1. Given s= 0.30/160	-u), where s is the spacing in miles (m1) and u is the coord in miles on hout I
drive the relationshi	P u-k, g-k, and u-g. Also, estimate the reposity lie a) at the
Solution:	(III mont) j vie podol way.
	$U_5 = 60$ $K_1 = \frac{60}{2} = 200$
Ou-K	·
@ 9-K	
3 u-q	
@ 9 max	
	Print 4 st.
2. The optimum speed	l and the optimum density for the high-speed freeway data set is assumed to be 60 s
per hour and 50	vehicles per mile per lane respectively determine the equation for the Grandon Un
and Northwestern	$U_f = 60 , K_j = \frac{60}{0.30} = 200$ $U = U_f + \frac{U_f}{K_j} K = 60 - \frac{60}{200} K = 60 - 0.30 K$ $Q = U_k = \frac{1}{100} (60 - 0.30 K) K = -0.30 K^2 + 60 K$ $U = Q$ $Q = U_k = U_0 + \frac{60 - U}{0.30} = -\frac{10}{3} U^2 + 200 U$ $Q = U_k = U_0 + \frac{1}{100} U^2 + 200 U$ $Q = U_k = U_0 + \frac{1}{100} U^2 + 200 U$ $Q = U_k = U_0 + \frac{1}{100} U^2 + 200 U$ $Q = U_k = U_0 + \frac{1}{100} U^2 + 200 U$ $Q = U_0 + \frac{1}{100} U^2 + \frac{1}{1$
Solution:	June 1 Mare 100%
	$u_0 = 40$, $k_0 = 50$, $u_1 = 40 \times 2 = 80$, $k_1 = 50 \times 2 = 100$
1) Green berg	
(E) Underwood	
Morthwestern	
	9=uk= 80e-1150)k= 80KP-1150)2
	7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7
3. A heliupter pilot	recorded the travel time of five vehicles on a 2-mile segment of a highway. Estimated the
time-mean speed and	space-mean speed of the vehicles.
Vehicles	Travel Times (Sec)
1	163

3 4

149

Solution:

$$v_{1} = \frac{d}{t_{1}} = \frac{2 \times 5280}{726} \text{ ft/s} = 83.81 \text{ ft/s}$$

$$v_{2} = \frac{d}{t_{1}} = \frac{2 \times 5280}{163} \text{ ft/s} = 64.79 \text{ ft/s}$$

$$v_{3} = \frac{2 \times 5280}{163} \text{ ft/s} = 64.79 \text{ ft/s}$$

$$V_3 = \frac{d}{t_3} = \frac{2 \times 1280}{149} \text{ ft/s} = 70.87 \text{ ft/s}$$

$$V_4 : \frac{d}{t_4} : \frac{2 \times 1280}{139} \text{ ft/s} : 75.97 \text{ ft/s}$$

