



廣東工業大學
Guangdong University of Technology

广东工业大学

第五章 正弦波振荡器

信息工程学院

李志忠

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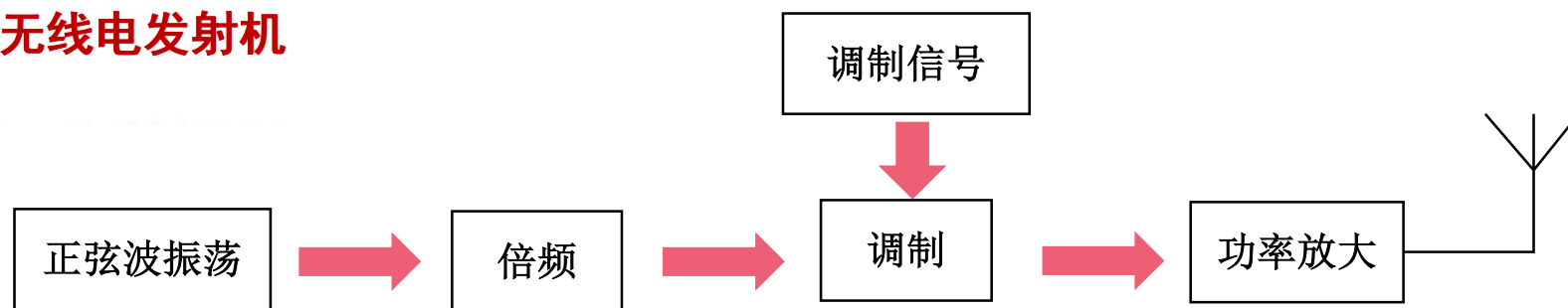
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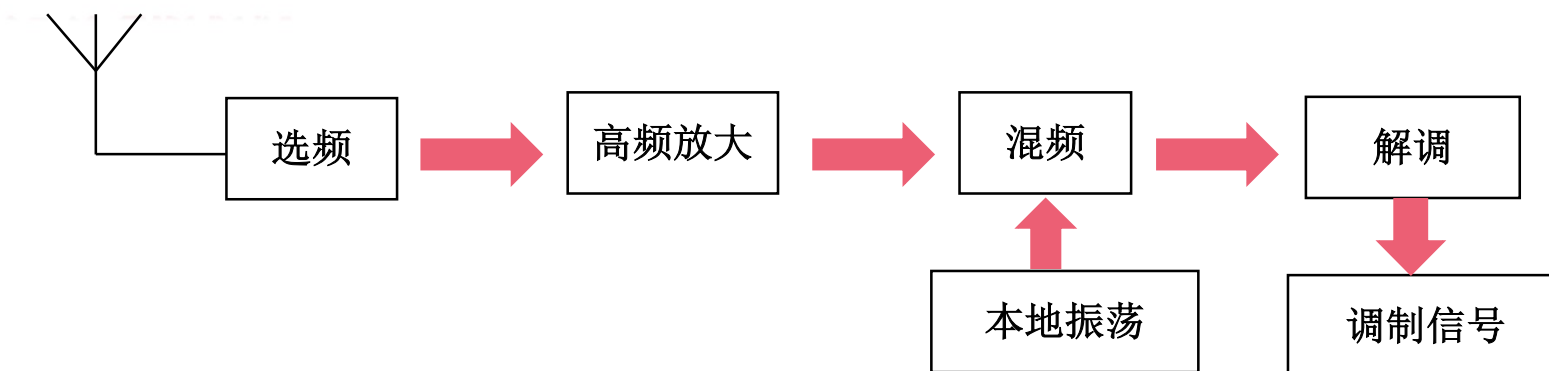
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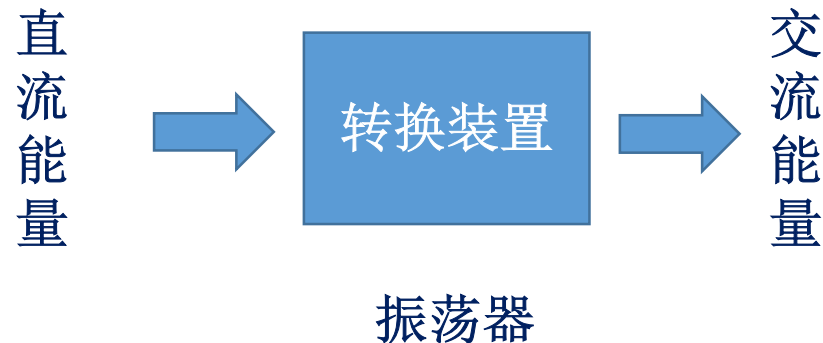
无线电接收机



振荡器？

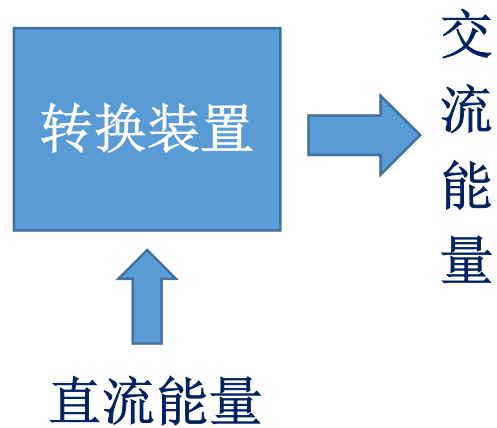
振荡器 (oscillator) : **没有输入信号**，只有直流电源供电，就可以产生并输出一定波形、一定频率和一定功率的交流信号的电路。

