

Project 5:

Learning the Development Environment

– The Final Step

EE/CSE 474 EMBEDDED MICROCOMPUTER SYSTEM

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**A Special Appreciation to Dr. James K. Peckol for developing
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Daniel Predmore, Christy Truong, Jonathan Hamberg for
their useful help and patience!**



" Go get a beer! "

— **James K.
Peckol**

Abstract

The final phase of development of a low cost, portable, medical monitoring system is completed in this lab. The following capabilities are added: the ability of modeling the control of blood pressure cuff with press button and switch; the ability of measuring patient's temperature, blood pressure, pulse rate, respiration rate and EKG modeled by signal generator generated signals; The ability to display detailed information on TFT console with special indication on critical data; The ability to support bidirectional communication with remote computer; The ability to respond to command from remote computer; The ability of displaying measurement, status and alarm information on a remote terminal.

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1. Introduction

This project focused on the design and implementation of system architecture, data model, control flow, data exchange, operation control, intersystem and LAN communication for a low cost, portable, medical monitoring system. The system is designed to dynamically control and schedule tasks based on user instructions and other inputs; measure, compute and display six kinds of health related information (blood pressure, body temperature, pulse rate, respiration rate, EKG and battery status) and communicate with remote computer. We used UML - Use Cases, Functional Decomposition, Sequence Diagrams, State Charts, and Data and Control Flow Diagrams to design the architecture of the system, C language to implement functionality, Codeblock IDE to debug and finally loaded the final product to the Arduino ATMega2560 and Arduino Uno.

2. Discussion of the Lab

Design Specification

Overall Summary

The product developed is the medical monitor device that can support the measurement, display and communication of several modeled health data input. For this final stage of development, the goal is to design, implement and integrate three main functionality into the system.

First, the support for modeling health data with various analog/digital signals will be added. Peripheral system will be able to measure/compute/store/communicate these modeled signals. The ability of measuring respiration rate and EKG will be added. Also, peripheral system will be able to control the modeled blood pressure cuff using the signal sent from press button/switch circuit.

Second, a remote communication/control system will be integrated with LAN. The system will be able to send data and receive command from remote computer, interpret and respond to command and the remote computer terminal will be able to display measurement data, warning and alarm information.

Last, the TFT display will be able to display more detailed measurement information and display any critical information with special pattern.

To achieve the desired functionality of such system, the system is divided into three subsystems: Uno as Peripheral, ATMega2560 as System Control and PuTTY as remote system terminal. In addition, TFT display panel is used as user interface with the ability to interact with user using touch screen. System control subsystem is responsible for overall task management of the system, Peripheral subsystem is responsible for receiving, process , storing and communicating user health data, TFT display panel is responsible for displaying and PuTTY terminal is responsible for controlling and communicating with the system remotely .

Use Cases

This is the topology of our fully implemented application. Served as Control or Kernel, ATMega2560 has a dynamic control kernel which can control the status of whole system. Connecting with pulse generator, Uno works as a measurement tool and it receives data from

outside world and send them to ATMega to processes and displays. As remote control system, PuTTY terminal connects with the rest of system through LAN, sends command to kernel to control system operation and display measurement data, warning information received.

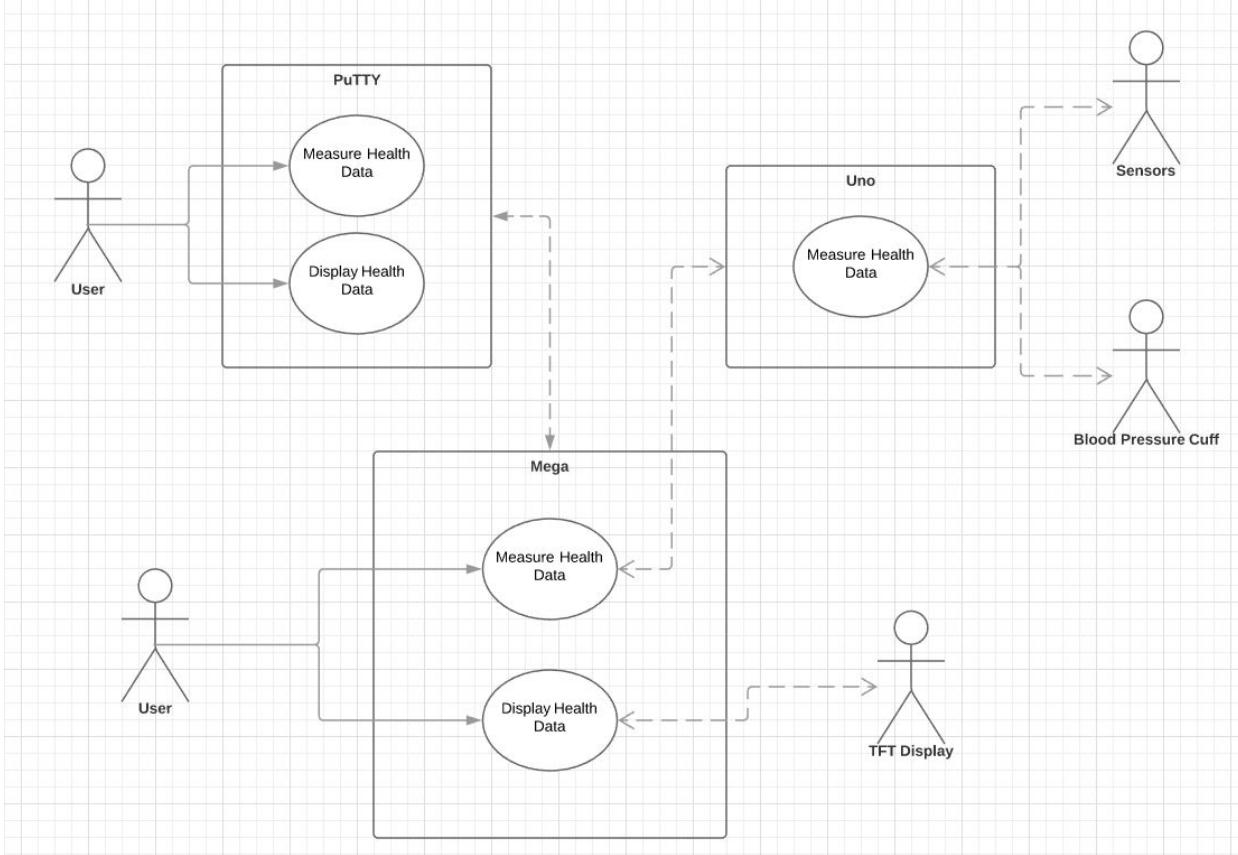


figure 1 Use Case Diagram

Interface

User to Computer Interface:

Input:

Task Selection Menu to selected measured task, Alarm Acknowledgement
Button to acknowledge alarms

Output:

Measurement Item

Body Temperature, Blood Pressure, Pulse Rate, Respiration Rate,
EKG

Annunciation

Blood Pressure, Body temperature, Pulse rate, Respiration Rate,
Battery Status

System Process Interface:

Input

Measurement:

Blood Pressure, Body temperature, Pulse rate, Respiration Rate,

EKG
Output

Display:
Blood Pressure, Body temperature, Pulse rate, Respiration Rate,
EKG

Status:
Battery state

Alarms:
Temperature, Blood pressure, Pulse rate 20% out of range

Warning:
Temperature out of range, blood pressure out of range, pulse rate
out of range

Side Effect:

After boot up, the display will show three text box options: Task Selection, Annunciation and Measurement. Tab on option will take user to corresponding sub menu.

In task selection, user will be able to selected which measurement task to perform, with selected task displayed in green text box and unselected tasks displayed in red text box.

In annunciation, user will be able to acknowledge warning by tabbing on “acknowledge” button. If the button is tab and warning are acknowledged, the tab will be in green text box, otherwise in red text box.

In measurement, user will be able to read all measurement data.

All the sub menu has a “back” button to return to top menu.

Pseudo English description of algorithms, functions, or procedures

Main function is the interface where users could choose the items they would like to measure and make system awake to work or sleep

```
main() :  
    If pressure on screen is in valid range:  
        If user is in top menu:  
            Find the range users touch  
        If user is in measurement selection menu:  
            If user choose return:  
                Return to top menu:  
            If choose to measure temperature:  
                Measure temperature  
            If choose to measure pulse:  
                Measure pulse  
            If choose to measure pressure:  
                Measure pressure  
            If choose to measure respiration rate:  
                Measure respiration rate  
        If choose to measure EKG:  
            Measure EKG
```

```

        Else if:
            If user is in annunciation menu:
                Call dynamic scheduler
        Else if:
            If user is in measurement menu:
                Call dynamic scheduler

```

Scheduler function is coupled with issue function where scheduler schedules task and send their information to issue. Then issue function issueses them.

```

Scheduler():
    Set task queue to be empty

    Check ekg capture flag and time constraint to add ekg
    capture task to task queue
    Check measure flag and time constraint to add measure
    task to task queue
    Check ekg process flag and time constraint to add ekg
    process task to task queue
    Check compute flag and time constraint to add compute
    task to task queue
    Check warning flag and time constraint to add warning
    task to task queue
    Check display flag and time constraint to add display
    task to task queue
    Check remote communication flag and time constraint
    to add remote communication task to task queue
    Check status flag and time constraint to add status
    task to task queue
    Check remote display flag and time constraint to add
    remote display task to task queue

    Execute each task in the task queue

```

To support the measurements of health data modeled by analog and digital signals, we implement the following functions in peripheral system:

```

setup():
    Setup pinMode
    Attachinterrupt cuff function
    Attachinterrupt pr_detect function

main() (loop):
    Debounce switch
    Debounce button

    Read inbyte
    Read function selection
    Read end byte

```

```

If pulse rate selected
    attach pr_detect to interrupt
    Detach pr_detect from interrupt

If temperature selected
    Measure temperature

If blood pressure selected
    Measure blood pressure

Write start byte
Write measure data
Write end byte

cuff():
    If switch is in up state
        pressure*1.1
        If pressure > 150
            Pressure = 150
    Else
        Pressure * 0.9
        If pressure < 50
            Pressure = 50

pr_detect():
    detect if we are measuring pulse rate
    if we are measuring the pulse rate
        set a new clock
        while clock != 1s
            start counting number of pulse
    pulse rate = count

respiration rate detect:
    detect if we are measuring respiration rate
    if we are measuring the respiration rate
        set a new clock
        while clock != 1s
            start counting number of pulse
    respiration rate = count

measure():
    If measure temperature
        Read signal from temperature pin
        Delay 5 seconds
    If measure blood pressure
        If cuff pressure is between 110 to 150
            Measure systolic pressure from analog port

```

```

        Set systolic flag
    If cuff pressure is between 50 to 80
        Measure diastolic pressure from analog
        port
        Set diastolic flag

```

Due to limit memory in Uno, we implemented EKG measurement in Mega with following functions:

```

ekg_capture():
    Set EkgCaptureFlag
    For (int i= 0; i < 256; i++) {
        Read from analog
        Offset by 2.5V
        Map the reading to -31 to 32 range
        Wait for sampling period
    }
    Set EkgProcessFlag

ekg_process():
    Index = max magnitude index found by provided optfft
    Ekg = index * sampling frequency / 256(buffer length)
    Write to ekg buffer
    Set EkgProcessFlag to false

