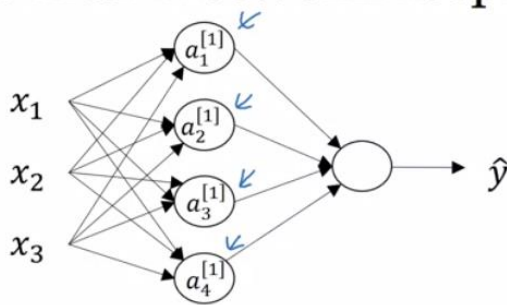


Week 3

$[l] \leftarrow$ layer
 $a_i \leftarrow$ node in layer.

Neural Network Representation



$$\begin{aligned} z_1^{[1]} &= w_1^{[1]T} x + b_1^{[1]}, & a_1^{[1]} &= \sigma(z_1^{[1]}) \\ z_2^{[1]} &= w_2^{[1]T} x + b_2^{[1]}, & a_2^{[1]} &= \sigma(z_2^{[1]}) \\ z_3^{[1]} &= w_3^{[1]T} x + b_3^{[1]}, & a_3^{[1]} &= \sigma(z_3^{[1]}) \\ z_4^{[1]} &= w_4^{[1]T} x + b_4^{[1]}, & a_4^{[1]} &= \sigma(z_4^{[1]}) \end{aligned}$$

$$z^{[1]} = \begin{bmatrix} -w_1^{[1]T} \\ -w_2^{[1]T} \\ -w_3^{[1]T} \\ -w_4^{[1]T} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ b_3^{[1]} \\ b_4^{[1]} \end{bmatrix} = \begin{bmatrix} \rightarrow w_1^{[1]T} x + b_1^{[1]} \\ \rightarrow w_2^{[1]T} x + b_2^{[1]} \\ \rightarrow w_3^{[1]T} x + b_3^{[1]} \\ \rightarrow w_4^{[1]T} x + b_4^{[1]} \end{bmatrix} = \begin{bmatrix} z_1^{[1]} \\ z_2^{[1]} \\ z_3^{[1]} \\ z_4^{[1]} \end{bmatrix}$$

$(4, 3)$

$$(w_i^{[1]})^T x$$

Vectorizing across multiple examples

for $i = 1$ to m :

$$z^{[1]}(i) = W^{[1]}x^{(i)} + b^{[1]}$$

$$a^{[1]}(i) = \sigma(z^{[1]}(i))$$

$$z^{[2]}(i) = W^{[2]}a^{[1]}(i) + b^{[2]}$$

$$a^{[2]}(i) = \sigma(z^{[2]}(i))$$

$$X = \begin{bmatrix} x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & & | \\ | & | & & | \\ | & | & & | \end{bmatrix}$$

(n_x, m)

$$z^{[1]} = W^{[1]}X + b^{[1]}$$

$$\rightarrow A^{[1]} = \sigma(z^{[1]})$$

$$\rightarrow z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

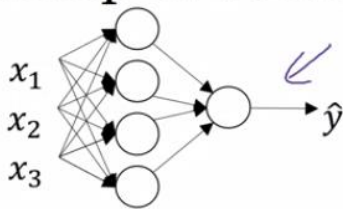
$$\rightarrow A^{[2]} = \sigma(z^{[2]})$$

$$z^{[1]} = \begin{bmatrix} z^{[1]}(1) & z^{[1]}(2) & \dots & z^{[1]}(m) \\ | & | & & | \end{bmatrix}$$

$$A^{[1]} = \begin{bmatrix} a^{[1]}(1) & a^{[1]}(2) & \dots & a^{[1]}(m) \\ | & | & & | \end{bmatrix}$$

