

RISK ZONE PREDICTION

Capstone Project 2020-2021

Multiprotexion

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1 Introduction

Multiprotexion is a company that provides satellite, data, and active video surveillance security for the transportation and logistics business, focused on preventing events such as cargo and warehouse thefts and robberies. It is a partner of many international distribution, transportation, and logistics companies.

Multiprotexion offers a range of devices which aim at protecting drivers, goods, and vehicles. These devices create a lot of data. It is essential to analyse and evaluate the collected data. This data can be used to develop new devices and sensors, as well as providing a base for developing predictive models.

The goal of this project is to analyse the collected data and determine the potentially dangerous regions for a truck. This could be useful for deciding whether to equip a truck with additional security devices when it needs to travel through a risk zone, or maybe to decide whether to avoid driving through certain zones.

2 Dataset

Multiprotexion provided two databases containing information about events triggered by sensors or other security devices, and the associated location, driver, reasons the event was triggered, which action was taken to remedy the event, and many more.

Figure 1 shows the tables present in the database “dbcentrale” and their relations. Attributes have been omitted for space reasons. The complete ER-diagrams for both databases can be found in the Appendix.

The data was provided via two databases. We downloaded the relevant information and saved it in csv files so as to not have to access the database each time we need to access the data.

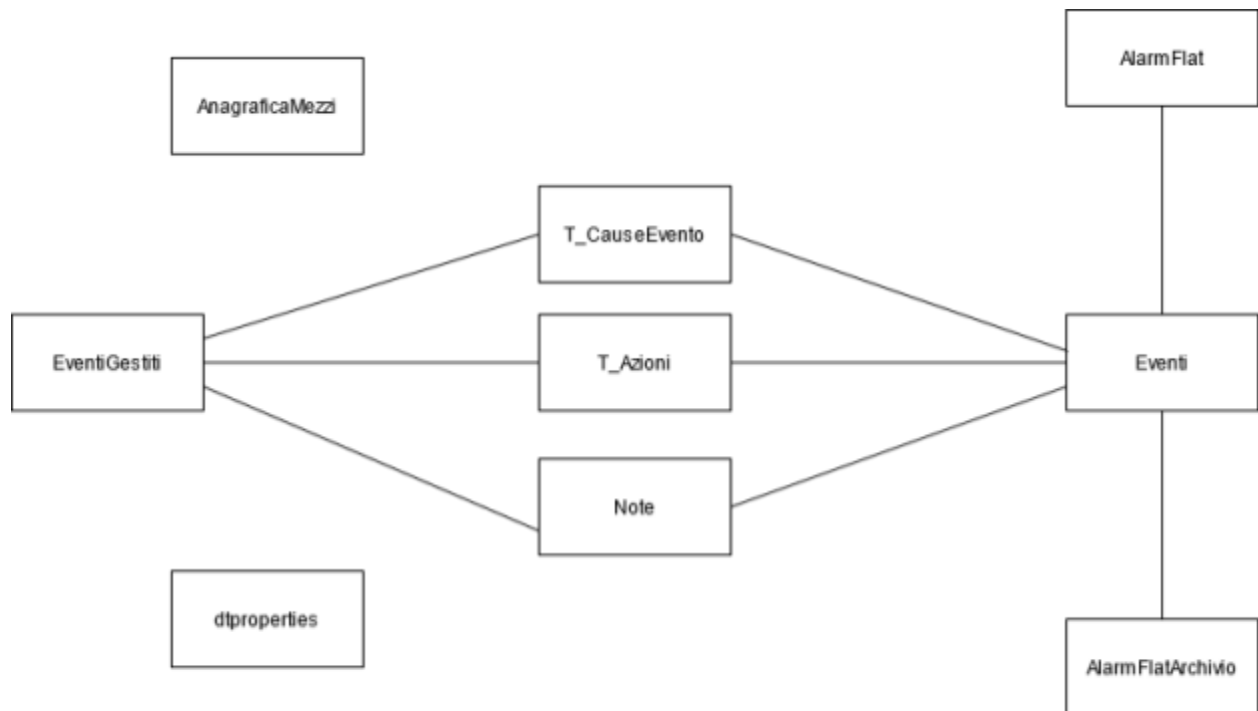


Figure 1: Representation of dbcentrale

3 Most Dangerous Cities

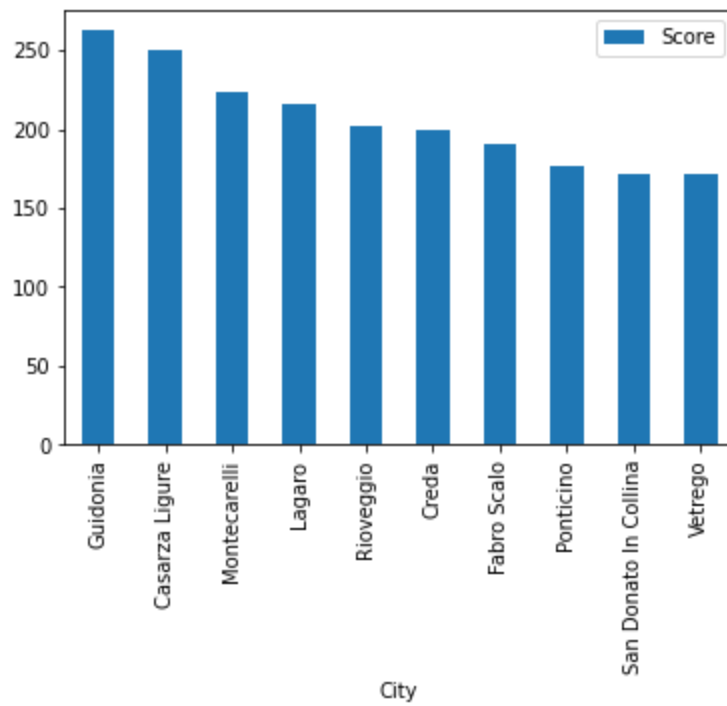
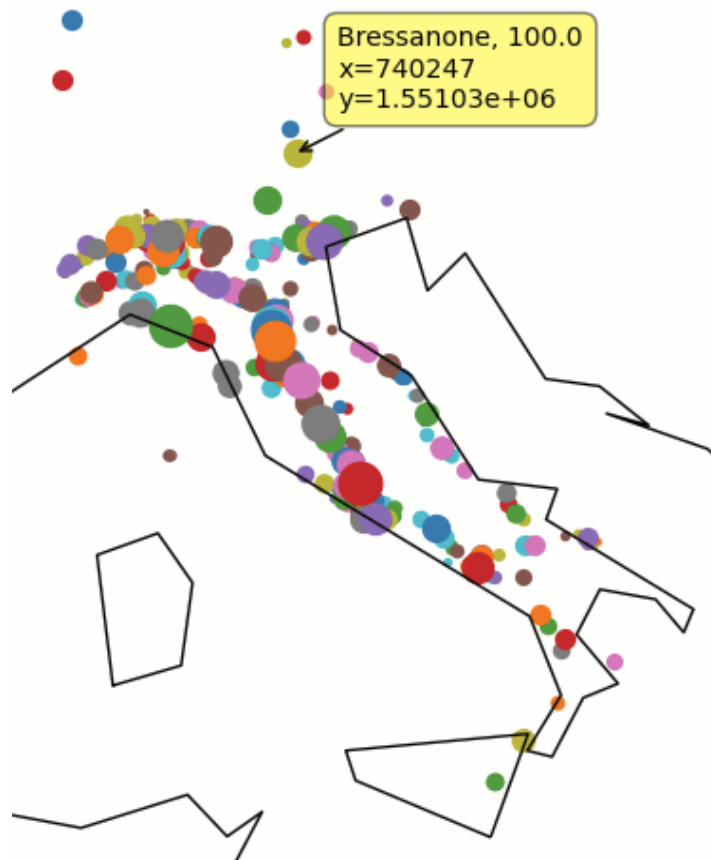
For analyzing the most dangerous cities we looked at the relation between the number of total alarms triggered by the sensors and the number of real alarms. Real alarms are all the alarms that are not triggered due to an anomaly of the sensors, test alarms, or other types of checks.

