

N-Physics

Components and Tools for Unity Physics

N-PHYSICS

UNITY EXTENSION

Helpers Components

Center Of Mass Locator
Collision Events
Collision Ignore Setup
Rigidbody Gizmos
Speed O Meter
Spring Renderer
Trajectory Display
Trigger Events

Rigidbody Components

Center Of Mass Position
Inertia Tensor Override
Density
Directional Drag
Initial Velocity
Initial Angular Velocity
Magnetic Force

Gravity Components

Gravity Vector
Gravity Controls

Interaction Components

Physics Simulation Controls
Point Click Force

Editor Tools

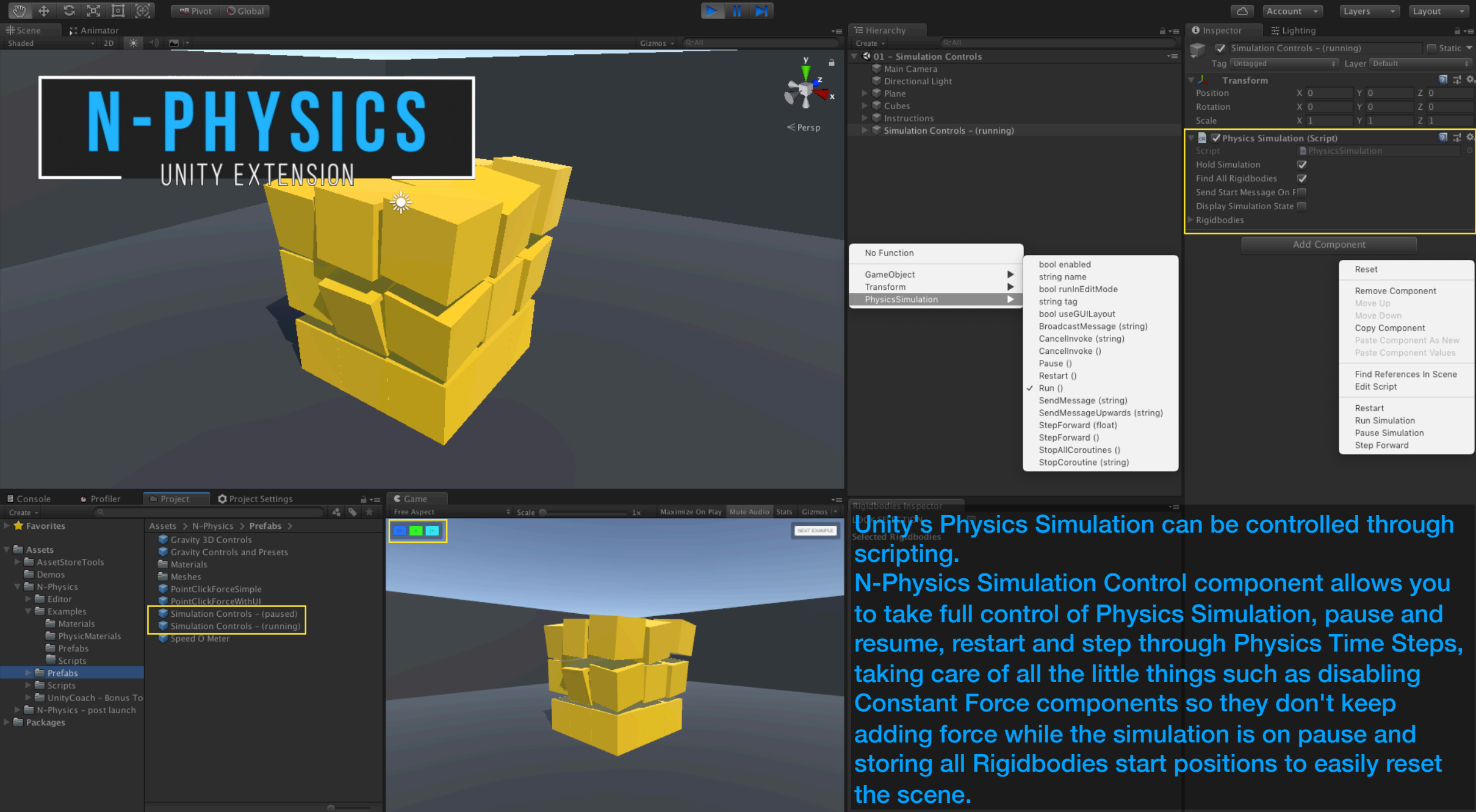
Rigidbody Inspector
Center Pivot On Colliders

