

# Hannah Lee

[hannah9@illinois.edu](mailto:hannah9@illinois.edu) | (720) 618-5152 | <https://hannahjmlee.github.io/>

## Professional Summary

---

PhD student at the University of Illinois Urbana-Champaign specializing in constraint-based search algorithms for multi-robot task and motion planning. Currently working with Dr. Nancy M. Amato at the Parasol Lab and collaborating with MIT Lincoln Laboratory on distributed path planning for large-scale multi-robot systems. Expected graduation in May 2025, actively seeking roles in industry and government.

## Education

---

### Doctor of Philosophy in Computer Science

University of Illinois at Urbana-Champaign

- Thesis: Studies in Constraint-Based Search for Multi-Robot Planning
- Advisor: Nancy M. Amato

Expected May 2025

GPA: 3.94/4.0

### Bachelor of Science in Computer Science

Colorado School of Mines

- Major: Computer Science – Robotics and Intelligent Systems
- Minor: Electrical Engineering – Digital Systems

Dec 2019

GPA: 3.95/4.0

## Research Interests

---

- Multi-Robot Task and Motion Planning
- Scalable Multi-Agent Systems
- Parallel Algorithms
- Distributed Multi-Robot Planning
- Navigation in Dynamic Environments
- Optimization Techniques for Robotics

## Awards and Honors

---

### Graduate Awards and Honors:

- NSF Graduate Research Fellowship, National Science Foundation

May 2020 – Aug 2023

### Undergraduate Awards and Honors:

- Summa Cum Laude, Colorado School of Mines
- Faculty Choice Senior Award, Colorado School of Mines CS Dept.
- Grace Hopper Celebration Research Scholarship, ACM-WP
- National Dean's List, Colorado School of Mines
- President's Scholarship, Colorado School of Mines

Dec 2019

Dec 2019

Oct 2019

Aug 2016 – Dec 2019

Aug 2016 – Dec 2019

## Skills

---

### Technical Experience:

- Task and Motion Planning
- Algorithms
- Computer Vision
- Multi-Robot Systems
- Artificial Intelligence
- Embedded Systems
- Robotics
- Machine Learning
- Software Engineering

### Programming Languages & Frameworks:

- C++
- R
- MATLAB
- Python
- C
- ROS
- Java
- Bash/Shell Scripting
- Solidworks (Certified)

## Peer-Reviewed Publications

---

- **Lee, Hannah**, Zachary Serlin, Marco Morales, and Nancy M. Amato. "PRISM: Online Decentralized Multi-Agent Pathfinding with Rapid Information Sharing using Motion Constraints"
  - Under Submission
- **Lee, Hannah**, James Motes, Marco Morales, and Nancy M. Amato. "An Analysis of Constraint-Based Multi-Agent Pathfinding Algorithms"
  - Under Submission
- **Lee, Hannah**, James Motes, Zachary Serlin, Marco Morales, and Nancy M. Amato. "Distributed Constraint-Based Search using Multi-Hop Communication", *Proceedings of the 2024 IEEE International Conference on Robotics and Automation (ICRA@40)*, 23-26 September 2024, Rotterdam.
  - Extended abstract presented at *ICRA@40*
- **Lee, Hannah**, James Motes, Marco Morales, and Nancy M. Amato. "Parallel Hierarchical Composition Conflict-Based Search for Optimal Multi-Agent Pathfinding." *IEEE Robotics and Automation Letters (RA-L)* 6, no. 4 (2021): 7001-7008.
  - Presented at the *2021 IEEE/RSJ International Conference on Intelligent Robotics and Systems (IROS)*
- Motes, James, Read Sandström, **Hannah Lee**, Shawna Thomas, and Nancy M. Amato. "Multi-robot task and motion planning with subtask dependencies." *IEEE Robotics and Automation Letters (RA-L)* 5, no. 2 (2020): 3338-3345.
  - Presented at the *2020 IEEE International Conference on Robotics and Automation (ICRA)*

## Technical Experience

---

### Graduate Research Assistant

Aug 2020 – Present

Parasol Lab, University of Illinois at Urbana-Champaign

- Engineered innovative hybrid task and motion planning algorithms, enhancing scalability and performance for multi-robot systems.
- Integrated multithreading and parallel programming techniques to significantly boost the efficiency of hybrid algorithms.
- Developed advanced multi-robot path planning algorithms for online, decentralized environments, enabling real-time coordination.
- Co-led the Open-Source initiative to make the Parasol Planning Library (PPL) publicly accessible, contributing to the development of novel planning algorithms in C++.

