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# Optimal Tube station locations with Linear Programming: The Bakerloo Line Extension case study

According to Transport for London’s report ‘Strategic Case for Metroisation in South and Southeast London’ (TfL, 2019), South London residents are missing out on opportunities because of inadequate public transit connectivity, with access to employment drops significantly in gaps between the few rapid transit lines that serve it such as the Northern Line, The Docklands Light Rail (DLR) and the London Overground – East London Line. The report also revealed that there are four times as many jobs within 45 minutes of Harrow (North London) compared to Sutton (South London). Consequently, residents are more likely to switch to the more environmentally unsustainable personal automobiles.

This necessitated the proposal by the Mayor of London to extend the Bakerloo Line from its current terminus at Elephant & Castle to Lewisham, connecting it to other rail services together with two brand new stations along Old Kent Road (Figure 1). The Bakerloo Line Extension (BLE) is, therefore, one major component of a larger strategy to revitalise South London and improve its residents' lives.

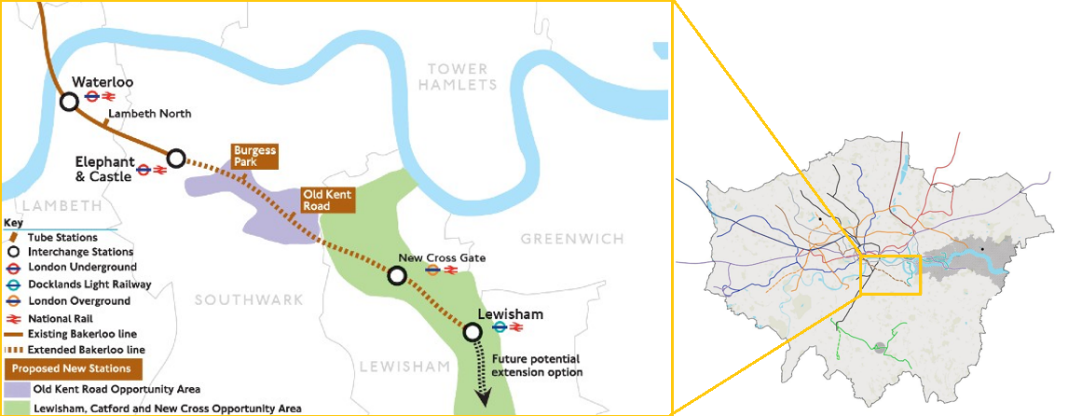


Figure 1 - Proposed Bakerloo Line Extension (Source: TfL)

With the BLE as our subject, this paper will use different Linear Programming models to determine the number and location of new stations along the new rail corridor needed to facilitate pedestrian access by minimising the time required to reach stations to a reasonable range. Finally, if found, the optimal solution for chosen station locations will be compared to TfL’s proposal to surface potential new location candidates.

## Methodology

Linear programming is a well-established methodology in transport planning, from service and employee scheduling (Gavish and Shlifer, 1979) to location planning (Jafari and Yaghini, 2019). When used in location planning, the main objective is to ensure that where the stations are located provides a positive effect on the travel experience compared to the status quo within the financial, technical, and operational constraints that all infrastructure projects need to contend with. In this study, the travel experience we seek to optimise will be how quick and easy it is for residents to access the new stations, one of many factors that motivate individuals to change their commute behaviour (Anwar, 2012). Research has shown that urban residents are only willing to walk up to around 10 minutes to reach a rapid transit station (Sarker, Mailer and Sikder, 2019).