Characters Components

Ragdoll Switch

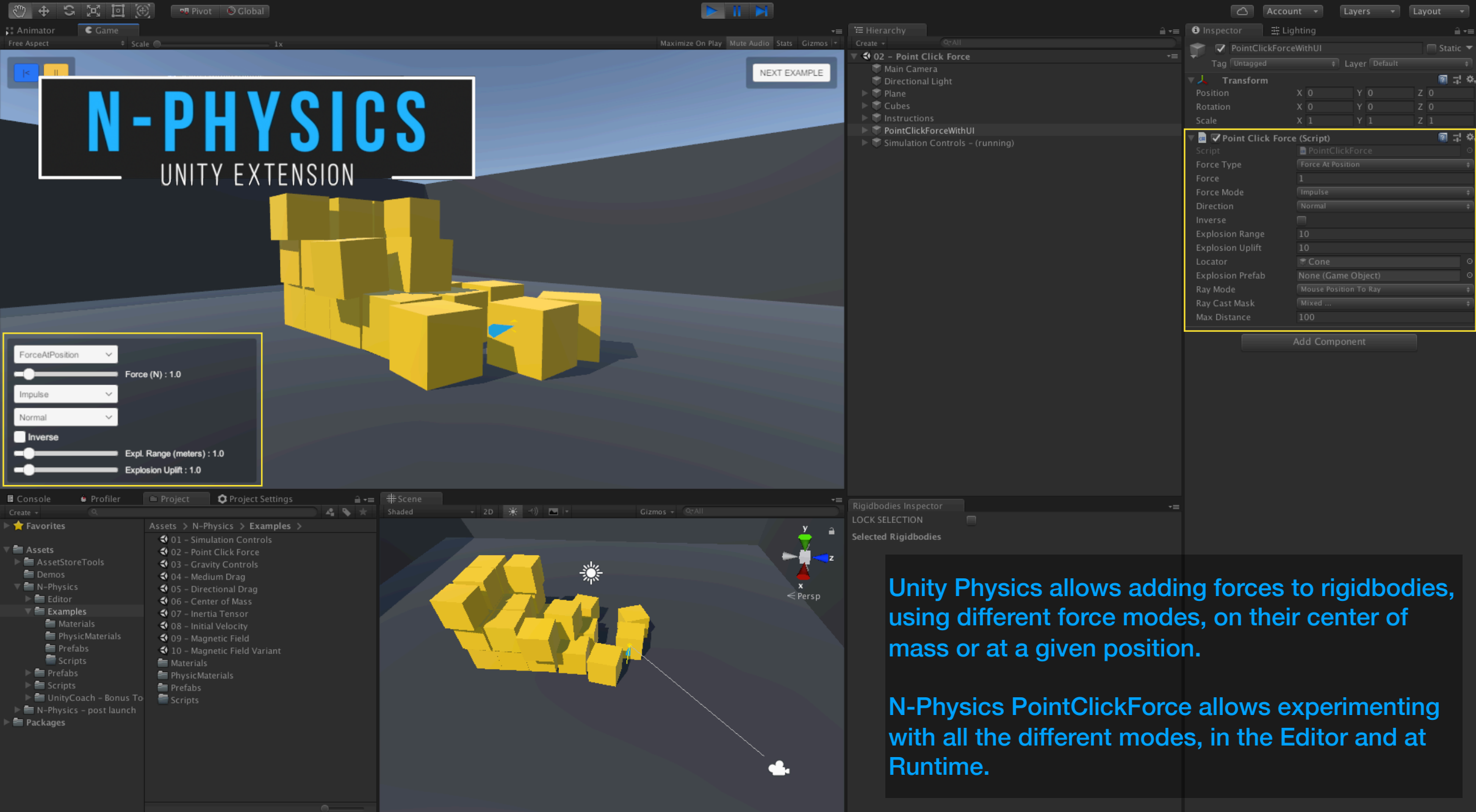
Medium Components

Drag Modifier



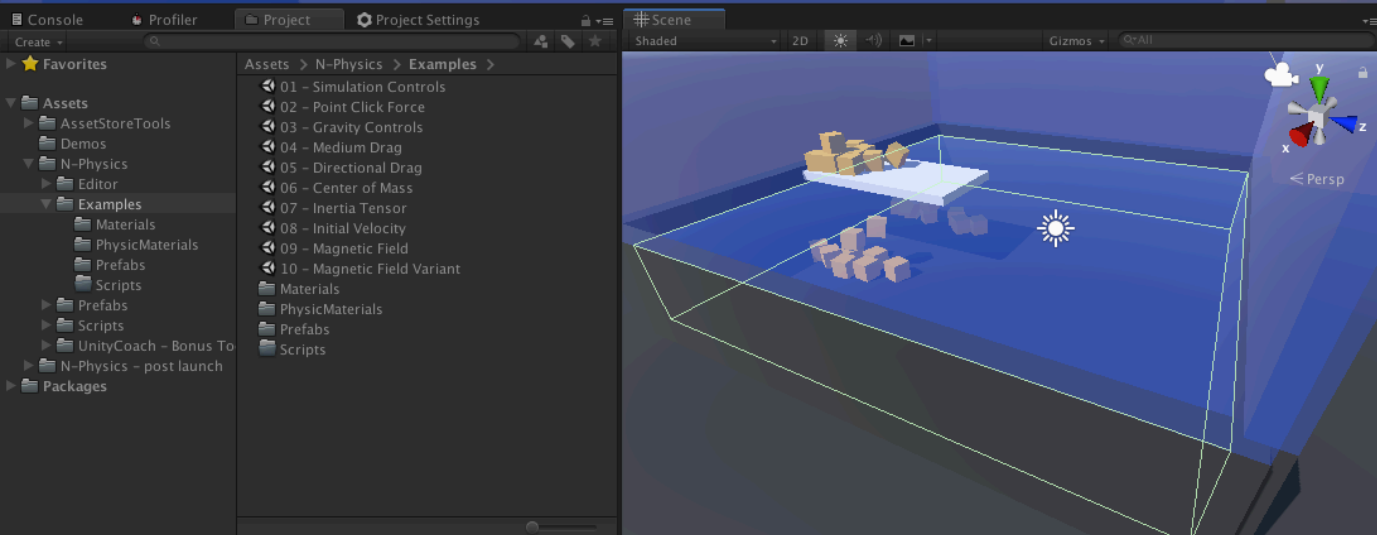
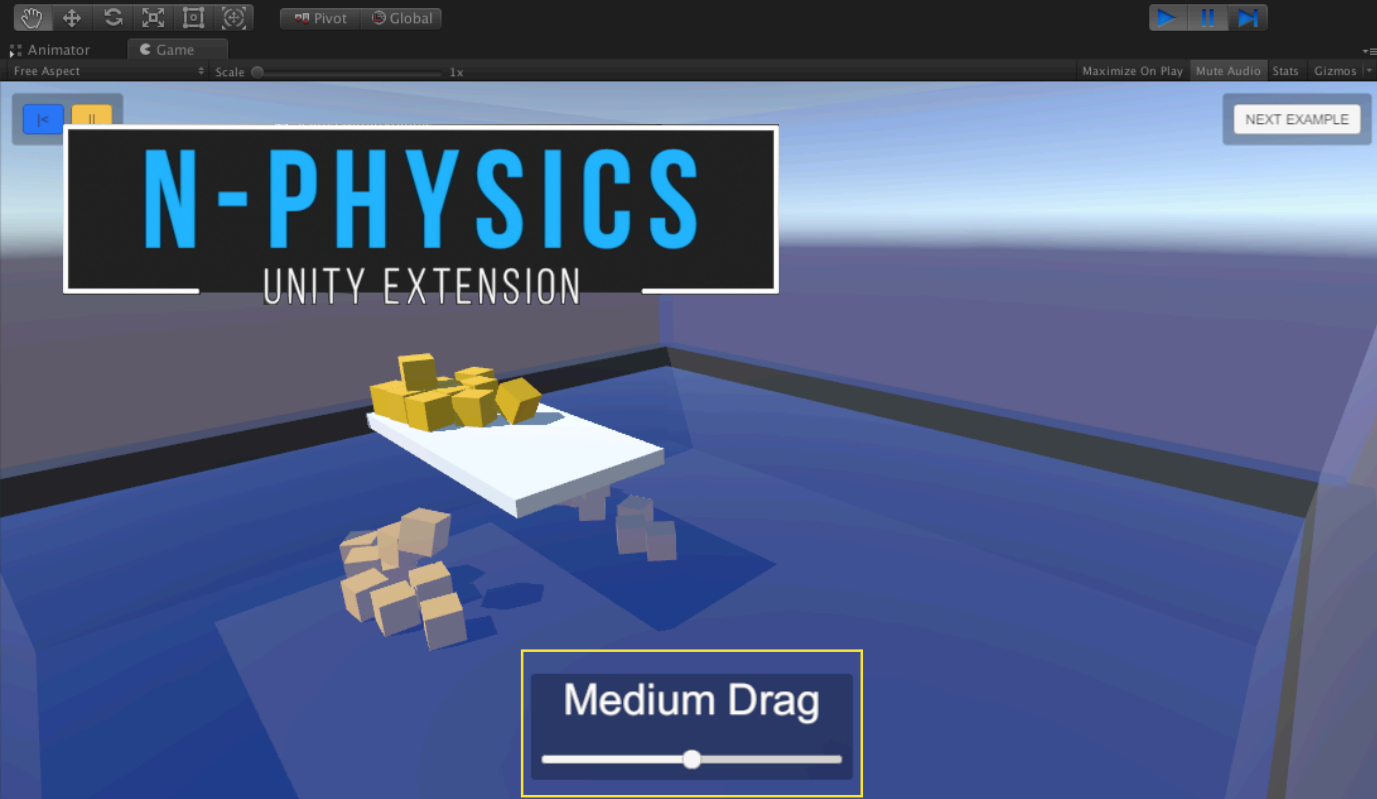
Unity's Physics Simulation can be controlled through scripting.

N-Physics Simulation Control component allows you to take full control of Physics Simulation, pause and resume, restart and step through Physics Time Steps, taking care of all the little things such as disabling Constant Force components so they don't keep adding force while the simulation is on pause and storing all Rigidbody start positions to easily reset the scene.