```

To support remote communication, remote control and remote display capability, we implement the following functions:

Remote Communication Data:

- Temperature display data
- Systolic pressure display data
- Diastolic pressure display data
- Pulse rate display data
- Respiration rate display data
- Ekg display data
- Temperature warning
- Display warning
- Pulse rate warning
- Respiration rate warning

Command Management Data:

- Temperature data
- Systolic pressure data
- Diastolic pressure data
- Pulse rate data
- Respiration rate data
- Ekg data
- Temperature display data
- Systolic pressure display data

```

Diastolic pressure display data
Pulse rate display data
Respiration rate display data
Ekg display data
Temperature warning
Display warning
Pulse rate warning
Respiration rate warning

Remote Communication Data Initial Value:
    Temperature display data = 78;
    Systolic display data = 78;
    Diastolic display data = 67;
    Pulse rate display data = 67;
    Respiration display data = 45;
    Ekg display data = 56;

Command Management Data Initial Value:
    Temperature data = NULL;
    Systolic pressure data = NULL;
    Diastolic pressure data = NULL;
    Pulse rate data = NULL;
    Respiration rate data = NULL;
    Ekg data = NULL;
    Temperature display data = 78;
    Systolic display data = 78;
    Diastolic display data = 67;
    Pulse rate display data = 67;
    Respiration display data = 45;
    Ekg display data = 56;
    Temperature warning = FALSE;
    Display warning = FALSE;
    Pulse rate warning = FALSE;
    Respiration rate warning = FALSE;

command():
    Receive command;
        If number of command is larger than 2
            Read command
        If command is i
            Enable command
        Else if command is s
            Enable system
        Else if command is p
            Stop system
        Else if command is d
            If display is off

```

```

Turn on
    Else
        turn off
    else if command is m
        update data
    else if command is w
        update warning
Else
    give error

remoteCom():
    if update data
        update all data
    if update warning
        update all warning
    if not update data && not update warning
        use old data

remoteDis():
    read temperature;
    print temperature;
    read systolic pressure
    print systolic pressure
    read diastolic pressure
    print diastolic pressure
    read pulse rate
    print pulse rate
    read respiration rate
    print respiration rate
    read ekg
    print ekg
    read warning
    if temp warning
        flash temp
    if systolic warning
        flash systolic
    if diastolic warning
        flash diastolic
    if pulse rate warning
        flash pulse rate
    if respiration rate warning
        flash respiration rate

```

To support the display of critical data, we made changes to display function and implement new function as follow:

```

display():
    If the measurement is in warning state
        Print nothing and skip that space
    Else
        Print out the information in format
    If acknowledge button is pressed, reset acknowledge
    flag

drawDisplay():
    Print out the formatted information without
    considering warning

flash():
    If temp measured
        If temp is in warning state
            Flash temp 2 second period
            Leave space for temp to display
    If blood pressure measured
        If blood pressure is in warning state
            Flash bp 1 second period
            Leave space for bp to display
    If pulse rate measured
        If pulse rate is in warning state
            Flash pr 0.5 second period
            Leave space for pr to display

```

Execution Time

For the first run, due to the cold start:

Measure: 16 μ s
 Compute: 236 μ s
 WarningAlarm: 88 μ s
 Display: 718676 μ s
 Status: 12 μ s
 EKGCapture: 2.5ms
 EKGProcess: 17 μ s

For the rest run (almost all of rest run):

Measure: 8 μ s
 Compute: 8 μ s
 WarningAlarm: 80 μ s
 Display: 8 μ s
 Status: 8 μ s
 EKGCapture: 2.5ms
 EKGProcess: 8 μ s

Annunciation will take 2 seconds to process.

However, due to the hierarchy of built-in cache, conflict miss or capacity miss, the time is varied. The probability to have such situation is pretty small.

Timing constraints

Due to the refresh rate of the screen and computation rate, the delay between each display should be larger than 10ms

EKG Measurement is hard real time task, we measure each sample at rate of 100ms to make capture possible at max input frequency of 3.5KHz.

Due to the scheduler algorithm, the remote control command can only be transmitted and updated to kernel when data is refreshed on putty.

Error handling

We try to give all data a flag to indicate their behavior. Out of Range or not, High, Low.

The reason we have so many flags is we can simplify our logic to avoid losing significant logic in controlling Warning Alarm and Measure function.

In addition, our user interface has forced users to operate under our process procedure where they have to choose things to measure, and return to top menu and press annunciation to start, otherwise it the whole system will not awake to start working.

