# HW6

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# **Data(image) Preparation**

## Data (image)

```
im = imageio.imread('image1.png').astype('float32')
im2 = imageio.imread('image2.png').astype('float32')
```

In use *imageio* to read image date in both algorithms, which can read image as array (100x100).

## Similarity matrix (W)

```
W1 = rbf_kernel(im,1)
W2 = rbf_kernel(im2,2)
```

We will use similarity matrix in both algorithms for two input images. The matrix is made up by given **RBF kernel** 

which is equivalent to

$$k(x, x') = e^{-\gamma_s \|S(x) - S(x')\|^2} \times e^{-\gamma_c \|C(x) - C(x')\|^2}$$

Where S(x) is the spatial information and C(x) is the color information.

## **Kernel K-means**

### **Initial Methods**

I tried two different initial methods.

1. **Random assign**: randomly assign data point into class $(0\sim k-1)$ 

```
def init(method,k,image_number):
    if method == 0:
        print('Init method: random')
        return np.random.randint(k,size=10000)
```

2. **K-means++**: from Line 26 – Line 58

In this method, I'll explain in pseudocode followed:

- A. Randomly choose a data point as the first cluster
- B. Calculate distances of each points to the closest clusters
- C. Turn distance into probability and choose next cluster by probability(The farther the higher probability to be choosed)
- D. Repeat B-C till find k cluster.
- E. (from Line 47)Assign each point into their closet cluster.

## Clustering

After initial, I use the kernel data (similarity matrix) and the initial information to cluster data points into  $k(2\sim4)$  clusters.

```
def classify(kernel_data,res_prev,k):
    res = np.zeros(10000)
    unique, counts = np.unique(res_prev, return_counts=True)
    third = third_term(kernel_data,res_prev,k)
    for j in range(10000):
        temp = np.zeros(k)
        for c in range(k):
            temp[c]+=(0-2*second_term(kernel_data,res_prev,j,c)/counts[c]+third[c]/counts[c]**2)
        res[j] = np.argmin(temp)
    return res
```

First, calculate the distance from kernel data to the means:

$$\|\phi(x_j) - \mu_k^{\emptyset}\| = k(x_j, x_j) - \frac{2}{|C_k|} \sum_n \alpha_{kn} k(x_j, x_n) + \frac{1}{|C_k|^2} \sum_p \sum_q \alpha_{kp} \alpha_{kq} k(x_p, x_q)$$

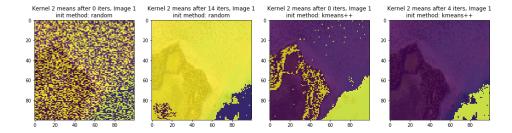
Then cluster each point into closest cluster use argmin.

Repeat this step until the difference in clustering result between two iteration converges. (By experiment, I set the stopping threshold < 50)

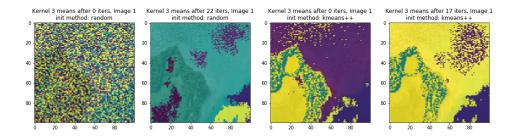
# Results

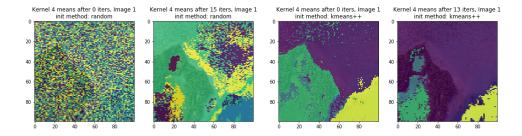
### • Image 1

## ■ K=2



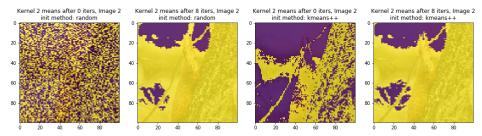
### ■ K=3



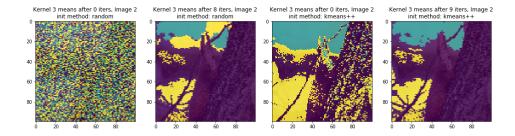


## • Image 2

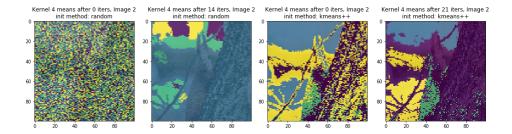
### ■ K=2



### ■ K=3



### ■ K=4



From the result we can see that in both input image, if we use kmeans++ as the initial method, since the starting center is far enough, it needs lesser time to converge and get more precise results.

# **Spectral Clustering**

## Ratio-Cut

To approximate the minimum of ratio-cut method, we can use unnormalized Laplacian L=D-W to approach, where D is the degree matrix, W is the similarity matrix.

```
D1 = np.diag(np.sum(W1,axis=1))

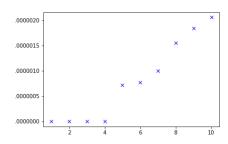
D2 = np.diag(np.sum(W2,axis=1))

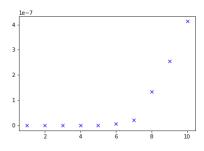
L1 = D1-W1

L2 = D2-W2
```