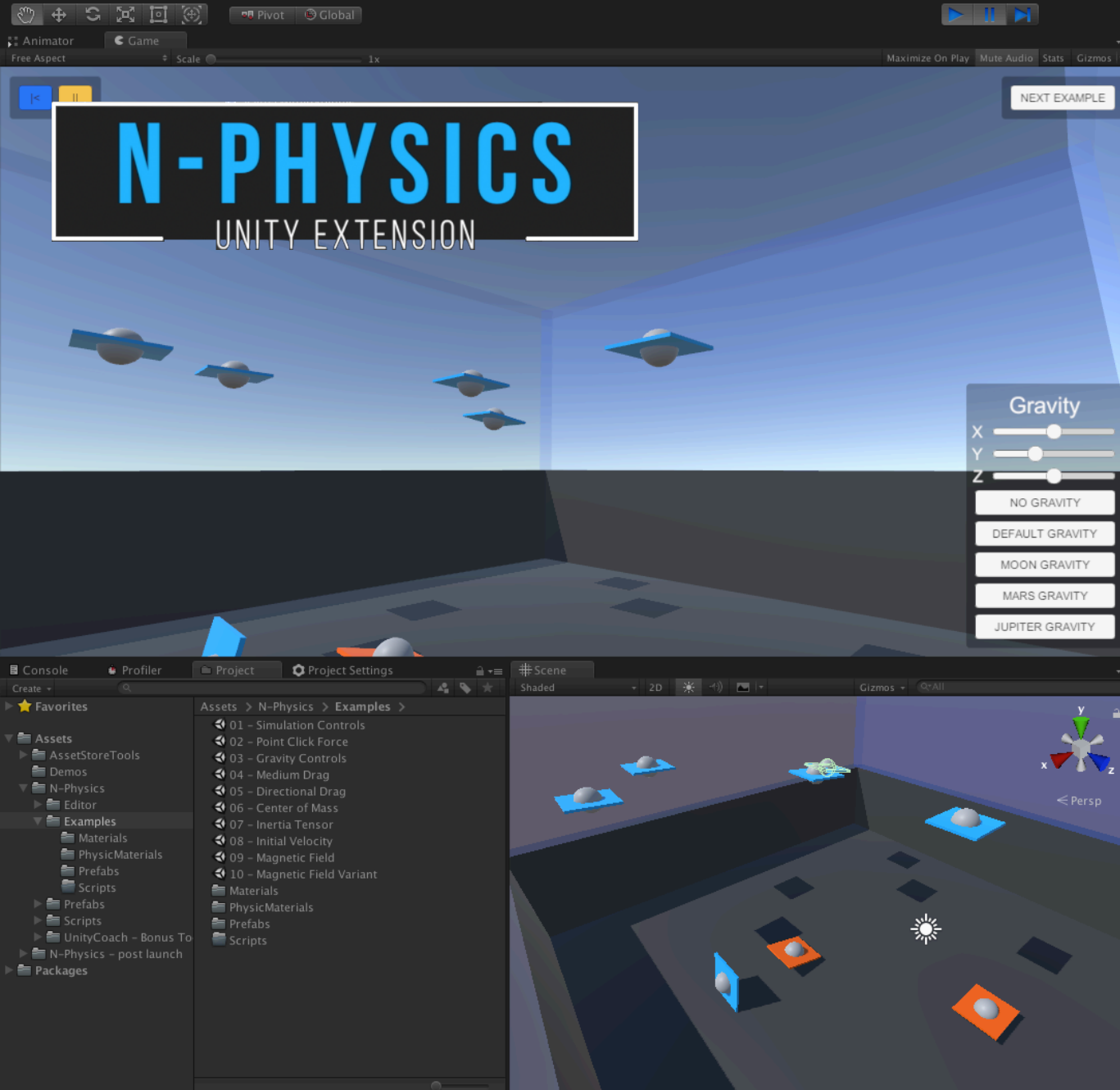


N-Physics Gravity Controls and Gravity Vector components allows setting a different gravity per scene and easily adjust Gravity using UI sliders.



