

NON-PARAMETRIC ESTIMATORS

Risk and Asset Allocation - Springer – *symmys.com*

Attilio Meucci

www.symmys.com

Formulas and figures in this presentation refer to the book **Risk and Asset Allocation**, Springer.

The notation, say, (5.24) refers to Formula 24 in Chapter 5 of the book

The notation, say, (T4.12) refers to Formula 12 in the Technical Appendices for Chapter 4, which can be downloaded from www.symmys.com

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$$\mathbf{G}[f_{\mathbf{X}}] \equiv \text{"unknown truth"}. \quad (4.6)$$

$$\text{information } i_T \mapsto \text{number } \hat{\mathbf{G}} \quad (4.9)$$

$$\overset{\uparrow}{i_T} \equiv \{\mathbf{x}_1, \dots, \mathbf{x}_T\} \quad (4.8)$$

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$$f_{i_T}(\mathbf{x}) \equiv \frac{1}{T} \sum_{t=1}^T \delta^{(\mathbf{x}_t)}(\mathbf{x}) \quad (4.35)$$

$$\lim_{T \rightarrow \infty} F_{i_T}(\mathbf{x}) = F_{\mathbf{X}}(\mathbf{x}) \quad (4.34)$$

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$$G [f_X] \equiv \int_{-\infty}^{+\infty} x f_X (x) dx. \quad (4.7)$$

$$\hat{G} [i_T] \equiv \int_{\mathbb{R}^N} \mathbf{x} f_{i_T} (\mathbf{x}) d\mathbf{x} \equiv \frac{1}{T} \sum_{t=1}^T x_t. \quad (4.41)$$

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$$\int_{-\infty}^{q_p [f_X]} f_X (x) dx \equiv p, \quad (4.38)$$

$$\widehat{q}_p [i_T] \equiv x_{[pT]:T} \quad (4.39)$$

NON-PARAMETRIC ESTIMATORS – ORDINARY LEAST SQUARES

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$$\mathbf{X} = \mathbf{B}\mathbf{F} + \mathbf{U}. \quad (4.50)$$

$$\mathbf{B}_r \equiv \mathbf{E} \{ \mathbf{X}\mathbf{F}' \} \mathbf{E} \{ \mathbf{F}\mathbf{F}' \}^{-1} \quad (3.121)$$

$$\hat{\mathbf{B}} [i_T] \equiv \left(\sum_t \mathbf{x}_t \mathbf{f}_t' \right) \left(\sum_t \mathbf{f}_t \mathbf{f}_t' \right)^{-1} \quad (4.52)$$

$$i_T \equiv \{ \mathbf{x}_1, \mathbf{f}_1, \dots, \mathbf{x}_T, \mathbf{f}_T \} \quad (4.51)$$