Then we find the eigenvalues and eigenvectors of L, sort eigenvalues to find the top k+1 small eigenvalues and their eigenvectors. Since we use RBF kernel here, which cause the fully-connected graph, we start from the  $2^{nd}$  smallest eigenvalue and its eigenvector. Let U be the matrix containing these k eigenvectors.

```
# Ratio-Cut
eigen_values_1, eigen_vectors_1 = np.linalg.eig(L1)
eigen_values_2, eigen_vectors_2 = np.linalg.eig(L2)
eigen_vectors_1_sort = eigen_vectors_1[:,np.argsort(eigen_values_1)]
eigen_vectors_2_sort = eigen_vectors_2[:,np.argsort(eigen_values_2)]
for k in range(2,5):
    U1 = (eigen_vectors_1_sort[:,1:k+1])
    U2 = (eigen_vectors_2_sort[:,1:k+1])
    k_means(k,U1,1,'ratio cut')
    k_means(k,U2,2,'ratio cut')
```





(Sorted eigen-value of

image1 and image2)

## Normal-Cut

We can use normalized Laplacian  $L_{sym} = D^{-1/2}LD^{-1/2}$  to approximate the minimum of normalized-cut. Then we also start from the 2<sup>nd</sup> smallest eigenvalue and its eigenvector of  $L_{sym}$ , let

U be the matrix of these k eigenvectors.

```
# Normal-Cut
D1_inv = np.linalg.inv(D1**0.5)
D2_inv = np.linalg.inv(D2**0.5)
L1_sym = np.dot(np.dot(D1_inv,L1),D1_inv)
L2_sym = np.dot(np.dot(D2_inv,L2),D2_inv)
eigen_values_normal_1, eigen_vectors_normal_1 = np.linalg.eig(L1_sym)
eigen_values_normal_2, eigen_vectors_normal_2 = np.linalg.eig(L2_sym)
eigen_vectors_normal_1_sort = eigen_vectors_normal_1[:,np.argsort(eigen_values_normal_1)]
eigen_vectors_normal_2_sort = eigen_vectors_normal_2[:,np.argsort(eigen_values_normal_2)]
for k in range(2,5):
    U1_normal = (eigen_vectors_normal_1_sort[:,1:k+1])
    U2_normal = (eigen_vectors_normal_2_sort[:,1:k+1])
    k_means(k,U1_normal,1,'normal_cut')
    k_means(k,U2_normal,2,'normal_cut')
```

Then we cluster the vector corresponding to the rows of U into k clusters with k-means algorithm.

### **Initial Methods**

I tried two different initial methods.

1. **Random assign**: randomly assign k data points to be the center

```
def init(U,method,k,image_number):
    means = np.zeros((k,k))
    if method == 0:
        print('Init method: random')
        temp = np.random.randint(10000,size=k)
        for i in range(k):
            means[i] = U[temp[i]]
```

- 2. **K-means++**: from Line 30 Line 42
  - In this method, I'll explain in pseudocode followed:
  - A. Randomly choose a data point as the first center
  - B. Calculate distances of each points to the closest center
  - C. Turn distance into probability and choose next center by probability(The farther the higher probability to be choosed)
  - D. Repeat B-C till find k centers.

## K-means

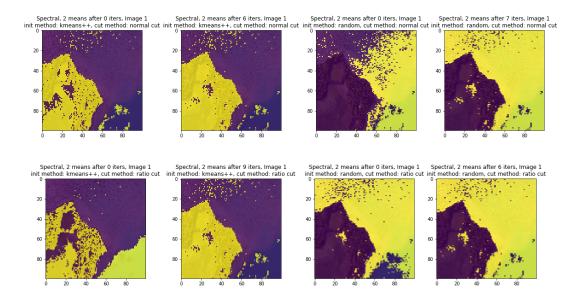
From Line 78 – Line 97, I implement the k-means algorithm:

- 1. Initial the centers using algorithm introduced aboved.
- 2. Cluster each point to their closest center (function classify, Line 45 Line 52)
- 3. Update center according to the point in the corresponding cluster. (function update, Line 54 Line 63)
- 4. Draw the result use matplotlib.

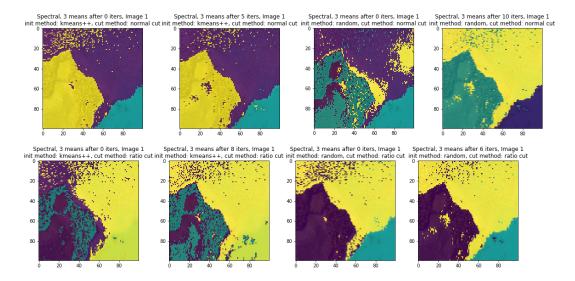
# Results

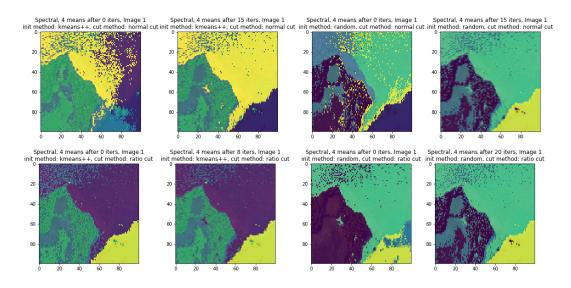
First line: normal-cut Second line: ratio-cut

### • Image 1



#### ■ K=3





### • Image 2

### ■ K=2