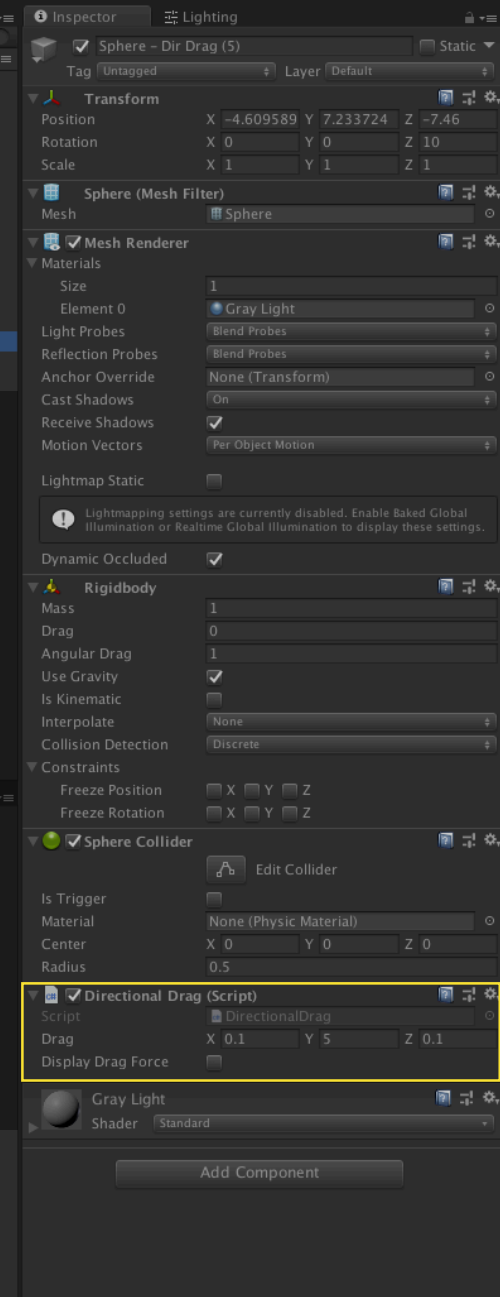
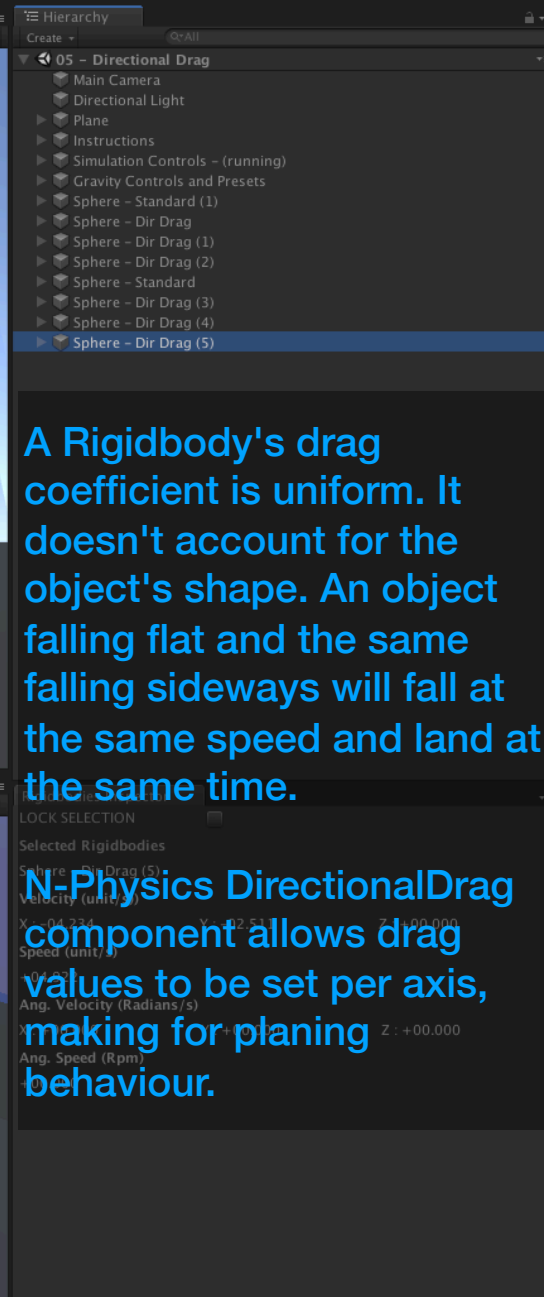
A Rigidbody's drag coefficient sets its Air Resistance.

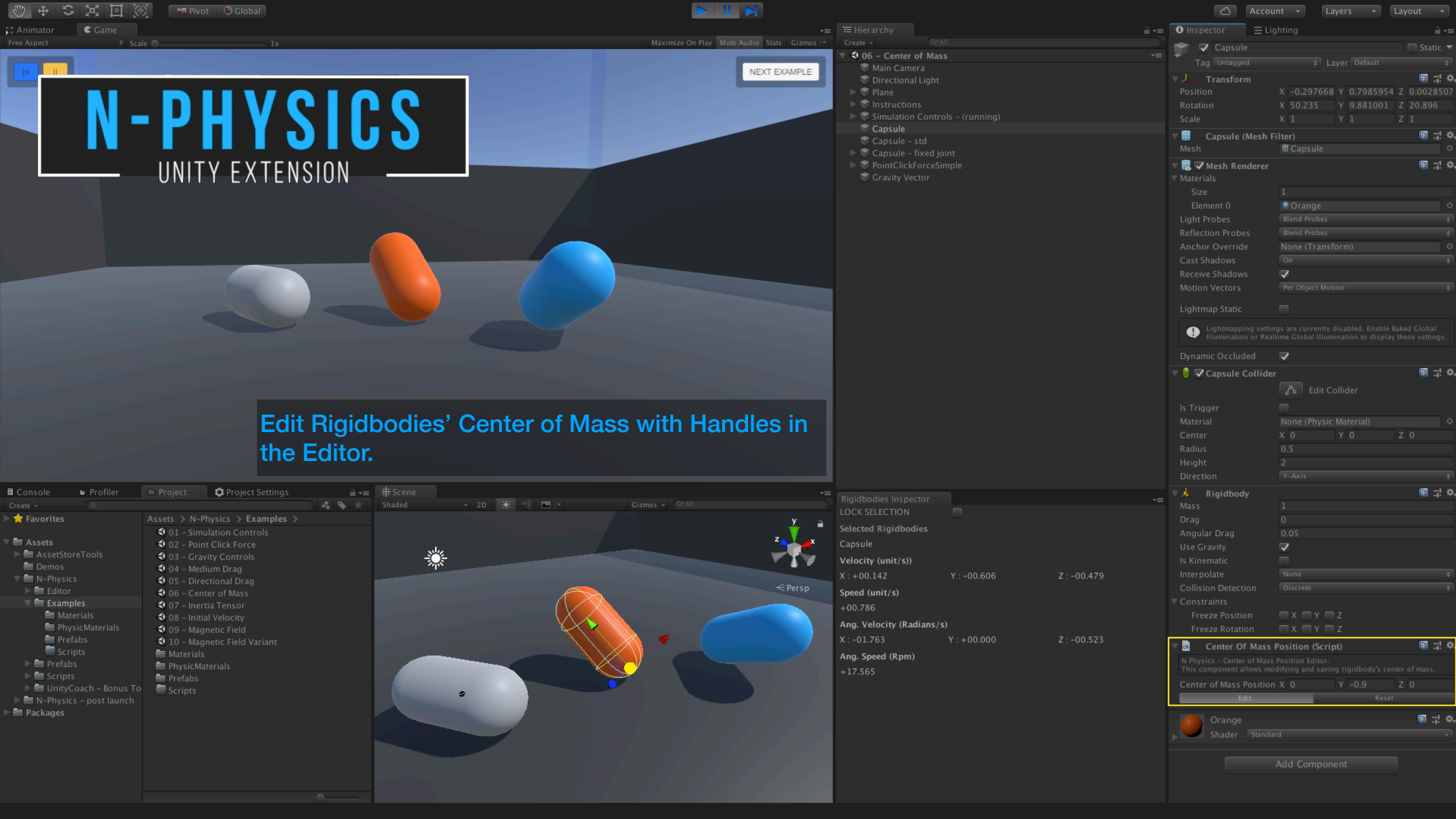
N-Physics Medium Drag component allows changing a Rigidbody's drag coefficient as it enters or exits a trigger collider (medium), making for objects slow down when then get into water or mud.