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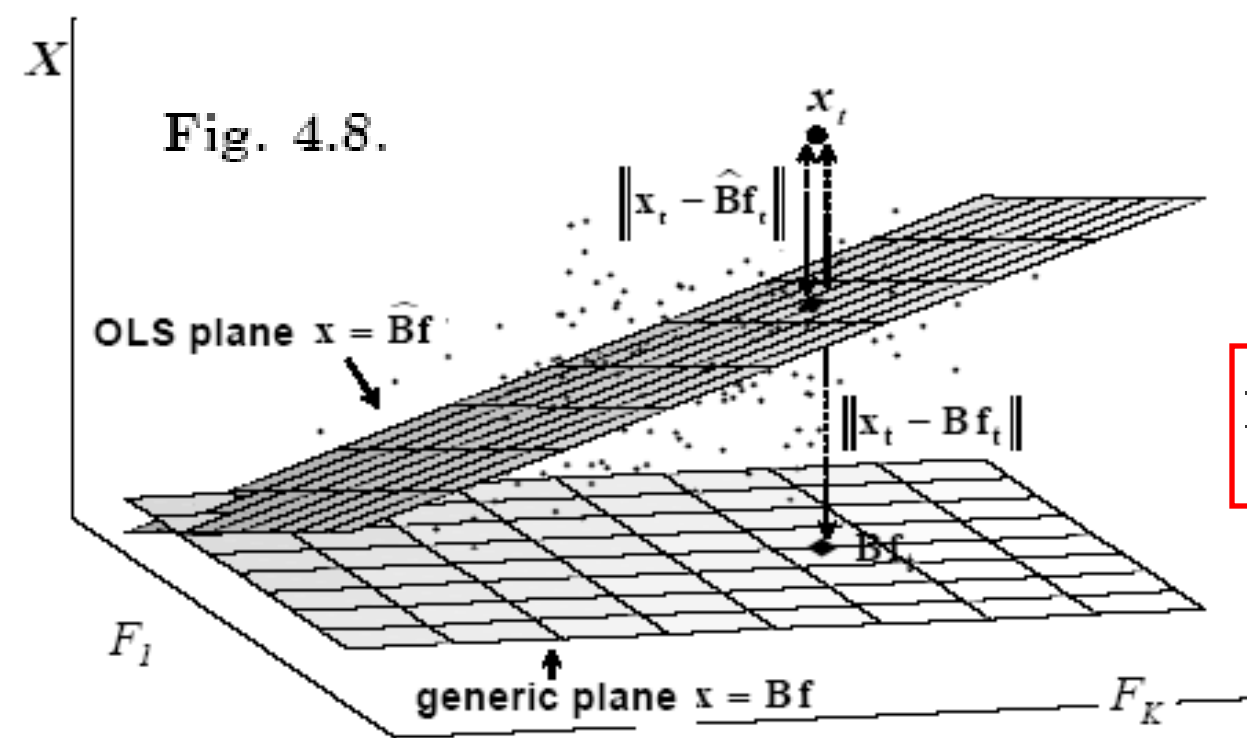
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$$\hat{\mathbf{B}} = \operatorname{argmin}_{\mathbf{B}} \sum_t \|\mathbf{x}_t - \mathbf{B}\mathbf{f}_t\|^2 \quad (4.53)$$

NON-PARAMETRIC ESTIMATORS – SAMPLE MEAN/COVARIANCE

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$$\mathbf{G}[f_{\mathbf{X}}] \equiv \text{"unknown truth"}. \quad (4.6)$$

$$\mathbf{E}\{\mathbf{X}\} \quad (2.54)$$

$$\text{Cov}\{\mathbf{X}\} \quad (2.67)$$

$$\text{information } i_T \mapsto \widehat{\mathbf{G}}[i_T] \equiv \mathbf{G}[f_{i_T}] \quad (4.36)$$

$$\widehat{\mathbf{E}}[i_T] = \frac{1}{T} \sum_{t=1}^T \mathbf{x}_t \quad (4.41)$$

$$\widehat{\text{Cov}}[i_T] = \frac{1}{T} \sum_{t=1}^T (\mathbf{x}_t - \widehat{\mathbf{E}}[i_T]) (\mathbf{x}_t - \widehat{\mathbf{E}}[i_T])' \quad (4.42)$$

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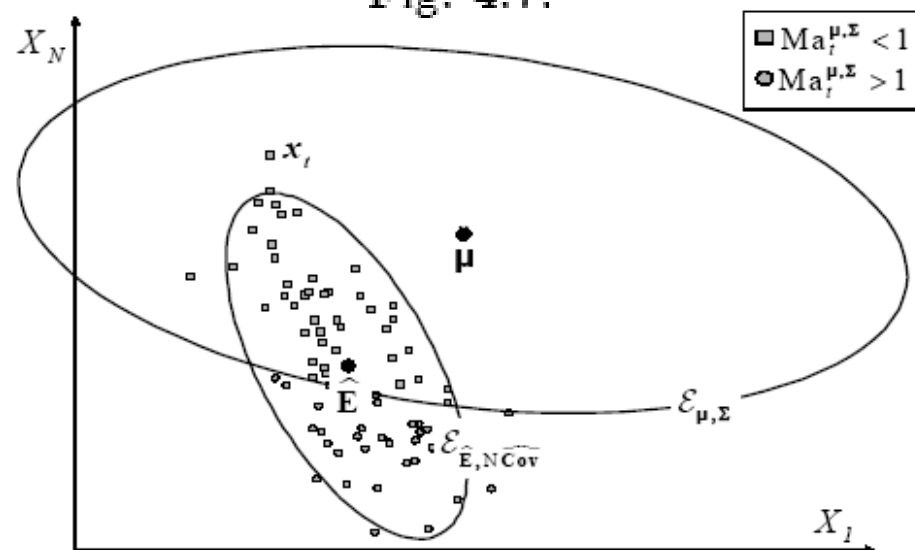
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$$\mathcal{E}_{\mu, \Sigma} \equiv \{ \mathbf{x} \in \mathbb{R}^N \text{ such that } (\mathbf{x} - \mu)' \Sigma^{-1} (\mathbf{x} - \mu) \leq 1 \} \quad (4.45)$$