The data does not contain explicit information about the closest city for each triggered alarm, but it does contain the geographical coordinates for the location where the alarm was triggered.

We downloaded a dataset containing the geographical coordinates for European cities¹ and mapped each alarm to the closest city. Then we divided the number of real alarms by the number of total alarms and created a map where each dot represents a city. The size of the dot represents the risk score. For visualization purposes the score was multiplied by 3. Therefore the risk score ranges from 0 to 300. As we can see in the image below, Bressanone has a score of 100. This means that one third of the alarms near Bressanone were real alarms. The biggest dots and therefore most dangerous cities seem to be along the A1. However, this could also be explained by the fact that the biggest amount of traffic is located on the A1. In the second figure, we see the cities with the highest risk score. Guidonia, Casarza Ligure, and Montecarelli have the three highest risk scores.

¹

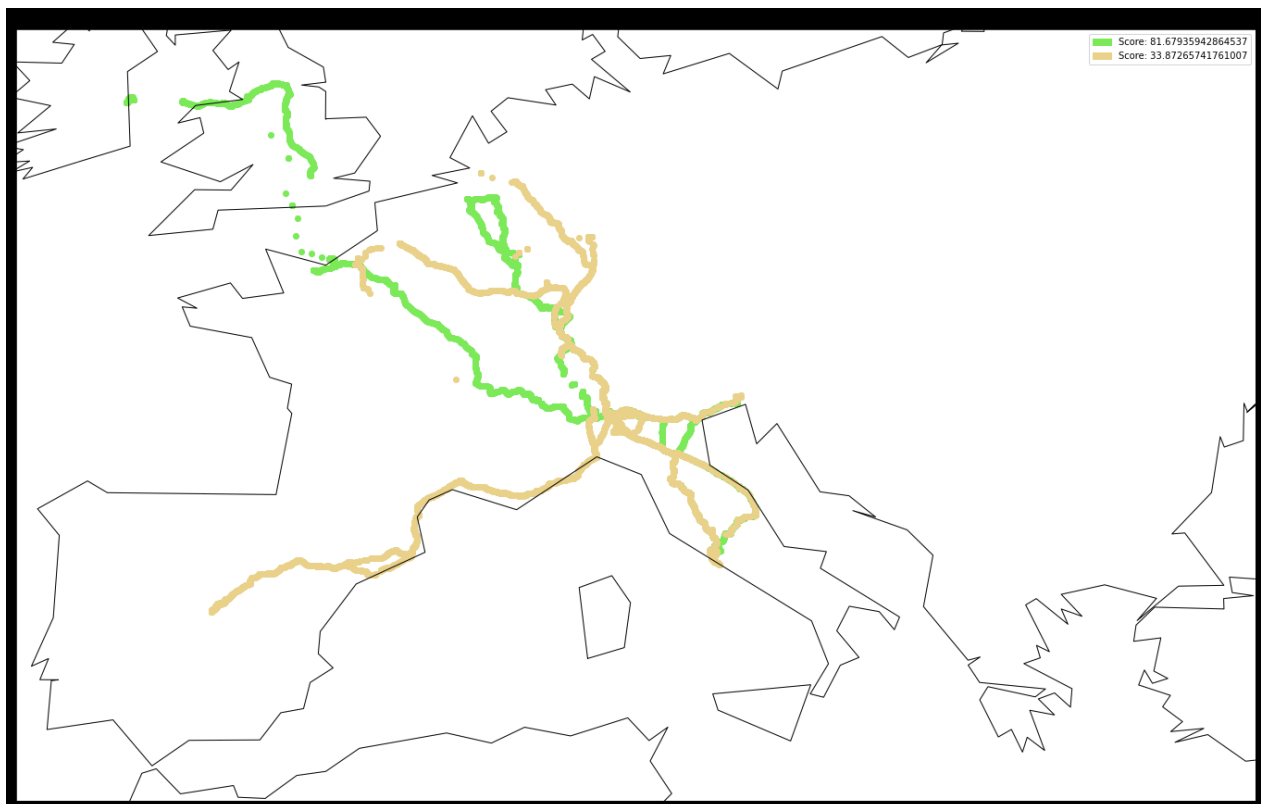
https://www.clearlyandsimply.com/clearly_and_simply/2010/10/geocoding-databases-for-europe.html

