

# Deep Network for Speech Emotion Recognition

—A Study of Deep Learning—



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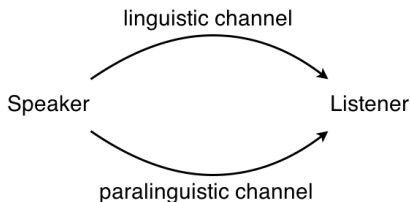
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## Speech Emotion Recognition

- Most current work focuses on speech processing based on linguistic information, e.g.: Skype Translator
- More natural human-machine interaction requires paralinguistic information such as age, gender, emotion.
- Speech Recognition / Speaker Identification / Emotion Recognition



## Deep Learning

- Deep architecture for extracting complex structure and building internal representations from input
- New research area of machine learning (from shallow to deep structure)
- Widely applied in vision/audition processing, e.g. handwriting recognition (Graves, Alex, et al. 2009), traffic sign classification (Schmidhuber, et al. 2011), text translation (Google, 2014)

## Foundations

- Mel Frequency Cepstral Features
- Emotion Recognition Approaches

## Conditional Restricted Boltzmann Machine

- Restricted Boltzmann Machine
- CRBM

## Conclusion and Outlook

## Foundations

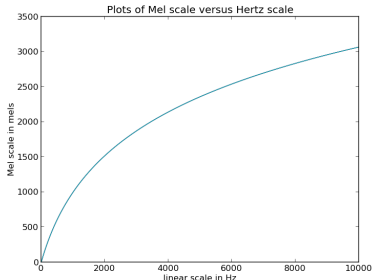
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## Conclusion and Outlook

- short-term power spectrum
- mel-scale approximate human perception
- widely-used in speech recognition tasks
- Transformation between Mel and Hertz scale



$$f_{mel} = 1125 \ln (1 + f_{Hz}/700)$$

$$f_{Hz} = 700 (\exp(f_{mel}/1125) - 1)$$

## Traditional Approaches

- pre-selected features
- supervised training
- low-level features not appropriate for classification
- shallow structure of classifiers

## Deep Learning Approaches

- learning representations from high-dim data
- extracting appropriate features without hand-crafting
- low-level features are used to build high-level features as network gets deeper
- frame-based classification

## Foundations

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Restricted Boltzmann Machine

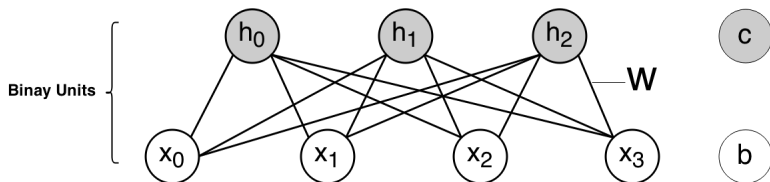
CRBM

## Conclusion and Outlook

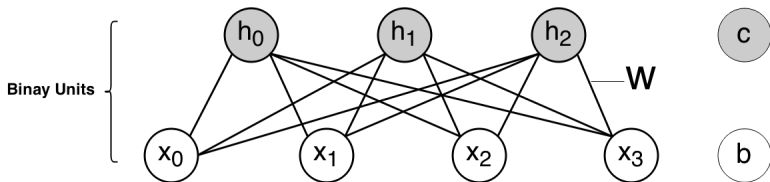


- Generative graphical model, capture data distribution  $P(\mathbf{x}|\theta)$
- Trained in unsupervised way, only use unlabeled input sequences  $\mathbf{x}$  for learning.
  - automatically extract useful features from data
  - Find hidden structure (distribution).
  - Learned features used for prediction or classification
- Successfully applied in motion capture (Graham W. Taylor, Geoffrey E. Hinton, 2006)
- Potential to be extend to capture temporal information

## Structure



## Structure



$$\text{Energy Function: } E_{\theta} = -\mathbf{x}^T \mathbf{W} \mathbf{h} - \mathbf{b}^T \mathbf{x} - \mathbf{c}^T \mathbf{h}$$

$$\text{Joint Distribution: } P^{RBM}(\mathbf{x}, \mathbf{h}) = \frac{1}{Z} e^{-E_{\theta}(\mathbf{x}, \mathbf{h})}$$

$$\text{Partition Function: } Z = \sum_{\mathbf{x}, \mathbf{h}} e^{-E_{\theta}(\mathbf{x}, \mathbf{h})}$$

$$\text{Free Energy: } \mathcal{F}(\mathbf{x}) = -\log \sum_{\mathbf{h}} e^{-E(\mathbf{x}, \mathbf{h})}$$

