

# Hao Tian

East China Normal University | School of Software Engineering | Ph.D. Student



## Personal Information

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Phone: +86-13795494199

E-mail: [nicktian.ecnu@gmail.com](mailto:nicktian.ecnu@gmail.com)

Graduation Date: March 2020

Personal Website: <https://hao-tian-ecnu.github.io/>

Research Interests: Computer Graphics, Human-Computer Interaction, VR/AR, Robotics

Address: B231 Science Building, 3663 N. Zhongshan Rd., Shanghai, China

## Education

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- East China Normal University Sep. 2014 – Present  
School of Software Engineering | Ph.D. Student  
Advised by Prof. Changbo Wang and Prof. Xinyu Zhang
- University of Maryland at College Park Mar. 2018 – Mar. 2019  
Department of Computer Science | Visiting Scholar  
Advised by Prof. Dinesh Manocha
- East China Normal University Sep. 2010 – Jul. 2014  
Software Engineering Institute | Bachelor

## Publications

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- **Transferring Grasp Configurations using Active Learning and Local Replanning [C].**  
**Hao Tian**, Changbo Wang, Dinesh Manocha, Xinyu Zhang.  
2019 IEEE International Conference on Robotics and Automation (ICRA). (CCF-B)
- **Realtime Hand-Object Interaction using Learned Grasp Space for Virtual Environments [J].**  
**Hao Tian**, Changbo Wang, Dinesh Manocha, Xinyu Zhang.  
2018 IEEE Transactions on Visualization and Computer Graphics (TVCG). (CCF-A, SCI)
- **Efficient Global Penetration Depth Computation for Articulated Models [J].**  
**Hao Tian**, Xinyu Zhang, Changbo Wang, Jia Pan, Dinesh Manocha.  
Journal of Computer-Aided Design, 2016, 70: 116-125. (CCF-B, SCI)
- **Interactive Grasping for High-genus Objects using Configuration Space Learning [C].**  
**Hao Tian**, Changbo Wang, Dinesh Manocha, Xinyu Zhang.  
2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). (CCF-C, workshop)
- **A Realtime Virtual Grasping System for Manipulating Complex Objects [C].**  
**Hao Tian**, Changbo Wang, Xinyu Zhang.  
2018 IEEE Conference on Virtual Reality and 3D User Interfaces (VR): 1-2. (CCF-A, poster)

- **SeLL: Second Language Learning Paired with VR and AI [C].**  
Juan Guo, Yu Chen, Qikai Pei, Hua Ren, Nan Huang, **Hao Tian**, Manni Zhang, Yao Liu, Guohe Fu, Huaqiang Hu, Xinyu Zhang.  
SIGGRAPH Asia 2017 Symposium on Education. (CCF-A)
- **A Penetration Depth Computation Method for Articulated Models.**  
Patent Number: ZL201510156024.0.  
Xinyu Zhang, Hao Tian. East China Normal University.

## Work & Project Experience

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- **VSpera Inc, Shanghai** May. 2016 – Sep. 2016  
Software Engineering Intern
  - Developed an interactive system for VR English learning software.
  - Encapsulated low-level interfaces of different devices and designed a uniform interface for other modules.
- **Low-cost Open Smart Glass and Augmented Reality Applications** Jan. 2015 – Dec. 2016
  - Advised by Prof. Xinyu Zhang. Founded by State Key Laboratory of Computer-Aided Design and Computer Graphics, Zhejiang University.
  - Assembled a low-cost smart glass using 3D printing and commercially available devices, like Android development board, monocular display, polarization prism, bone conduction headset, etc.
- **Virtual Shadow Play System based on Motion Sensing Technology** Jan. 2015 – Jan. 2016
  - Advised by Prof. Changbo Wang. Founded by China Association for Science and Technology
  - Developed a virtual shadow display software based on Intel RealSense and Kinect. Users can use their body to control virtual shadow play characters.

## Technical Strengths

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- Programming Skills: C/C++, Python
- Software and Tool: OpenGL, Unity3D, PCL, CUDA, OMPL, PyTorch

## Scholarships & Awards

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- 2017, 2018 ECNU & Focus Media Scholarship
- Jun. 2014 Outstanding graduate student of East China Normal University
- Sep. 2013 Third-class school outstanding student scholarships
- Sep. 2012 Second-class school outstanding student scholarships.

