Clicker Question #1

How can we best describe the runtime of BruteForceChange?

- A. Linear
- B. Quadratic
- C. Polynomial (but not linear or quadratic)
- D. Exponential
- E. Factorial

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Dynamic Programming

CPSC 320 2024S

Optimization problems

- Just as with Greedy algorithms, this unit primarily deals with optimization problems:
 - We have a problem with several valid solutions
 - There is a score, or objective function, that tells us how good (or bad) each solution is
 - We are looking for the valid solution that minimizes or maximizes the score

When to use dynamic programming

- A greedy dynamic programming algorithm proceeds by:
 - Making a single choice based on a simple, local criterion
 - Considering a (polynomial) number of possible choices
 - Solving one or more subproblem(s) that result from each choice
 - Combining the choice and its associated subproblem(s) (e.g., by calculating the total score)
 - Selecting the best choice (with maximum or minimum score)
- This technique is useful when the possible choices lead to repeated or overlapping subproblems

When to use dynamic programming?

Repeated/overlapping subproblems:

- Meaning that if two of the subproblems are A and B then smaller subproblems of A are also smaller subproblems of B
- Choosing an algorithm design technique:
 - If you have a simple, local criterion to make a choice that leads to an optimal (or good enough!) solution → Greedy
 - If not, and subproblems overlap → Dynamic programming
 - If subproblems don't overlap → Divide and conquer

Dynamic programming versus memoization?

- These are variants of the same problem-solving approach
- In this class we use memoization to refer to to a recursive implementation (top-down approach)
- We use dynamic programming to refer to an *iterative* implementation (bottom-up approach)

An interesting question is, "Where did the name, dynamic programming, come from?" The 1950s were not good years for mathematical research. [...] Wilson [...] was Secretary of Defense [...] I felt I had to do something to shield Wilson and the Air Force from the fact that I was really doing mathematics [...] I was interested in planning, in decision making, in thinking. But planning, is not a good word for various reasons. I decided therefore to use the word "programming". I wanted to get across the idea that this was dynamic, this was multistage, this was time-varying. I thought [...] it's impossible to use the word dynamic in a pejorative sense. [...] Thus, I thought dynamic programming was a good name. It was something not even a Congressman could object to.

— Richard Bellman, Eye of the Hurricane: An Autobiography (1984, page 159)

- Step 1: determine the possible choices (and associated subproblems)
 - E.g., which intervals from 1 to j to choose in the weighted interval scheduling problem
 - E.g., which coins to give in the change-making problem (current worksheet!)
 - E.g., which items to choose for the knapsack problem

- Step 2: define a recurrence relation for the value of the objective function in terms of its value(s) for one of more subproblems
- E.g., OPT(j) = min{OPT(i-25), OPT(i-10), OPT(i-1)}
- E.g., HP[i,j] = max{1, min{HP[i+1,j], HP[i,j+1]- G[i,j]} (in upcoming tutorial and assignment)
 (base cases omitted here)
- A table is used to store values of the objective function for different subproblems

- Step 3: determine the "shape" of the table that stores solutions to subproblems
 - Dimension will depend on the number and range of parameters in the subproblem
 - It's usually an array with as many dimensions as there are parameters to the subproblem
 - E.g., M[1, ..., n] for weighted interval scheduling
 - E.g., M[0, ..., n][0, ..., W] for knapsack

- Step 4: implement the algorithm
 - Approach 1: memoization (recursion)
 - Like a straightforward recursive approach to compute the value given by the recurrence relation
 - But first look at the table to see if this solution has already been computed
 - If so, return it immediately

- Approach 2: iteration (sometimes only called "dynamic programming")
 - Loop over the problem, starting with the base cases
 - Then solve later subproblems
 - Make sure that by the time subproblem S needs the solution to S',
 the solution to S' has already been computed
- For each subproblem:
 - Compute the optimal solution to the subproblem, using table lookups instead of recursive calls

- Step 5: retrieve the optimal solution
 - Step 4 gives us the value of the objective function for the optimal solution, but not the solution
 - To retrieve the solution:
 - Start with the original problem and determine the last choice we made
 - Insert this choice into the solution (usually at the end)
 - Then repeat starting from the subproblem we get after making that choice
- We don't want to store solutions for every subproblem because it would increase the space

A non-optimization example: Fibonacci numbers

- Each Fibonacci number is the sum of the two previous Fibonacci numbers
 - The sequence: 1, 1, 2, 3, 5, 8, 13, 21, ...
- Recurrence:
 - \circ FIB(0) = 0, FIB(1) = 1 // base cases
 - FIB(n) = FIB(n-1) + FIB(n-2) // recursive cases

A straightforward recursive implementation

```
def fibonacci(n):
    if n <= 1:
        return n
    else:
        return fibonacci(n-1) + fibonacci(n-2)</pre>
```

A memoized implementation

```
# memoized version
def fibonacci mem(n, memo={}):
    if n in memo:
        return memo[n]
    elif n <= 1:
        return n
    else:
        memo[n] = fibonacci_mem(n-1, memo) + fibonacci_mem(n-2, memo)
        return memo[n]
```

An iterative implementation – clicker question

An iterative implementation

```
# iterative dynamic programming version

def fibonacci_iter(n):
    fib = [0, 1] # Initialize Fibonacci sequence with the first two numbers
    for i in range(2, n + 1):
        fib.append(fib[i - 1] + fib[i - 2])
    return fib[n]
```