Andrew

Recap of vectorizing across multiple examples



$$X = \begin{bmatrix} | & | & \dots & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & & | \end{bmatrix}$$

$$A^{[1]} = \begin{bmatrix} | & | & \dots & | \\ a^{[1]}(1) & a^{[1]}(2) & \dots & a^{[1]}(m) \\ | & | & & | \end{bmatrix}$$

for $i = 1$ to m

$$\rightarrow z^{[1]}(i) = W^{[1]}x^{(i)} + b^{[1]}$$

$$\rightarrow a^{[1]}(i) = \sigma(z^{[1]}(i))$$

$$\rightarrow z^{[2]}(i) = W^{[2]}a^{[1]}(i) + b^{[2]}$$

$$\rightarrow a^{[2]}(i) = \sigma(z^{[2]}(i))$$

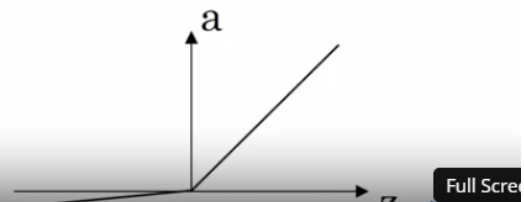
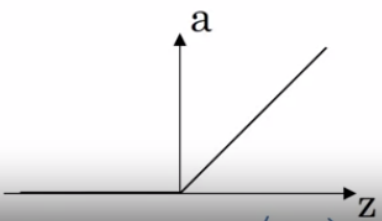
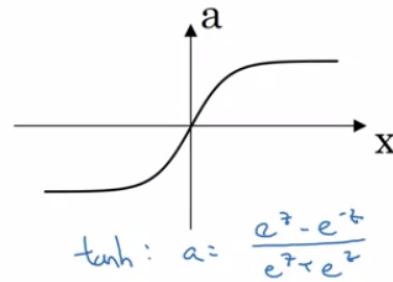
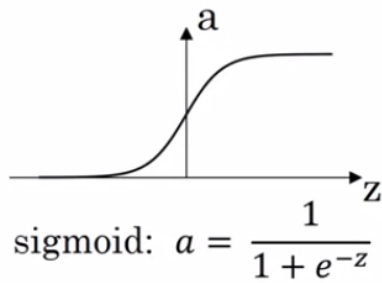
$$Z^{[1]} = W^{[1]}X + b^{[1]}$$

$$A^{[1]} = \sigma(Z^{[1]})$$

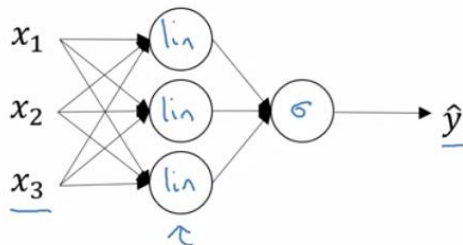
$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = \sigma(Z^{[2]})$$

Pros and cons of activation functions



Activation function



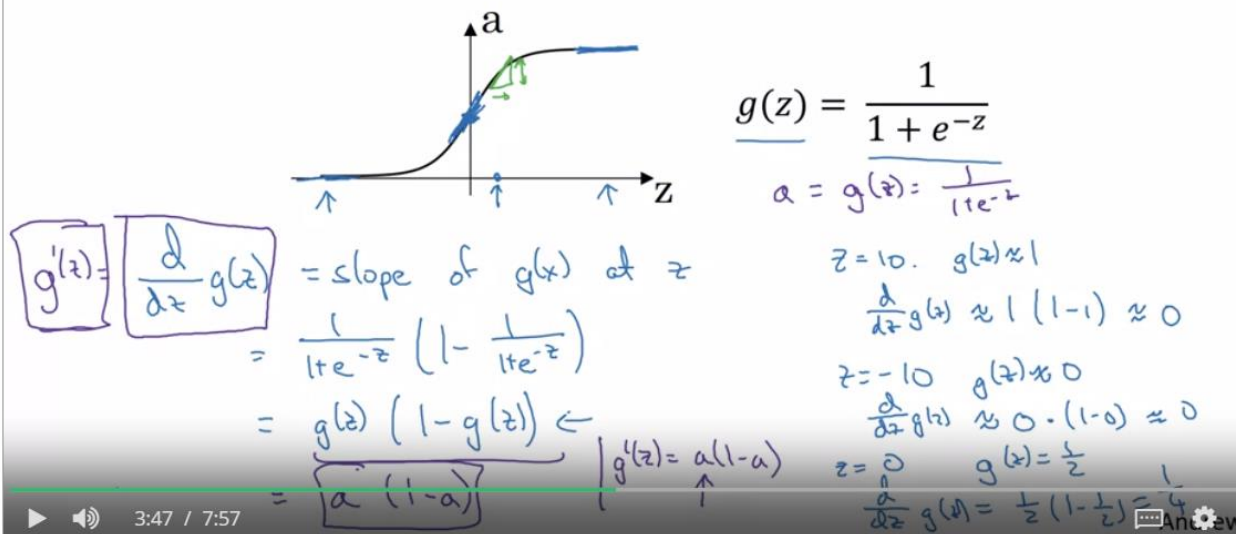
Given x :