振荡器也可以看作是将直流电源**能量转换**为交流电能量的装置



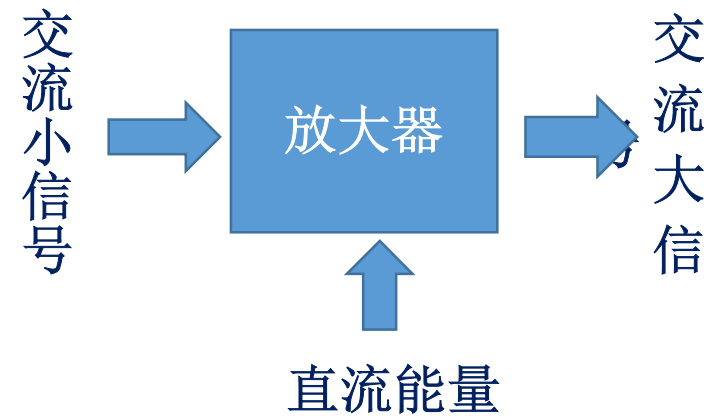
振荡器与放大器的区别

振荡器无信号输入
自己产生交流信号



振荡器无中生有

放大器有信号输入
将输入的交流信号放大



放大器照猫画虎

—. Classification



◆ 5.1 反馈式振荡器的工作原理

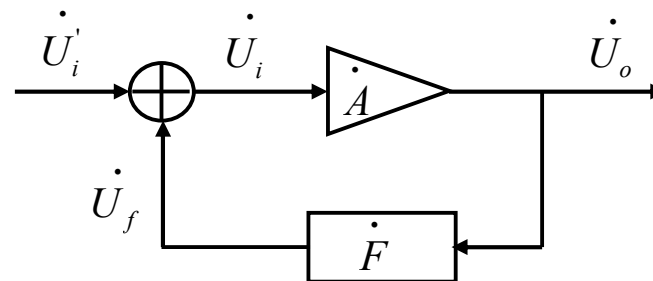
$$\dot{U}_o = \dot{A}\dot{U}_i \quad \dot{U}_f = \dot{F}\dot{U}_o$$

$$\ominus \quad \dot{U}_i = \dot{U}_i' - \dot{U}_f$$

$$\dot{U}_o = \dot{A}(\dot{U}_i' - \dot{U}_f) = \dot{A}\dot{U}_i' - \dot{A}\dot{F}\dot{U}_o$$

$$\therefore \frac{\dot{U}_o}{\dot{U}_i'} = \frac{\dot{A}}{1 + \dot{A}\dot{F}}$$

Negative Feedback Amplifier



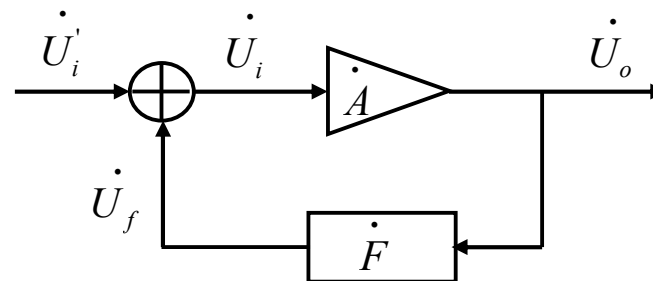
$$\oplus \quad \dot{U}_o = \dot{A}\dot{U}_i' + \dot{A}\dot{F}\dot{U}_o \quad \therefore \frac{\dot{U}_o}{\dot{U}_i'} = \frac{\dot{A}}{1 - \dot{A}\dot{F}}$$

$$\dot{A}\dot{F} = 1 \quad \frac{\dot{U}_o}{\dot{U}_i'} = \infty$$

◆ 5.1.1 平衡条件

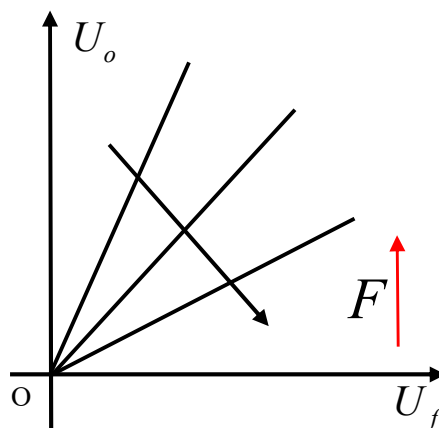
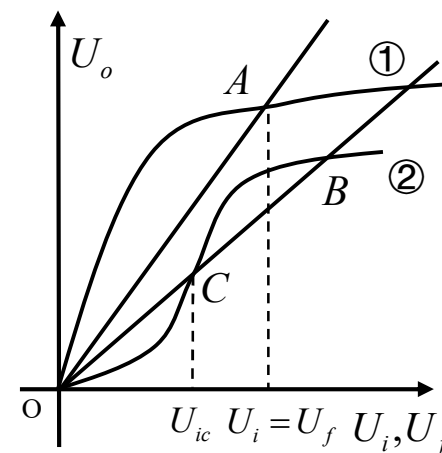
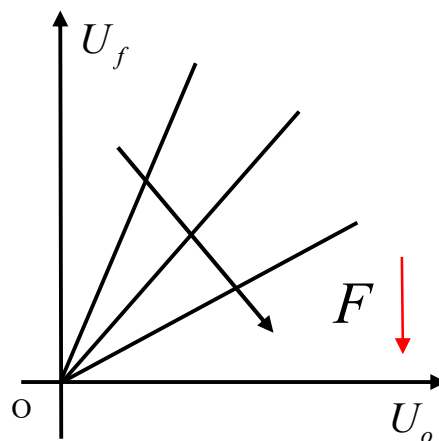
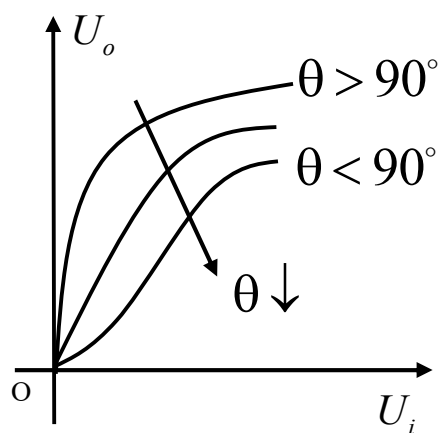
$$\dot{A}\dot{F} = 1 = \frac{\dot{U}_o}{\dot{U}_i} \cdot \frac{\dot{U}_f}{\dot{U}_o} = \frac{\dot{U}_f}{\dot{U}_i}$$