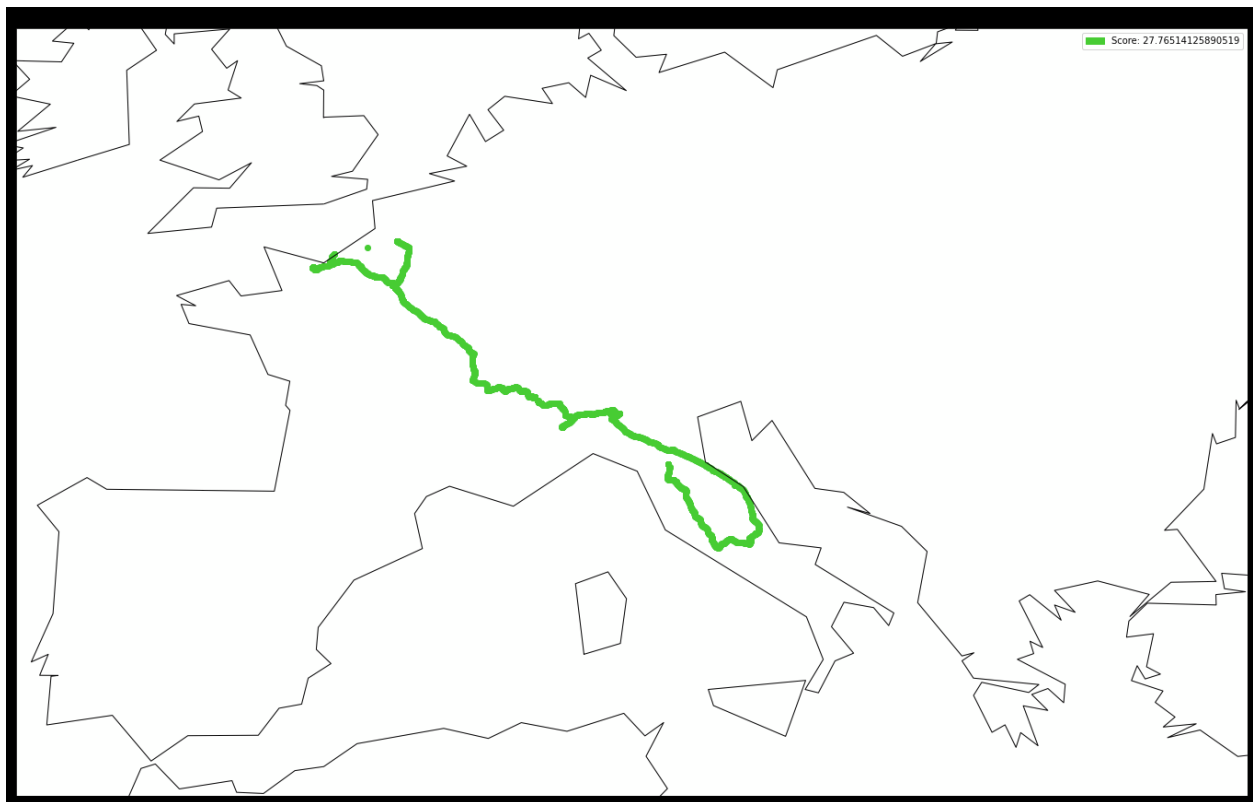
