# semi simulation

library(MASS)
library(Iso)

## Iso 0.0-17

library(mvtnorm)

### Model overview

#### Basic model

Recently Wang and Zhou (2018) proposed a parametric transformation model for biomarker data, of the form

$$f(\mathbf{t}|\mathbf{x}, \mathbf{z}) = \sum_{d=0}^{L-1} \pi_d(\mathbf{z}) \prod_{k=1}^K J(t_k, \lambda_k) g(H_k(t_k, \lambda_k|\mathbf{x}),$$

where  $g(\cdot|\mathbf{x})$  is a known parametric density,  $H(\cdot,\cdot)$  is a given transformation,  $J(t_k,\lambda_k)$  is the transformation Jacobian, and  $\pi_d(\mathbf{z})$  is the mixture proportion, which is specified as a logit form. In their model, the joint density is independent given the covariate  $\mathbf{x}$ 

#### Our extension

Here our model is more general, the joint density is not independent, and the monotone transformations  $H_k(\cdot)$ 's are also unknown to be estimated The observed data is  $D_n = \{(\mathbf{y}_i, \mathbf{x}_i)\} : i = 1, ..., n\}$  from n subjects.  $\mathbf{y}_i = (y_{i1}, ..., y_{ik})^T$  is the observation of the i-th subject with k biomarkers,  $\mathbf{x}_i = (x_{i1}, ..., x_{iq})$  is the corresponding covariates, we assume the  $(\mathbf{y}_i, \mathbf{x}_i)$ 's are iid.

The goal is to classify each subject to one of the two groups, normal and disabled. For this, we first need to specify a model, then estimate the model parameters and finally, classify the subjects.

The normal model is easy to use but not robust to model assumption. For robustness we propose the following semi-parametric transformation model for the observed data. First, for each margin, we specify the transformation

$$g_j(y_{ij}) = \mathbf{x}_i^T \beta_j + \epsilon_{ij}$$
  $(i = 1, 2, ..., n; j = 1, ..., k)(1)$ 

where  $g_j(\cdot) \in \mathcal{G}$ ,  $\mathcal{G}$  is the collection of bounded monotone non-decreasing functions, and  $\epsilon_{ij}$  is the noise. We assume  $\epsilon_i := (\epsilon_{i1}, ..., \epsilon_{ik})^T \sim N(\mathbf{0}, \Omega)$ ,  $\Omega = (\omega_{ij})_{k \times k}$ . Denote  $\mathbf{g}(\mathbf{y}_i) = (g_1(y_{i1}), ..., g_k(y_{ik}))^T$  and  $\mathbf{x}_i = (x_{i1}, ..., x_{iq})^T$ ,  $\mathbf{beta}_j = (\beta_{j1}, ..., \beta_{jq})^T$  and  $\mathbf{B}^T = (\beta_1, ..., \beta_k)$ . Let  $\phi(\cdot|\Omega)$  be the density function of the  $N(\mathbf{0}, \Omega)$  distribution. Next, since the group status of each subject is unknown, the joint model is specified as a mixture

$$f(\mathbf{y}_i|\mathbf{x}_i) = \sum_{d=0}^{1} \pi_d(\mathbf{x}_i) \phi(\mathbf{g}(\mathbf{y}_i) - \mathbf{x}_i^T \mathbf{B} | \Omega)(2)$$

where

$$\pi_0(\mathbf{x}_i|\eta) = 1 - \pi_1(\mathbf{x}_i|\eta) = \frac{\exp(\mathbf{x}_i^T \eta)}{1 + \exp(\mathbf{x}_i^T \eta)}$$

is the mixing proportions.  $\pi_d(\mathbf{x}_i|\eta)$  is the probability subject i belongs to group d.

## Simulation settings:

• Assumption1: joint density is not independent, and  $H_k(\cdot) = I_k(\cdot)$ , k = 2 (2 biomarkers) with q = 2 (2 covariates).

We need to estimate  $\eta = \{\eta_1, \eta_2, ..., \eta_q\}$ ,  $\theta = \{\eta_{jd}, \ \omega_{jr}: j, r=1, ..., k; d=0,1\}$  and  $\mathbf{g}(\cdot) = (g_1(\cdot), ..., g_k(\cdot))$ . Note that since the  $\omega_{jr}$ 's are symmetric, we only need to estimate  $\omega_{jr}$  for  $j=1, ..., k; r \geq j$ . Let  $\delta_i$  be the latent group indicator of the *i*-th subject,  $\delta_i = 0$  if this subject belongs to group 0, and  $\delta_i = 1$  otherwise. Let  $D_{n,c} = \{(\mathbf{y}_i, x_i, \delta_i): i=1, ..., n\}$  be the "complete" data. The log-likelihood of the complete data is

$$\ell(\eta, \theta, \mathbf{g}|D_{n,c}) = \sum_{i=1}^{n} \sum_{d=0}^{1} \left[ I_d(C_i) \left( \log \pi_d(\mathbf{x}_i|\eta) - \frac{1}{2} (\mathbf{g}(\mathbf{y}_i) - \mathbf{x}_i^T \mathbf{B})^T \Omega^{-1} (\mathbf{g}(\mathbf{y}_i) - \mathbf{x}_i^T \mathbf{B}) \right) - \frac{n}{2} \log |\Omega|.(3) \right]$$

We estimate  $(\eta, \theta, \mathbf{g})$  by

$$(\hat{\eta}, \hat{\theta}, \hat{\mathbf{g}}) = \arg \max_{(\eta, \theta, \mathbf{g}) \in (\mathbf{B}, \mathbf{\Theta}, \mathcal{G}^k)} \ell(\eta, \theta, \mathbf{g} | D_{n,c}).(4)$$

• Simulation1