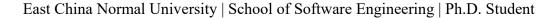
Hao Tian





Personal Information

Phone: +86-13795494199 E-mail: nicktian.ecnu@gmail.com

Graduation Date: March 2020 Personal Website: https://hao-tian-ecnu.github.io/

Research Interests: Computer Graphics, Human-Computer Interaction, VR/AR, Robotics

Address: B231 Science Building, 3663 N. Zhongshan Rd., Shanghai, China

Education

• East China Normal University
School of Software Engineering | Ph.D. Student
Advised by Prof. Changbo Wang and Prof. Xinyu Zhang

University of Maryland at College Park
 Department of Computer Science | Visiting Scholar
 Advised by Prof. Dinesh Manocha

• East China Normal University Sep. 2010 – Jul. 2014 Software Engineering Institute | Bachelor

Publications

- Transferring Grasp Configurations using Active Learning and Local Replanning [C].
 Hao Tian, Changbo Wang, Dinesh Manocha, Xinyu Zhang.
 2019 IEEE International Conference on Robotics and Automation (ICRA). (CCF-B)
- Realtime Hand-Object Interaction using Learned Grasp Space for Virtual Environments [J].
 Hao Tian, Changbo Wang, Dinesh Manocha, Xinyu Zhang.
 2018 IEEE Transactions on Visualization and Computer Graphics (TVCG). (CCF-A, SCI)
- Efficient Global Penetration Depth Computation for Articulated Models [J]. Hao Tian, Xinyu Zhang, Changbo Wang, Jia Pan, Dinesh Manocha. Journal of Computer-Aided Design, 2016, 70: 116-125. (CCF-B, SCI)
- Interactive Grasping for High-genus Objects using Configuration Space Learning [C].
 Hao Tian, Changbo Wang, Dinesh Manocha, Xinyu Zhang.
 2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). (CCF-C, workshop)
- A Realtime Virtual Grasping System for Manipulating Complex Objects [C]. Hao Tian, Changbo Wang, Xinyu Zhang.
 2018 IEEE Conference on Virtual Reality and 3D User Interfaces (VR): 1-2. (CCF-A, poster)

• SeLL: Second Language Learning Paired with VR and AI [C].

Juan Guo, Yu Chen, Qikai Pei, Hua Ren, Nan Huang, **Hao Tian**, Manni Zhang, Yao Liu, Guohe Fu, Huaqiang Hu, Xinyu Zhang.

SIGGRAPH Asia 2017 Symposium on Education. (CCF-A)

A Penetration Depth Computation Method for Articulated Models.

Patent Number: ZL201510156024.0.

Xinyu Zhang, Hao Tian. East China Normal University.

Work & Project Experience

• VSpera Inc, Shanghai

May. 2016 – Sep. 2016

Software Engineering Intern

- Developed an interactive system for VR English learning software.
- Encapsulated low-level interfaces of different devices and designed a uniform interface for other modules.

• Low-cost Open Smart Glass and Augmented Reality Applications Jan. 2015 – Dec. 2016

- Advised by Prof. Xinyu Zhang. Founded by State Key Laboratory of Computer-Aided Design and Computer Graphics, Zhejiang University.
- Assembled a low-cost smart glass using 3D printing and commercially available devices, like Android development board, monocular display, polarization prism, bone conduction headset, etc.

• Virtual Shadow Play System based on Motion Sensing Technology Jan. 2015 – Jan. 2016

- Advised by Prof. Changbo Wang. Founded by China Association for Science and Technology
- Developed a virtual shadow display software based on Intel RealSense and Kinect. Users can use their body to control virtual shadow play characters.

Technical Strengths

- Programming Skills: C/C++, Python
- Software and Tool: OpenGL, Unity3D, PCL, CUDA, OMPL, PyTorch

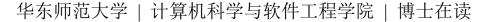
Scholarships & Awards

- 2017, 2018 ECNU & Focus Media Scholarship
- Jun. 2014 Outstanding graduate student of East China Normal University
- Sep. 2013 Third-class school outstanding student scholarships
- Sep. 2012 Second-class school outstanding student scholarships.

