# Data Mining & Machine Learning

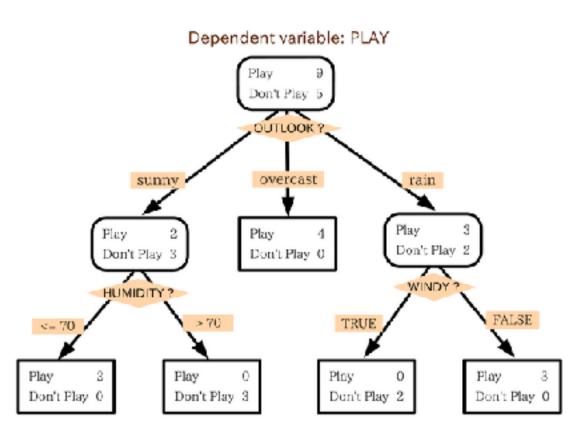
CS37300 Purdue University

Sept 18, 2017

Decision trees

### Tree models

- Easy to understand knowledge representation
- Can handle mixed variables
- Recursive, divide and conquer learning method
- Efficient inference



# Tree learning

- Top-down recursive divide and conquer algorithm
  - Start with all examples at root
  - Select best attribute/feature
  - Partition examples by selected attribute
  - Recurse and repeat
- Other issues:
  - How to construct features
  - When to stop growing
  - Pruning irrelevant parts of the tree

Fraud	Age	Degree	StartYr	Series7
+	22	Υ	2005	N
•	25	N	2003	Υ
-	31	Υ	1995	Υ
-	27	Υ	1999	Υ
+	24	<b>A</b>	2006	Ν
•	29	N	2003	N

choose split on Series7

Score each attribute split for these instances: Age, Degree, StartYr, Series7

StartYr **Degree** Series7 Υ Ν 2003 Υ 1995 Υ

Υ

1999

**Fraud** 

Age

25

31

27

Υ

Fraud	Age	Degree	StartYr	Series7
+	22	Υ	2005	N
+	24	N	2006	N
-/	29	N	2003	N

choose split on Age>28 Score each attribute split for these instances: Age Degree, StartYr

Fraud	Age	Degree	StartYr	Series7
-	29	N	2003	N

Fraud	Age	Degree	StartYr	Series7
+	22	Υ	2005	N
+	24	N	2006	N

```
DecisionTree(examples, classLabel, attributes)
    features <- {}</pre>
    for each attribute
        for each attribute value
            create feature f
            features \leq features + f
     create root node of tree
    growTree(root, examples, features)
growTree(node, examples, features)
    maxScore <- 0
    maxFeature <- null</pre>
    for each feature in features
       calculate score of feature on examples
            if score > maxScore & stopping criteria not met
            maxFeature <- feature; maxScore <- score</pre>
     if maxFeature is null
       nodeClassDist <- distribution of classLabel in examples</pre>
                                                                    //to make predictions
       return //stop growing
     else
        nodeFeature <- maxFeature
       create nodes leftChild and rightChild
       1ChildExamples <- examples that pass nodeFeatureTest</pre>
       rChildExamples <- examples that fail nodeFeatureTest
       //recurse on partitioned data
       growTree(leftChild, leftChildExamples, features)
       growTree(rightChild, rightChildExamples, features)
```

### Tree models

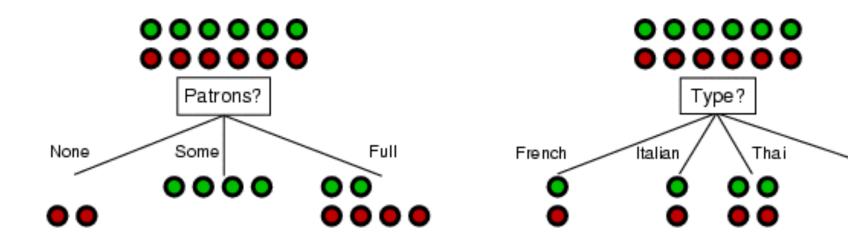
- Most well-known systems
  - CART: Breiman, Friedman, Olshen and Stone
  - ID3, C4.5: Quinlan
- How do they differ?
  - Split scoring function
  - Stopping criterion
  - Pruning mechanism
  - Predictions in leaf nodes

Scoring functions: Local split value

# Choosing an attribute/feature

 Idea: a good feature splits the examples into subsets that distinguish among the class labels as much as possible... ideally into pure sets of "all positive" or "all negative"