$$\begin{cases} \dot{U}_f = \dot{U}_i \\ \dot{U}_i = \dot{U}_i' + \dot{U}_f \end{cases} \Rightarrow \dot{U}_i' = 0$$



$$\dot{A}\dot{F} = 1 \Rightarrow \begin{cases} AF = 1 \Leftrightarrow U_f = U_i & \text{振幅平衡条件} \\ \varphi_A + \varphi_F = 2n\pi, n = 0, 1, 2, \dots & \text{相位平衡条件} \end{cases}$$

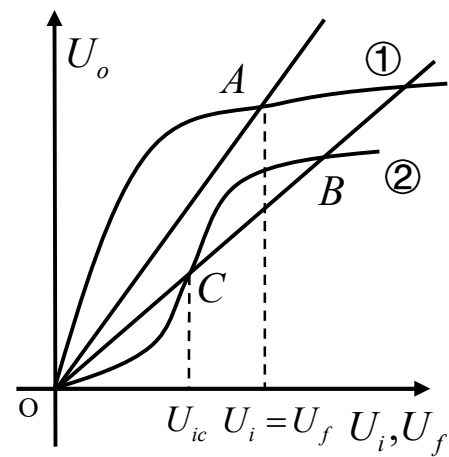
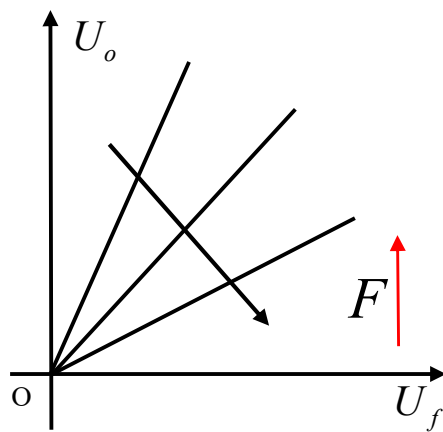
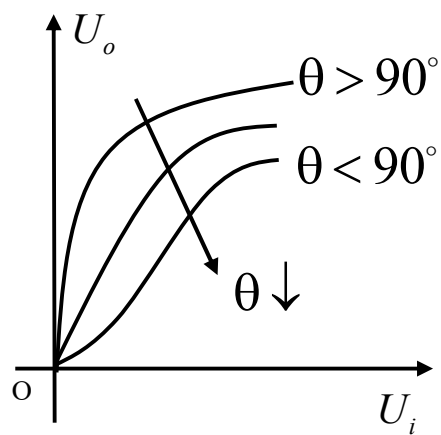
◆ 1. 振幅平衡条件



$$AF = 1 \Leftrightarrow U_f = U_i \quad \text{振幅平衡条件}$$

振幅平衡条件：反馈电压等于输入电压幅值；

$U_f = U_i$ 的点即为满足振幅平衡条件的平衡点，
相应的 U_o ，就是振荡器产生的电压振幅



$$\left. \begin{aligned} \dot{U}_o &= \dot{A} \dot{U}_i \\ \dot{U}_o &= \frac{\dot{U}_f}{\dot{F}} \end{aligned} \right\}$$

$$\left. \begin{aligned} \dot{A} \dot{F} \dot{U}_i &= \dot{U}_f \\ \dot{U}_i &= \dot{U}_f \end{aligned} \right\}$$

$$AF = 1$$

◆ 2. 相位平衡条件

$\varphi_A + \varphi_F = 2n\pi$ 反馈电压 \dot{U}_f 与输入电压 \dot{U}_i 同相，即 **正** 反馈

$$\dot{U}_o = \dot{I}_L \dot{Z}_L(\omega) = \dot{g}_m \dot{U}_i \dot{Z}_L(\omega)$$

$$A = \frac{\dot{U}_o}{\dot{U}_i} = \frac{\dot{g}_m \dot{U}_i \dot{Z}_L(\omega)}{\dot{U}_i} = \dot{g}_m \dot{Z}_L(\omega) = A e^{i\varphi_A}$$

$$\therefore \varphi_A = \varphi_Y + \varphi_Z$$

$$f_0 \ll f_T \quad \dot{g}_m = g_m \quad \varphi_Y = 0$$

φ_Y : 集电极电流基波分量

φ_Z : 负载的相角

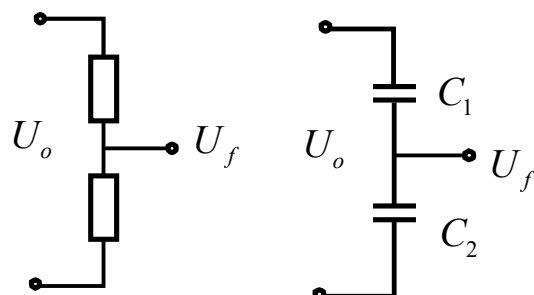
$$n = 0 \quad \varphi_A + \varphi_F = 0 \quad \therefore \varphi_A = -\varphi_F$$

$$\varphi_A + \varphi_F = \varphi_Y + \varphi_Z + \varphi_F = 0$$

若令 $\varphi_Y + \varphi_F = \varphi_{YF}$ ，则 $\varphi_Z = -\varphi_{YF}$

$$\varphi_A + \varphi_F = \varphi_Y + \varphi_Z + \varphi_F = 0 \quad \varphi_Y + \varphi_F = \varphi_{YF} \quad \varphi_Z = -\varphi_{YF}$$