= 70.03 ft/s (space-mean speed SAA; = ti+ti+t; +tx+tr = 126+163+1×9+139+193

$$SMS = \frac{d}{d} = \frac{1x4}{2 \times x280} + t/s = 68.57 + t/s$$

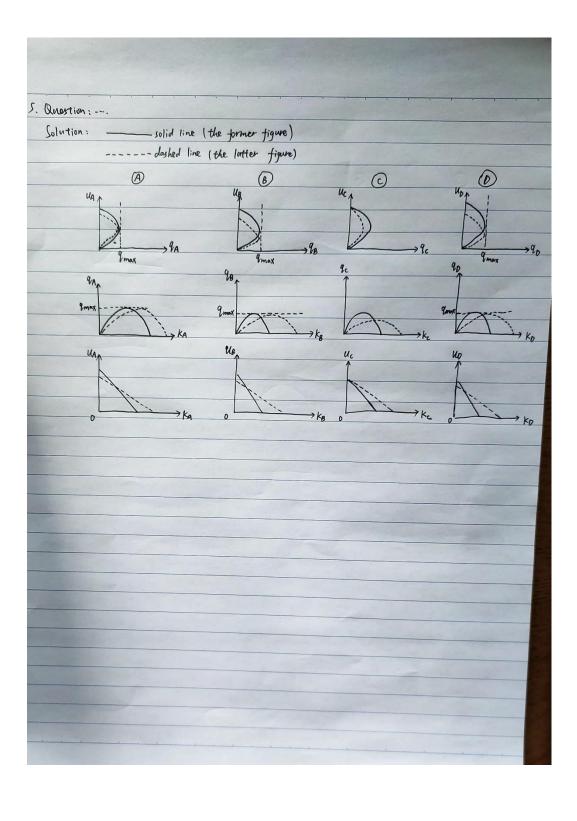
4. A line of rehicles are in corfolowing mode and all rehicles are traveling on 44 feet per second with distance headways of 114 feet. The lead vehicle suddenly decelerates at a rate of 46 feet per second writing worth it stops completely Calculate and plot the projectory of the lead and only the first following vehicle for every second of time until both vehicles are stapped. Use the GM first cor-following model. Consider three different drivers in the following rehicle with the following characteristics.

Driver	Repetien Time D	t Sensitivity	forameter d
	10	0.17	177
ì	1-55	0.37	
. 3	2.2	0.74	SHILL PL

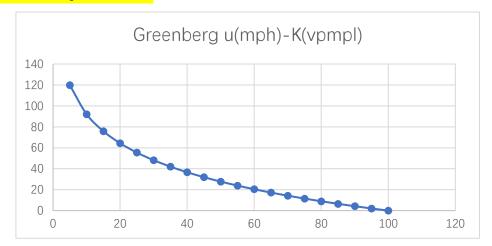
Solution:

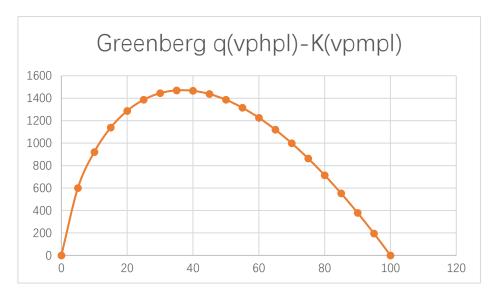
$$\begin{array}{lll} \textit{Model} & \dot{X}_{net}(t+\delta t) = \lambda \left[\dot{X}_{n}(t) - \dot{X}_{net}(t*) \right] \\ \textit{Order} & \dot{X}_{L}(t+\delta t) = 0.17 \left[\dot{X}_{1}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.37 \left[\dot{X}_{1}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.37 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t+\delta t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X}_{L}(t) - \dot{X}_{L}(t) \right] \\ \dot{X}_{L}(t) = 0.74 \left[\dot{X$$

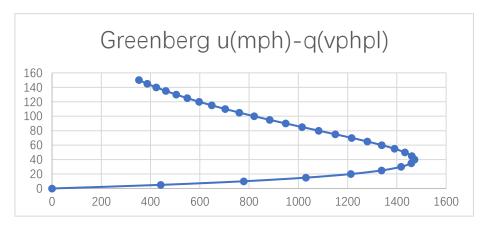
For more information, please infer the following charts and figures.

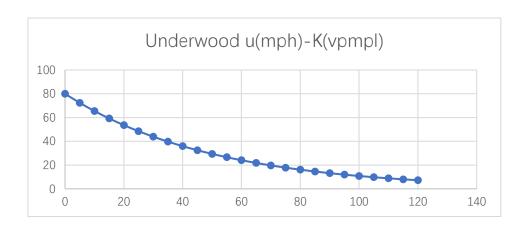


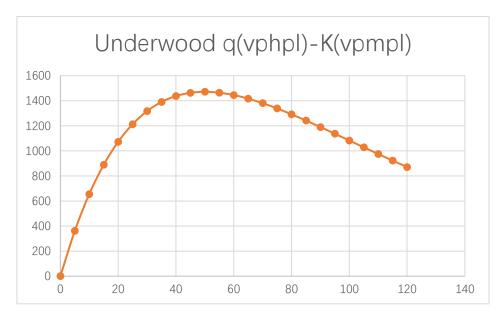
Figures for Question 2:

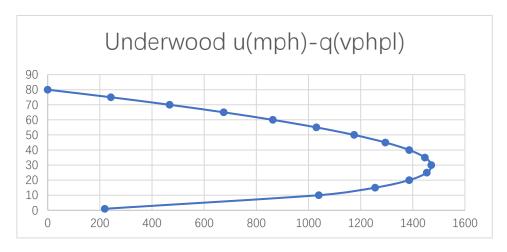


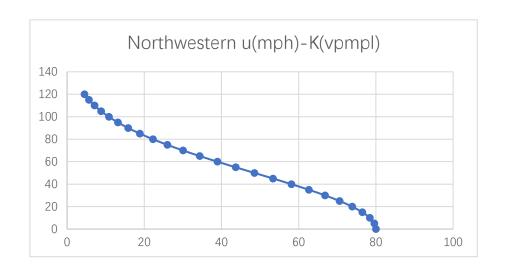


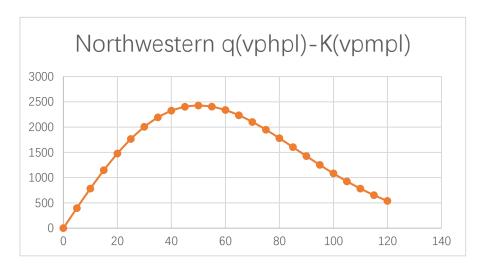


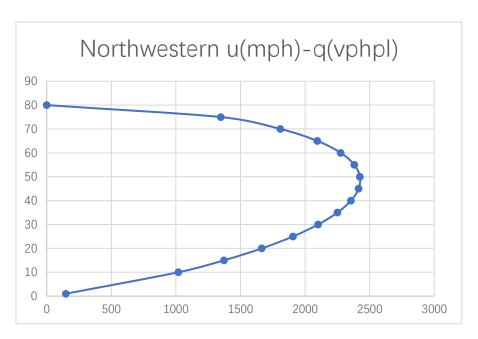


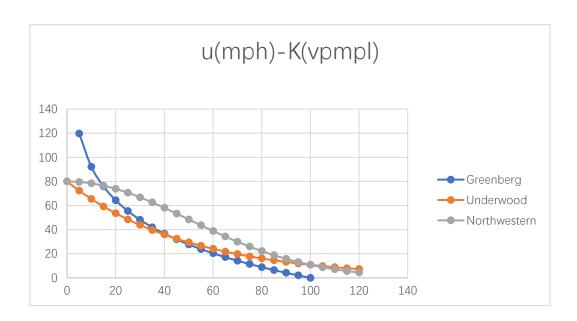


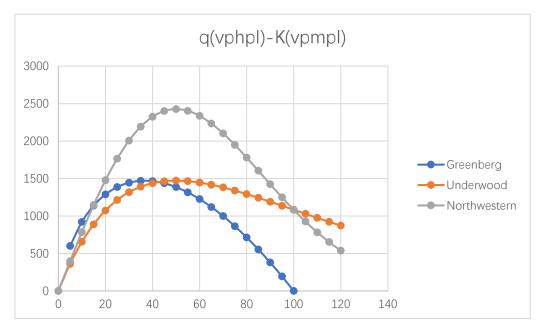


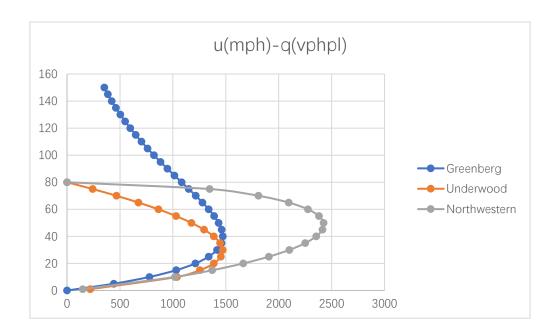






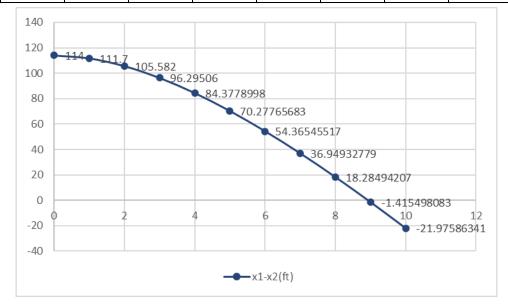




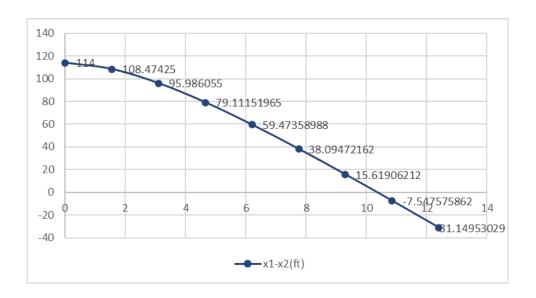


Charts and Figures for Question 4:

t(s)	x1'(ft/s)	x2'(ft/s)	α(1/s)	x2''(ft/s/s)	Δx1(ft)	Δx2(ft)	x1-x2(ft)
0	44	44	0.17	0	0	0	114
1	39.4	44		-0.782	41.7	44	111.7
2	34.8	43.218		-1.43106	37.1	43.218	105.582
3	30.2	41.78694		-1.96978	32.5	41.78694	96.29506
4	25.6	39.81716		-2.41692	27.9	39.81716	84.3779
5	21	37.40024		-2.78804	23.3	37.40024	70.27766
6	16.4	34.6122		-3.09607	18.7	34.6122	54.36546
7	11.8	31.51613		-3.35174	14.1	31.51613	36.94933
8	7.2	28.16439		-3.56395	9.5	28.16439	18.28494
9	2.6	24.60044		-3.74007	4.9	24.60044	-1.4155
10	-2	20.86037		-3.88626	0.3	20.86037	-21.9759



