Transformer to BERT

20191106 MEANIMO_NLP 한승우

0. Attention

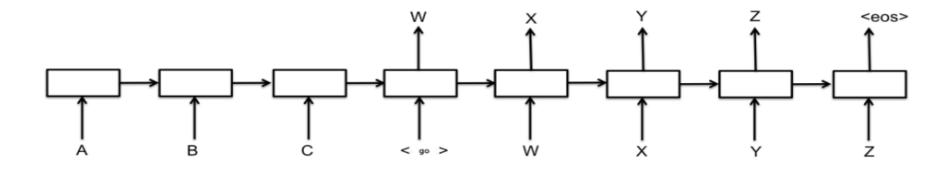
- 0-1. Sequence to Sequence 0-2. Attention
- 0-3. Attention in sequence to sequence

1. Transformer

- 1-1Scaled Dot-Product Attention
- 1-2MultiHead Attention
- 1-3Pointwise Feedforward Networks

2. BERT

Sequence to Sequence



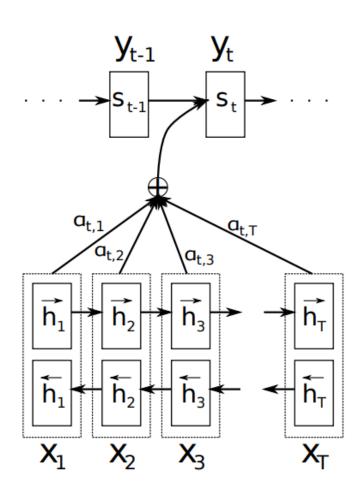
Encoder: Input sentence [A,B,C] 의 언어적 지식을 학습

Decoder: Output(target) sentence [W,X,Y,Z]의 언어적 지식을 학습

Sequence to Sequence 가 학습하는 기준은 $maximize \sum P_{\theta}\left(y_{1:m}|x_{1:n}\right)$ x:1:n과 y1:m의 상관성을 최대화 하는 것

$$P(y_{1:m}|x_{1:n}) = \prod_{i} P(y_{i}|y_{1:i-1}, c)$$

Sequence to Sequence with Attention



"하나의 Context Vector c 로는 Decoder의 각 단어를 충분히 표현할 수 없다."

그래서,

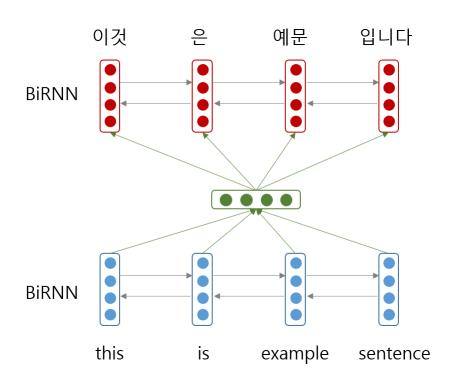
$$c_i = \sum_j a_{ij} * h_j$$

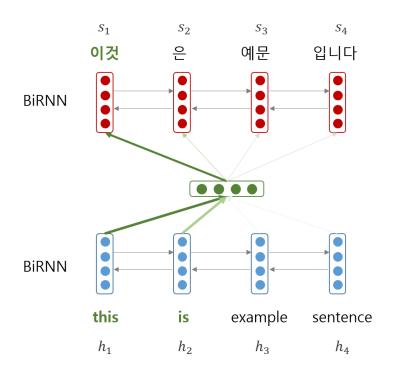
- $-a_{ij}$ 는 y_i 를 선택할 때 encoder RNN의 h_i 를 얼만큼 이용할지에 대한 값
- hj 는 Encoder의 hidden state

$$-a_{ij} = \frac{\exp(e_{ij})}{\Sigma(\exp(e_{ij}))}$$

$$-e_{ij} = f(s_{i-1}, \mathbf{h_j})$$

Sequence to Sequence with Attention





Transformer

Seq2Seq 모델들의 한계점

- 1. 모델의 크기가 크다.
- 2. RNN은 반드시 sequence의 마지막 부분까지 계산이 완료되어야 한다.
- 3. Sequence에 대한 작업을 병렬적으로 진행 불가
- 4. Long dependency문제

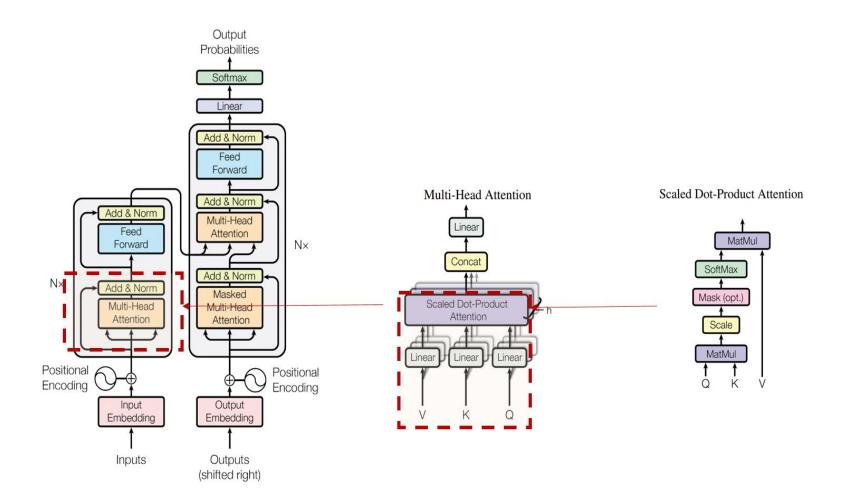
"Encoder 와 Decoder에 모두 Attention을 이용하자!!"

