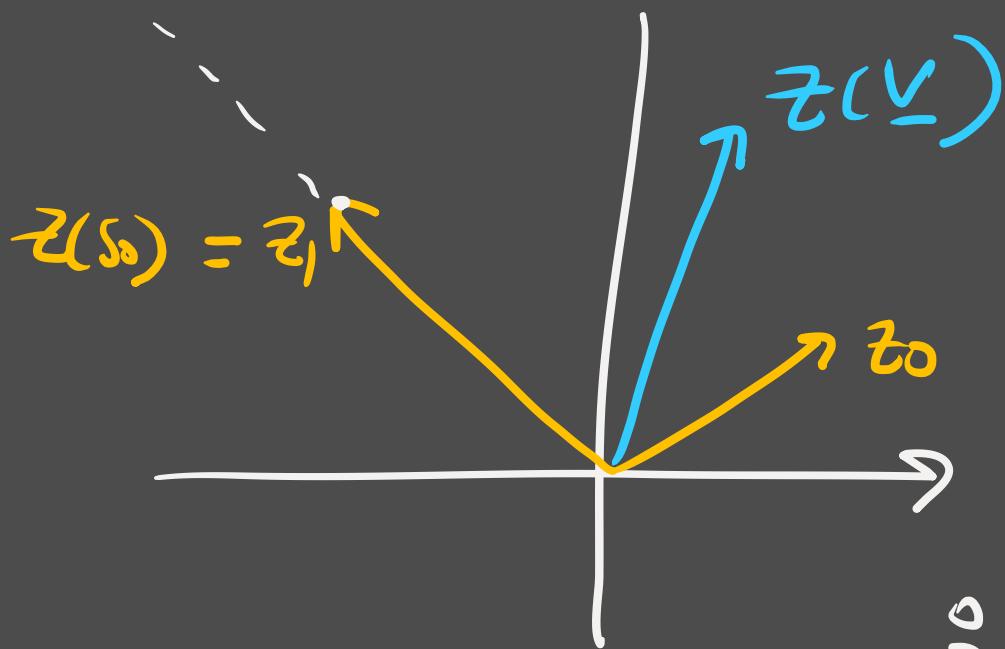
$$\begin{aligned} S_0: \quad 0 &\xrightarrow{0} \mathbb{C} && \text{(simple rep.)} \\ &\downarrow 0 & \downarrow \alpha \\ \underline{V}: \quad \mathbb{C}^n &\xrightarrow{\Phi_x} \mathbb{C}^m \\ &\downarrow \Phi_y & \end{aligned}$$

If $m > 0$ then S_0 is always a subrep. of \underline{V} .

Suppose $\phi(z_1) > \phi(z_0)$:



- $\bar{z}(s_0) = z_1$
- If $\lambda > 0$, $\phi(s_0) > \phi(v)$, so v is not stable.



Similar argument for $s_1: \mathbb{C} \xrightarrow{\phi} \mathbb{C}$
shows that s_0, s_1 are the only stable reps

Suppose instead $\phi(z_1) < \phi(z_0)$:

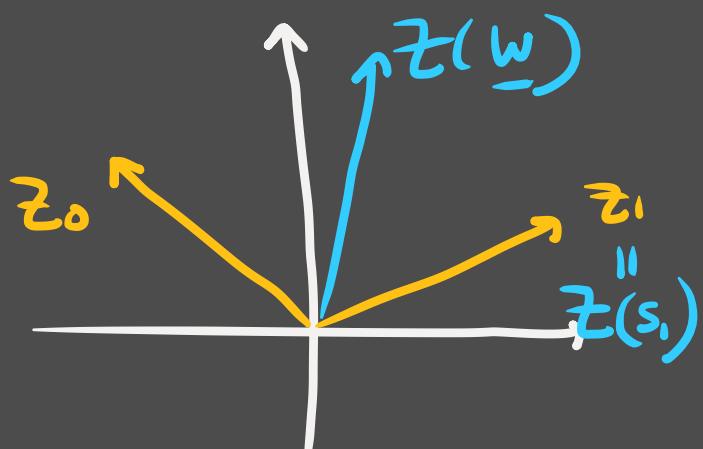
Consider:

$$S_1: \mathcal{O} \xrightarrow{\alpha} \mathcal{O}$$

$\downarrow \alpha$

$$\underline{w}: \mathcal{O} \xrightarrow{\gamma} \mathcal{O}$$

$\downarrow \mu$



$$\Rightarrow \phi(S_1) < \phi(\underline{w})$$

Hence S_1 does not destabilise \underline{w} .