Software Implementation

Functional Decomposition Diagram for the System Control

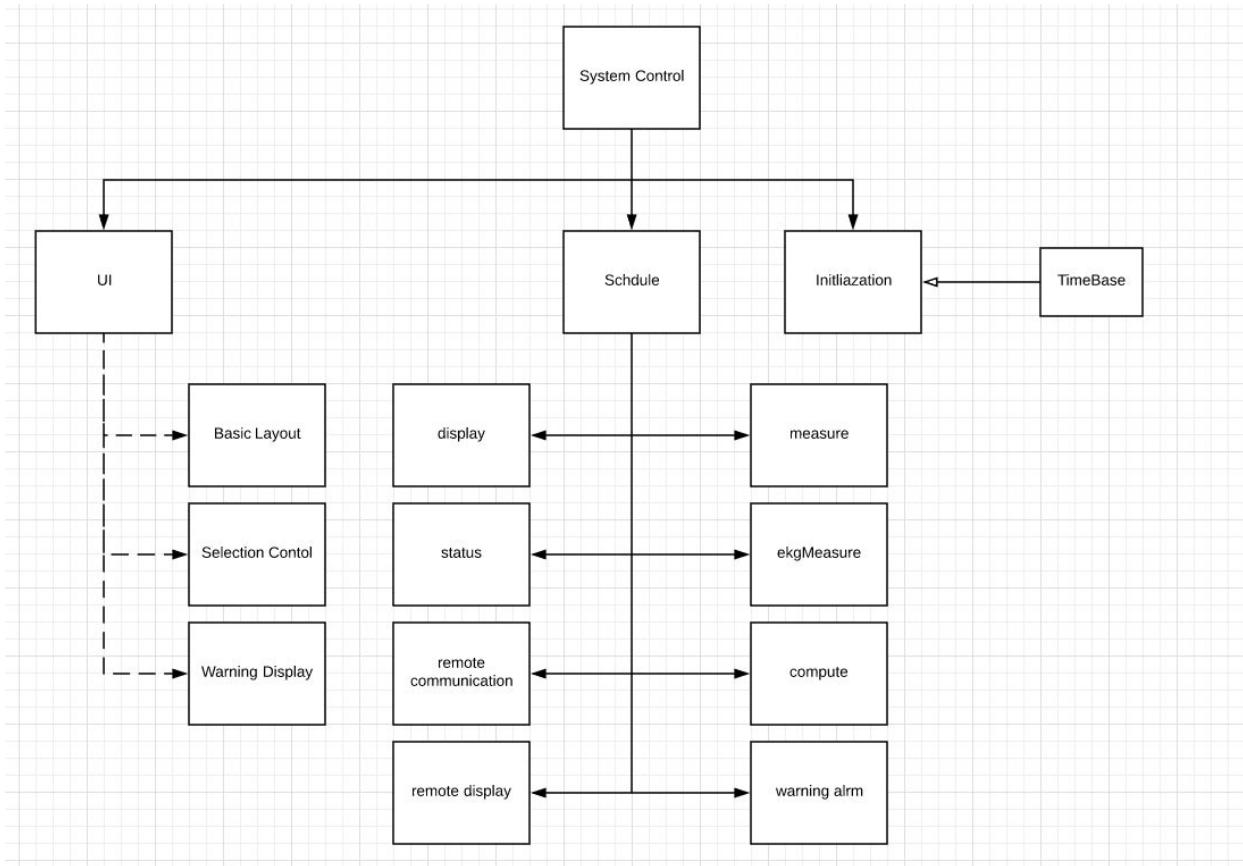


Figure 2 System Control Functional Decomposition Diagram

System Control Task/Class Diagrams

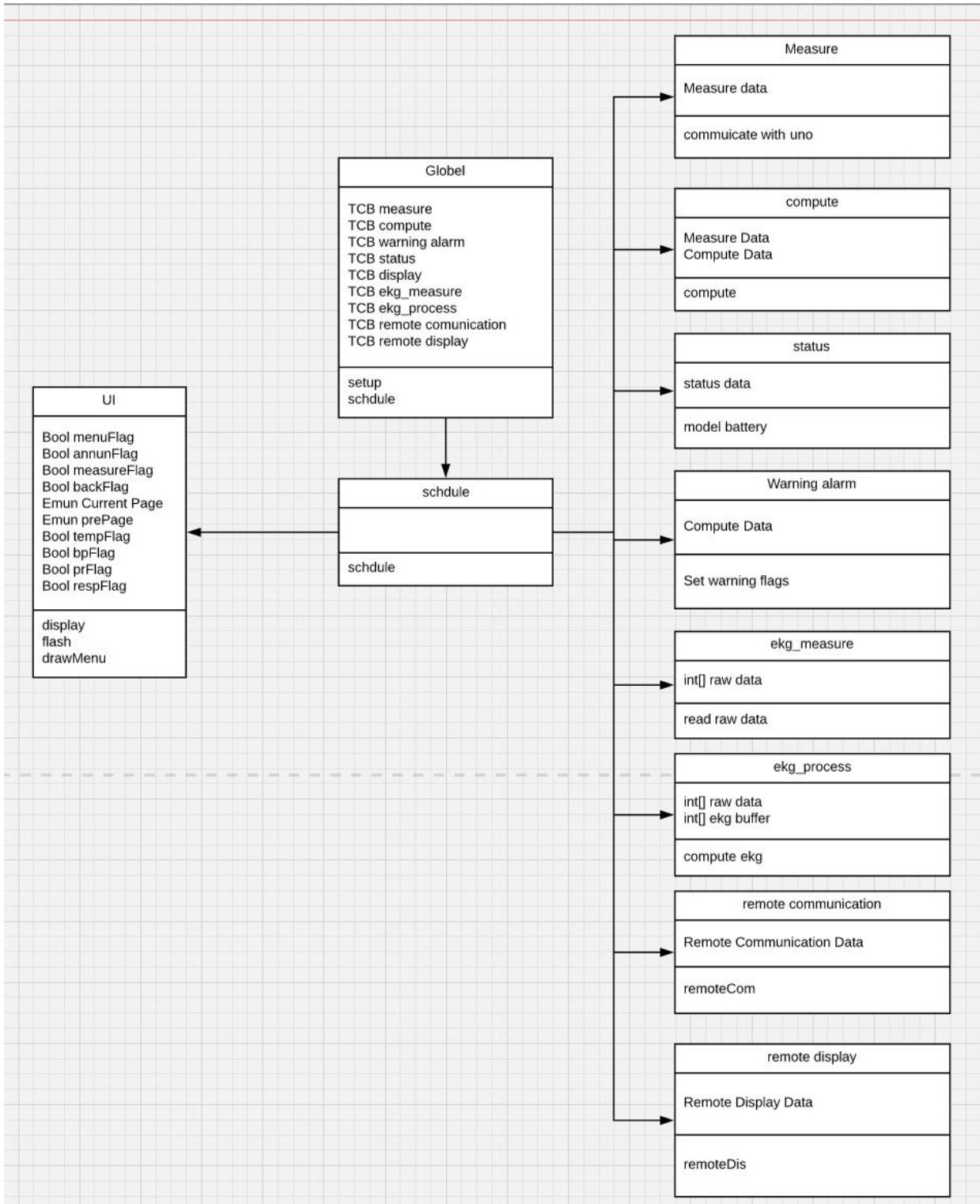


Figure 3 System Control task/class diagrams

System Control Activity Diagrams

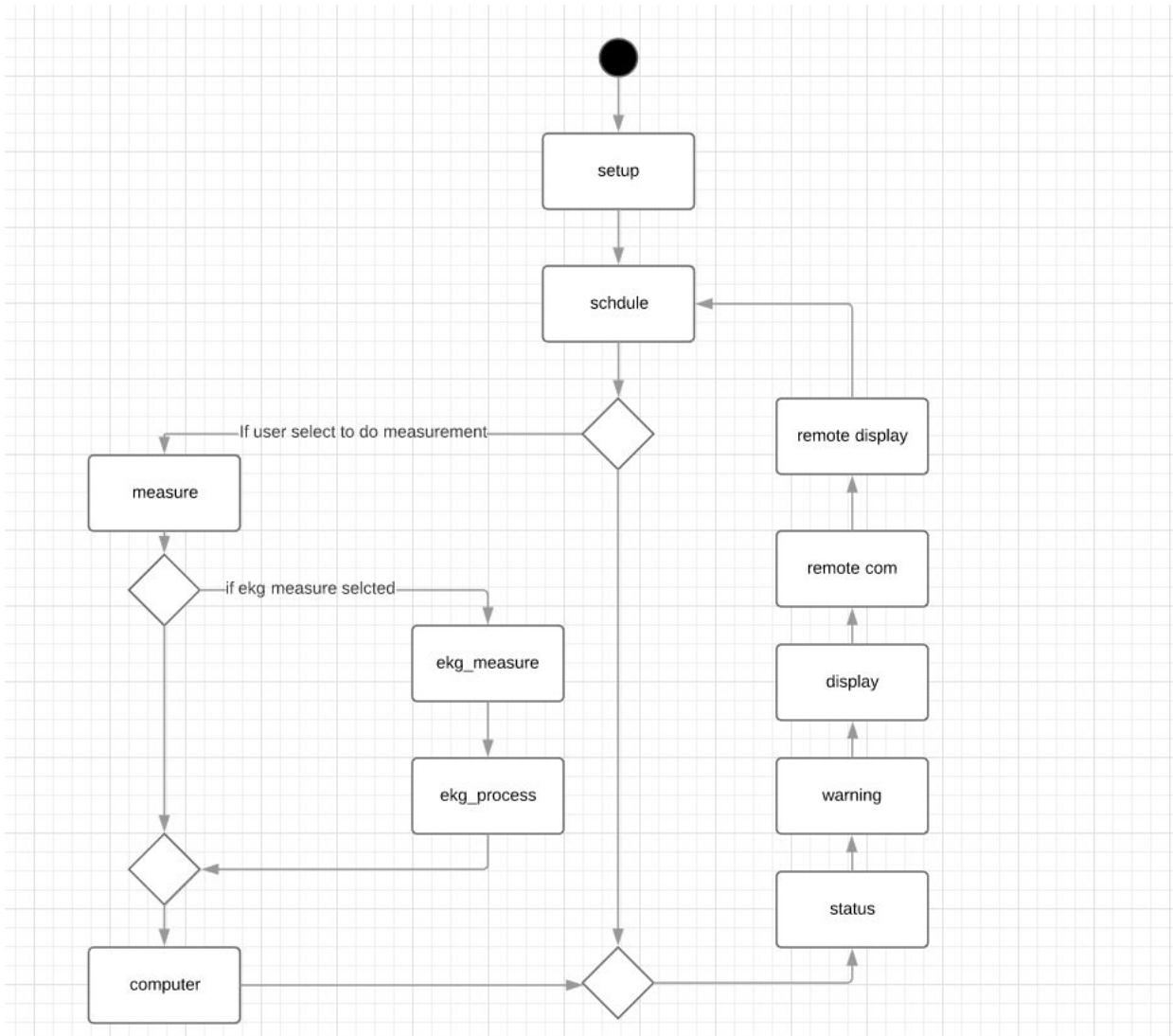


Figure 4 System Control Communication Task Diagrams

Functional Decomposition Diagram for the Peripheral Subsystem

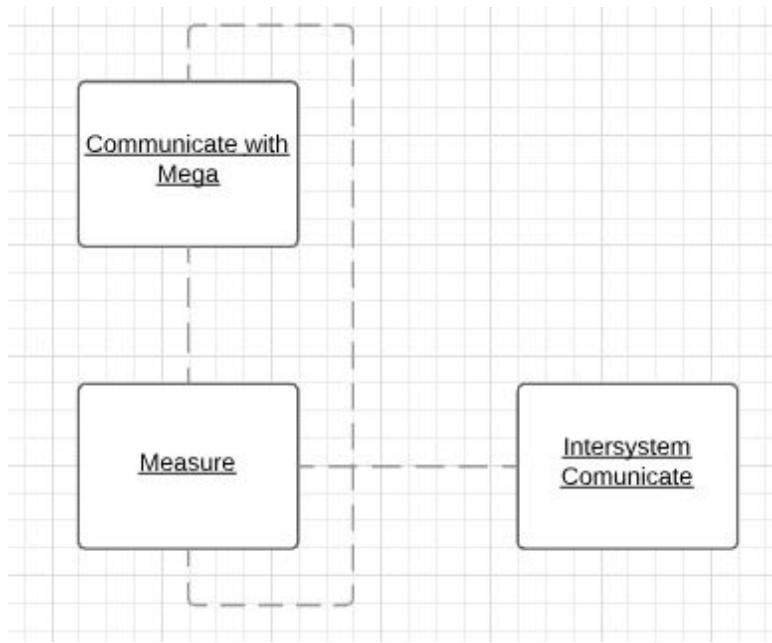


Figure 5 Peripheral Subsystem Functional Decomposition Diagram

Peripheral Subsystem Task/Class Diagrams

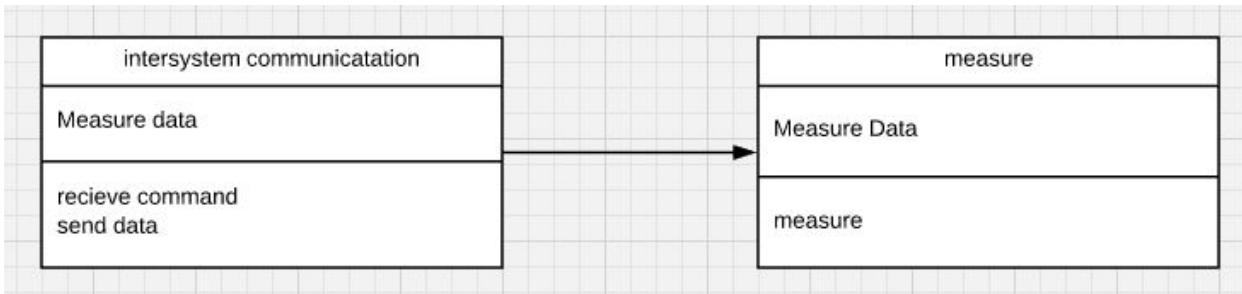


Figure 6 Peripheral Subsystem task/class Diagrams

Peripheral Subsystem Activity Diagrams

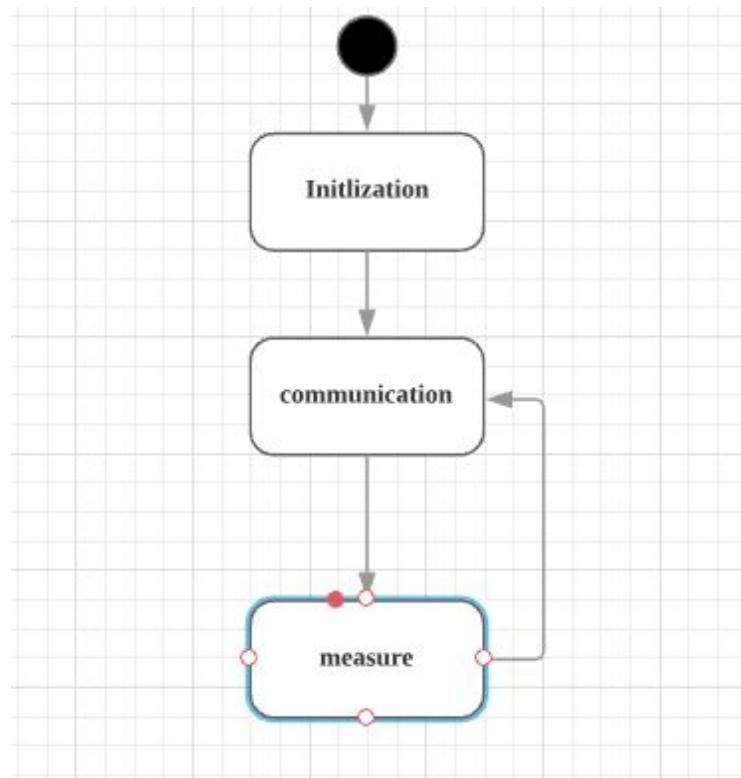


Figure 7 Peripheral Subsystem Activity Diagrams

Startup Sequence Diagram:

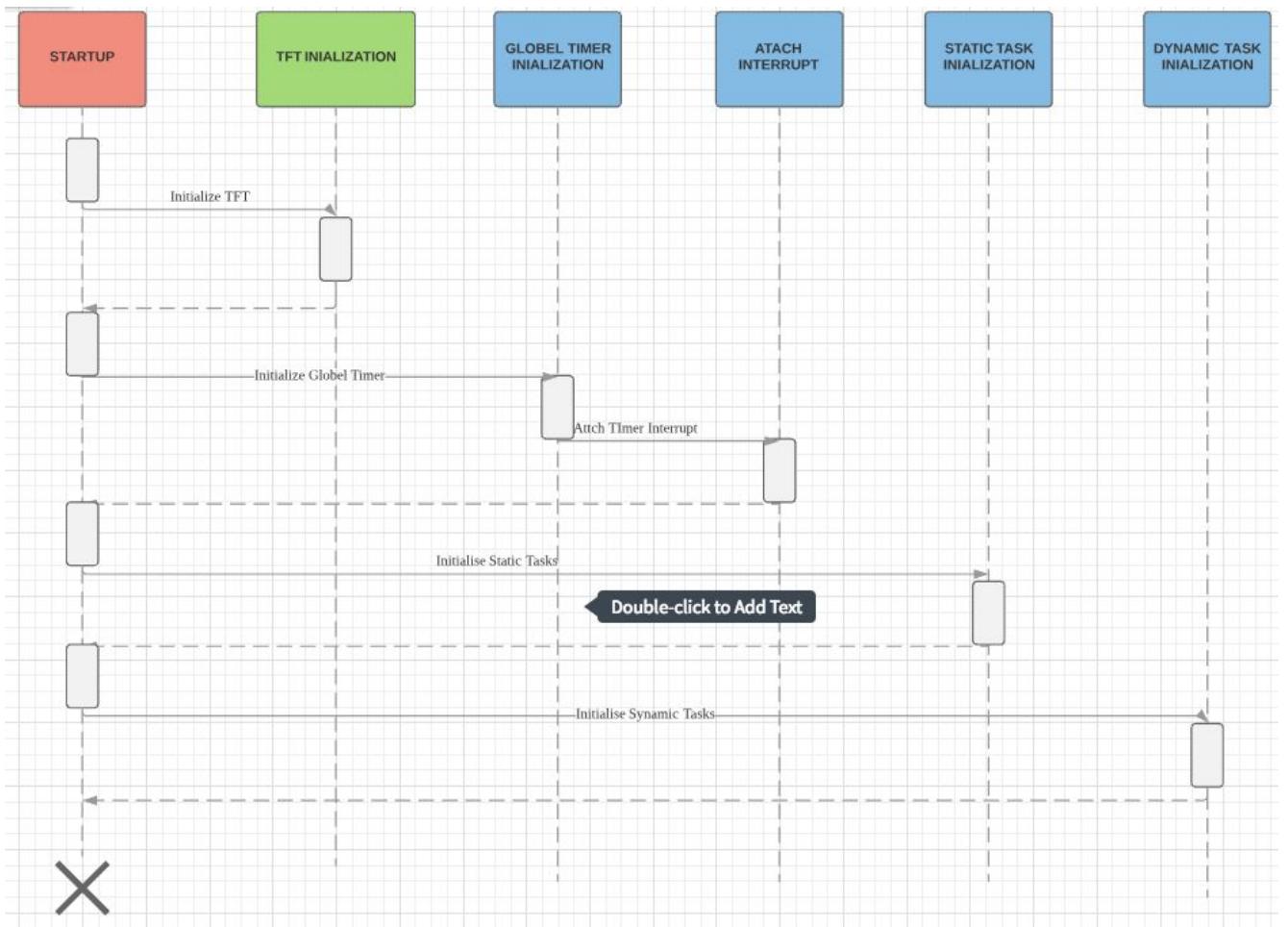


Figure 8 Startup Sequence Diagram

Static Tasks are given the same priorities since all static tasks are based on TCBs and will execute in the same sequence every time.

Schedule State Chart:

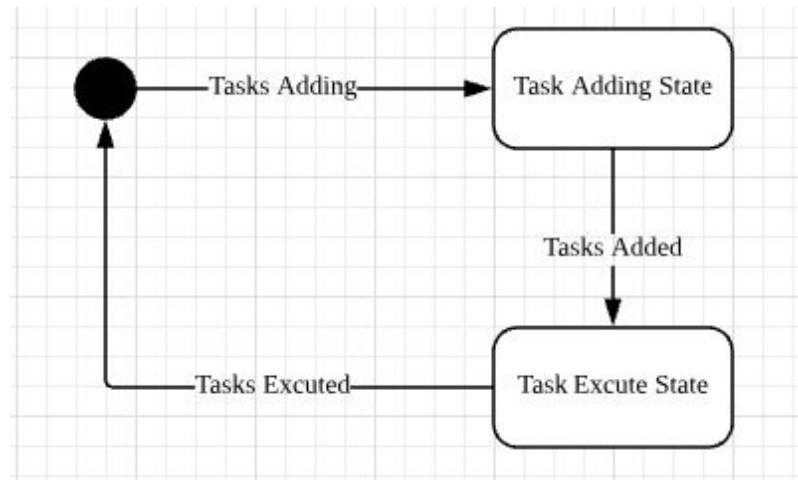


Figure 9 Schedule State Chart

Display Front Panel Diagram:

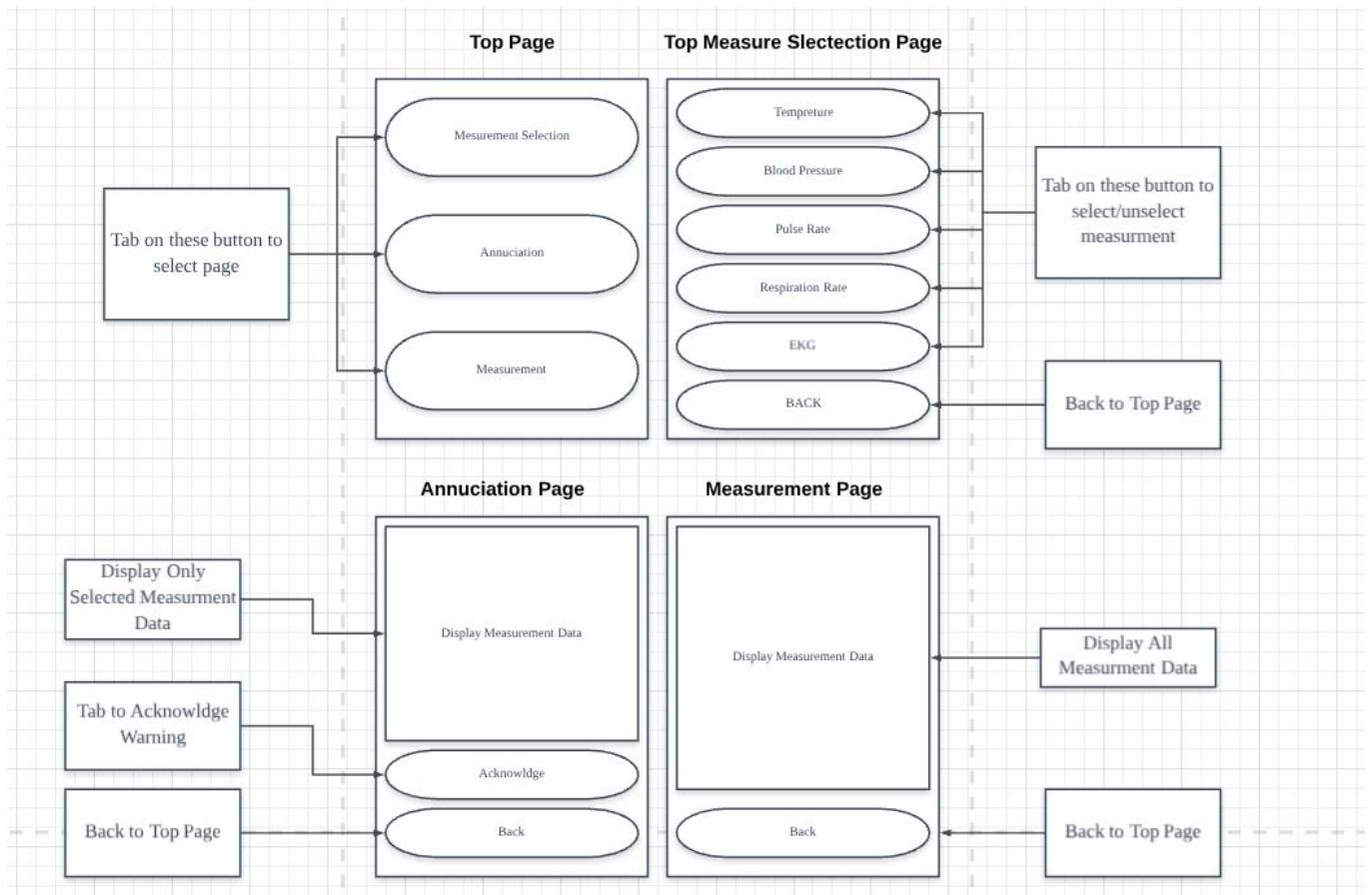


Figure 10 Display Layout

Remote Web Page Layout:

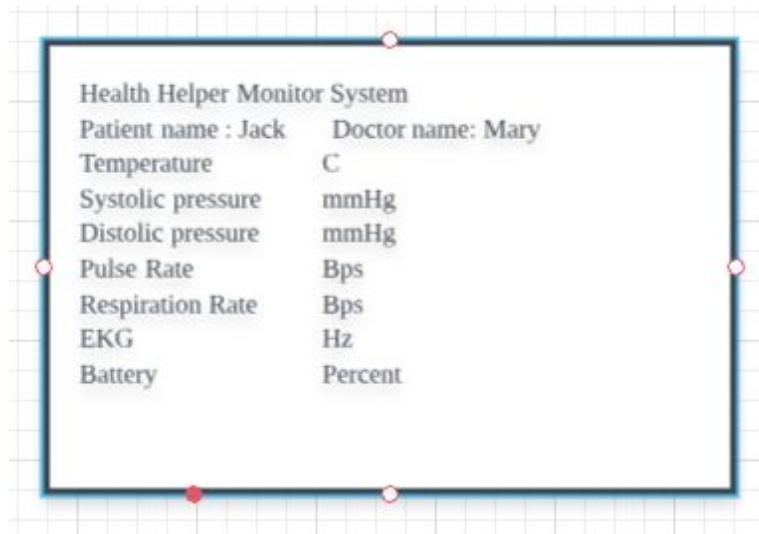


Figure 11 Remote Web page Layout

3. Presentation, discussion, and analysis of the results

Overview:

The final product has critical checkpoints which need to be confirmed to ensure the correctness of the implementation. First, temperature, blood pressure, and respiration measurements are switch from software modeling to analog input modeling. We need to ensure the correctness of each measurement. Also, for blood pressure measurements, we need to ensure the modeled blood pressure cuff is working as expected. Second, we need to ensure the display function flash the warning measurement in correct rate. Third, we need to ensure the EKG measurement works as expected. At last, we need to ensure the PuTTY remote control and communication works as expected. The rest of rules from previous lab remains in effect. Since there is no alternation made on those parts of implementation, we ensure the correctness by inspection and the result will not be included in this lab report. Please refer “EE474 Lab3 report” for more information.

Temperature Measurement:

The temperature measurement is now measured from analog signal and should be map to human body temperature range.

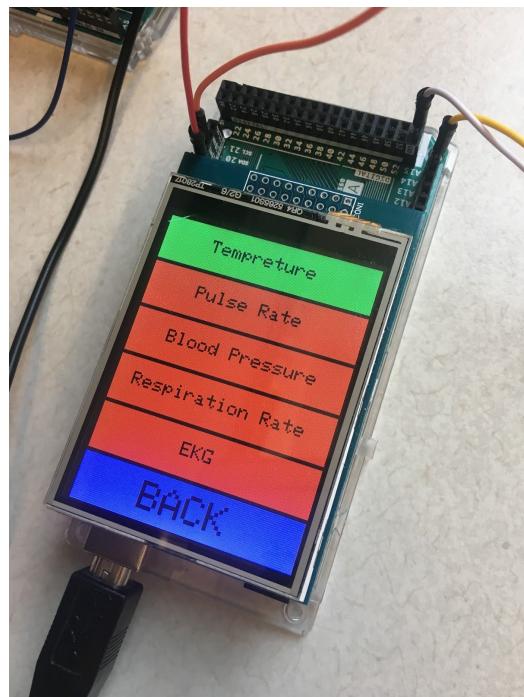


Figure 12 Select To Measure Temperature



Figure 13 Temperature Signal Generated by Signal Generator

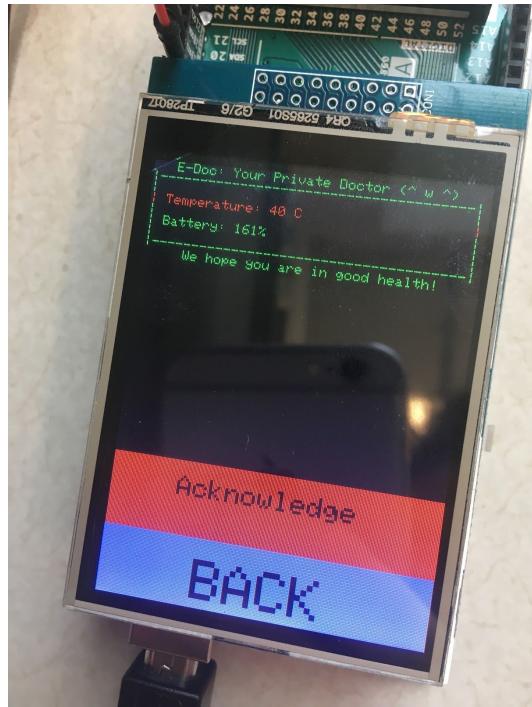


Figure 14 Temperature Reading with Correct scaling

As figure 12 to 14 demonstrated, temperature measurement is selected on mega, got schedule correctly, read input from signal generator, scale correctly and displayed on the TFT panel with correct waring color.