## Services & Other Experience

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- 2017, 2019 Invited speaker of ROS (Robotic Operation System) summer school
- 2015-2017 Volunteer for ROS (Robotic Operation System) summer school
- Oct. 2016 Participated in Shanghai International Marathon and completed the full marathon.
- Nov. 2016 Participated in Thousand Island Lake Marathon and completed the full marathon
- Sep. 2015 Volunteer for National Popular Science Day

# 田 浩

华东师范大学 | 计算机科学与软件工程学院 | 博士在读



## 个人信息

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毕业时间: 2020 年 3 月

个人主页(英文): <https://hao-tian-ecnu.github.io/>

研究方向: 计算机图形学, 自然人机交互与仿真, AR/VR, 机器人

地址: 上海市普陀区中山北路 3663 号华东师范大学理科大楼 B231

## 教育经历

- **华东师范大学** 2014.09 – 至今  
计算机科学与软件工程学院 | 本科直博  
导师: 王长波教授, 张新宇副教授
- **美国马里兰大学帕克分校** 2018.03 – 2019.03  
计算机科学系 | 国家留学基金委公派联合培养博士生  
导师: Dinesh Manocha 教授
- **华东师范大学** 2010.09 – 2014.06  
软件工程学院 | 学士

## 学术成果

- **Transferring Grasp Configurations using Active Learning and Local Replanning [C].**  
**Hao Tian**, Changbo Wang, Dinesh Manocha, Xinyu Zhang.  
2019 IEEE International Conference on Robotics and Automation (ICRA). (CCF-B)
- **Realtime Hand-Object Interaction using Learned Grasp Space for Virtual Environments [J].**  
**Hao Tian**, Changbo Wang, Dinesh Manocha, Xinyu Zhang.  
2018 IEEE Transactions on Visualization and Computer Graphics (TVCG). (CCF-A, SCI)
- **Efficient Global Penetration Depth Computation for Articulated Models [J].**  
**Hao Tian**, Xinyu Zhang, Changbo Wang, Jia Pan, Dinesh Manocha.  
Journal of Computer-Aided Design, 2016, 70: 116-125. (CCF-B, SCI)
- **Interactive Grasping for High-genus Objects using Configuration Space Learning [C].**  
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- **SeLL: Second Language Learning Paired with VR and AI [C].**  
Juan Guo, Yu Chen, Qikai Pei, Hua Ren, Nan Huang, **Hao Tian**, Manni Zhang, Yao Liu, Guohe Fu, Huaqiang Hu, Xinyu Zhang.  
SIGGRAPH Asia 2017 Symposium on Education. (CCF-A)
- 一种多关节模型穿透深度的计算方法. **ZL201510156024.0**. 专利, 已授权.  
张新宇, 田浩. 华东师范大学

## 实习&项目经历

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- **围光智能科技(上海)有限公司** 2016.05 – 2016.09  
软件工程实习生  
主要工作: 在实习期间负责 VR+英语学习平台的交互模块开发, 探索并开发 VR 学习环境中最有效的交互过程, 如基于仿真手的交互; 将交互技术适配多种主流 VR 设备, 包括 HTC Vive 和 Oculus Rift 等; 将底层设备和相关接口进行封装, 提供统一的数据获取接口给其他业务模块。
- **低成本智能眼镜 OpenGlass 与增强现实应用** 2015.01 – 2016.12  
指导教师: 张新宇副教授 | 浙江大学 CAD/CG 国家重点实验室开放课题  
主要工作: 作为项目主要负责人, 承担硬件与软件开发任务; 利用 3D 打印和市场上可买到的零部件设备, 如安卓开发板、单目显示器、偏振立方棱镜、骨传导耳机等, 制作了一副低成本智能眼镜; 在低成本 AR 眼镜上开发轻量级的 AR 应用, 如天气预报。
- **基于体感交互技术的皮影戏虚拟展示与科普宣传** 2015.01 – 2016.01  
指导教师: 王长波教授 | 中国科协科普部研究生科普能力提升项目  
主要工作: 作为项目负责人, 研究基于人体动作的交互技术, 开发基于 Kinect 的体感皮影交互系统。该项目利用 Kinect 设备捕捉人体骨骼数据, 与二维的数字皮影模型绑定, 实现通过身体来实时控制虚拟皮影人物功能。

## 专业技能

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- 编程技能: C/C++, OpenGL, Unity3D, PCL, CUDA, OMPL, Python, Pytorch
- 英语能力: CET-6

## 奖学金&获奖

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- 2017, 2018 年 华东师范大学分众奖学金
- 2014 年 11 月 “创青春”全国大学生创业大赛公益创业赛铜奖
- 2014 年 6 月 华东师范大学优秀毕业生
- 2012, 2013 年 分别获得华东师范大学优秀学生二、三等奖学金

## 社会服务&其他经历

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- 2017, 2019 年 机器人操作系统(ROS)暑期学校特邀演讲嘉宾
- 2015 – 2017 年 三届机器人操作系统(ROS)暑期学校志愿者
- 2016 年 10 月 上海国际全程马拉松完赛; 11 月千岛湖全程马拉松完赛
- 2015 年 9 月 上海市“全国科普日”活动志愿者