Contents

5 #include <bits/stdc++.h>

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_	
1	Priority Queue
	<pre>priority_queue<int, vector<int="">, greater<int>> p; // min heap priority_queue<int, vector<int="">, less<int>> p; // max heap</int></int,></int></int,></pre>
2	Connected Components
in	t bfs(bool *visited, vector <int> *adjList, int *buffer, int size, int start) {</int>
	<pre>int count = 0; queue<int> q;</int></pre>
	q.push(start);
	<pre>visited[start] = true;</pre>
	<pre>while (!q.empty()) {</pre>
	<pre>start = q.front(); q.pop();</pre>
	for (auto i : adjList[start]) {
	<pre>if (!visited[i]) {</pre>
	<pre>visited[i] = true; buffer[count++] = i;</pre>
	q.push(i);
	} }
	}
}	return count;
3	$_{ m BFS}$
/** * To compile and run:	
* clang++ -o bfs bfs.cpp && ./bfs	

```
using namespace std;
   int n;
10
     * Unweighted shortest path with BFS
     * Oparam graph: adjacency list, directed or undirected
12
     * Oparam s: starting edge
14
     * distance: min distance of nodes to s
     * path: last node to s
16
   void bfs(vector<int>* graph, int s){
18
        queue<int> q;
19
        int v, w;
20
        q.push(s);
21
22
        int* distance = new int[n];
23
        int* path = new int[n];
24
        memset(distance, -1, n * sizeof(int));
25
        memset(path, -1, n * sizeof(int));
26
27
        distance[s] = 0;
        while(!q.empty()){
29
            v = q.front();
            q.pop();
31
            for(int i = 0; i < graph[v].size(); i++){</pre>
                 w = graph[v][i];
33
                 if(distance[w] == -1){
34
                     distance[w] = distance[v] + 1;
35
                     path[w] = v;
36
                     q.push(w);
37
                     cout<<"("<<v<", "<<w<<")"<<endl;
38
                 }
39
            }
40
        }
41
   }
42
43
   int main(){
44
        cin>>n;
45
        auto graph = new vector<int>[n]();
46
        for(int i = 0; i < n; i ++){
            int t;
48
            cin>>t;
            for(int j = 0; j < t; j++){
50
                 int s;
51
                 cin>>s;
52
                 graph[i].push_back(s);
53
            }
54
        }
55
56
        bfs(graph, 0);
57
        return 0;
59
```

60 }

4 Dijkstra

```
#include <bits/stdc++.h>
   using namespace std;
   constexpr int SIZE = 20;
   double graph[SIZE] [SIZE];
   double *dijkstra(int n, int v) {
        auto *distance = new double[n];
        distance[v] = 0;
        for (int j = 1; j < n; ++j)
            distance[j] = 10e300; //numeric_limits<double>::max();
11
        auto comp = [=](int a, int b) {
            return distance[a] > distance[b];
13
        };
        priority_queue<int, vector<int>, decltype(comp)> q(comp);
15
        q.push(v);
        while (!q.empty()) {
17
            v = q.top();
18
            q.pop();
19
            for (int i = 0; i < n; i++) {
                 auto weight = graph[v][i];
21
                 if (weight == 0) continue;
22
                 if (distance[v] + weight < distance[i]) {</pre>
23
                     distance[i] = distance[v] + weight;
24
                     q.push(i);
25
                 }
26
            }
27
        }
28
        return distance;
   }
30
   int main() {
32
        auto *dist = dijkstra(SIZE, 0);
33
        for (int i = 0; i < SIZE; i++) {
34
            cout << dist[i] << " ";</pre>
35
36
        cout << endl;</pre>
        return 0;
38
   }
```