Blood Pressure Measurement:

The blood pressure measurement is now modeled by analog signal. To determine whether to perform systolic or diastolic measurement, the modeled blood pressure cuff should be inflated or deflated to certain range. In this project, the blood pressure cuff is modeled by circuit with a switch and a button. If the switch is at up state, press the button will increase the pressure by 10%. If the switch is at down state, press the button will decrease by 10%.

After connect the signal generator to the correct pin, the switch is turned to up state.

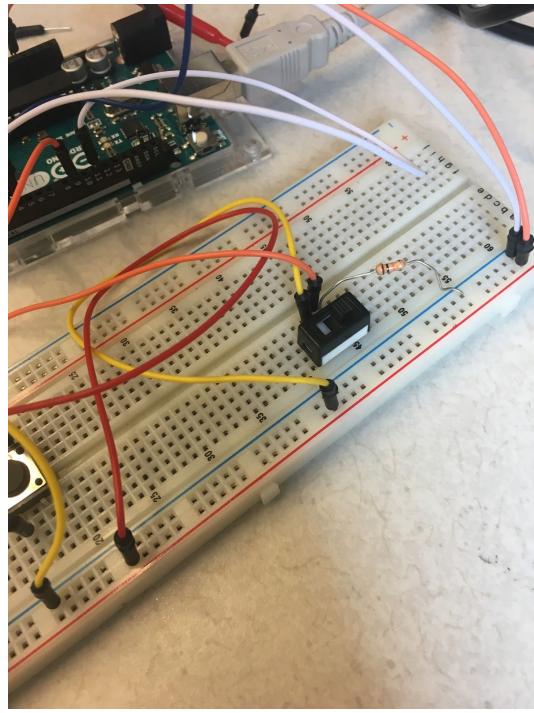


Figure 15 Switch is at Up State

After the button was pressed few time to get the pressure into the range of systolic pressure reading, the system read in the signal and scaled it correctly as Figure 12 demonstrated.

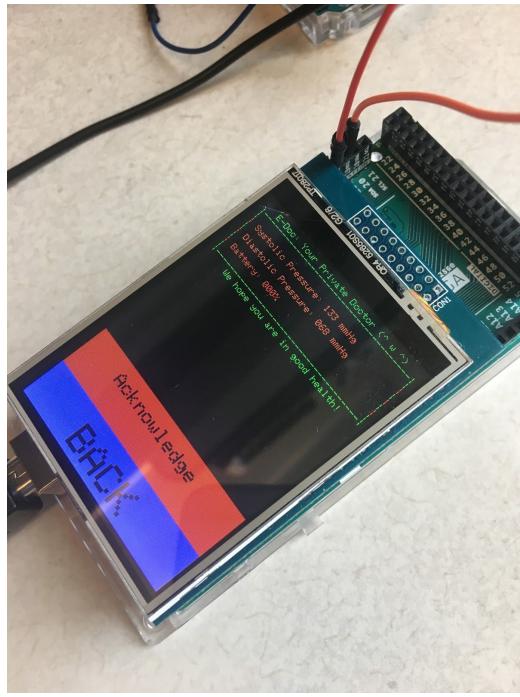


Figure 16 Systolic Pressure Reading Updated

Then, the switch is turn to down state for diastolic pressure measurement.

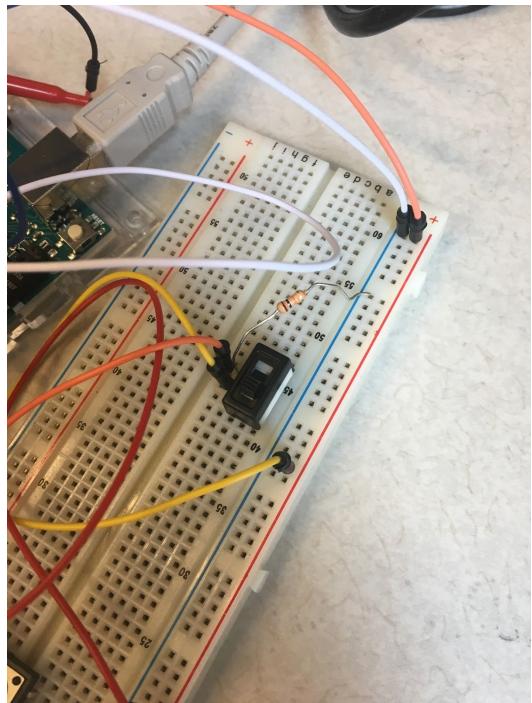


Figure 17 Switch is at Down State

After the button was pressed few time to get the pressure into the range of diastolic pressure reading, the system read in the signal and scaled it correctly as figure 14 demonstrated.



Figure 18 Systolic Pressure Reading Updated

Respiration Measurements:

The respiration rate measurement is now measured from analog signal and should be map to human respiration rate range. The input frequency is corresponding with the output frequency as demonstrated by Figure 19 to 22.

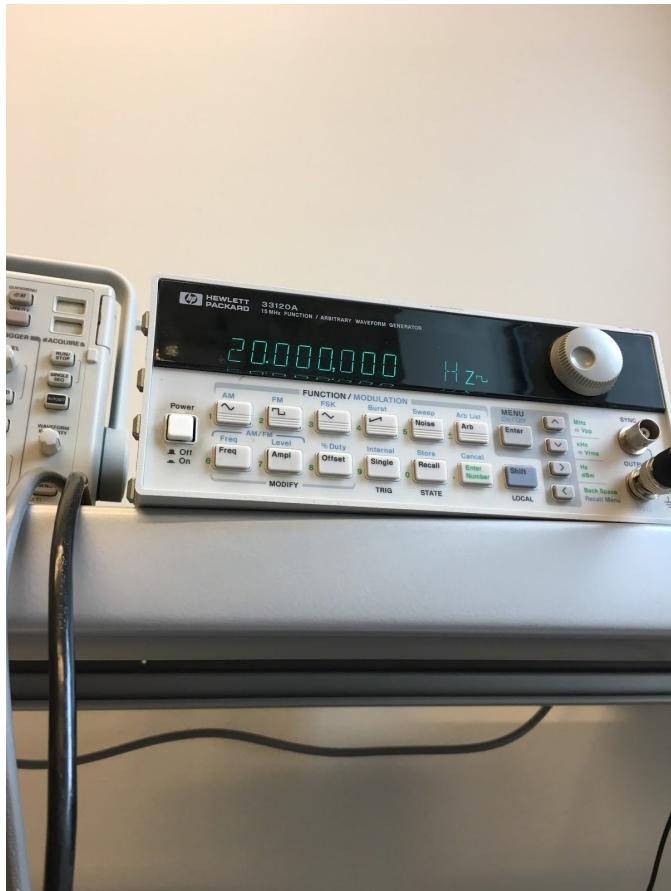


Figure 19 Set Input Frequency to 20Hz



Figure 20 Respiration Rate Matches with Input

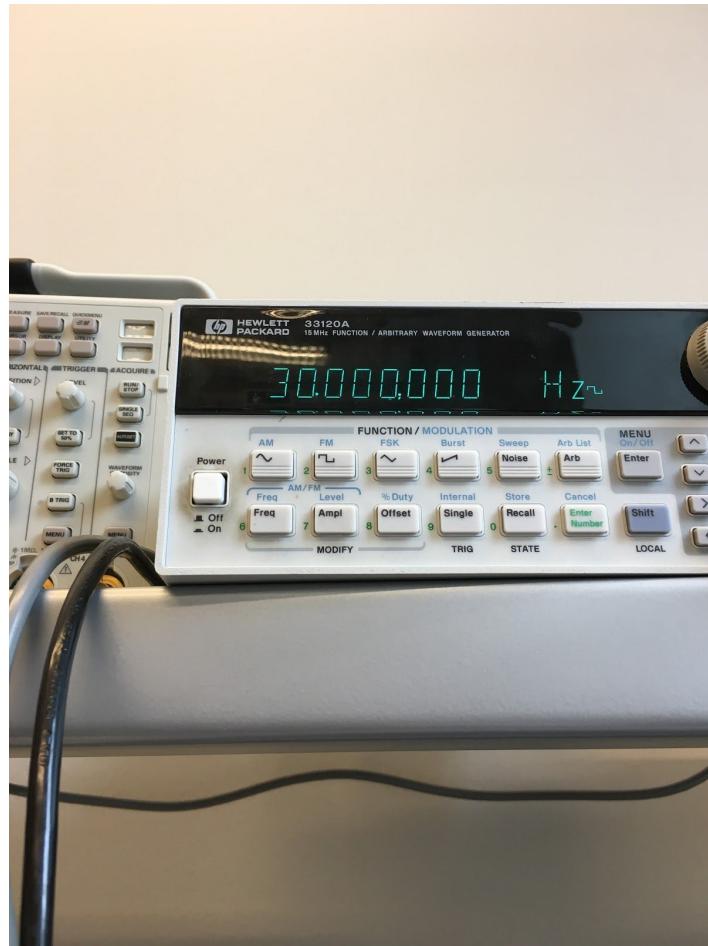


Figure 21 Set Input Frequency to 30Hz



Figure 22 Respiration Rate Matches with Input

Flash On Warning:

Figure 23 to 28 demonstrated that the temperature is flashed at 1 second period. The temperature display went from on to off in one second and back on at the beginning of the next second.



Figure 23 Temperature is On at 16:52:21



Figure 24 Temperature is off at 16:52:21



Figure 25 Temperature is off at 16:52:22

Figure 22 to 24 demonstrated that the pulse rate is flashed at 2 second period. The pulse rate display stay on for one second stay off at the next second.



Figure 26 Pulse Rate is on at 16:52:21



Figure 27 Pulse Rate is off at 16:52:22



Figure 28 Pulse Rate is on at 16:52:23

Figure 29 to 32 demonstrated that the Blood Pressure is flashed at 0.5 second period. The Blood Pressure display went from on to off to on to off in one second.