Services & Other Experience

- 2017, 2019 Invited speaker of ROS (Robotic Operation System) summer school
- 2015-2017 Volunteer for ROS (Robotic Operation System) summer school
- Oct. 2016 Participated in Shanghai International Marathon and completed the full marathon.
- Nov. 2016 Participated in Thousand Island Lake Marathon and completed the full marathon
- Sep. 2015 Volunteer for National Popular Science Day

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个人信息

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研究方向: 计算机图形学,自然人机交互与仿真,AR/VR,机器人地址:上海市普陀区中山北路 3663 号华东师范大学理科大楼 B231

教育经历

● **华东师范大学** 2014.09 – 至 今

计算机科学与软件工程学院 | 本科直博导师: 王长波教授,张新宇副教授

● 美国马里兰大学帕克分校 2018.03 - 2019.03

计算机科学系 | 国家留学基金委公派联合培养博士生导师: Dinesh Manocha 教授

● 华东师范大学 2010.09 – 2014.06

软件工程学院 | 学士

学术成果

- Transferring Grasp Configurations using Active Learning and Local Replanning [C].
 Hao Tian, Changbo Wang, Dinesh Manocha, Xinyu Zhang.
 2019 IEEE International Conference on Robotics and Automation (ICRA). (CCF-B)
- Realtime Hand-Object Interaction using Learned Grasp Space for Virtual Environments [J].
 Hao Tian, Changbo Wang, Dinesh Manocha, Xinyu Zhang.
 2018 IEEE Transactions on Visualization and Computer Graphics (TVCG). (CCF-A, SCI)
- Efficient Global Penetration Depth Computation for Articulated Models [J]. Hao Tian, Xinyu Zhang, Changbo Wang, Jia Pan, Dinesh Manocha. Journal of Computer-Aided Design, 2016, 70: 116-125. (CCF-B, SCI)
- Interactive Grasping for High-genus Objects using Configuration Space Learning [C]. Hao Tian, Changbo Wang, Dinesh Manocha, Xinyu Zhang.
 2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). (CCF-C, workshop)
- A Realtime Virtual Grasping System for Manipulating Complex Objects [C]. Hao Tian, Changbo Wang, Xinyu Zhang.
 2018 IEEE Conference on Virtual Reality and 3D User Interfaces (VR): 1-2. (CCF-A, poster)

• SeLL: Second Language Learning Paired with VR and AI [C].

Juan Guo, Yu Chen, Qikai Pei, Hua Ren, Nan Huang, **Hao Tian**, Manni Zhang, Yao Liu, Guohe Fu, Huaqiang Hu, Xinyu Zhang.

SIGGRAPH Asia 2017 Symposium on Education. (CCF-A)

• 一种多关节模型穿透深度的计算方法. ZL201510156024.0.专利,已授权.

张新宇,田浩.华东师范大学

实习&项目经历

• 围光智能科技(上海)有限公司

2016.05 - 2016.09

软件工程实习生

主要工作:在实习期间负责 VR+英语学习平台的交互模块开发,探索并开发 VR 学习环境中最有效的交互过程,如基于仿真手的交互;将交互技术适配多种主流 VR 设备,包括 HTC Vive 和 Oculus Rift等;将底层设备和相关接口进行封装,提供统一的数据获取接口给其他业务模块。

• 低成本智能眼镜 OpenGlass 与增强现实应用

2015.01 - 2016.12

指导教师: 张新宇副教授 | 浙江大学 CAD/CG 国家重点实验室开放课题 主要工作: 作为项目主要负责人,承担硬件与软件开发任务;利用 3D 打印和市场上可买到的零部件设备,如安卓开发板、单目显示器、偏振立方棱镜、骨传导耳机等,制作了一副低成本的智能眼镜;在低成本 AR 眼镜上开发轻量级的 AR 应用,如天气预报。

• 基于体感交互技术的皮影戏虚拟展示与科普宣传

2015.01 - 2016.01

指导教师: 王长波教授 | 中国科协科普部研究生科普能力提升项目 主要工作: 作为项目负责人,研究基于人体动作的交互技术,开发基于 Kinect 的体感皮影交互系 统。该项目利用 Kinect 设备捕捉人体骨骼数据,与二维的数字皮影模型绑定,实现通过身体来实 时控制虚拟皮影人物功能。

专业技能

• 编程技能: C/C++, OpenGL, Unity3D, PCL, CUDA, OMPL, Python, Pytorch

● 英语能力: CET-6

奖学金&获奖

- 2017, 2018 年 华东师范大学分众奖学金
- 2014年 11 月 "创青春"全国大学生创业大赛公益创业赛铜奖
- 2014年 6 月 华东师范大学优秀毕业生
- 2012, 2013 年 分别获得华东师范大学优秀学生二、三等奖学金

社会服务&其他经历

- 2017, 2019 年 机器人操作系统(ROS)暑期学校特邀演讲嘉宾
- 2015 2017 年 三届机器人操作系统(ROS)暑期学校志愿者
- 2016年10月上海国际全程马拉松完赛;11月千岛湖全程马拉松完赛
- 2015 年 9 月 上海市"全国科普日"活动志愿者