$$\begin{aligned} \rightarrow z^{[1]} &= W^{[1]}x + b^{[1]} \\ \rightarrow a^{[1]} &= g(z^{[1]}) \\ \rightarrow z^{[2]} &= W^{[2]}a^{[1]} + b^{[2]} \\ \rightarrow a^{[2]} &= g(z^{[2]}) \end{aligned}$$

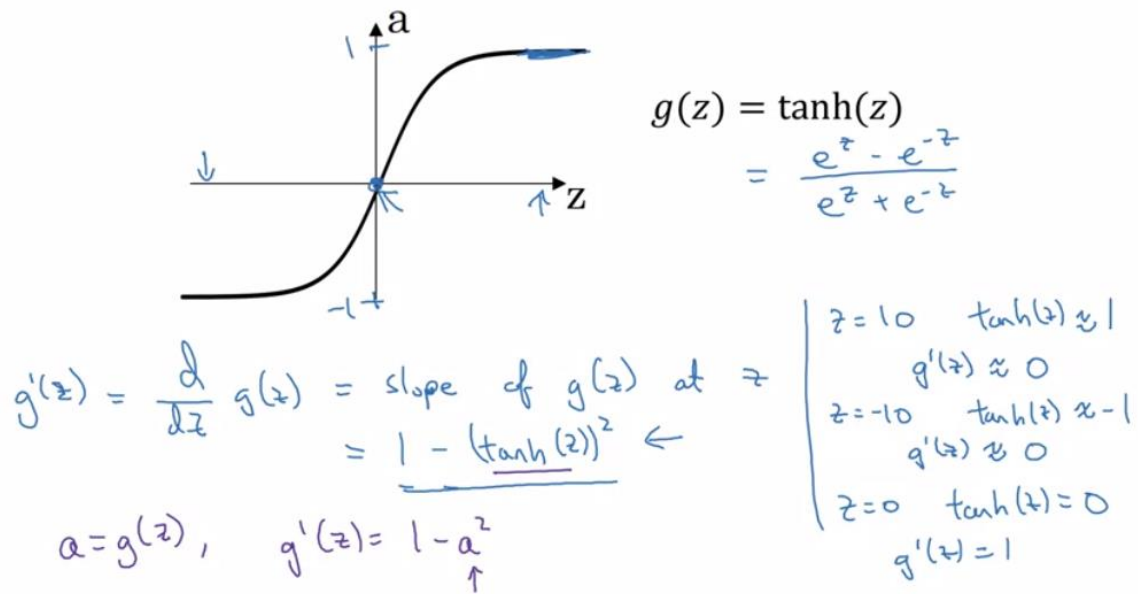
$g(z) = z$
"linear activation function"

$$\begin{aligned} a^{[1]} &= z^{[1]} = W^{[1]}x + b^{[1]} \\ a^{[2]} &= z^{[2]} = W^{[2]}a^{[1]} + b^{[2]} \\ a^{[2]} &= W^{[2]}(W^{[1]}x + b^{[1]}) + b^{[2]} \\ &= (W^{[2]}W^{[1]})x + (W^{[2]}b^{[1]} + b^{[2]}) \\ &= W'x + b' \end{aligned}$$