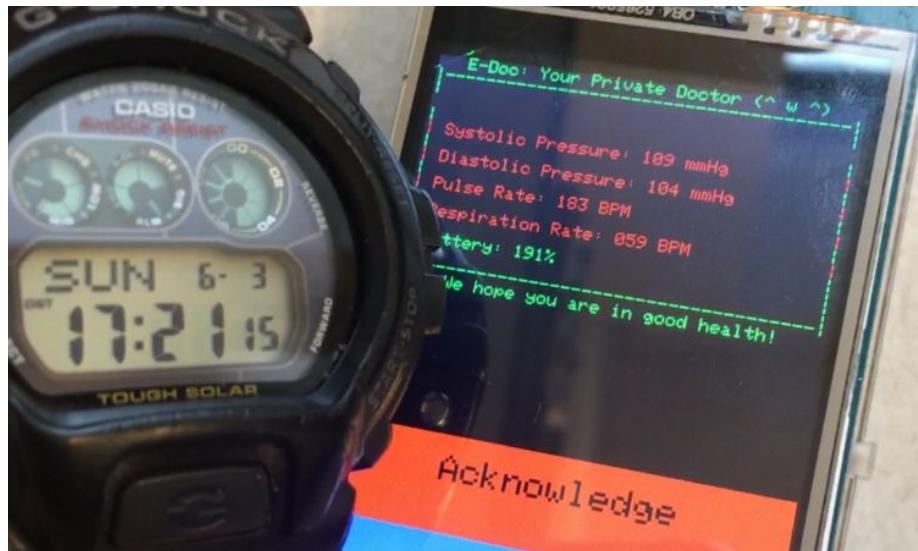


Figure 29 Systolic Pressure is on at 17:21:15



Figure 30 Systolic Pressure is on at 17:21:15



Figure 31 Systolic Pressure is on at 17:21:15



Figure 32 Systolic Pressure is on at 17:21:15

EKG Measurement:

For the input frequency range from 35Hz to 3.75kHz, the system is able to measure, store and process the input signal and produce EKG data corresponding to the input frequency. Figure 33 to 36 demonstrates that the EKG reading is corresponding to the input frequency.

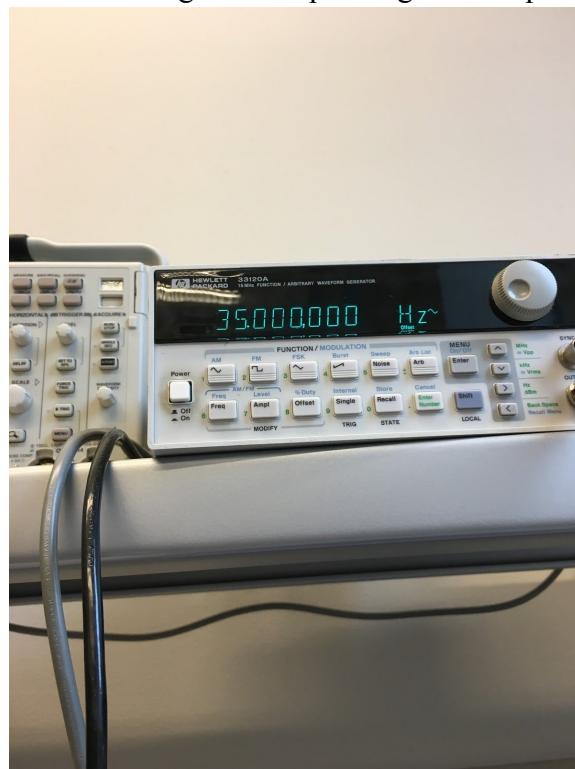


Figure 33 Input Frequency is Set to 35 Hz



Figure 34 EKG Reading is 23 Hz

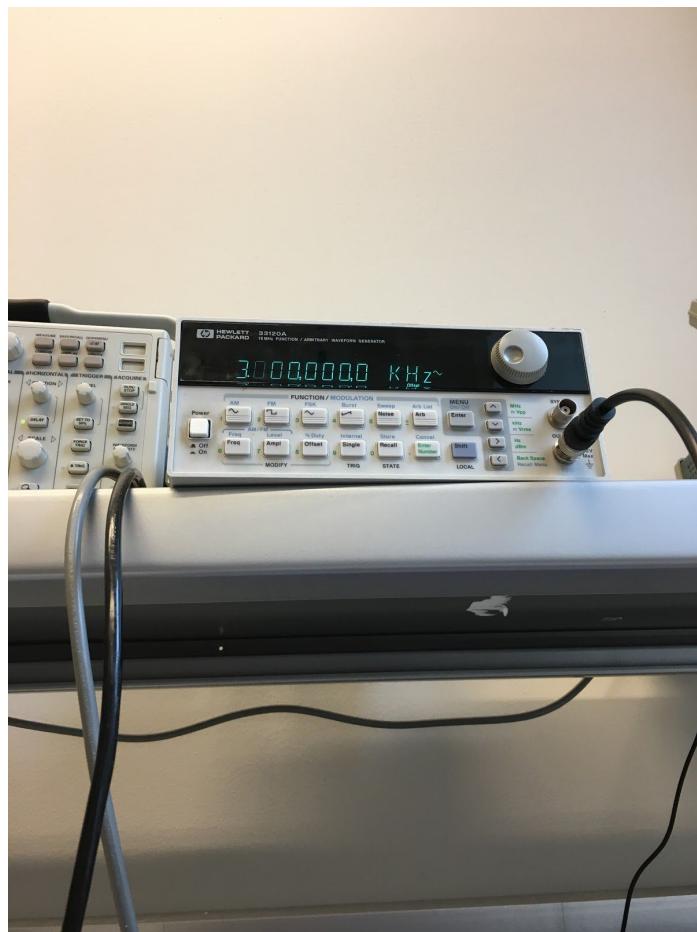


Figure 35 Input Frequency is Set to 3000 Hz



Figure 36 EKG Reading is 2783 Hz

Remote Command:

Figure 37 demonstrates that enter “I” command on PuTTY terminal initializes the network communications between your system and the browser page.

```
Serial.read(); // s = 4'bxxxx  
'ekg_capture";  
'skg_capture";  
read();  
  
COM28 - PuTTY  
index & Health Helper Monitoring System  
apt(digPatient name : Jack Doctor name: Mary  
upt(prTemperature 78 C  
Systolic pressure 78 mmHg  
Distolic pressure 67 mmHg  
index & OPulse Rate 67 Bps  
rupt(digRespiration Rate 45 Bps  
rupt(prEKG 56 Hz  
rupt(Command enabled  
  
:  
nIndex &  
Data data  
);  
(1);  
  
ressure  
onIndex &  
eData data  
(3);  
  
te(9);  
te((char) temperatureRaw);  
te((char) Pressure);  
te((char) EKG);
```

Figure 37 Remote Computer System Initiation Prompt

Figure 38 demonstrates that the E error response is given for incorrect commands or non-existent commands on PuTTY terminal.

```
bad(); // s = 4'bxxxxx
picture");
ture);

COM28 - PuTTY
Health Helper Monitoring System
Patient name : Jack Doctor name: Mary
Temperature 78 C
Systolic pressure 78 mmHg
Diastolic pressure 67 mmHg
Pulse Rate 67 Bps
Respiration Rate 45 Bps
EKG 56 Hz
E invalid command
E invalid command
E invalid command

&
ata

e
x &
data

ar) temperatureRaw);
ar) Pressure);
ar) systolicPressRaw);
ar) diastolicPressRaw);
```

Figure 38 Remote Computer System Invalid Command Prompt

Figure 39 demonstrates that enter “S” command indicates START mode. The command shall start the embedded tasks by directing the hardware to initiate the measurement tasks.

```
(*)>
}
Serial.read(); // s = 4'bxxxx
("ekg_capture");
(ekg_capture);
..read();

COM28 - PuTTY
Index & Health Healper Monitoring System
:rupt(digPatient name : Jack Doctor name: Mary
:rupt(prfTemperature 78 C
    Systolic pressure 78 mmHg
    Diastolic pressure 67 mmHg
Index & OPulse Rate 67 Bps
:rupt(digRespiration Rate 45 Bps
:rupt(prfEKG 56 Hz
    System started
    TOP

ire
ionIndex &
reData data
(1);
ire(1);

pressure
tationIndex &
ureData data
re(3);

write(9);
write((char) temperatureRaw);
write((char) Pressure);
write((char) systolicPressRaw);
write((char) diastolicPressRaw);
write((char) pulseRateRaw);
write((char) respirationRateRaw);
```

Figure 39 Remote Computer System Task Started Prompt

Figure 40, 41 demonstrates that enter “P” command indicates STOP mode. This command shall stop the embedded tasks by terminating any running measurement tasks.

```
    te(9) {  
  
        Serial.read(); // s = 4'bxxxx  
        n("ekg_capture");  
        n(ekg_capture);  
        l.read();  
  
        COM28 - PUTTY  
nIndex & Health Helper Monitoring System  
rrupt(digPatient name : Jack Doctor name: Mary  
rrupt(prPulse Rate 67 Bps  
nIndex & 0  
rrupt(digRespiration Rate 45 Bps  
rrupt(prEKG 56 Hz  
System stoped  
TOP  
re  
onIndex &  
eData data  
(1);  
re(1);  
  
pressure  
ionIndex &  
reData data  
(3);  
  
te(9);  
te((char) temperatureRaw);  
te((char) Pressure);  
te((char) systolicPressRaw);  
te((char) diastolicPressRaw);  
te((char) pulseRateRaw);
```

Figure 40 Remote Computer System Task Stopped Prompt

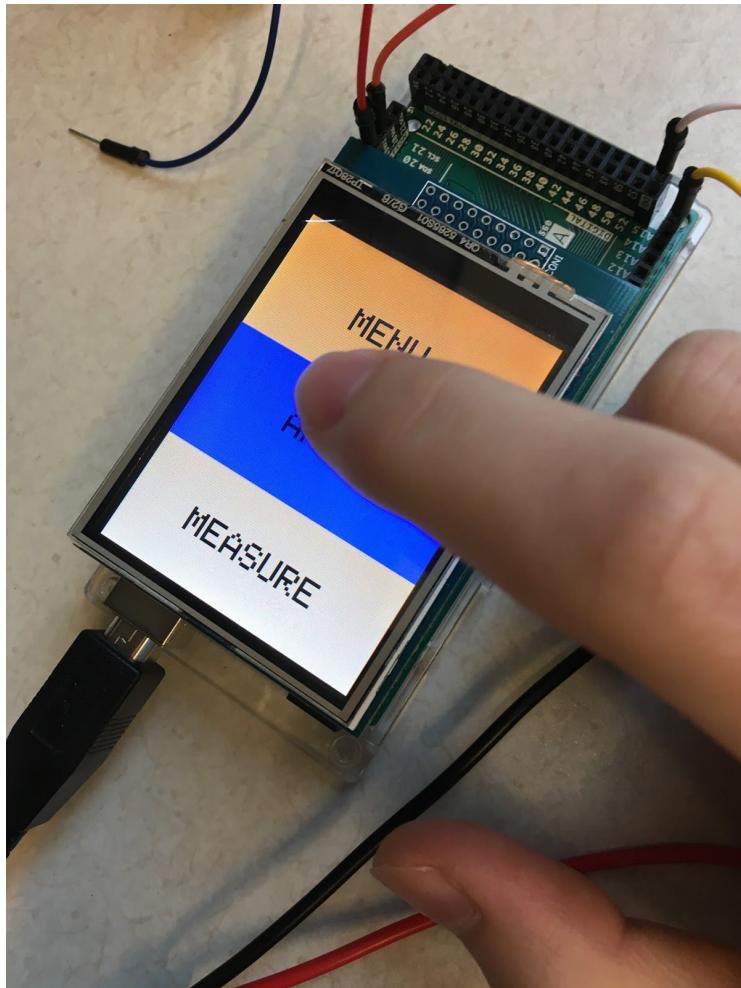


Figure 41 System no longer Responsive to Touch After Task Stopped

Figure 42 to 45 demonstrates that enter “D” command enables or disables the local display.

```
    }9) {  
  
    Serial.read(); // s = 4'bxxxx  
n("ekg_capture");  
n(ekg_capture);  
al.read();  
  
COM28 - PuTTY  
nIndex & Health Helper Monitoring System  
errrupt(digPatient name : Jack Doctor name: Mary  
errrupt(prTemperature 78 C  
Systolic pressure 78 mmHg  
Distolic pressure 67 mmHg  
nPulse Rate 67 Bps  
errrupt(digRespiration Rate 45 Bps  
errrupt(prEKG 56 Hz  
Display changed  
TOP  
ure  
ionIndex &  
ureData data  
(1);  
are(1);  
  
pressure  
tionIndex &  
ureData data  
te(3);  
  
rite(9);  
rite((char) temperatureRaw);  
rite((char) Pressure);  
rite((char) systolicPressRaw);  
rite((char) diastolicPressRaw);  
rite((char) pulseRateRaw);
```