## Inference

$$P(\mathbf{x}) = \sum_{\mathbf{h}} P(\mathbf{x}, \mathbf{h})$$

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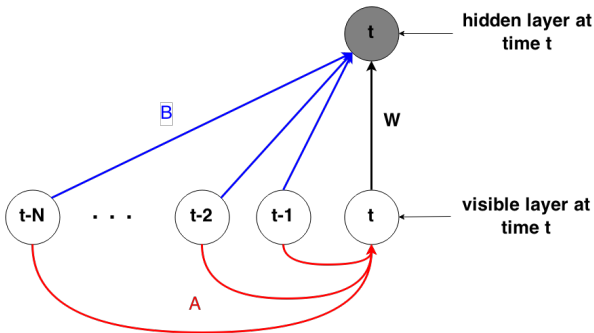
$$P(\mathbf{x}|\mathbf{h}) = \frac{P(\mathbf{x}, \mathbf{h})}{P(\mathbf{h})}$$

$$P(h_j = 1 \mid \mathbf{x}) = \text{sigmoid}(\sum_i x_i W_{ij} + c_j)$$

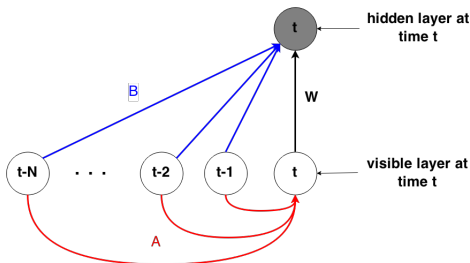
$$P(x_i = 1 \mid \mathbf{h}) = \text{sigmoid}(\sum_j W_{ij} h_j + b_i)$$

- Consider visible units from previous time step as additional bias for current visible and hidden layer
- $A$  and  $B$  are weight parameter of visible (history) - visible and visible (history) - hidden connections
- Visible layer is linear units with independent Gaussian noise to model real-valued data, e.g. spectral features

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$$\text{Energy Function: } E_{\theta}^{CRBM}(\mathbf{x}, \mathbf{h}) = \left\| \frac{\mathbf{x} - \tilde{\mathbf{b}}}{2} \right\|^2 - \tilde{\mathbf{c}}^T \mathbf{h} - \mathbf{x}^T \mathbf{W} \mathbf{h}$$

$$\tilde{\mathbf{b}} = \mathbf{b} + \mathbf{A} \cdot \mathbf{x}_{<t}$$

$$\tilde{\mathbf{c}} = \mathbf{c} + \mathbf{B} \cdot \mathbf{x}_{<t}$$

$$\theta = \{\mathbf{W}, \mathbf{A}, \mathbf{B}, \mathbf{b}, \mathbf{c}\}$$

$$\text{Free Energy: } \mathcal{F}(\mathbf{x}) = \left\| \mathbf{x} - \tilde{\mathbf{b}} \right\|^2 - \log(1 + e^{\tilde{\mathbf{c}} + \mathbf{x} \cdot \mathbf{W}})$$

Maximum Likelihood Estimation  $P(\mathbf{x}|\boldsymbol{\theta})$

Note that KL is non-negative

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Kullback-Leibler Divergence:

$$\begin{aligned} Q(\mathbf{x}) \| P(\mathbf{x}|\boldsymbol{\theta}) &= \int_{-\infty}^{\infty} Q(\mathbf{x}) \cdot \log \frac{Q(\mathbf{x})}{P(\mathbf{x}|\boldsymbol{\theta})} d\mathbf{x} \\ &= \int_{-\infty}^{\infty} Q(\mathbf{x}) \cdot \log Q(\mathbf{x}) d\mathbf{x} - \int_{-\infty}^{\infty} Q(\mathbf{x}) \cdot \log P(\mathbf{x}|\boldsymbol{\theta}) d\mathbf{x} \\ &= \langle \log Q(\mathbf{x}) \rangle_{Q(\mathbf{x})} - \langle \log P(\mathbf{x}|\boldsymbol{\theta}) \rangle_{Q(\mathbf{x})} \end{aligned}$$

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$P(\mathbf{x}|\boldsymbol{\theta})$ , model distribution

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$\tilde{\mathbf{x}}$ , all possible vectors in the data space, generated by model.