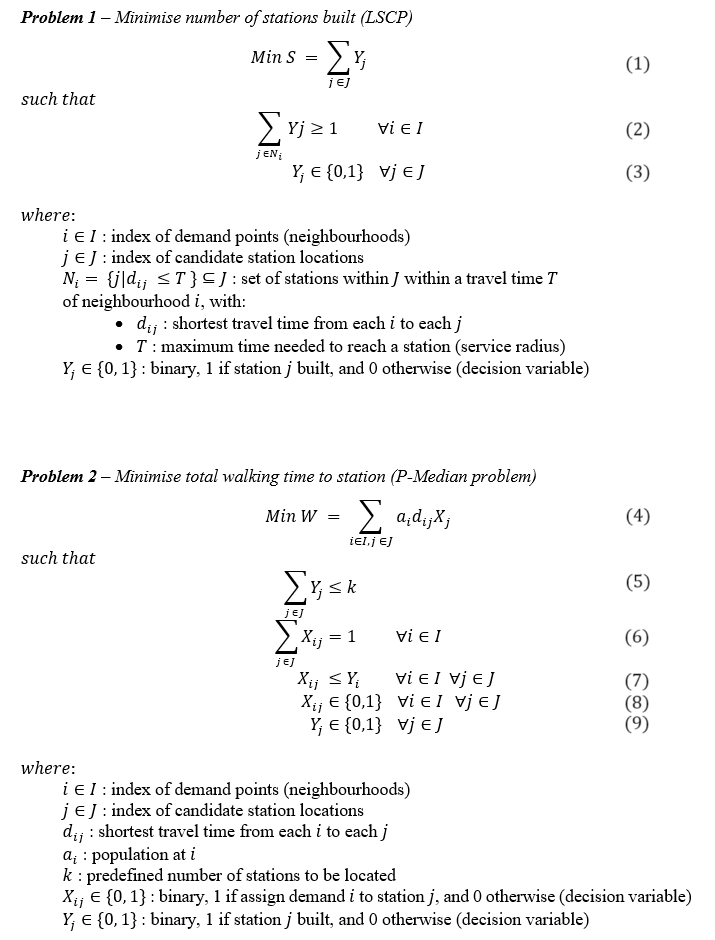
A theoretical framework for determining station sites was outlined in detail by Hamacher et al. (2001), who defined two main objectives of this endeavour:

1. *Accessibility:* All or a predetermined share of the transit demand must be covered by at least a station. In the case of a single line segment, the problem will resemble the classic Location Set Covering Problem.
2. *Travel Time:* The station locations must also minimise both the time spent reaching them on foot and the incremental delays to passengers onboard with each additional stop added.[[1]](#footnote-1)

This framework forms the foundation for our methodology, which involves formulating these two objectives as linear programming problems: First, to minimise stations built to cover all demand, the Location Set Covering Problem was used (Church and Murray, 2018). Secondly, an adapted P-Median Problem formulation (Hakimi, 1965) was used to minimise the walking time. This was chosen over the Maximum Coverage Location Problem for its focus on explicitly minimising population-weighted cost (or, in this context, walking time) rather than maximising population-weighted coverage (Karatas, Razi and Tozan, 2016).

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The mathematical formulation above may be verbally interpreted as follows:

Objective functions for the two problems.

Binary constraints for the decision variables.

Every neighbourhood *i* is within a max walking time T of min 1 station.

Maximum stations can be assigned.

Each neighbourhood is assigned only one station.

Each neighbourhood is assigned to station only if it’s built.

A note on our approach to problem formulation: As with most real-life problems with interlocking objectives, the industry convention is to formulate a Multi-objective Mathematical Programming (MMP) problem, commonly seen in transit planning research using linear programming (Benli and Akgün, 2023). Here, the objective functions are solved together with the others, producing a final set of Pareto-efficient solutions (i.e., Pareto front), from which decision-makers can weigh different options, each with its trade-off on one objective or another. (Chen and Zhou, 2022).

Due to our limited scope, we will instead explore a snapshot of the optimal solution universe by varying a key input parameter per problem within a manually set range. More specifically, we will explore all optimal solutions to **Problem 1** by varying (max walking time), and all optimal solutions to **Problem 2** by varying (max number of stations that can be built). However, such a brute-force approach would not be suitable for complex problems with more objectives.

## Data preparation

The neighbourhood and candidate location sets, and respectively, were acquired from the following workflow[[2]](#footnote-2):

1. Create a linestring for the corridor connecting Elephant & Castle with Lewisham, mainly following Old Kent Road (7.5 km)
2. Create a set of points 250m apart along the linestring as candidate stations.
3. Create the set of neighbourhoods (demand points) from the set of the Output Area centroids that intersect within a 1 km buffer area of the corridor.
4. Extract the population of all points in to population
5. Calculate the walking time of all and pairs, or , using the OpenStreetMaps pedestrian routing server.

For BLE, we also designated candidate locations that must be included in the solution to allow connection with other lines at Elephant & Castle, New Cross Gate, and Lewisham stations. The candidates closest to the three locations above are . Therefore, we added the ad-hoc constraint :

(10)

The resulting sets are visualised in Figure 2.

A map of a city

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Figure 2 - Station candidate and neighbourhood sets

Finally, we need to address some oversimplifications made so far:

* The neighbourhood location set does not consider the propensity to use public transit, future transit demand, or local politics that might stipulate certain neighbourhoods to be included in (or excluded from) the catchment area, such as the designated Opportunity Areas in Southeast London. (*London City Hall*, 2023)
* The station candidate location set does not consider engineering feasibility, assuming all sites can accommodate an underground train station.
* Different routing services, such as that offered by Google or Mapbox, may yield a different cost matrix and, thus, different solutions to the problems.