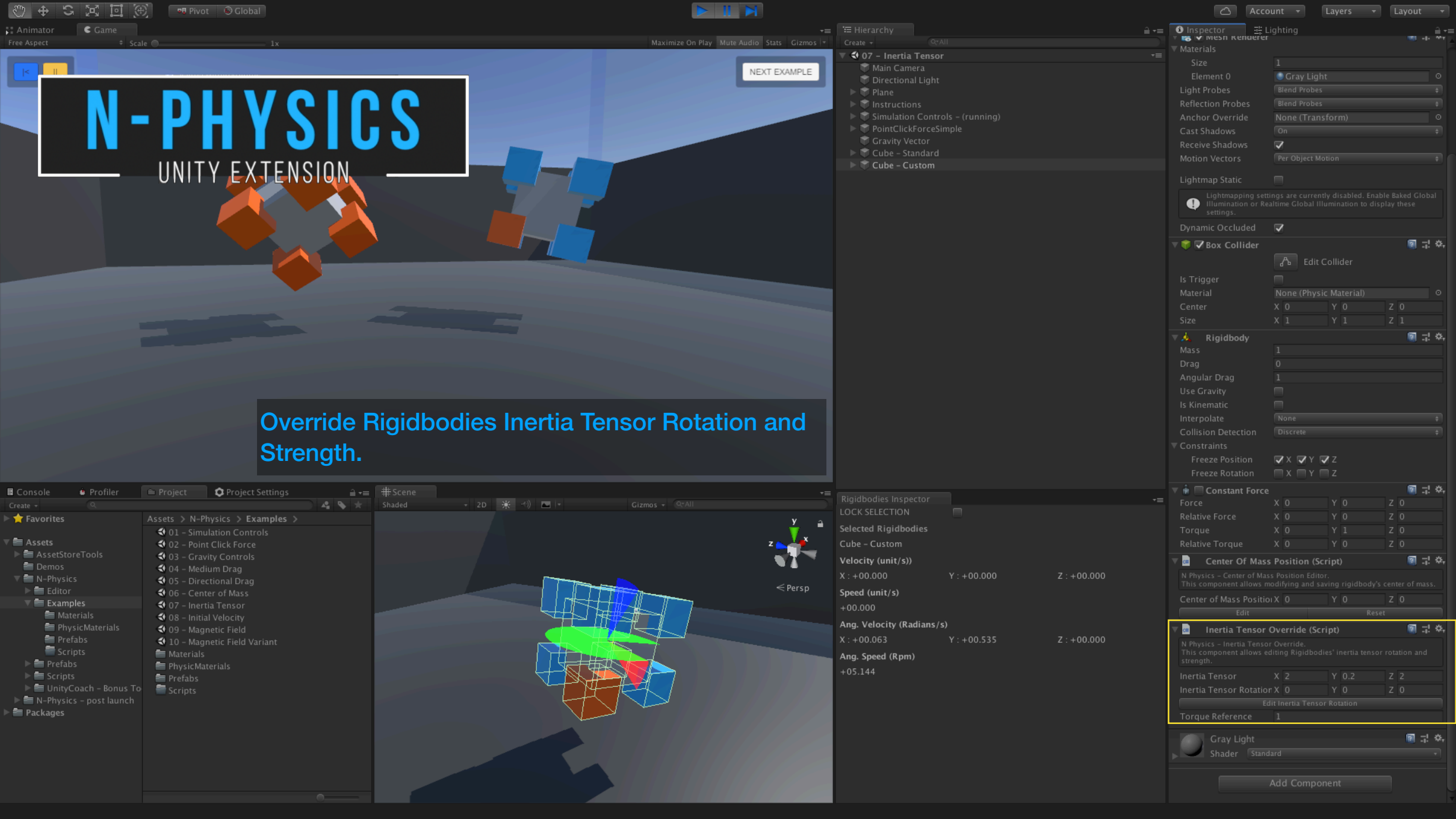


A Rigidbody's drag coefficient is uniform. It doesn't account for the object's shape. An object falling flat and the same falling sideways will fall at the same speed and land at the same time.