### Student Technical Assistant

May 2023 – Present

MIT Lincoln Laboratory

- Designed novel algorithms to enhance collaboration in multi-robot systems, improving efficiency and coordination.
- Developed planning frameworks and hierarchies optimized for decentralized systems, online planning and dynamic environments.
- Led projects on coordinating teams of surface vehicles for wide-area ocean mapping and synchronizing drone swarms for complex tasks.

### DREU Student Researcher

May 2019 – Aug 2020

Parasol Lab, University of Illinois at Urbana-Champaign

- Participated in the Distributed Research Experience for Undergraduates (DREU), sponsored by the Computing Research Association for Widening Participation (CRA-WP).
- Developed Task and Motion Planning Conflict-Based Search for optimal multi-agent multi-task planning, solving complex payload transportation with heterogeneous robot teams.

**Undergraduate Student Researcher**

Nov 2018 – Aug 2019

MInDS@Mines Lab, Colorado School of Mines

- MInDS: Machine learning, Informatics, and Data Science, led by Prof. Hua Wang.
- Collaborated with graduate students to apply machine learning techniques in deciphering complex interactions within diverse biological datasets.
- Developed innovative algorithms for analyzing large-scale, heterogeneous data, contributing to breakthroughs in biological data science.

**Software Intern**

June – Aug 2018

Ricoh USA, Inc.

- Redesigned an automated testing platform using JavaScript and Django to simulate and evaluate the efficiency, accuracy, and quality of cutsheet printer outputs.
- Enhanced efficiency and functionality by optimizing database operations, reducing redundant testing, and streamlining the user interface for a better user experience.

**Computer Science Capstone Project**

May – June 2018

Uber Technologies, Inc.

- Developed a proof-of-concept mobile application that verifies user locations by generating and comparing 3D models from 2D images.
- Automated image processing using Python and built a mobile application in Java to capture images and send them to a testing server.
- Leveraged openMVG, openSFM, and MeshLab libraries to analyze 2D images and construct accurate 3D models.

**Summer Intern**

May – Aug 2017

Computer Science Department, Colorado School of Mines

- Organized CS career events for high school students and presented at STEM Fairs in Denver elementary schools.
- Led summer camps for middle school students, teaching coding in Racket, Java (for video game programming and Finch robots), and Python (sensor systems and basic circuits).
- Conducted K-12 teacher workshops, including Python training for middle school teachers, managing CS Unplugged sessions for elementary teachers, and organizing the Computer Science Professional Development Week.

**Teaching Experience**

---

**Lead Instructor**

May 2022 – Present

**Instructor**

Aug 2021 – May 2022

**Teaching Assistant**

Jan – Aug 2021

AI4ALL

- AI4ALL: A program dedicated to expanding AI education to underrepresented groups, aiming to diversify the AI workforce.
- Lead Instructor for Ignite AI (2024 – Present) and Discover AI (2021 – 2023): Spearheaded courses that teach foundational AI and ML concepts, alongside critical discussions on ethics, tailored for undergraduates from a wide range of backgrounds.
- Mentored and guided new AI4ALL instructors, providing support and sharing best practices to ensure effective teaching and engagement.
- Designed and delivered interactive workshops and educational content for the Discover AI course, contributing to its success across all participating campuses.