φ_F :



$$F = \frac{U_f}{U_o} = \frac{i \frac{1}{j\omega c_2}}{i \frac{1}{j\omega c_2 // c_1}} = \frac{c_2 // c_1}{c_2} = \frac{c_1}{c_2 + c_1}$$

$$\therefore \varphi_F = 0$$

一般情况：晶体管少数载流子通过基区有效宽度时，总需要一定的扩散时间，即 I_c 总滞后于 U_i

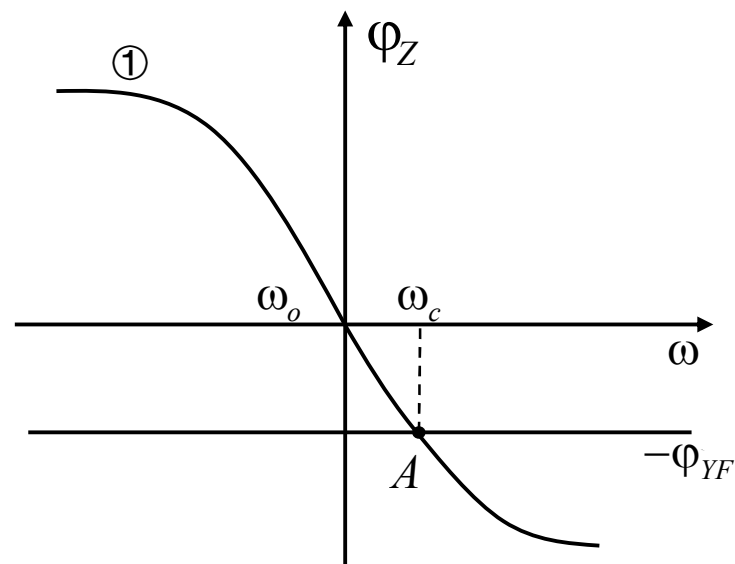
$$\therefore \varphi_Y < 0 \quad \therefore \varphi_{YF} = \varphi_Y + \varphi_F \neq 0 \quad \therefore \varphi_Z = -\varphi_{YF} \neq 0$$

\therefore 谐振时呈现纯阻 \therefore 失谐工作即： $\omega_c \neq \omega_o$

ω_c : 电路参数决定的振荡频率 ω_o : 回路谐振频率

$$\because (\omega_c - \omega_o) \downarrow$$

$$\therefore \omega_c \approx \omega_o$$



LC并联振荡回路
负载相角与频率的关系

◆ 5.1.2 稳定条件 stabilization Condition

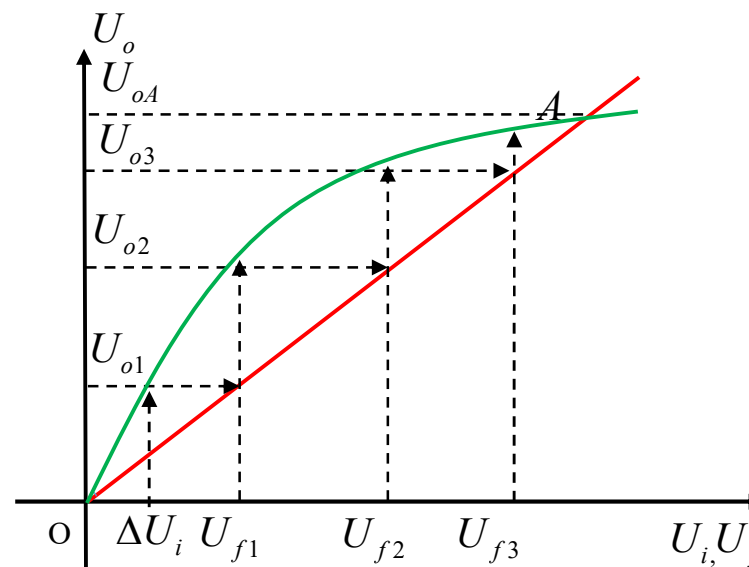
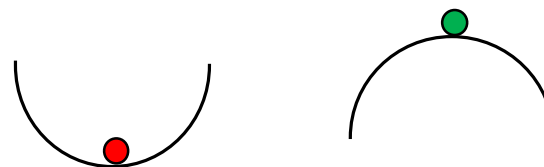
1. 振幅稳定条件

$$\theta \geq 90^\circ$$

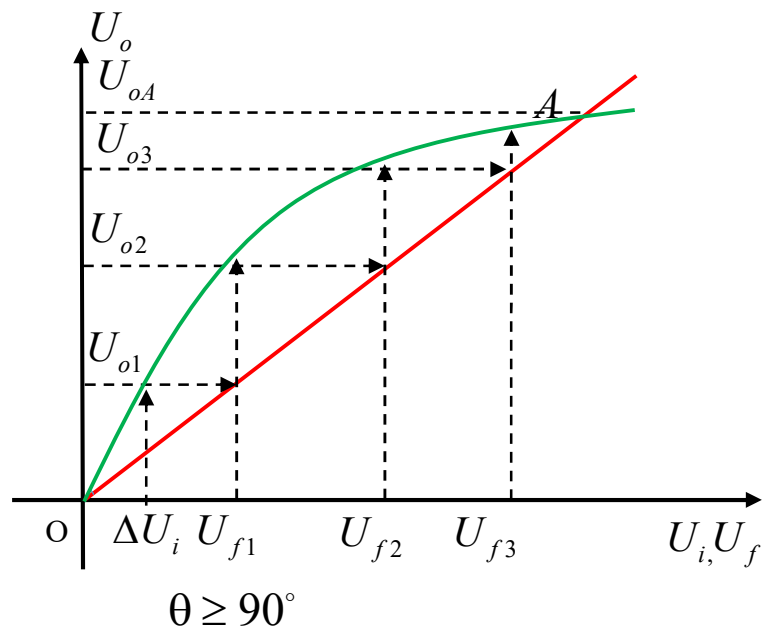
放大特性与反馈特性有两个交点O、A

电源接通瞬间 $\dot{U}_i = 0, \dot{U}_o = 0$ 外界电磁感应在放大器输入端感应电压 ΔU_i ，放大器输出 U_{o1} ，经过反馈网络，反馈电压 U_{f1} ，由于 $U_{f1} > \Delta U_i$ ，振荡器就会脱离开原点而振荡起来。