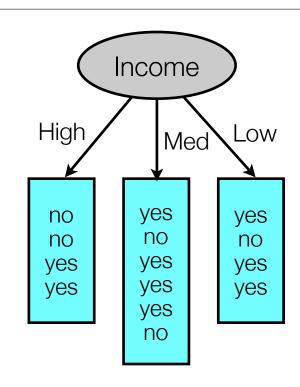
Burger



### Association between attribute and class label

#### Data

age	income	student	credit_rating	buys_computer
<=30	high	no	fair	no
<=30	high	no	excellent	no
3140	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
3140	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
3140	medium	no	excellent	yes
3140	high	yes	fair	yes
>40	medium	no	excellent	no



#### **Contingency table**

Class label value

Attribute value

_	<b>J</b> 1011010		
		Buy	No buy
	High	2	2
	Med	4	2
	Low	3	1

# Information gain

How much does a feature split decrease the entropy?

$$Gain(S, A) = \underbrace{Entropy(S)}_{v \in values(A)} - \underbrace{\sum_{v \in values(A)} \frac{|S_A|}{|S|}}_{Entropy(S_A)}$$

000	incomo	otudont	orodit roting	huve computer
age	income	student		buys_computer
<=30	high	no	fair	no
<=30	high	no	excellent	no
3140	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
3140	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
3140	medium	no	excellent	yes
3140	high	yes	fair	yes
>40	medium	no	excellent	no

# Entropy

- Used to quantify the amount of randomness of a probability distribution.
- Definition: The entropy H(X) of a discrete random variable X is defined by:

$$H(X) = -\sum_{x} p(x) \log_2 p(x)$$

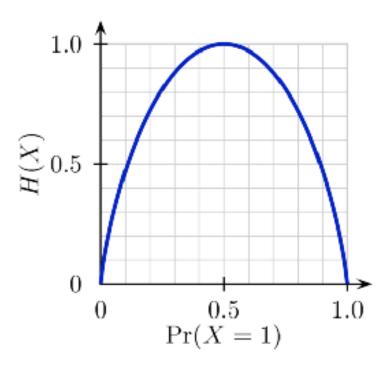
# Entropy of a random variable

A completely random binary variable with X=[0.5,0.5] has entropy:  $H(X) = -(0.5 \log 0.5 + 0.5 \log 0.5) = -(-.05 + -0.5) = 1$ 

A deterministic variable with X=[1,0] has entropy:  $H(X) = -(1 \log 1 + 0 \log 0) = -(0+0) = 0$ 

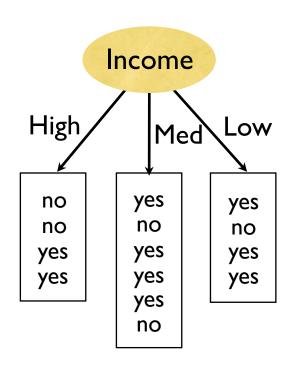
A biased variable with X=[0.75,0.25] has entropy: H(X) = 0.8113

The entropy of a probability distribution *p* expresses the *amount of uncertainty* that we have about the values of X



# Information gain

$$Gain(S, A) = Entropy(S) - \sum_{v \in values(A)} \frac{|S_A|}{|S|} Entropy(S_A)$$



Entropy(Income=high) =  $-2/4 \log 2/4 - 2/4 \log 2/4 = 1$ 

Entropy(Income=med) = -4/6 log 4/6 -2/6 log 2/6 = 0.9183

Entropy(Income=low) = -3/4 log 3/4 - 1/4 log 1/4 = 0.8113

Gain(D,Income) = 0.9400 - (4/14 [1] + 6/14 [0.9183] + 4/14 [0.8113]) = 0.029

# Gini gain

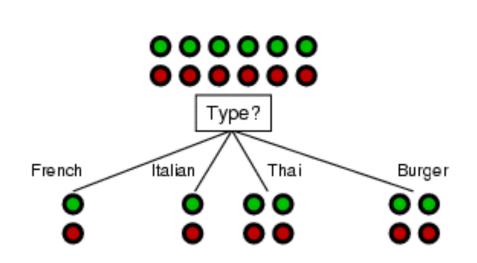
- Similar to information gain
- Uses gini index instead of entropy