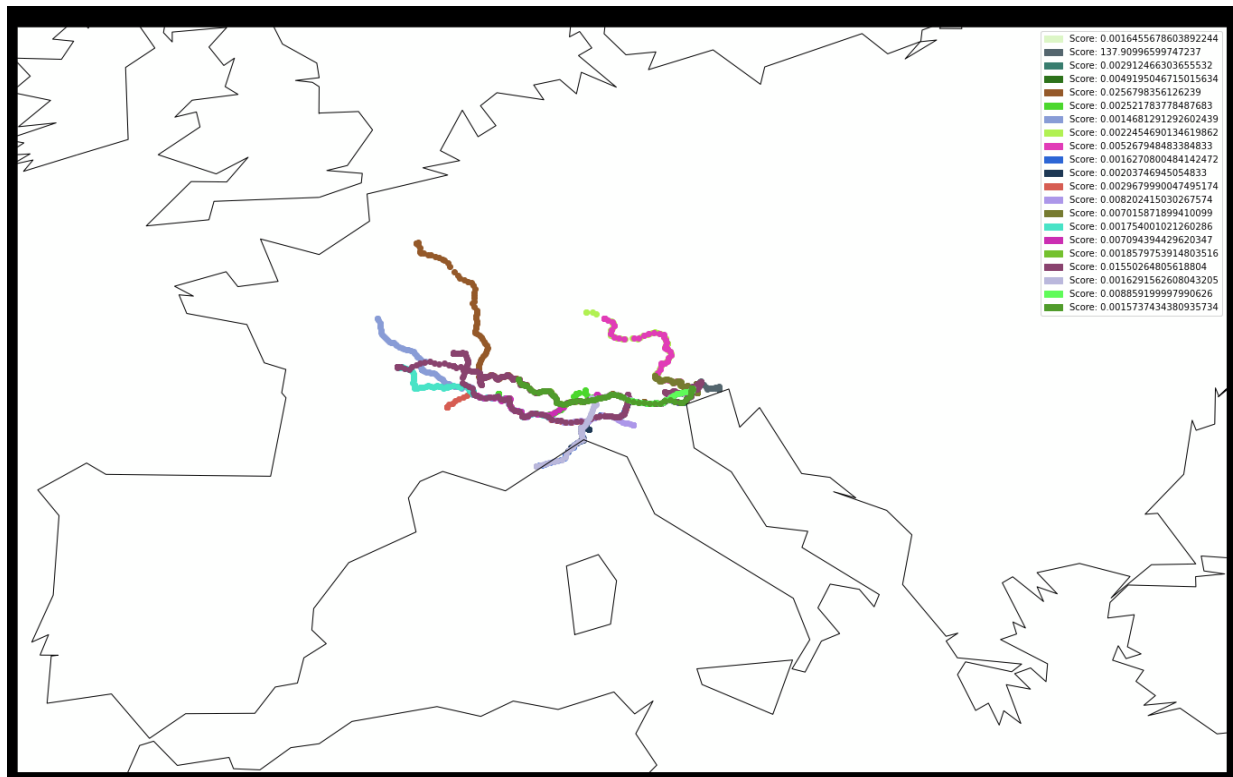