若因外界因素振荡偏离A点，仍可返回



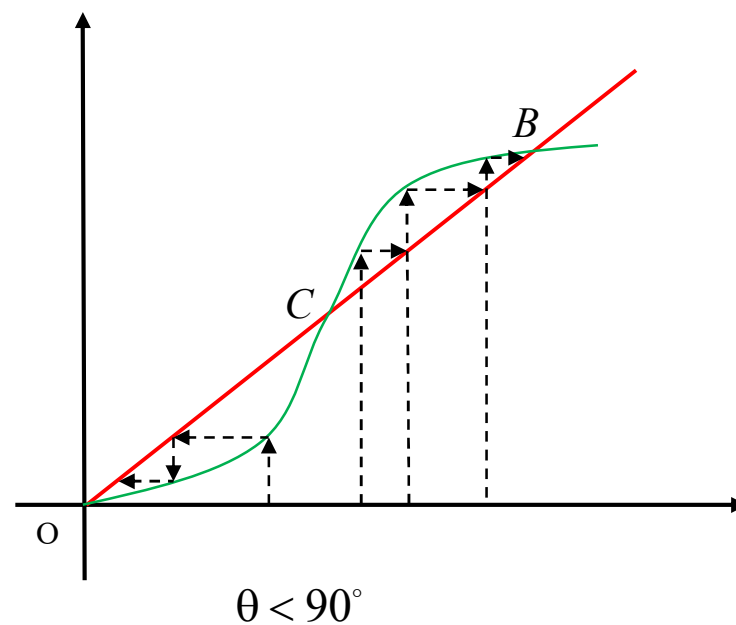
$\theta \geq 90^\circ$ 的放大特性与反馈特性



A 稳定点

Soft Self Excitation

软自激



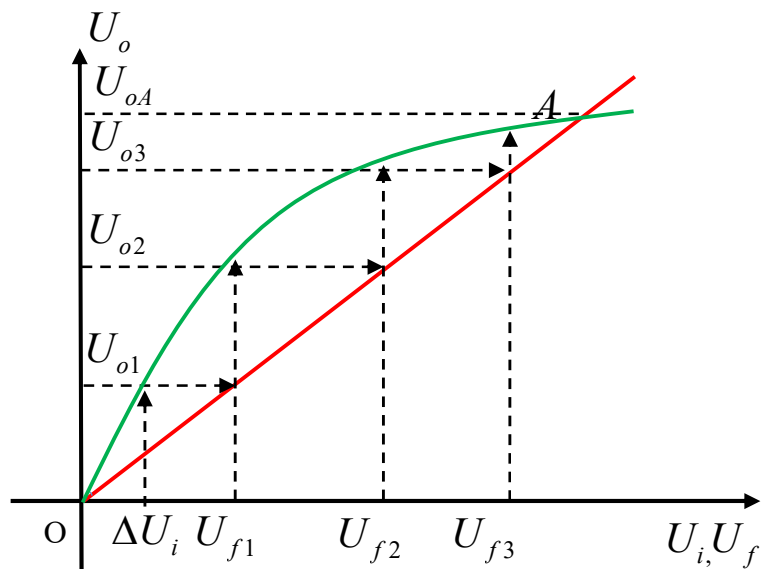
O、B 稳定点；C 非稳定点

初始为 O，不起振

$U_i > U_c$ 自动起振

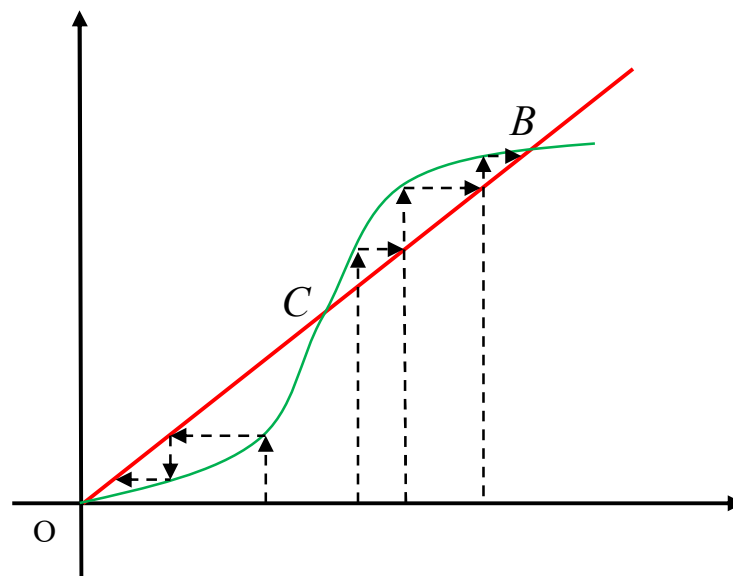
Hard Self Excitation

硬自激



$\theta \geq 90^\circ$

A 稳定点



$\theta < 90^\circ$

O、B 稳定点；C 非稳定点

稳定：放大特性斜率小于反馈特性斜率

$$\left. \frac{\partial U_o}{\partial U_i} \right|_p < \left. \frac{\partial U_o}{\partial U_f} \right|_p$$