Transformer

Transformer 네트워크의 구성

- 1. Scaled Dot-Product Attention
- 2. MultiHead Attention
- 3. Pointwise Feedforward Networks

Seq2Seq 과 Transformer



Seq2Seq ~= **Transformer**

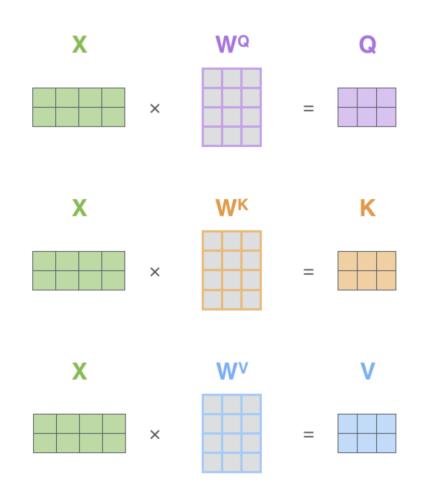
$$s_{i-1} = Query$$

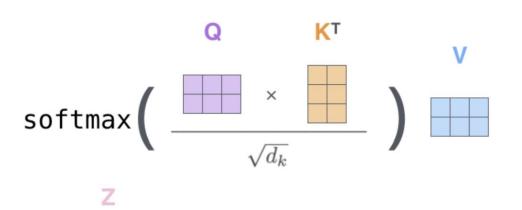
 $h_i = Key$, Value

Seq2Seq != Transformer

Additive Attention != Multiplicative Attention

Scaled Dot-Product Attention

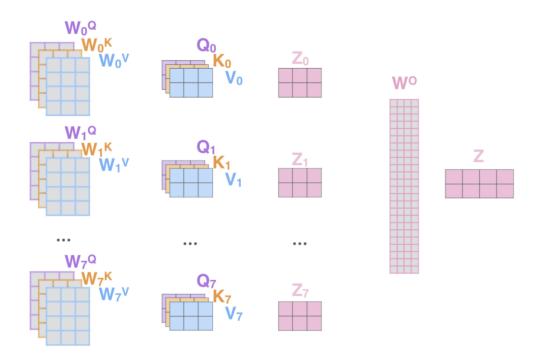




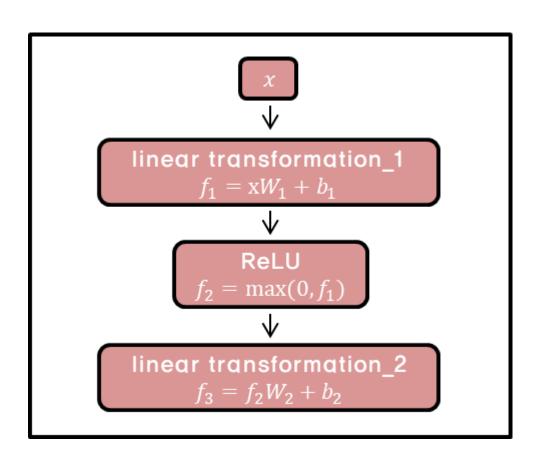
- 1. Dot-Product
- 2. Attention
- 3. Scaled

Multi-Head Attention

```
MultiHead(Q,K,V) = Concat(head_1, head_2, ..., head_h)W^O
* head_i = Attention(QW_i^Q, KW_i^K, VW_i^V)
```

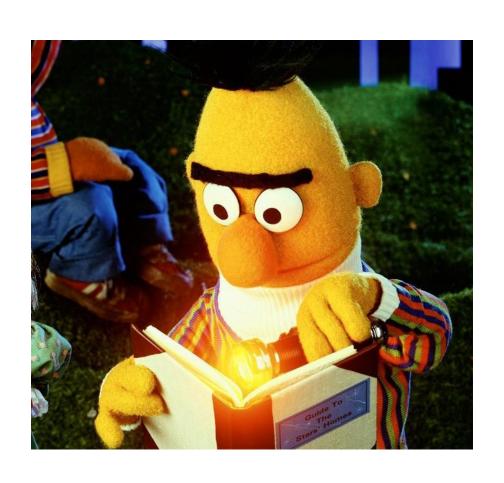


Pointwise Feedforward Networks



$$FFN(x) = max(0,x*W1+b1)W2 +b2$$

BERT



Masked Language Model

단방향 언어 모델 : 나는 어제 ____.
 양방향 언어 모델 : 나는 어제 ____ 먹었다.

GPT self-attention SDP = 보다
$$\begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0.9 & 0 & 0 \end{pmatrix}$$
 $\begin{pmatrix} V_{\text{T}} \\ V_{\text{L}} \\ V_{\text{H}} \\ V_{\text{H}} \end{pmatrix}$ = 보다 $\begin{pmatrix} 0V_{\text{T}} & 0V_{\text{L}} \\ 1V_{\text{T}} & 0V_{\text{L}} \\ 0.9V_{\text{T}} & 0V_{\text{L}} \\ 0.9V_{\text{L}} \\ 0.9V_{\text{L}} & 0V_{\text{L}} \\ 0.9V_{\text{L}} & 0V_{\text{L}} \\ 0.9V_{\text{L}} & 0V_{\text{L}} \\ 0.9V_{\text{L}} \\ 0.9V_{\text{L}} & 0V_{\text{L}} \\ 0.9V_{\text{L}} \\ 0.9V_{$

BERT Model Structure

