# Deep Neural Network for Speech Emotion Recognition —A Study of Deep Learning—



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### **Motivation**



# Why speech emotion recognition

- Most current work focuses on speech processing based on linguistic information, e.g.: Skype Translator
- More natural human-machine interaction requires paralinguistic information such as age, gender, emotion.
- Speech Recognition / Speeker Identification / Emotion



# Deep Network Applications

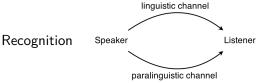
- Handwriting Digit Recognition
- Image Recognition

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- Image Recognition



#### **Foundations**

Mel Frequency Cepstral Features Emotion Recognition Approaches

Conditional Restricted Boltzmann Machine Concept

Deep Neural Networks

Concept
Problems and Solutions

Long Short Term Memory Recurrent Neural Network

Experiments



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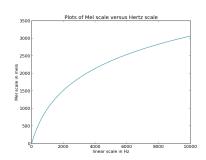
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# Mel Frequency Cepstral Features



- short-term power spectrum
- mel-scale approximate human perception
- widely-used in speech recognition tasks
- Transformation between Mel and Hertz scale



$$f_{mel} = 1125 \ln \left(1 + f_{Hz}/700\right)$$
 (1)

$$f_{Hz} = 700 \left( \exp(f_{mel}/1125) - 1 \right)$$
 (2)

# **Emotion Recognition Approaches**



# Traditional Approaches

- pre-selected features
- supervised training
- low-level features not appropriate for classification
- shallow structure of classifiers

# Deep Learning Approaches

- learning representations from high-dim data
- extracting appropriate features without hand-crafting
- low-level features are used to build high-level features as network gets deeper
- frame-based classfication



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### Restricted BM



- undirected graphical probablistic model based on PoE, capable in modeling high-dimensioanl data (speech emotion)
- speicifies a joint distribution over input and hidden variables, can either generating data, or with bayesian rule to form conditional distribution.

Desired: P(x, h)



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# Computing net-activation

$$\begin{array}{rcl} \underline{z}_k^{(l+1)} & = & \mathbf{W}^{(l)}\underline{a}_k^{(l)} + \underline{b}^{(l)} \\ \underline{a}_k^{(l+1)} & = & \underline{\Phi}\left(\underline{z}_k^{(l+1)}\right) \\ \underline{\hat{y}}_k & = & \underline{a}_k^{(ol)} \end{array}$$

- Arbitrary non-linear mapping from  $\underline{x}_k$  to  $\hat{\underline{y}}_k$  possible
- lacktriangle Relation  $N\Leftrightarrow \mathsf{Complexity}$
- Deep Architectures  $(l \uparrow)$  more efficient than shallow ones  $(l \downarrow, N_l \uparrow)$

# **Determining the parameters**



# Training objective

$$J(\mathbf{W}, \underline{b}) = \sum_{\forall k} \frac{1}{2} ||\underline{y}_k - \underline{\hat{y}}_k||^2 + \frac{\lambda}{2} \sum_{\forall l} ||\mathbf{W}^{(l)}||_F^2$$
 (3)

$$\mathbf{W}, \underline{b} = \arg\min_{\mathbf{W}, b} J(\mathbf{W}, \underline{b})$$
 (4)

#### Numerical minimization

- Gradient calculation with Backpropagation
- Stochastic gradient descent
- Limited memory Broyden-Fletcher-Goldfarb-Shanno (L-BFGS)

## **Problems**



- Optimization problem non-convex⇒ getting stuck in poor local minima
- Diffusion of gradients
- Large p small n problem  $\Rightarrow$  overfitting

# **Solutions**



Layerwise Pre-training

■ Layerwise Pre-training



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- modelling sequential data, emotion in speech
- Same Structure as MLP but differs from feed-forward network, enabling nonlinear mapping.
- Feedback connection between previous hidden units and current hidden units, enabling memory past hidden state.
- Potentially to model arbitary dynamic system
- Trained with backpropagation through time (BPTT)



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$$h_t = \mathcal{H}(W_{xh}x_t + W_{hh}h_{t-1} + b_h)$$
$$y_t = W_{hy}h_t + b_y$$

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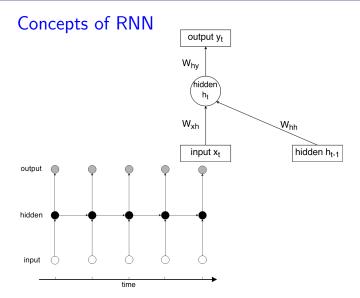


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### From RNN to LSTM



### Problems with RNN

- lacktriangledown gradient vanishing during backpropagation as time steps increases (>100)
- difficult to capture long-time dependency (which is required in emotion recognition)

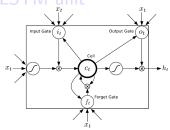
### Solutions

# Long short term memory



# S. Hochreiter and J. Schmidhuber, Lovol. 9, pp. 1735-1780, 1997.

### LSTM unit



$$i_{t} = \sigma(W_{xi}x_{t} + W_{hi}h_{t-1} + W_{ci}c_{t-1} + b_{i})$$

$$f_{t} = \sigma(W_{xf}x_{t} + W_{hf}h_{t-1} + W_{cf}c_{t-1} + b_{f})$$

$$c_{t} = f_{t}c_{t-1} + i_{t}\tanh(W_{xc}x_{t} + W_{hc}h_{t-1} + b_{f})$$

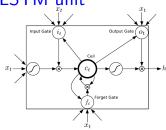
$$h_{t} = \sigma(W_{xo}x_{t} + W_{ho}h_{t-1} + W_{co}c_{t} + b_{o})$$

$$h_{t} = o_{t}\tanh(c_{t})$$

# Long short term memory



# LSTM unit



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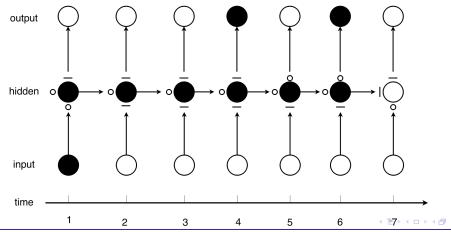
$$h_{t} = o_{t}\tanh(c_{t})$$

# Long short term memory



# Features in LSTM

- gates are trained to learn when it shoud be open/closed.
- Constant Error Carousel
- preserve long-time dependency by maintaining gradient over time.





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