N-Physics DirectionalDrag component allows drag values to be set per axis, making for planing behaviour.







N-PHYSICS

UNITY EXTENSION

Override Rigidbodies Inertia Tensor Rotation and Strength.

Hierarchy

Create

07 - Inertia Tensor

- Main Camera
- Directional Light
- Plane
- Instructions
- Simulation Controls - (running)
- PointClickForceSimple
- Gravity Vector
- Cube - Standard
- Cube - Custom

Inspector

Mesh Renderer

Materials

- Size: 1
- Element 0: Gray Light
- Light Probes: Blend Probes
- Reflection Probes: Blend Probes
- Anchor Override: None (Transform)
- Cast Shadows: On
- Receive Shadows: ☒
- Motion Vectors: Per Object Motion

Lightmap Static

Lightmapping settings are currently disabled. Enable Baked Global Illumination or Realtime Global Illumination to display these settings.

Dynamic Occluded: ☒

Box Collider

Edit Collider

Is Trigger: ☐

Material: None (Physic Material)

Center: X 0 Y 0 Z 0

Size: X 1 Y 1 Z 1

Rigidbody

Mass: 1

Drag: 0

Angular Drag: 1

Use Gravity: ☐

Is Kinematic: ☐

Interpolate: None

Collision Detection: Discrete

Constraints

Freeze Position: ☒ X ☒ Y ☒ Z

Freeze Rotation: ☐ X ☐ Y ☐ Z

Constant Force

Force: X 0 Y 0 Z 0

Relative Force: X 0 Y 0 Z 0

Torque: X 0 Y 1 Z 0

Relative Torque: X 0 Y 0 Z 0

Center Of Mass Position (Script)

N Physics - Center of Mass Position Editor. This component allows modifying and saving rigidbody's center of mass.

Center of Mass Position: X 0 Y 0 Z 0

Edit Reset

Inertia Tensor Override (Script)

N Physics - Inertia Tensor Override. This component allows editing Rigidbodies' inertia tensor rotation and strength.

Inertia Tensor: X 2 Y 0.2 Z 2

Inertia Tensor Rotation: X 0 Y 0 Z 0

Edit Inertia Tensor Rotation

Torque Reference: 1

Gray Light

Shader: Standard

Add Component

N-PHYSICS

UNITY EXTENSION

Set Rigidbodies initial velocity and initial angular velocity to put them in motion upon Start.

Hierarchy

- Create
- 08 - Initial Velocity
 - Main Camera
 - Directional Light
 - Plane
 - Instructions
 - Simulation Controls - (running)
 - PointClickForceSimple
 - Gravity Vector
 - Cube

Inspector

Cube

Tag Untagged Layer Default

Transform

Position	X 0.127688	Y 1.181011	Z 0
Rotation	X 0	Y -7.2	Z 32.999
Scale	X 1	Y 1	Z 1

Cube (Mesh Filter)

Mesh Cube

Mesh Renderer

Materials

Size 1

Element 0 Yellow

Light Probes Blend Probes

Reflection Probes Blend Probes

Anchor Override None (Transform)

Cast Shadows On

Receive Shadows ☒

Motion Vectors Per Object Motion

Lightmap Static ☐

Lightmapping settings are currently disabled. Enable Baked Global Illumination or Realtime Global Illumination to display these settings.

Dynamic Occluded ☒

Box Collider

Edit Collider

Is Trigger ☐

Material None (Physic Material)

Center X 0 Y 0 Z 0

Size X 1 Y 1 Z 1

Rigidbody

Mass 1

Drag 0

Angular Drag 0

Use Gravity ☒

Is Kinematic ☐

Interpolate None

Collision Detection Discrete

Constraints

Freeze Position ☐ X ☐ Y ☐ Z

Freeze Rotation ☐ X ☐ Y ☐ Z

Initial Velocity (Script)

N Physics - Initial Velocity.

This component allows giving a Rigidbody an initial velocity.

Direction X 0.638436 Y 0.769674 Z 0

Magnitude 10

Use World Space ☒

Edit

Initial Angular Velocity (Script)

N Physics - Initial Angular Velocity.

This component allows giving a Rigidbody an initial angular velocity.