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objective function by averaging log-likelihood over data:

$$-\left\langle \frac{\partial \log P(\mathbf{x}|\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} \right\rangle_{\mathbf{x}} = \left\langle \frac{\partial \mathcal{F}(\mathbf{x})}{\partial \boldsymbol{\theta}} \right\rangle_{\mathbf{x}} - \left\langle \frac{\partial \mathcal{F}(\tilde{\mathbf{x}})}{\partial \boldsymbol{\theta}} \right\rangle_{\tilde{\mathbf{x}}}$$

## Gibbs sampling

$$\mathbf{x}^{(1)} \sim P(\mathbf{x})$$

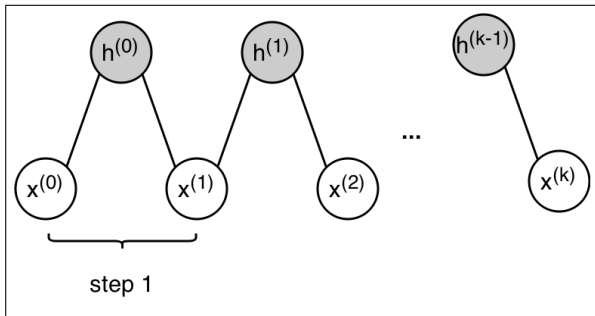
$$\mathbf{h}^{(1)} \sim P(\mathbf{h}|\mathbf{x}^{(1)})$$

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⋮

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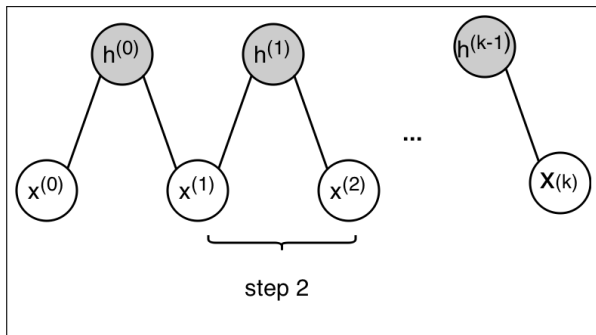
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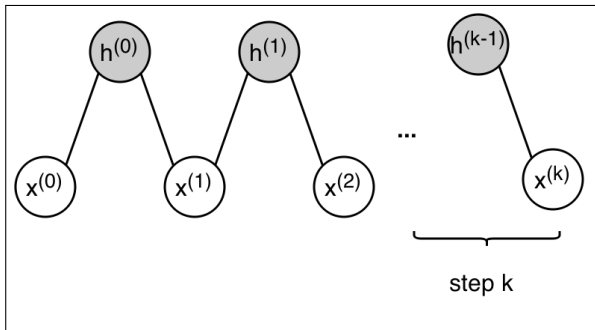
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- $k=0$ ,  $P_0(\mathbf{x})$  is true data distribution, independent of parameter  $\theta$
- Performing  $k$ -Gibbs steps to generate  $P_k(\mathbf{x}|\theta)$ , with  $k \rightarrow \infty$  the Markov chain converges to stationary distribution:

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## Contrastive Divergence: Perform CD-1

$$\begin{aligned} & - \frac{\partial}{\partial \boldsymbol{\theta}} (P_0 \| P_{\infty}^{\boldsymbol{\theta}} - P_1^{\boldsymbol{\theta}} \| P_{\infty}^{\boldsymbol{\theta}}) \\ &= \left\langle \frac{\partial \mathcal{F}(\mathbf{x})}{\partial \boldsymbol{\theta}} \right\rangle_{P_0} - \left\langle \frac{\partial \mathcal{F}(\mathbf{x})}{\partial \boldsymbol{\theta}} \right\rangle_{P_1^{\boldsymbol{\theta}}} + \frac{\partial P_1^{\boldsymbol{\theta}}}{\partial \boldsymbol{\theta}} \frac{\partial (P_1^{\boldsymbol{\theta}} \| P_{\infty}^{\boldsymbol{\theta}})}{\partial P_1^{\boldsymbol{\theta}}} \end{aligned}$$

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Parameter Update

$$\Delta \theta \sim \left\langle \frac{\partial \mathcal{F}(\mathbf{x})}{\partial \theta} \right\rangle_{P_0} - \left\langle \frac{\partial \mathcal{F}(\mathbf{x})}{\partial \theta} \right\rangle_{P_1^\theta}$$

## Foundations

Mel Frequency Cepstral Features

Emotion Recognition Approaches

## Conditional Restricted Boltzmann Machine

Restricted Boltzmann Machine

CRBM

## Conclusion and Outlook

- Model with long-term dependencies shall be used for speech emotion
- CRBM is appropriate for short-term modelling, but not for long-term variation
- LSTM is good at modelling long time dependency
- Frame-based classification can also reach good result
  - CRBM-LSTM 71.98%
  - LSTM 81.59%
  - LSTM with rectifier layers 83.43%

- Stacking CRBM to form deeper structure
- Train CRBM with more/larger database
- Second order optimization to speed up learning process
- Bi-directional LSTM, capturing future dependencies

# Thank You!