t(s)	x1'(ft/s)	x2'(ft/s)	α(1/s)	x2"(ft/s/s)	x1(ft)	x2(ft)	x1-x2(ft)
0	44	44	0.37	0	0	0	114
1.55	36.87	44		-2.6381	62.67425	68.2	108.4743
3.1	29.74	41.3619		-4.3001	51.62275	64.11095	95.98606
4.65	22.61	37.0618		-5.34716	40.57125	57.44579	79.11152
6.2	15.48	31.71463		-6.00681	29.51975	49.15768	59.47359
7.75	8.35	25.70782		-6.42239	18.46825	39.84712	38.09472
9.3	1.22	19.28543		-6.68421	7.41675	29.89241	15.61906
10.85	-5.91	12.60122		-6.84915	-3.63475	19.53189	-7.54758
12.4	-13.04	5.752067		-6.95306	-14.6863	8.915704	-31.1495



t(s)	x1'(ft/s)	x2'(ft/s)	α(1/s)	x2''(ft/s/s)	x1(ft)	x2(ft)	x1-x2(ft)
0	44	44	0.74	0	0	0	114
2.2	33.88	44		-7.4888	85.668	96.8	102.868
4.4	23.76	27.52464		-2.78583	63.404	60.55421	105.7178
6.6	13.64	21.39581		-5.7393	41.14	47.07077	99.78702
8.8	3.52	8.769354		-3.88452	18.876	19.29258	99.37044
11	-6.6	0.223406		-5.04932	-3.388	0.491493	95.49095
13.2	-16.72	-10.8851		-4.31783	-25.652	-23.9472	93.78616