To solve the two optimisation problems, we used the COIN-OR Linear Program solver deployed with pulp and spopt (specialised Python libraries for linear program and spatial optimisation, respectively)[[3]](#footnote-3)

## Results

Figure 3 shows all optimal solutions for ***Problem 1*** *(Minimise station)* at different values (i.e., max walking time). We can see that, if < 1800 seconds (30 minutes), the problem is unsolvable. Therefore, if an average walking time of 10 minutes is used as a benchmark, there are no feasible solutions.

*A graph of station time

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*Figure 3 - Minimum stations needed at varying max walking time (Problem 1)*

Figure 4, on the other hand, shows all optimal solutions to ***Problem 2*** *(Minimise walking time)* at different values (i.e., number of stations). The problem is solvable at all values between 3 and 31, with a ‘knee’ at , where the optimal solution yielded 586 seconds (~10 minutes) of average walking time[[4]](#footnote-4). Based on the external benchmark of 10 minutes, we can declare this solution where to be selected.

*A graph with a line

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*Figure 4 - Minimum average walking time at varying numbers of stations given (Problem 2)*

## Discussion

When the chosen locations (k=7) are juxtaposed with the official proposal for the BEL, as shown in Figure 5, we can make several observations and recommendations:

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Figure 5 – Optimal solution with seven stations built (gold circles)   
vs. TfL proposal (station names)

* The segment between Elephant & Castle and Burgess Park has no stations planned in between, while the solution suggests adding an infill station here to benefit residents in the populated area around Bricklayer’s Arms / Ring Road Square.
* The solution also seems to suggest adding two stations 250m apart between New Cross Gate and Lewisham (near St John’s railway station). This is possibly due to this area’s density or poor pedestrian connection. Since such an alignment is unlikely to pass, stakeholders could consider adding only one station here and improving pedestrian accessibility around the station’s catchment area.
* The Old Kent Road Station in the official TfL proposal does not correspond to any chosen candidate in the solution, possibly because this area is sparsely populated but already well connected on foot to other stations. However, it is worth noting that this area will see more development in the future as a designated Opportunity Area (*London City Hall*, 2023), and will anticipate convenient access to a Tube station.

To summarise, with Linear Programming, we can put forth a recommendation to add two stations to the TfL proposal, one between Elephant & Castle and Burgess Park, and another between New Cross Gate and Lewisham, for a total of 6 new Tube stations for the BLE.

**Limitations**

There are various limitations in formulating the objectives and constraints. For *Problem 1*, the construction cost of each station candidate should be added to serve as the weight parameter. (Church and Murray, 2018). For *Problem 2,*time delay to passengers on the trains with each additional station can also be added as an objective to be minimise. (Hamacher *et al.*, 2001). In addition, to make the models more robust, realistic operational constraints should also be considered, such as budget, station capacity, etc.

Lastly, the model reveals a shortcoming of not accommodating future population growth. To remedy this, instead of the current population, the future projected population could be used to populate input parameter.

## Conclusion

This has been an attempt to apply Linear Programming to determine where to build new stations for the Bakerloo Line Extension that can cover all neighbourhoods in a certain area and minimise walking time to the station to improve transit accessibility in South London.

Our findings suggest that a simple formulation of the Location Set Covering Problem (#1) yielded unsatisfactory results in terms of max walking time. On the other hand, an adapted P-Median Problem (#2) to minimise walking time as the primary objective while varying the parameter for the number of stations returned a more reasonable solution. Contrasting the solution with the official proposal for the BEL leads us to recommend a total of 6 new Tube stations for the BLE, instead of 4 in the current proposal.

The formulation explored in this paper can be further generalised for use by future research on station location planning. More specifically, there are merits in expanding the P-Median Problem (#2) into a Multi-objective Mathematical Programming (MMP) problem by combining with other secondary objectives to derive a more insightful set of Pareto-efficient solutions, and to make decision-making on complex problems more effective.

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1. Note that, for the sake of simplicity, in our model, we will assume potential transit riders will only walk to stations instead of driving or taking the bus. The passenger time delay component will also be omitted. [↑](#footnote-ref-1)
2. Data source: Office of National Statistics, Bing Maps [↑](#footnote-ref-2)
3. The codes used were based on PySAL library’s tutorials: <https://pysal.org/spopt/tutorials.html> and can be found in the GitHub repository: <https://github.com/hanukikanker/bakerloo-ext-lp> [↑](#footnote-ref-3)
4. Avg. walking time equals total walking time (objective function) divided by total population. [↑](#footnote-ref-4)