5 Line Equations

```
#include <bits/stdc++.h>
using namespace std;

/**

* parametric line equation

* <x, y> = s * <v1, v2> + <b1, b2>
*/
*/
```

```
struct Line {
        double v1;
9
        double v2;
10
        double b1;
        double b2;
12
   };
13
14
   struct Point {
        double x;
16
        double y;
17
   };
18
19
   Line lines[100];
20
21
   Point intercept(const Line &11, const Line &12) {
22
        double temp = 12.v1 * 11.v2 - 12.v2 * 11.v1;
23
        if (abs(temp) < 1e-7)
24
            return {10e300, 10e300};
25
        double w1 = 11.b1 - 12.b1;
26
        double w2 = 11.b2 - 12.b2;
27
        double s = (12.v2 * w1 - 12.v1 * w2) / temp;
        return {l1.v1 * s + l1.b1, l1.v2 * s + l1.b2};
29
   }
30
31
   double dist(const Point &p1, const Point &p2) {
        double dx = p1.x - p2.x;
33
        double dy = p1.y - p2.y;
34
        return sqrt(dx * dx + dy * dy);
35
   }
36
37
   int main() {
38
        int n;
39
        cin >> n;
40
        for (int i = 0; i < n; ++i) {
41
            int x1, y1, x2, y2;
42
            cin >> x1 >> y1 >> x2 >> y2;
43
            double dx = x2 - x1;
44
            double dy = y2 - y1;
            lines[i].v1 = dx;
46
            lines[i].v2 = dy;
            lines[i].b1 = x1;
48
            lines[i].b2 = y1;
        }
50
   }
```

6 Non Prime

```
#include <bits/stdc++.h>
using namespace std;

constexpr int MAX = 2000001;
uint16_t not_prime[MAX] = { 0 };
```

```
int main() {
        ios_base::sync_with_stdio(false);
        cin.tie(nullptr);
10
        for (int x = 2; x * x < MAX; x++) {
11
            if (!not_prime[x]) {
                for (int i = x * x; i < MAX; i += x)
13
                    not_prime[i] = 1;
            }
15
        }
16
        for (int x = 2; x < MAX; x++) {
17
            if (not_prime[x]) {
18
                for (int i = x; i < MAX; i += x)
19
                    not_prime[i] += 1;
20
            }
21
        }
22
        for (int j = 2; j < MAX; ++j) {
23
            not_prime[j] += not_prime[j] == 0;
24
25
26
        int q, i;
27
        cin >> q;
28
        for (int _ = 0; _ < q; ++_) {
            cin >> i;
30
            cout << not_prime[i] << '\n';</pre>
32
        return 0;
   }
34
        Prim
    #include <bits/stdc++.h>
   using namespace std;
   constexpr int SIZE = 2000;
   double graph[SIZE] [SIZE];
   double prim(int n) {
        int start = 0;
        auto comp = [](auto &a, auto &b) { return a.second > b.second; };
        priority_queue<pair<int, double>, pair<int, double>, decltype(comp)> q(comp);
9
        auto *visited = new bool[n]();
11
        auto *keys = new double[n]();
12
        keys[0] = 0;
13
        for (int i = 1; i < n; i++) {
14
            keys[i] = 10e300;
15
16
        q.push({start, 0});
17
        while (!q.empty()) {
18
            start = q.top().first;
19
            q.pop();
20
            visited[start] = true;
            for (int i = 0; i < n; i++) {
22
```

```
double weight = graph[start][i];
23
                if (!visited[i] && weight < keys[i]) {</pre>
24
                    keys[i] = weight;
25
                    q.push({i, weight});
                }
27
            }
29
       delete[] visited;
31
        delete[] keys;
       return accumulate(keys, keys + n, 0.0);
33
   }
34
        Prime Sieve
   #include <bits/stdc++.h>
   using namespace std;
   #define MAX 123456
   bool prime[MAX];
   int main() {
6
       memset(prime, true, sizeof(prime));
       for (int x = 2; x * x < MAX; x++) {
8
            if (prime[x]) {
                for (int i = x * x; i < MAX; i += x)
10
                    prime[i] = false;
11
            }
12
       }
13
   }
14
        TopSort
   9
     * To compile and run:
     * clang++ -o topsort topsort.cpp && ./topsort
     */
   #include <bits/stdc++.h>
   using namespace std;
   /**
     * Oparam graph is the adjacency list, graph[a] contains b if a is pre-req of b
     * Oparam degrees is the in-degree of nodes in graph, e.g. 0 if no pre-req
10
     * @returns topological order of the graph
12
13
   vector<int> topsort(vector<vector<int>>& graph, int* degrees){
14
        int counter = 0;
        queue<int> q;
16
       vector<int> result;
18
       for(int i = 0; i < graph.size(); i++){</pre>
            if(degrees[i] == 0){
20
                q.push(i);
```

```
}
22
        }
23
24
        while(!q.empty()){
25
            int idx = q.top();
26
            q.pop();
27
            result.push_back(idx);
28
            for(auto v : graph[idx]){
29
                 degrees[v] -= 1;
30
                 if(degrees[v] == 0){
31
                     q.push(v);
32
                 }
33
            }
34
            counter++;
35
        }
36
    }
37
    int main(){
39
40
    }
41
```