Script InitialAngularVelocity

Direction X 0 Y 1 Z 0

Rpm 60

Use World Space ☐

Rigidbody Inspector

LOCK SELECTION

Selected Rigidbodies

Cube

Velocity (unit/s)

X : +06.384 Y : +07.501 Z : +00.000

Speed (unit/s)

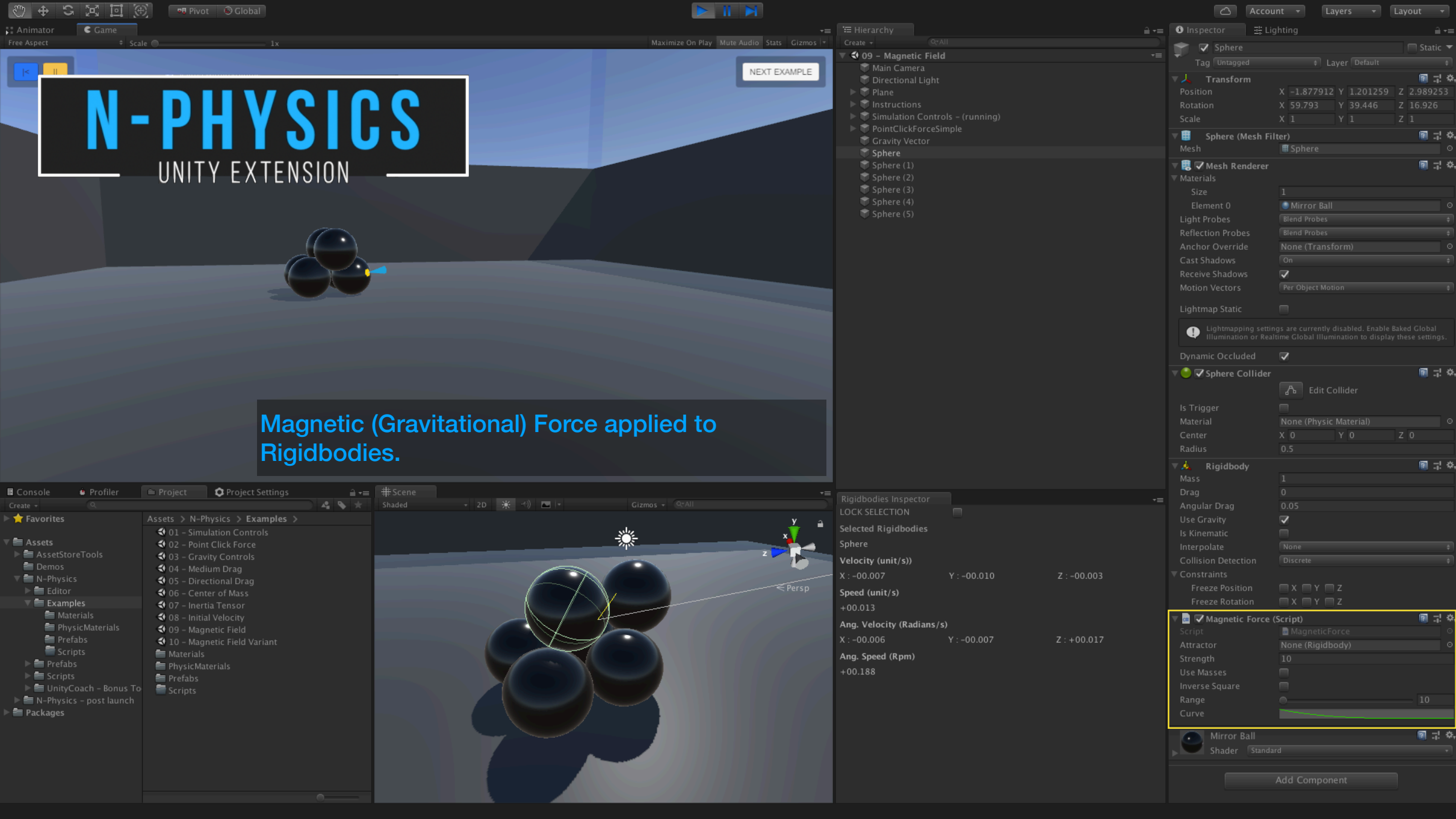
+09.850

Ang. Velocity (Radians/s)

X : -00.000 Y : -06.283 Z : +00.000

Ang. Speed (Rpm)

+60.000



N-PHYSICS

UNITY EXTENSION

Magnetic (Gravitational) Force applied to Rigidbodies.

NEXT EXAMPLE

Hierarchy

Create

09 - Magnetic Field

- Main Camera
- Directional Light
- Plane
- Instructions
- Simulation Controls - (running)
- PointClickForceSimple
- Gravity Vector
- Sphere
 - Sphere (1)
 - Sphere (2)
 - Sphere (3)
 - Sphere (4)
 - Sphere (5)

Inspector

Lighting

Sphere

Tag Untagged

Layer Default

Transform

Position

Rotation

Scale

Sphere (Mesh Filter)

Mesh

Mesh Renderer

Materials

Size

Element 0

Light Probes

Reflection Probes

Anchor Override

Cast Shadows

Receive Shadows

Motion Vectors

Lightmap Static

Dynamic Occluded

Sphere Collider

Is Trigger

Material

Center

Radius

Rigidbody

Mass

Drag

Angular Drag

Use Gravity

Is Kinematic

Interpolate

Collision Detection

Constraints

Freeze Position

Freeze Rotation

Magnetic Force (Script)

Script

Attractor

Strength

Use Masses

Inverse Square

Range

Curve

Mirror Ball

Shader

Standard

Add Component



N-PHYSICS

UNITY EXTENSION

Spring Renderer, renders a SpringJoint using a LineRenderer.

N-PHYSICS

UNITY EXTENSION

N-Physics Window Help
Center Transform on Colliders Bounds
Rigidbody Inspector



Rigidbody Inspector
allows reading velocity values