Figure 42 Remote Computer System Display Changed Prompt

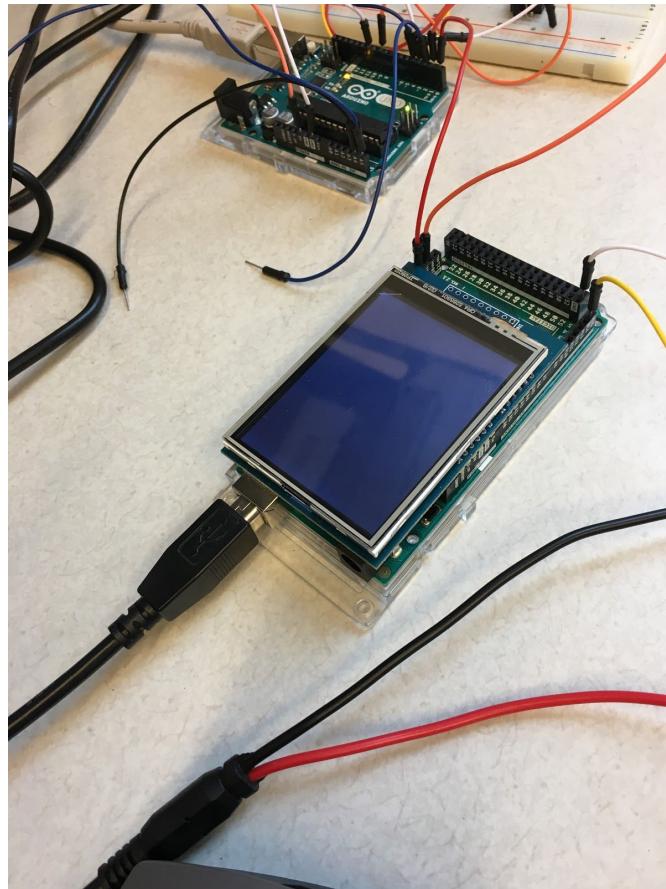


Figure 43 System Display is Off After the D Command

```
    }9) {  
  
    Serial.read(); // s = 4'bxxxx  
n("ekg_capture");  
n(ekg_capture);  
al.read();  
  
COM28 - PuTTY  
nIndex & Health Helper Monitoring System  
errrupt(digPatient name : Jack Doctor name: Mary  
errrupt(prTemperature 78 C  
Systolic pressure 78 mmHg  
Distolic pressure 67 mmHg  
nPulse Rate 67 Bps  
errrupt(digRespiration Rate 45 Bps  
errrupt(prEKG 56 Hz  
Display changed  
TOP  
  
ure  
ionIndex &  
ureData data  
(1);  
are(1);  
  
pressure  
tionIndex &  
ureData data  
te(3);  
  
rite(9);  
rite((char) temperatureRaw);  
rite((char) Pressure);  
rite((char) systolicPressRaw);  
rite((char) diastolicPressRaw);  
rite((char) pulseRateRaw);
```

Figure 44 Remote Computer System Display Changed Prompt

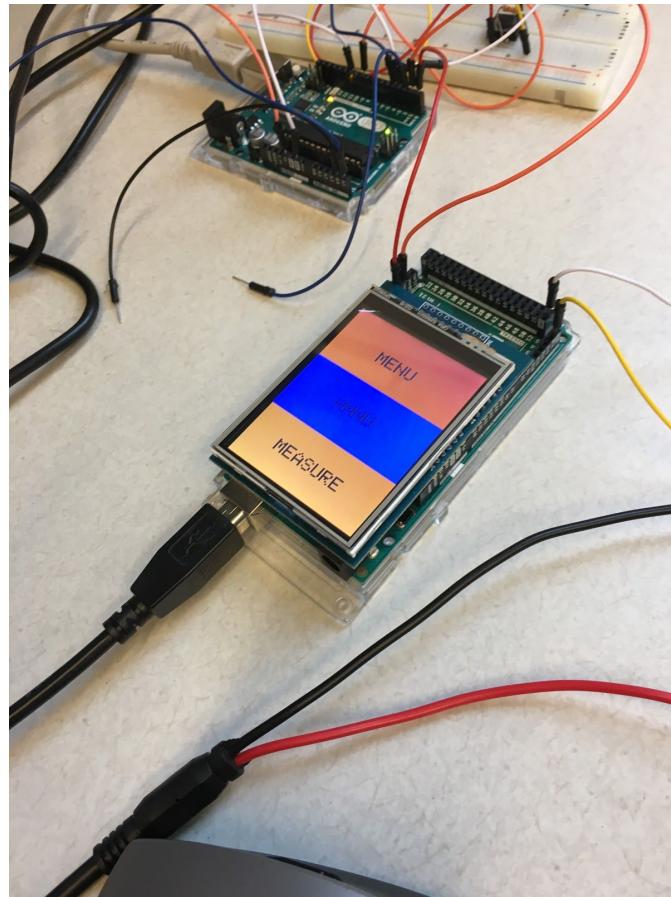


Figure 45 System Display is On After Reenter the D Command

Figure 46 demonstrates that enter “M” command return the the most recent value(s) of all measurement data

The screenshot shows a terminal window titled "COM28 - PuTTY". The window displays a series of data entries from a "Health Helper Monitoring System". The entries include patient information ("Patient name : Jack Doctor name: Mary"), temperature ("Temperature 38 C"), blood pressure ("Systolic pressure 115 mmHg", "Diastolic pressure 68 mmHg"), pulse rate ("Pulse Rate 102 Bps"), respiration rate ("Respiration Rate 130 Bps"), and EKG data ("EKG 1118 Hz"). A message "Data updated" is also present. The background of the terminal window is dark, and the text is white or light-colored.

```
9) {
    Serial.read(); // s = 4'bxxxx
    n("ekg_capture");
    n(ekg_capture);
    ul.read();

    COM28 - PuTTY
nIndex & Health Helper Monitoring System
rrupt(prfPatient name : Jack Doctor name: Mary
rrupt(prfTemperature 38 C
    Systolic pressure 115 mmHg
    Diastolic pressure 68 mmHg
nIndex & Pulse Rate 102 Bps
errupt(prfRespiration Rate 130 Bps
errupt(prfEKG 1118 Hz
    Data updated

are
ionIndex &
reData data
(1);
re(1);

    pressure
tionIndex &
ureData data
e(3);

ite(9);
rite((char) temperatureRaw);
rite((char) Pressure);
rite((char) systolicPressRaw);
rite((char) diastolicPressRaw);
rite((char) enVal);
```

Figure 46 Remote Computer System Data Updated Prompt

Figure 47 demonstrates that enter “W” command indicates return the most recent value(s) of all warning and alarm data.

```

rial.read(); // s = 4'bxxxx
ekg_capture");
kg_capture);
ead();

[Terminal Output]
COM28 - PuTTY
dex & Health Helper Monitoring System
pt(digPatient name : Jack Doctor name: Mary
pt(prTemperature 39 C
Systolic pressure 115 mmHg
Diastolic pressure 68 mmHg
dex & CPulse Rate 47 Bps
upt(digRespiration Rate 4 Bps
upt(prEKG 1070 Hz
warning updated

Index &
ata data
;
(1);

essure
nIndex &
Data data
);

(9);
e((char) temperatureRaw);
e((char) Pressure);
e((char) systolicPressRaw);
e((char) diastolicPressRaw);
e((char) pulseRateRaw);

```

Figure 47 Remote Computer System Display Warning Updated Prompt

Remote Display:

Figure 48 demonstrates that the remote display displays all required information which includes:

- The name of the product
- The patient's name
- The doctor's name.
- Temperature: <temperature> C
- Systolic pressure: <systolic pressure> mm Hg
- Diastolic pressure: <diastolic pressure> mm Hg
- Pulse rate: <pulse rate> BPM
- Respiration rate <pulse rate> BPM
- EKG < Measured Frequency reading > Hz
- Battery: <charge remaining>

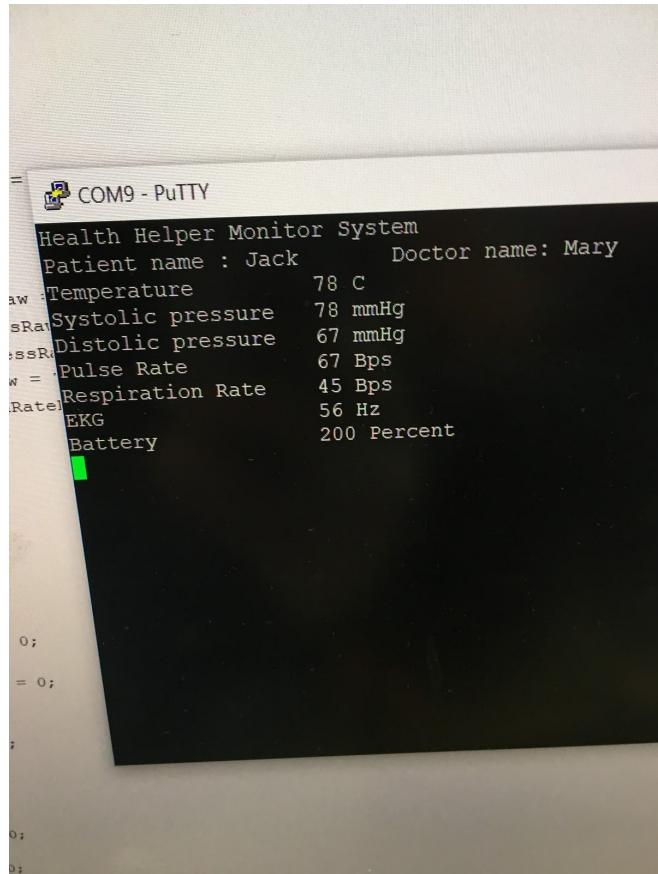


Figure 48 Remote Computer Terminal With Required Information Displayed

4. Analysis of errors needed to be resolved

Our design is error-free and we do not have any unresolved error to be fixed.

5. Analysis of errors encountered

1. Memory Size Limit

Cause: The dynamic Memory Size of UNO is only 2048 bytes, and due to the FFT, we required 13% bytes more. We previously use char array to store sample, but the accuracy is not good then cause the unstable FFT Output.