$$\frac{\partial U_o}{\partial U_i} \frac{\partial U_f}{\partial U_o} < 1$$

$$\left. \frac{\partial U_f}{\partial U_i} \right|_p < 1$$

$$\frac{\partial U_f}{\partial U_i} \Big|_{p < 1} \quad \frac{\partial U_f}{\partial U_i} = \dot{F} \dot{U}_i \frac{\partial \dot{A}}{\partial \dot{U}_i} + \dot{A} \dot{U}_i \frac{\partial \dot{F}}{\partial \dot{U}_i} + \dot{A} \dot{F} \frac{\partial \dot{U}_i}{\partial \dot{U}_i} < 1$$

$$U_f = \dot{A} \dot{F} \dot{U}_i$$

平衡点：

$$\dot{A} \dot{F} = 1 \quad \dot{F} \dot{U}_i \frac{\partial \dot{A}}{\partial \dot{U}_i} + \dot{A} \dot{U}_i \frac{\partial \dot{F}}{\partial \dot{U}_i} < 0 \quad \dot{F} \frac{\partial \dot{A}}{\partial \dot{U}_i} + \dot{A} \frac{\partial \dot{F}}{\partial \dot{U}_i} < 0$$

$$\left\{ \begin{array}{ll} F = \text{常数} & \frac{\partial \dot{F}}{\partial \dot{U}_i} = 0 \quad \therefore \dot{F} \frac{\partial \dot{A}}{\partial \dot{U}_i} < 0 \\ A = \text{常数} & \frac{\partial \dot{A}}{\partial \dot{U}_i} = 0 \quad \therefore \dot{A} \frac{\partial \dot{F}}{\partial \dot{U}_i} < 0 \end{array} \right.$$

内稳幅条件
非线性放大器

外稳幅条件
非线性反馈网络

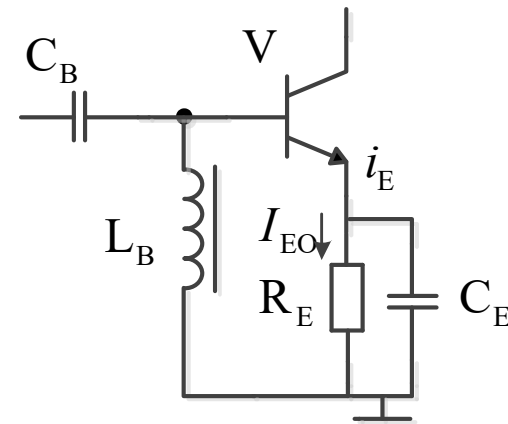
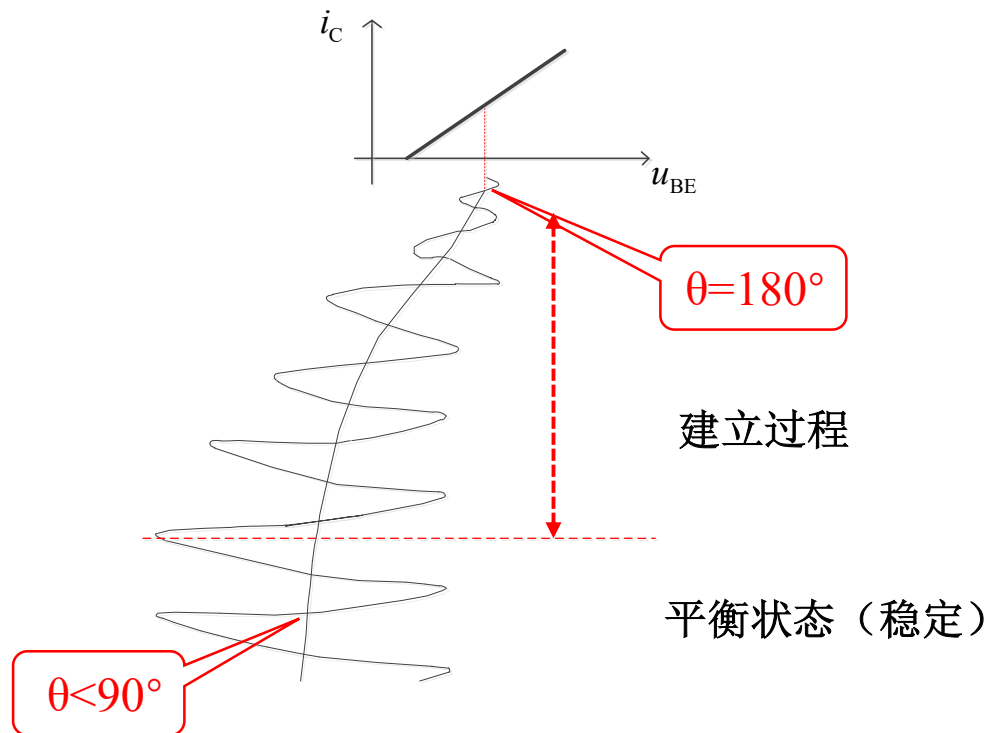
稳定: $\theta \geq 90^\circ$ Soft Self Excitation 软自激

$\theta < 90^\circ$ Hard Self Excitation 硬自激

自动起振: 电源接通瞬间A类($\theta = 180^\circ$)

