

03/24/2023 Recitation #3 Handout

1. Environment

A mechanism design environment $\mathcal{E} = \{N, \{\Theta_i\}_{i \in N}, p, X, \{u_i\}_{i \in N}\}$

- $N = \{1, 2, \dots, n\}$ set of agents
- Θ_i set of agent i 's types (Write $\Theta = \prod_{i \in N} \Theta_i$)
- $p \in \Delta(\Theta)$ common prior distribution
- X set of outcomes (or social alternatives)
- $u_i : X \times \Theta \rightarrow \mathbb{R}$ agent i 's utility function

Notes: (1) \mathcal{E} has *independent types*, if p is a product distribution; (2) \mathcal{E} has *private values*, if we can write $u_i(x, \theta) = u_i(x, \theta_i)$.

2. Social Choice Function/Correspondence

- A social choice function (SCF) $f : \theta \rightarrow x$ assigns each type profile θ an outcome x .
- A social choice correspondence (SCC) $F : \Theta \rightrightarrows X$ assigns each type profile θ a set of outcomes.

3. Mechanisms A mechanism $\Gamma = \{\{S_i\}_{i \in N}, g\}$

- S_i set of agent i 's actions (Write $S = \prod_{i \in N} S_i$)
- $g : S \rightarrow X$ outcome function

Notes: Γ is a direct mechanism if $S_i = \Theta_i, \forall i \in N$.

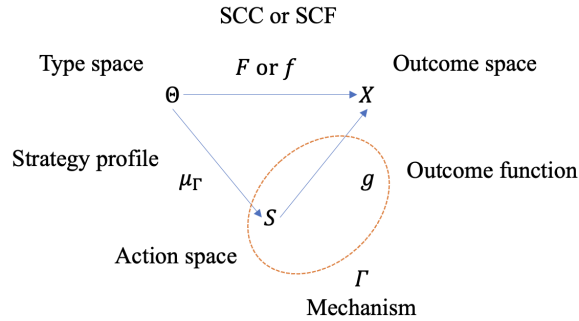


Figure 1: The Mount-Reiter Diagram

\mathcal{E} and Γ defines a Bayesian game $\mathcal{G} = \{N, \{S_i\}_{i \in N}, \{\Theta_i\}_{i \in N}, \{p_i\}_{i \in N}, \{v_i\}_{i \in N}\}$, where agents' first-order beliefs p_i are derived from p ¹ and the utility functions are defined by $v_i(s, \theta) = u_i(g(s), \theta)$.

¹Many applications of Bayesian games employ the common prior assumption—the assumption that the players' first-order beliefs $p_i : \Theta_i \rightarrow \Delta(\Theta_{-i})$ are conditional probabilities generated from some p .

4. Implementation

We need to impose some assumption on μ_Γ , i.e., to specify the equilibrium concept we are using: dominant strategies, NE, BNE, rationalizability...

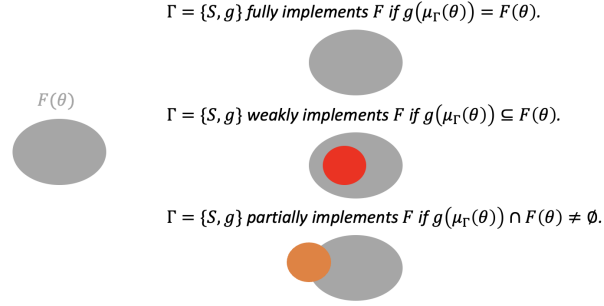


Figure 2: Implementation

Our goal is to find a mechanism that implements F . It might not be an easy task, since the set of all possible mechanisms is very large.

5. Revelation Principle

We will show that one can focus on mechanisms of a particular simple kind. To fix ideas, let's consider implementing a social choice function f .

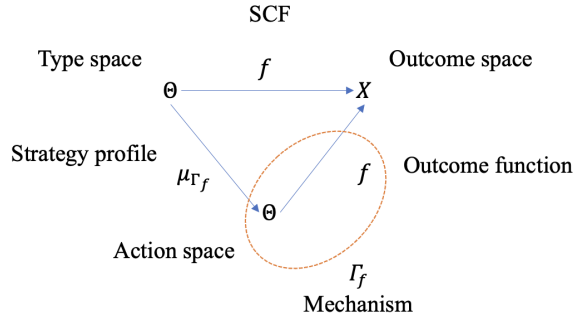


Figure 3: Γ_f

- Γ_f is an equivalent direct mechanism for SCF f .
- F is incentive-compatible (IC) under equilibrium concept μ , if $\forall \theta \in \Theta, \theta \in \mu_{\Gamma_f}(\theta)$.

Theorem 1. *If there is a $\Gamma = \{\{S_i\}_{i \in N}, g\}$ that implements f in dominant strategies, then the direct mechanism $\Gamma_f = \{\{\Theta_i\}_{i \in N}, f\}$ truthfully implements f in dominant strategies. Thus, a social choice function is dominant strategy implementable by some mechanism if and only if it is dominant strategy incentive-compatible!*

Sketch of the Proof. Simply use $g(\mu_{\Gamma(1)}(\theta_1), \mu_{\Gamma(2)}(\theta_2), \dots, \mu_{\Gamma(n)}(\theta_n)) = f(\theta_1, \dots, \theta_n), \quad \forall \theta.$ □