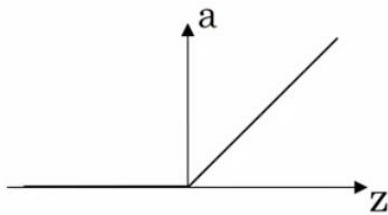
Sigmoid activation function



Tanh activation function



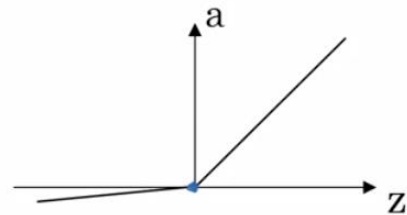
ReLU and Leaky ReLU



ReLU

$$g(z) = \max(0, z)$$

$$\rightarrow g'(z) = \begin{cases} 0 & \text{if } z < 0 \\ 1 & \text{if } z \geq 0 \end{cases}$$



Leaky ReLU

$$g(z) = \max(0.01z, z)$$

$$g'(z) = \begin{cases} 0.01 & \text{if } z < 0 \\ 1 & \text{if } z > 0 \end{cases}$$

Andrew M

Formulas for computing derivatives

Forward propagation:

$$Z^{(1)} = W^{(0)} X + b^{(1)}$$

$$A^{T_{12}} = g^{T_{12}}(z^{T_{12}}) \leftarrow$$

$$z^{(2)} = W^{(2)} A^{(1)} + b^{(2)}$$

$$A^{[2]} = g^{[2]}(z^{[2]}) = \sigma(z^{[2]})$$

Back propagation:

Back propagation:

$$\delta z^{[2]} = A^{[2]} - y \quad \leftarrow$$

$$d\omega^{[2]} = \frac{1}{n} dz^{[2]} A^{[n]T}$$

$$d b^{T2} = \frac{1}{m} \text{np.sum}(d z^{T2}, \text{axis}=1, \text{keepdims}=\text{True})$$

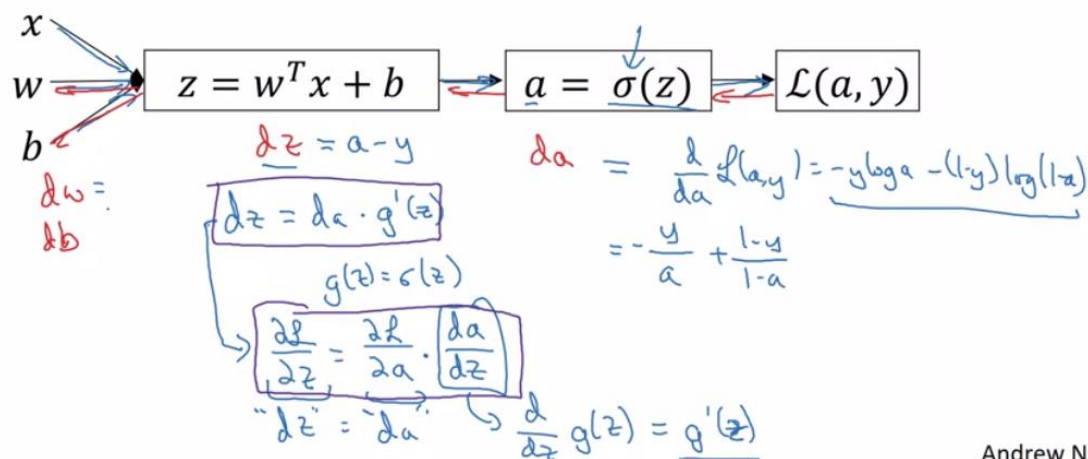
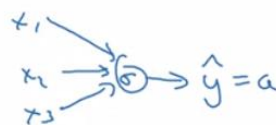
$$dz^{[1]} = \underbrace{W^{[2]T}}_{(n^{[2]}, m)} dz^{[2]} \otimes \underbrace{g^{[1]'}(z^{[1]})}_{\text{element-wise product}} (n^{[1]}, m)$$