$$\text{Ma}_t^{\mu, \Sigma} \equiv \text{Ma}(\mathbf{x}_t, \mu, \Sigma) \equiv \sqrt{(\mathbf{x}_t - \mu)' \Sigma^{-1} (\mathbf{x}_t - \mu)} \quad (4.46)$$

Fig. 4.7.



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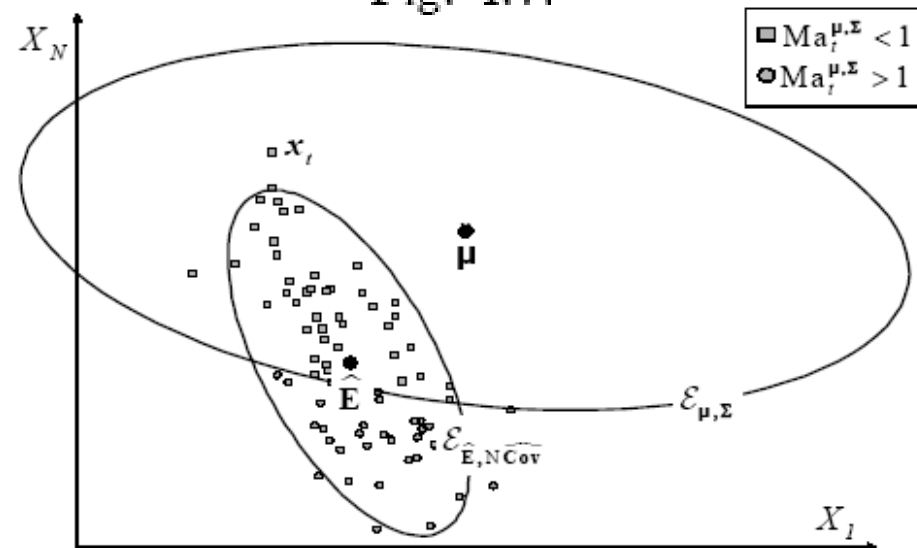
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$$\overline{r^2}(\mu, \Sigma) \equiv \frac{1}{T} \sum_{t=1}^T \left(\text{Ma}_t^{\mu, \Sigma} \right)^2 \quad (4.47)$$

$$\begin{aligned} (\widehat{\mathbf{E}}, N\widehat{\text{Cov}}) &= \underset{(\mu, \Sigma) \in \mathcal{C}}{\text{argmin}} [\text{Vol}\{\mathcal{E}_{\mu, \Sigma}\}] \\ \overline{r^2}(\mu, \Sigma) &\equiv 1 \end{aligned} \quad (4.48)$$

Fig. 4.7.



NON-PARAMETRIC ESTIMATORS – KERNELS

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$$f_{i_T}(\mathbf{x}) \equiv \frac{1}{T} \sum_{t=1}^T \delta^{(\mathbf{x}_t)}(\mathbf{x}) \quad (4.35)$$



$$\text{information } i_T \mapsto \hat{\mathbf{G}}[i_T] \equiv \mathbf{G}[f_{i_T;\epsilon}] \quad (4.56)$$

$$f_{i_T} \mapsto f_{i_T;\epsilon} \equiv \frac{1}{T} \sum_{t=1}^T \frac{1}{(2\pi)^{\frac{N}{2}} \epsilon^N} e^{-\frac{1}{2\epsilon^2} (\mathbf{x} - \mathbf{x}_t)' (\mathbf{x} - \mathbf{x}_t)}. \quad (4.55)$$