Moreover:

$$S_0: \mathcal{O} \xrightarrow{\alpha} \mathcal{O} \quad \text{commutes} \Leftrightarrow (\gamma, \mu) = (0, 0)$$

$\downarrow \alpha \qquad \downarrow \mu$ IN PARTICULAR:

$$\underline{w}: \mathcal{O} \xrightarrow{\gamma} \mathcal{O} \quad (\gamma, \mu) \neq (0, 0) \Rightarrow \underline{w} \text{ stable}$$

Remark:

stable objects

$$\mathcal{O} \xrightarrow{\gamma} \mathcal{O} \text{ up to } \xleftarrow[\text{iso.}]{} \text{1:1 points in } \mathbb{P}^1$$

This hints at:

$$D^b(\text{Rep}_{\mathbb{C}}(\mathbb{G}_m)) \cong D^b(\mathbb{P}^1_{\mathbb{C}})$$

Slope stability

- \mathcal{E}, \mathcal{F} vector bundles or $\text{Coh}(X)$
- \mathcal{E} semistable of phase ϕ
 $\mathcal{F} \hookrightarrow \mathcal{E} \Rightarrow \phi(\mathcal{F}) \leq \phi(\mathcal{E})$
If \mathcal{E} is S.S., \exists no map $\mathcal{F} \rightarrow \mathcal{E}$
 $\phi(\mathcal{F}) > \phi(\mathcal{E})$
- \mathcal{E} stable bundle of phase ϕ
 $\mathcal{F} \hookrightarrow \mathcal{E} \Rightarrow \phi(\mathcal{F}) < \phi(\mathcal{E})$
 \mathcal{E} has no nontrivial subbundles
of same phase
- Slope-stable bundles/sheaves are building blocks of $\text{Coh}(X)$ /vector fields
- $\chi(\mathcal{E}) = -\deg(\mathcal{E}) + i \text{rank}(\mathcal{E}) \in \mathbb{H}$
- If $\mathcal{E} \neq 0$, $\chi(\mathcal{E}) = \frac{m(\mathcal{E})}{e(R_{>0})} e^{i\pi\phi}$

Bridged stability $\sigma = (\rho, \tau)$

- $\mathcal{E}, \mathcal{F} \in \mathcal{D}$: triangulated category 

- $\mathcal{E} \in \underline{\mathcal{P}(\phi)}$ subcategory of \mathcal{D} $\forall \phi \in \mathbb{R}$

$\phi_1 > \phi_2, \mathcal{F} \in \mathcal{P}(\phi_1), \mathcal{E} \in \mathcal{P}(\phi_2)$

$$\text{Hom}(\mathcal{F}, \mathcal{E}) = 0$$

- $\mathcal{E} \in \mathcal{P}(\phi)$ is stable if \mathcal{E} is a simple object of $\mathcal{P}(\phi)$

- $\mathcal{P}(\phi)[1] = \mathcal{P}(\phi + 1)$

(Recall: $A \rightarrow B \rightarrow C \rightarrow A[1]$ exact triangle)

- stable objects: building blocks of \mathcal{D}

- $\tau : \underline{\mathcal{K}(\mathcal{D})} \rightarrow \mathbb{C}$ group homomorphism
[Grothendieck group, $A \rightarrow B \rightarrow C \rightarrow A[1]$]

If $\mathcal{E} \neq 0, \mathcal{E} \in \mathcal{P}(\phi)$: $\Rightarrow [B] = [A] + [C]$

$$\tau(\mathcal{E}) := \tau([\mathcal{E}]) = \underbrace{m(\mathcal{E})}_{\mathcal{K}(\mathcal{D})} \cdot e^{i\pi\phi} \quad \epsilon \in \mathbb{R}_{>0}$$

PLUS

- \mathbb{Z} factor via Δ for dm lattice
- "support property"

If Δ factors via $\text{Knum}(\mathcal{D})$, σ is called "numerical"

Rmk: can equivalently define:

$$\sigma = (\mathcal{A}, \mathbb{Z}_{\mathcal{A}})$$

heart of a bdd
t-structure on \mathcal{D}

Stability function
" $\mathbb{Z}_{\mathcal{A}} : \mathcal{A} \rightarrow \mathbb{H}$ "
+ N.N.

e.g. $\text{Rep } Q$ is a \mathfrak{D} for $D^b(\text{Rep } Q)$. Hence
 $\sigma = (\text{Rep } Q, \mathbb{Z})$ is a Bridgeland stability condition.
(from earlier)

Let X : sm. proj. variety / \mathbb{C} , $D^b(X) := D^b(\text{coh}(X))$.

Def'n A Bridgeland stability condition is geometric

if all skyscraper sheaves of points are stable
and of the same phase.

$$\mathcal{O}_x \leadsto x \in X$$

Bridgeland

$\text{Stab}_X := \{\text{all stability conditions on } X\}$

↳ Bri'07: This is a complex manifold
 $(P, z) \rightarrow z$ local coordinate

What we know:

- $\text{Stab}(\mathbb{P}^1) \cong \mathbb{C}^2$
- $\overset{\text{def}}{=} \text{Stab}(\text{Rep } P_2)$
- $\text{Stab}(C) \cong \widetilde{\text{GL}_2^+(\mathbb{C})}$
C: sm. proj. curve of $g > 1$
- $\text{Stab}(X)$ known when X : abelian surface

Thm [Liu Fu, Chung-i Li, Xiaolei Zhao]

X has finite Albanese morphism \Rightarrow all stability conditions are geometric

$$X \xrightarrow{a'} \text{Alb}(X) = \text{Pic}^0(P_{\mathcal{A}^0}(X))$$

\downarrow $\mathcal{B} \subset \mathcal{E}$!
abelian