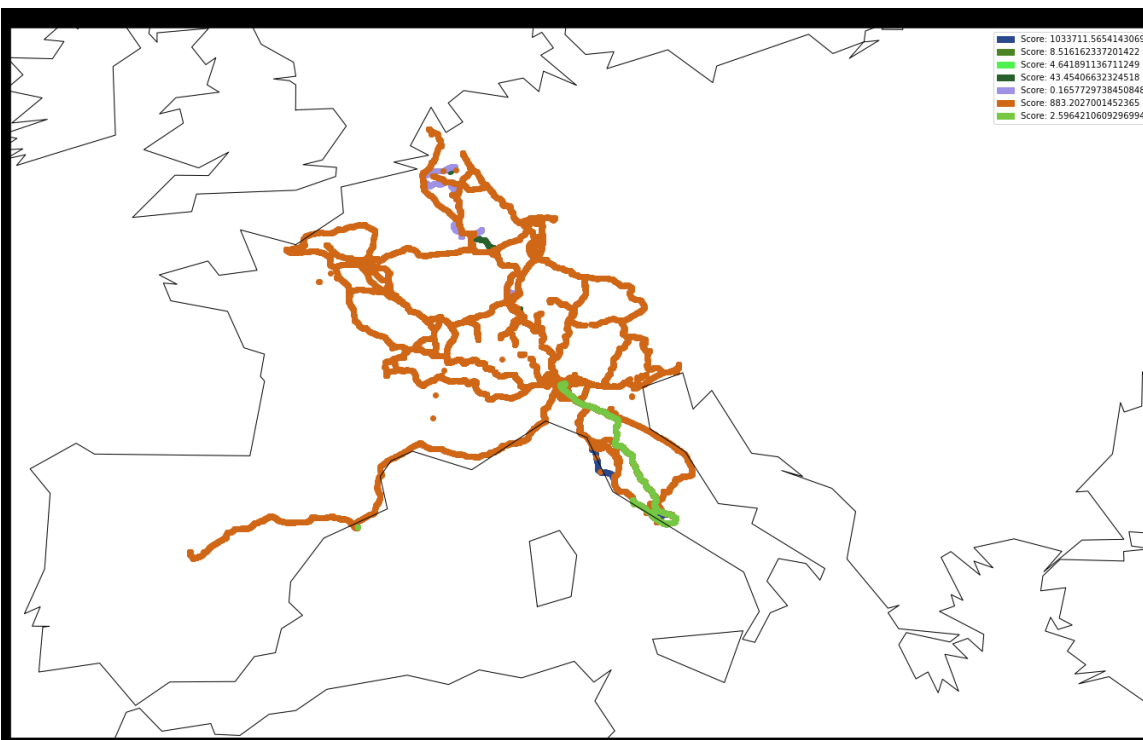
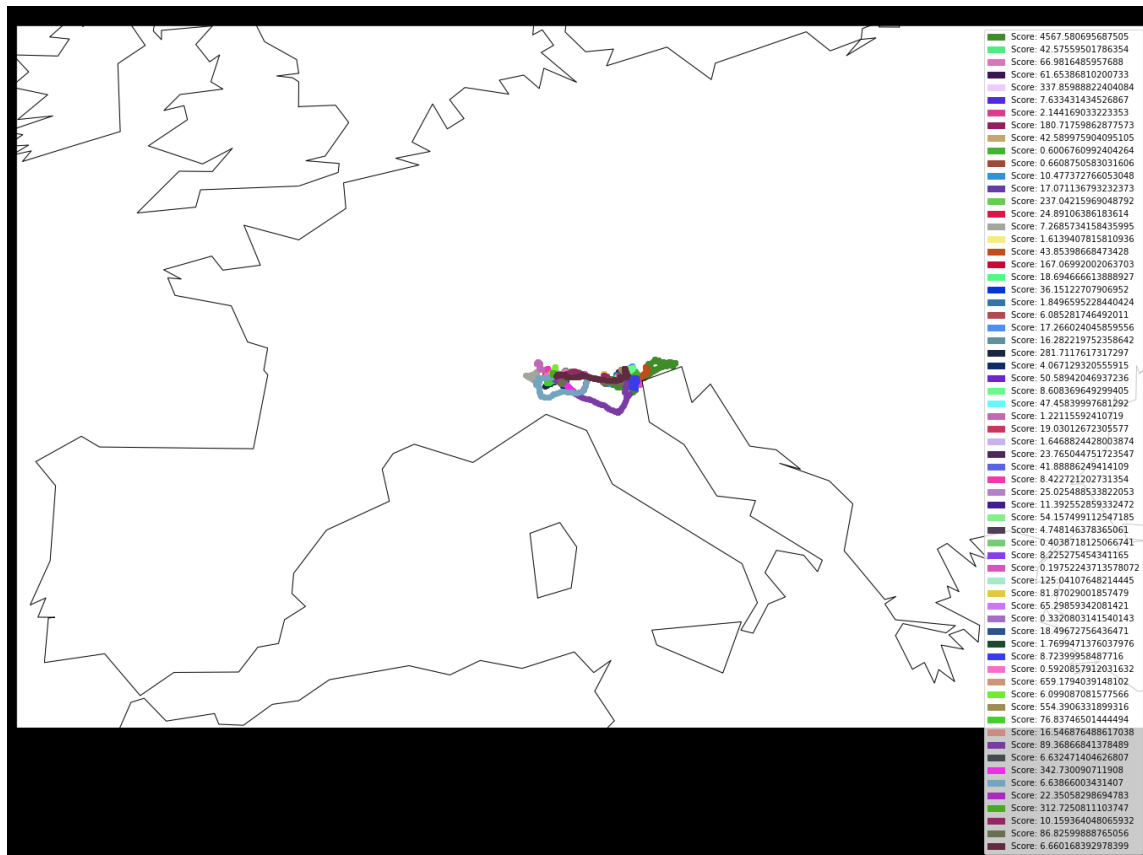
4 Route Risk Score

