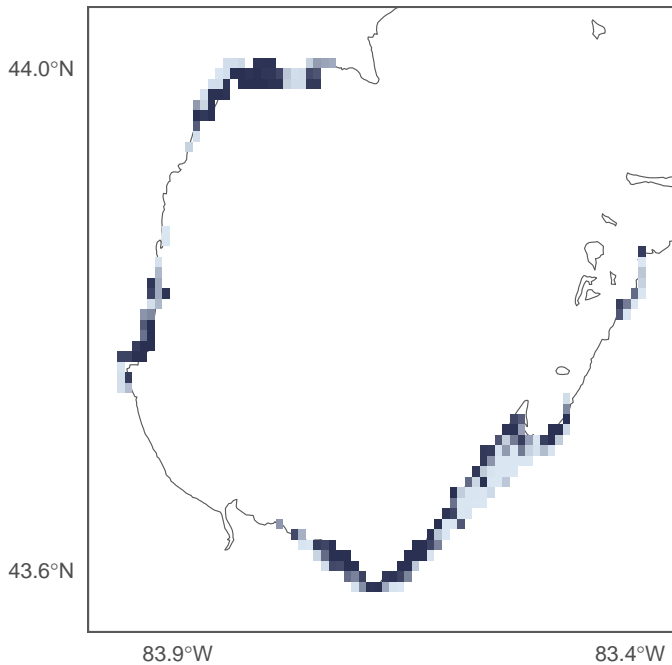
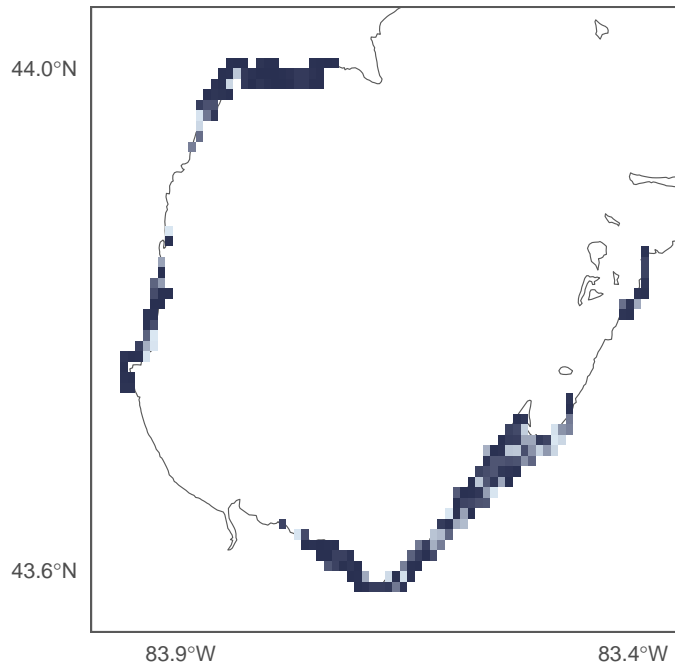


Presence-background



Presence-absence



Probability of suitable habitat