2. EKG measurements are not stable when input Frequency is larger than 3.3KHz

Cause: We changed real and imaginary from integer to character so that EKG measurement can be put on UNO, which caused frequent overflow when calculating FFT.
Fixation: Put EKG measurement on ATMega and use integer type.

6. Test

Test Plan

* Tests for data structures and some features are the same as those in lab 3 and we tested them using the same plan and cases as we did for lab 3. Please refer “EE474 Lab3 report” for more information.

UNO side

We need to verify that functionalities about peripheral on UNO side works properly.

1. We need to verify that cuff value are changed by buttons and uno can capture systolic and diastolic pressure from analog signal from function generator
2. We need to verify that Uno can be measure frequencies of incoming square wave and be able to respond to interrupt we have attached.
3. We need to verify that analogRead value are reasonable

ATMega side

1. We need to verify that remote display window can display data sent from Mega and Mega is able to receive command characters and responds properly to those commands.
2. We need to verify that new added UI works properly (EKG selection button & Display mode button).
3. New measurement EGK can return stable value

Test Specification

Uno side:

1. Cuff value should have the same behaviors as described below in table:

Cuff value	Switch value (indicating direction of changes)	Button Pressed
Stay the same	1	Not pressed

+10%	1	Pressed
Stay the same	0	Not pressed
-10%	0	Pressed

Uno should only return a new blood pressure measurement only if one of conditions stated below is met.

Which pressure to update	Cuff value	When
Systolic pressure	Between 110 to 150 mmHg	First time cuff value is in this range
Diastolic pressure	Between 50 to 80 mmHg	First time cuff value is in this range
None	Any other value	NONE

2. We need to verify that square wave given to UNO is VPP 3.3 V and 50 % duty cycle and value obtained by UNO read is alternating between 0 and 1. We make sure interrupt function is called every time interrupt conditions are meet. We put a counter in interrupt function to monitor how many times interrupts are enabled.

Respiration rate and pulse rate are all handled by interrupt, value returned by function should be approximately the same as frequencies of input square wave.

3. We need to verify that analog read in uno can return reasonable value. Analog read value should be in the range of 0 - 300 (we tune the function generator so that analogread value should be in that range).

Measurements use analogread should return value in that range.

ATMega side

1. We should verify that remote control system can change state of our cardio-monitor and should follow specifications described in table below.

Command sent	Behavior	Can monitor respond to touches and continue to make measurements
I	Enable remote command system	As long as user start system
S	Start monitoring system	Yes
P	Pause monitoring system	No
M	Send newest data to remote display	Yes
W	Send newest warning data to remote display	Yes
D	Turn off display	No

2. We added more UI buttons to ATMega

EKG selection button can be tapped and change color.

We can enter display mode by tapping Measurement in Top menu.

3. For this section we divide this into three part

1. Make sure that analogread can return value ranging from 0 - 1024
2. Make sure that repressed value sent to TFF ranges from -31 to 31.
3. Make sure that index return by TFF is stable, if not increase sampling rate

Test Cases

UNO side:

Cuff testing:

Case 1 : switch at 1 press button for five time

Case 2 : switch at 0 press button for five time

Case 3 : when buff is in range observe whether blood pressure will only change for once

Interrupt test:

Case 1 : Frequency 2k

Case 2 : Frequency 34
Case 3 : Frequency 1k

Analog read:

Case : provide analog pin a tuned sinusoidal wave, record printed read value

ATMega side:

Remote command

We enter a series of commands and record system responses.

Case 1 : S S D D P

Case 2 : I S P P S D D

Case 3 : I S wait for some seconds w, m

UI testing:

Case 1: click EKG option for multiply times and observe effect

Case 2 : click measurement mode to see whether measurements are up to date

EKG testing

Case 1 : print analog read value

Case 2 : print adjusted analog value

Case 3 : print final index and make ture it is stable and linear

Test Result

Uno side :

Original Cuff value is 80

Case Number	Result
1	80 -> 88 -> 96 -> 105 -> 115 -> 126
2	80 -> 72 -> 65 -> 59 -> 54 -> 49
3	If in range corresponding value will only change once and remain stable until next time cuff value is in range

Interrupt test:

Case Number	Result
1	1990 Hz
2	40 Hz

3	1010 Hz
---	---------

Analog read value:

Analog read value ranges from 0 to 300 which is what we expected.

ATMega side:

Remote tests:

Case 1 :

Command sent	Response
s	Error message
s	Error message
d	Error message
d	Error message
p	Error message

Case 2 :

Command sent	Reponse
i	Command enabled
s	System started
p	System pausd
p	nothing happened
s	System started
d	Display turned off
d	Display turned on

Case 3 :

Command	Reponse
---------	---------

i	Command enabled
s	System started
m	Measurement Data updated
w	Warning data updated

UI testing:

Case 1: Ekg selection button will change color as long as we tap it and it will remain the same color as we left it when we re-enter selection menu.

Case 2 : Display mode display temperature, blood pressure, respiration rate, pulse rate and EKG properly

EKG testing

Case 1 : Analog raw data ranges from 0 to 1023 periodically and they are evenly spaced.

Case 2 : Adjusted analog raw data ranges from -31 to 31 and they are evenly spaced.

Case 3 :

Frequency	Index returned
36	1
1000	83
2000	171
3000	240

Index returned are stable at given frequency and approximately linear with frequencies.

7. Summary and Conclusion

Summary

Lab4 and Lab5 are based on Lab1 Lab2 and Lab3. According to the infrastructure, we additionally use Interrupt Service Routine to implement Measure Task including Pulse Rate,

Respiration Rate and Blood Pressure on Uno, measure EKG by implementing a hard real time task and implement remote control. In Lab4, we model our patient use resistors, and switch and model Cuff using a button. In Lab5, our main task is to build remote control communication using Putty through serial communication port, and experience hard real time task to measure EKG. In the end, we integrate our whole system and implement a medical embedded system which can be controlled by either remote control from other terminal or by local display. Now the system support to measure Temperature, Blood Pressure, Pulse Rate, Respiration Rate and EKG, and allow remote measurement.

1. Timing Issue

Due to the refresh rate of Screen on Uno, the minimum user friendly output's rate should be larger than 10ms.

When choose measurement items, user should click the button and release the button as soon as possible, otherwise it will not change the previous status of measurement.

When choose annunciation, the whole system will stall for 2 seconds due to the process time which is inevitable.

2. Potential Bug.

Continuing press on button without release will make system stall until users release.

3. Test Issue

It is hard to read time in second with small error range. Because our delay can be accurate in 10x ms, so we need to test our output delay is correct or acceptable.

4. Tradeoff

Due to the dynamic Memory Size, we measure and process EKG in ATMega 2560 rather than in Uno. In our original design, we support put our RTOS kernel in ATMega2560 and do all the measurement in Uno which could be more convenient for the future upgrade. However, the dynamic memory size in Uno has only 2048 bytes which is 13% bytes smaller than our original expected value, so we put EKG measure in ATMega 2560 as well.

Conclusion

This is the end of our 474 project but is also the start of our new journey. We start from Code Block to simulate some functions to integrate whole measurement and can even use remote control to control the whole system. We experience how to design a RTOS kernel to control the system, how to use ISR to measure data, how to implement hard real time task, how to communicate with two MCU and how to use remote control to control the whole systems. We

experience bugs and challenges, complaint and beer. Now, our system, the medical embedded system can fully operate. It can measure Temperature, Blood Pressure, Pulse Rate, Respiration Rate, and EKG and users can remotely use it!

We appreciate Dr. James Peckol and our TA: Daniel Predmore, Christy Truong, Jonathan Hamberg for their help and advice. Congrats to your graduation! We really enjoy this quarter and this course!

8. Individual Contribution

Name	Contribution
Gaohong Liu, Shawn Xu, Yongqin Wang	Software design & testing
Gaohong Liu, Shawn Xu, Yongqin Wang	System integration
Gaohong Liu, Shawn Xu, Yongqin Wang	Lab Report

table 14

9. Appendices

User Manual

There are two parts of our system. Users can either operate our systems using remote control, or using local display.

Remote Control has following command:

- I The I command initializes the network communications between your system and the browser page.
- E The E error response is given for incorrect commands or non-existent commands.
- S The S command indicates START mode. The command shall start the embedded tasks by directing the hardware to initiate the measurement tasks. In doing so, the command shall also enable all the interrupts.

P The P command indicates STOP mode. This command shall stop the embedded tasks by terminating any running measurement tasks. Such an action shall disable any data collecting interrupts.

D The D command enables or disables the local display.

M The M command. The M command requests the return of the most recent value(s) of all measurement data.

W The W command. The W command requests the return of the most recent value(s) of all warning and alarm data.

IMPORTANT

User has to type I to initialize the remote control and type S to use whole system, otherwise the system will stall until activate.

After system is ready to work, users now have two thing to choose

1) Measurement Menu

Inside Measurement Menu, Users have three things to choose, left button is body temperature, middle button is pulse rate, and right button is blood pressure. If they are in green, it means users are currently measuring and they are in red, it means they are disabled. After finish measurement selection, users could press return button to back to mean menu.

2) Annunciation

If users press Annunciation button, the system will begin to measure and calculate and display panel will display measured data on panel. User still could use return button to return back to main menu.

3) Measurement

If users press Measure button, the system will begin to measure and calculate everything(include EKG) without warning. User still could use return button to return back to main menu.

Source Code

Source code locates at ee474_proj5.zip

Extra Question

1. Q: Hard copy of your pseudo code

A: Included in Discussion of Lab Section.

2. Q: Hard copy of your source code.

A: Included in Source Code Section.

3. Q: Empirically measured individual task execution time.

A: We have following data:

For the first run, due to the cold start:

Measure: 16 μ s

Compute: 236 μ s

WarningAlarm: 88 μ s

Display: 718676 μ s

Status: 12 μ s

EKGMeasure: 2.5ms

EKGProcess: 17 μ s

For the rest run (almost all of rest run):

Measure: 8 μ s

Compute: 8 μ s

WarningAlarm: 80 μ s

Display: 8 μ s

Status: 8 μ s

EKGMeasure: 2.5ms

EKGProcess: 8 μ s

4. Q: Include a high-level block diagram with your report.

A: Included in Discussion of Lab Section.

- 5. Q: If you were not able to get your design to work, include a contingency section describing the problem you are having, an explanation of possible causes, a discussion of what you did to try to solve the problem, and why such attempts failed.**

A: We have finished our Lab with all specification required.

- 6. Q: The final report must be signed by team members attesting to the fact that the work contained therein is their own and each must identify which portion(s) of the project she or he worked on.**

A: Included in Individual Contribution Section.

- 7. Q: If a stealth submersible sinks, how do they find it?**

A:First, try to find the signal sent from the submersible.

Second, if technicians can not track signals, try to locate the track of submersible which should be in some limited range.

Third, use sonar to locate it.

- 8. Q: Does a helium filled balloon fall or rise south of the equator?**

A: Rise. Because the density of helium is smaller than Air.

10. Reference

[1]Class.ee.washington.edu. (2018). ***EE474 Workload and Grading.*** [online] Available at: <https://class.ee.washington.edu/474/peckol/admin/expectations.html> [Accessed 6 Apr. 2018].

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