## Adjunct Professor

Jan – May 2020

Computer Science Department, Colorado School of Mines

- Instructor for CSCI 261: Programming concepts: Taught a class of 60 students, providing a comprehensive introduction to programming with a focus on C++.
- Developed and organized course materials, including lectures, assignments, and assessments, ensuring the content was accessible and engaging for students from diverse academic backgrounds.
- Taught fundamental programming concepts in C++, including basic data structures and algorithms, tailored to meet the learning needs of students.
- Fostered a supportive learning environment by offering regular office hours, personalized feedback, and additional resources to help students grasp complex concepts and succeed in the course.

## Teaching Assistant

Jan 2017 – May 2020

Computer Science Department, Colorado School of Mines

- Teaching Assistant for CSCI 101: Introduction to Computer Science (Jan 2017 – May 2018) and CSCI 262: Data Structures (Aug 2018 – May 2020).
- Supported classroom instruction by assisting the instructor in delivering lectures and addressing student questions.
- Managed record keeping tasks, including tracking attendance, grading assignments, and maintaining accurate records of student performance.
- Contributed to the development of classroom materials, such as lecture slides, handouts, homework assignments, and exam questions, enhancing the learning experience for students.
- Provided one-on-one and group assistance to students, helping them with homework, projects, and exam preparation, and ensuring they understood key concepts in programming and data structures.

## Teaching Assistant

Aug 2017 – Dec 2018

## Web Manager

Jan 2018 – Dec 2019

DECTech, Colorado School of Mines

- DECTech (Discover, Explore, Create Technology) is a program designed to inspire and engage grade school girls by exposing them to STEM topics and potential careers in science and technology.
- Led weekly interactive activities, teaching a wide range of STEM topics, including programming, engineering principles, and scientific concepts, fostering curiosity and enthusiasm for STEM among young learners.
- Managed and maintained the DECTech website, ensuring that program information, resources, and updates were accessible and up to date, contributing to the program's outreach and communication efforts.

## Professional Activities

---

### Conference Presentation:

- |  |      |
|--|------|
| • <i>International Conference on Robotics and Automation (ICRA@40)</i>     | 2024 |
| • <i>International Conference on Intelligent Robots and Systems (IROS)</i> | 2021 |
| • <i>International Conference on Robotics and Automation (ICRA)</i>        | 2020 |
| • <i>Grace Hopper Celebration of Women in Computing</i>                    | 2019 |

### Conference Participation:

- |   |            |
|---|------------|
| • <i>Air, Missile, and Maritime Defense Technologies (AMMDT) Conference</i> | 2023, 2024 |
| • <i>International Conference on Intelligent Robots and Systems (IROS)</i>  | 2023       |
| • <i>CMD-IT/ACM Richard Tapia Conference</i>                                | 2021       |
| • <i>NSF RESET Conference</i>   | 2021       |

**Reviewer Roles:**

- Reviewer for *IEEE Robotics and Automation Letters (RA-L)* 2019 – Present
- Reviewer for *IEEE International Conference on Robotics and Automation (ICRA)* 2019 – Present
- Reviewer for *IEEE International Conference on Intelligent Robots and Systems (IROS)* 2020 – Present
- Reviewer for the *Workshop on the Algorithmic Foundations of Robotics (WAFR)* 2024 – Present

**Professional Memberships:**

- IEEE Graduate Student Member 2020 – Present
- Member of IEEE Robotics and Automation Society (RAS) 2020 – Present
- Member of Colorado School of Mines ACM-W 2018 – 2019

**Research Mentorships:**

- iCAN Students: one-year, cohort-based graduate certificate program where students from different disciplines learn the fundamentals of computing and research
  - Azhar Karypbayeva 2021
  - Ana Elissa Cabrera 2022-2023
- CS STARS: undergraduate students interested in pursuing undergraduate research while also serving as school leaders to recruit and empower women in CS
  - Athena Zheng 2022
  - Rachel Wei 2022
  - Mia Erdenebileg 2022 – 2024
  - Anushka Kansal 2022 – 2023
  - Nikhila Puppall 2022 – 2024
  - Melissa Aninagyei-Bonsu 2022 – 2024
- DREU and Open-Sourcing Students:
  - Tavie Kittredge 2022
  - Sam Pasquesi 2022 – 2023
  - Brad Yang 2022 – 2024