$$U_i \uparrow \quad U_o \uparrow \quad \theta \downarrow$$

$\theta < 90^\circ$ (C类) 达到平衡 $\dot{A}\dot{F} = 1$



发射极自给偏置电路

2. 相位稳定条件

$$U = U_m \sin(\omega t + \varphi_0)$$

$$\omega' = \frac{d\varphi(t)}{dt} = \frac{d(\omega t + \varphi_0)}{dt}$$

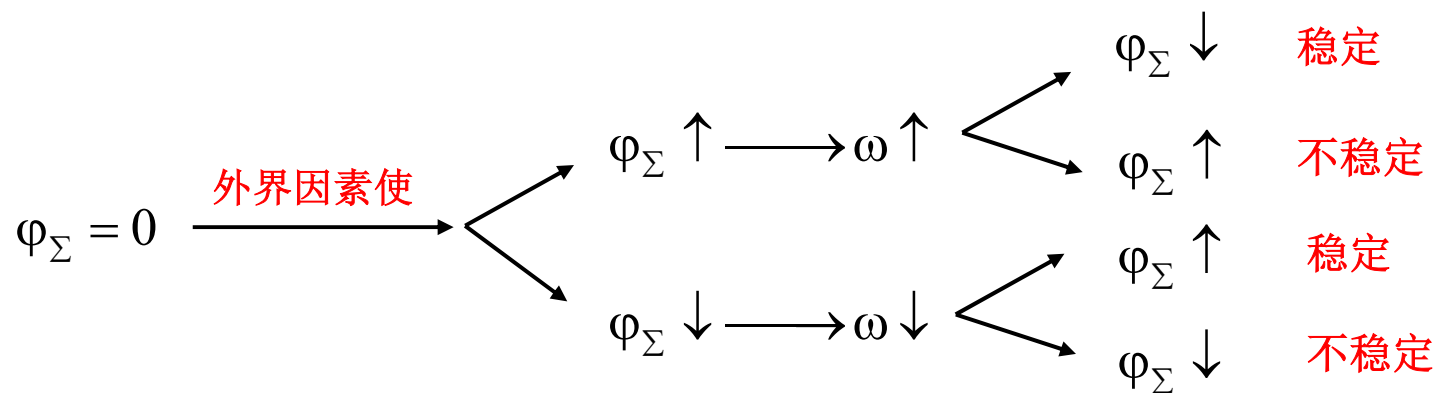
$$\varphi_0: \text{常数} \quad \omega' = \omega$$

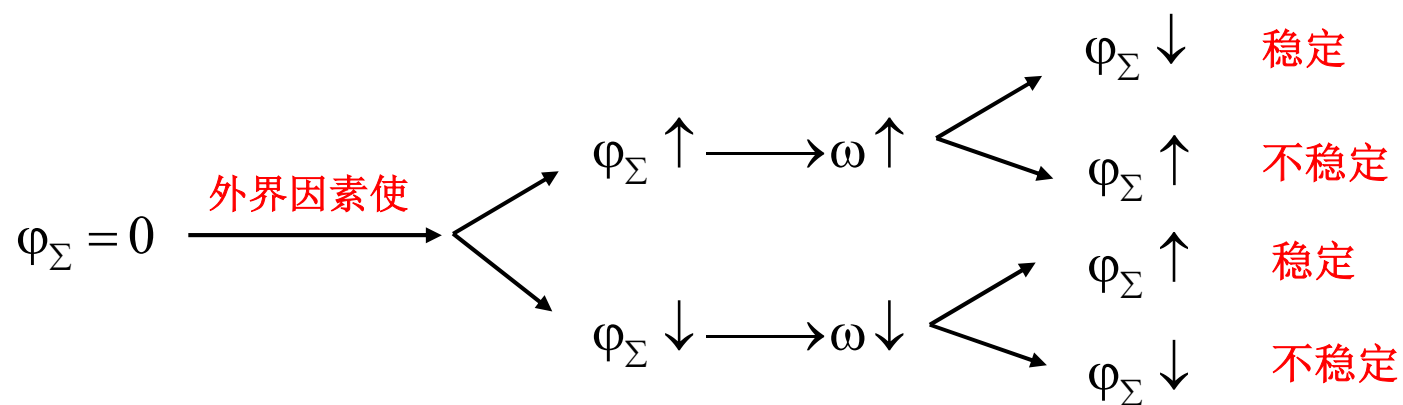
$$\varphi_0: \text{非常数} \quad \omega' = \omega + \frac{d\varphi_0}{dt} = \omega + \Delta\omega$$

$$\therefore \varphi \uparrow \quad \omega \uparrow \quad f \uparrow$$

相位超前

频率增大

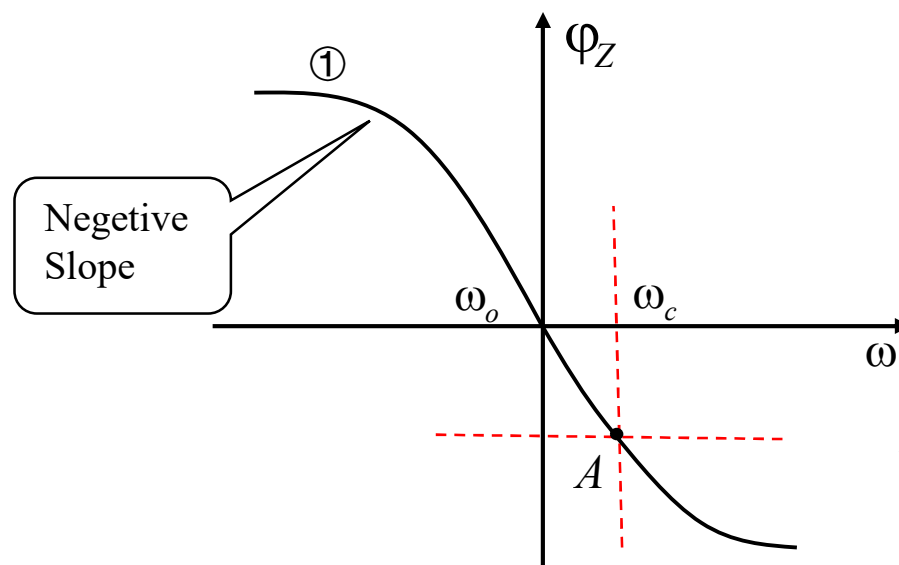




相位稳定条件: $\left. \frac{\partial \varphi_\Sigma}{\partial \omega} \right|_p = \left(\left. \frac{\partial \varphi_Y}{\partial \omega} \right|_p + \left. \frac{\partial \varphi_F}{\partial \omega} \right|_p + \left. \frac{\partial \varphi_Z}{\partial \omega} \right|_p \right) < 0$