$$dW^{(1)} = \frac{1}{n} dZ^{(1)} X^T$$

$$d\mathbf{b}^{(L)} = \frac{1}{n} \text{np.sum}(d\mathbf{z}^{(L)}, \text{axis}=1, \text{keepdims}=\text{True})$$

Computing gradients

Logistic regression



Andrew Ng

Summary of gradient descent

$$\underline{dz}^{[2]} = \underline{a}^{[2]} - \underline{y}$$

$$dW^{[2]} = dz^{[2]} a^{[1]T}$$

$$db^{[2]} = dz^{[2]}$$

$$\underset{(n^{[2]}, 1)}{dz^{[1]}} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

$$dW^{[1]} = dz^{[1]} x^T$$

$$db^{[1]} = dz^{[1]}$$

$$\underline{dZ}^{[2]} = A^{[2]} - Y$$

$$dW^{[2]} = \frac{1}{m} dZ^{[2]} A^{[1]T}$$

$$db^{[2]} = \frac{1}{m} \text{np.sum}(dZ^{[2]}, \text{axis} = 1, \text{keepdims} = \text{True})$$

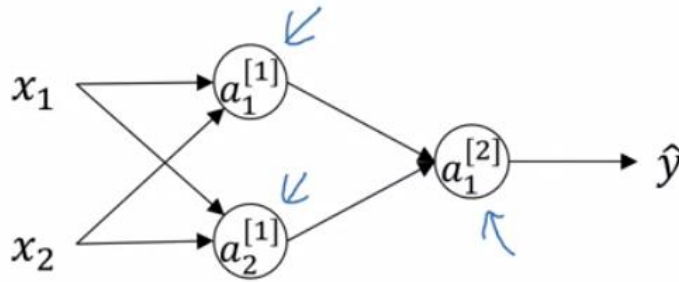
$$\underset{(n^{[2]}, m)}{dZ^{[1]}} = \underset{(n^{[2]}, m)}{W^{[2]T} dZ^{[2]}} * \underset{(n^{[1]}, m)}{g^{[1]'}(Z^{[1]})}$$

$$dW^{[1]} = \frac{1}{m} dZ^{[1]} X^T$$

$$db^{[1]} = \frac{1}{m} \text{np.sum}(dZ^{[1]}, \text{axis} = 1, \text{keepdims} = \text{True})$$

$$J(\cdot) = \frac{1}{m} \sum_{i=1}^n \mathcal{L}(\hat{y}_i, y_i)$$

Random initialization



$\rightarrow w^{[1]} = \text{np.random.randn}(2,2) * \frac{0.01}{100?}$
 $b^{[1]} = \text{np.zeros}(2,1)$
 $w^{[2]} = \dots$
 $b^{[2]} = 0$



```
In [6]: # Train the logistic regression classifier
clf = sklearn.linear_model.LogisticRegressionCV();
clf.fit(X.T, Y.T);
```

You can now plot the decision boundary of these models. Run the code below.

```
In [7]: # Plot the decision boundary for logistic regression
plot_decision_boundary(lambda x: clf.predict(x), X, Y)
plt.title("Logistic Regression")

# Print accuracy
LR_predictions = clf.predict(X.T)
print('Accuracy of logistic regression: %d ' % float((np.dot(Y,LR_predictions) + np.dot(1-Y,1-LR_predictions))/float(Y.size)*100)
      '% ' + "(percentage of correctly labelled datapoints)")
```

Accuracy of logistic regression: 47 % (percentage of correctly labelled datapoints)

