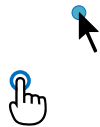
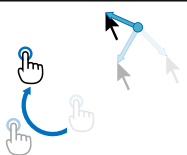


鼠标点击



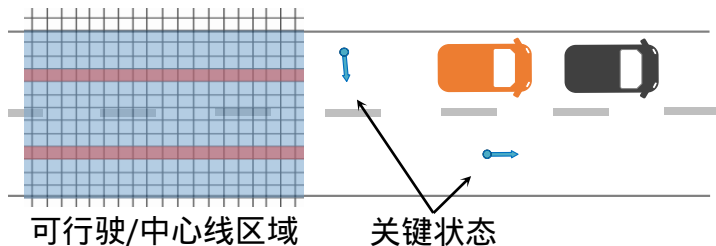
鼠标拖拽



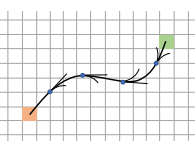
已有轨迹



离散化场景



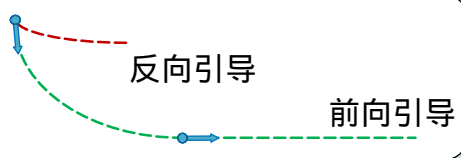
启发式搜索



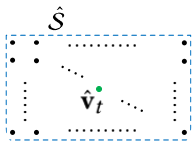
参考路径

反向引导

前向引导



速度采样

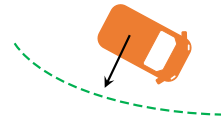


基于优化的交通仿真

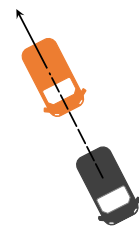
自驱动



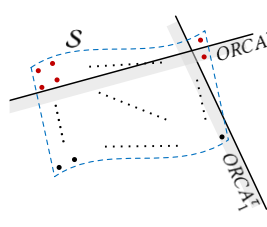
路径保持



碰撞避免



软约束



硬约束