The previous approach only focused on the alarms and did not take into consideration the total number of routes passing through a certain point. Intuitively, the risk score of a route should be represented by the number of real alarms triggered along a route divided by the total length of the route. We wanted to use this concept for assigning risk scores to each route. For achieving this goal we first had to look at how to extract the information about routes from the data. The dataset did not contain explicit information about routes. However, it did contain geographical points for every communication between the sensors on the truck and the central server. The average temporal difference between two successive communications is about 16 minutes. This means that we have information about each truck's route where each point is on average 16 minutes apart from the previous point. This gives us a detailed route for each truck. Most of the trucks did not just drive one route, but multiple routes. Given that there was no explicit information about when a route starts or ends, we had to develop our own means of determining when one route finishes and another route starts. We decided to declare a route finished and a new route started whenever the difference between two points was greater than 4 hours. Now we had information about all the routes for all the trucks. The next step was to assign a risk score to each route. We already extracted the data for the alarms in the previous approach. Therefore, we only had to count the number of real alarms that happened on each route. To achieve this, we used the Python library *shapely*. Using its function *buffer* we created a buffer of 0.001 for each point of a route, so the area for a possible intersection with alarms was larger than just a single point. Then, using the function *intersects* we checked for each alarm point if it intersected the previously created buffer. This way, we counted the number of alarms that occurred on each route and used this as a score. However, now the longer the route the more likely it is to have a large amount of alarms along it. Therefore, we decided to divide the length of the route by the previously calculated score. This was done using the first and last point of each route and calculating the Python library *geopy*'s function *distance.distance* and use

the result as risk score. Intuitively, this should yield values between 0 and 1. However, using the previously mentioned function we did not calculate the actual length of the route, but just the distance between the start and end point as the crow flies (bee-line). Therefore, some scores consist of larger numbers. In the following some examples. Some particularly dangerous routes according to the calculated risk score are Monfalcone-Treviso, Grosseto-Livorno, and Venice-Milan:







5 Conclusions and Possible Next Steps

We presented two different approaches for risk zone prediction. We assigned a risk score to cities depending on the relation between all alarms and real alarms. The second approach was to assign a risk score to each route based on the number of real alarms that occurred along the route. For this approach we used the distance between the start and end points as the crow flies. Therefore, we obtained some very high scores. A possible next step could be to calculate the length of a route in a different way, so the actual length of the route can be used when calculating the risk score. This will lead to a more reliable risk score.

6 Appendix