窄带可认为: $\frac{\partial \varphi_F}{\partial \omega} \approx 0$ $\frac{\partial \varphi_Y}{\partial \omega} \approx 0$

相位稳定条件: $\left. \frac{\partial \varphi_Z}{\partial \omega} \right|_p < 0$



◆ 5.1.3 起振条件

$$\begin{cases} A_0 F > 1 & U_f > U_i & \text{振幅起振条件} \\ \varphi_\Sigma = 2n\pi & & \text{相位起振条件} \end{cases}$$

起始 U_i 小，工作于A类，自起振

∴ 起振用小信号微变等效电路分析法

起始状态

$$\dot{A}_0 \dot{F} > 1$$

工作于 A 类， $\theta \geq 90^\circ$

小信号、线性

微变等效电路分析法

稳定状态

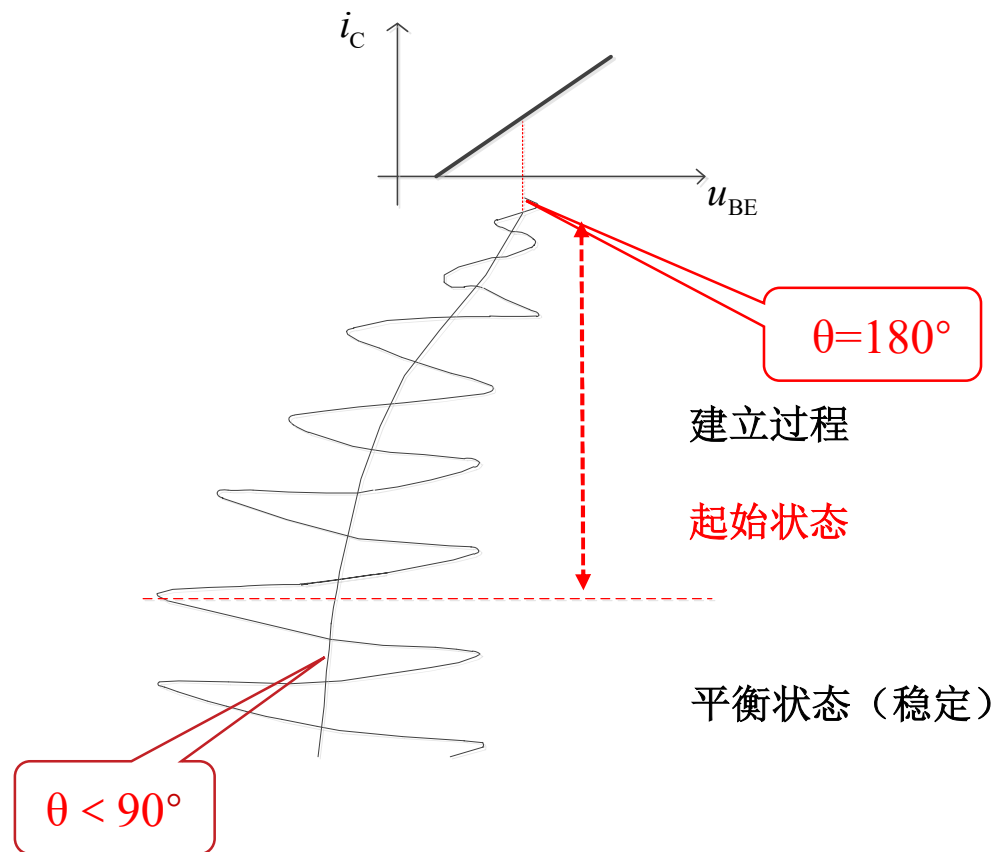
$$\dot{A} \dot{F} = 1$$

工作于 C 类， $\theta < 90^\circ$

大信号、非线性

不能用微变等效电路分析法

Y参数等效电路分析法



$$\dot{A}\dot{F} > 1$$

工作于 A 类, $\theta \geq 90^\circ$

小信号、线性

微变等效电路分析法

$$\dot{A}\dot{F} = 1$$

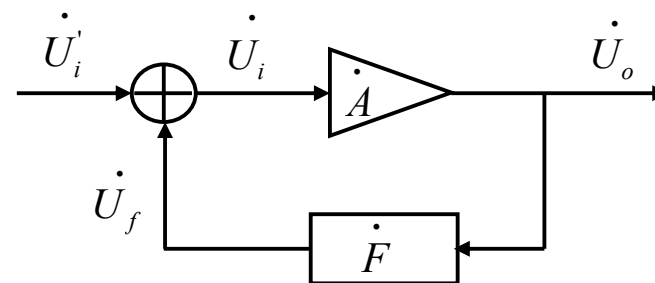
工作于 C 类, $\theta < 90^\circ$

大信号、非线性

不能用微变等效电路分析法

Y参数等效电路分析法

振荡器 振荡条件	平衡	振幅平衡	$AF=1$
		相位平衡	$\varphi_{\Sigma} = 2n\pi$
	稳定	振幅稳定	$\dot{F} \frac{\partial \dot{A}}{\partial \dot{U}_i} + \dot{A} \frac{\partial \dot{F}}{\partial \dot{U}_i} < 0$
		相位稳定	$\frac{\partial \varphi_{\Sigma}}{\partial \omega} < 0$
	起振	振幅起振	$A_0 F > 1$
		相位起振	$\varphi_{\Sigma} = 2n\pi$



振荡器 组成	放大器:	BJT、FET、差分放大器、运算放大器等
	反馈网络:	RC 移相、电容分压、电感分压、变压器耦合或电阻分压网络等
	选频网络:	LC、RC、晶体滤波器等

谢谢！