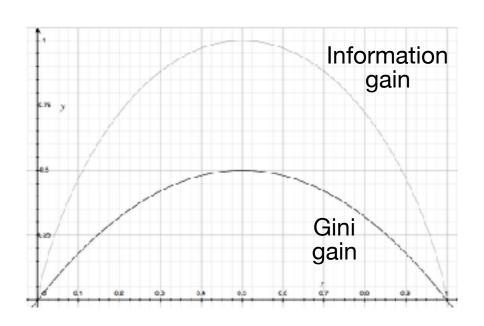
$$Gini(X) = 1 - \sum_x p(x)^2$$

Measures decrease in gini index after split:

$$Gain(S, A) = Gini(S) - \sum_{v \in values(A)} \frac{|S_A|}{|S|} Gini(S_A)$$

# Comparing information gain to gini gain

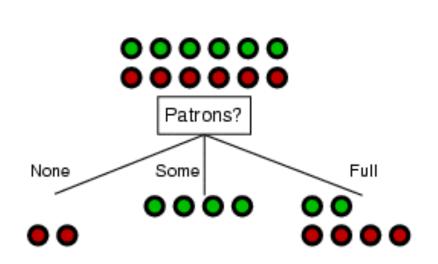


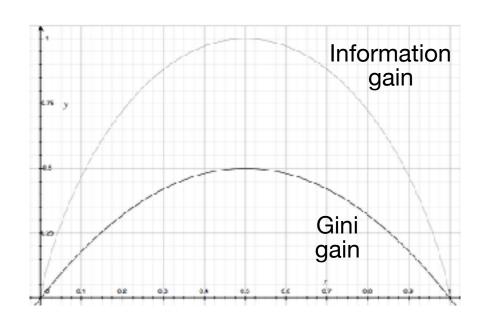


$$IG = 0$$

$$GG = 0$$

# Comparing information gain to gini gain

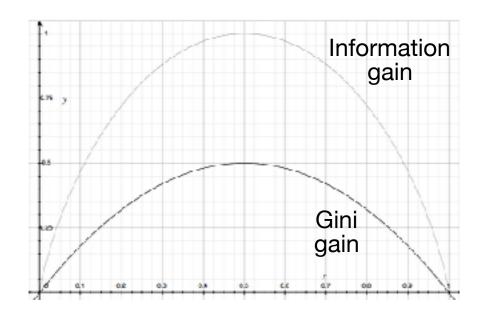


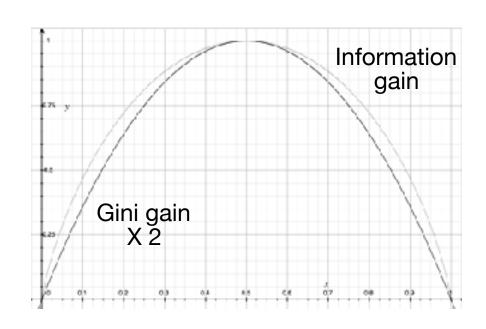


$$IG = 1.0 - \left[\frac{2}{12} \ 0\right] - \left[\frac{4}{12} \ 0\right] - \left[\frac{6}{12} \ 0.919\right] = 0.541$$

$$GG = 0.5 - \left[\frac{2}{12} \ 0\right] - \left[\frac{4}{12} \ 0\right] - \left[\frac{6}{12} \ 0.444\right] = 0.278$$

### How does score function affect feature selection?





66% split :Entropy = 0.919

 $Gini \times 2 = 0.889$ 

85% split :Entropy = 0.610

 $Gini \times 2 = 0.510$ 

Lower scores produce larger gains

# Chi-Square score

- Widely used to test independence between two categorical attributes (e.g., feature and class label)
- Considers counts in a contingency table and calculates the normalized squared deviation of observed (predicted) values from expected (actual) values

$$\chi^2 = \sum_{i=1}^k \frac{\left(o_i - e_i\right)^2}{e_i}$$

 Sampling distribution is known to be chi-square distributed, given that cell counts are above minimum thresholds

# Contingency tables

	Buy	No buy	
High	2	2	4
Med	4	2	6
Low	3	I	4
	9	5	14

# Calculating expected values for a cell

$$\chi^2 = \sum_{i=1}^k \frac{\left(o_i - e_i\right)^2}{e_i}$$

$$\frac{1}{\sqrt{2}}$$
O
a
b
c
d

$$o_{(0,+)} = a$$

$$e_{(0,+)} = p(A = 0, C = +) \cdot N$$

$$= p(A = 0)p(C = +|A = 0) \cdot N$$

$$= p(A = 0)p(C = +) \cdot N \qquad \text{(assuming independence)}$$

$$= \left\lceil \frac{a+b}{N} \right\rceil \cdot \left\lceil \frac{a+c}{N} \right\rceil \cdot N$$

# Example calculation

#### Observed

	Buy	No buy
High	2	2
Med	4	2
Low	3	I

#### **Expected**

	Buy	No buy
High	2.57	1.43
Med	3.86	2.14
Low	2.57	1.43

$$\chi^{2} = \sum_{i=1}^{k} \frac{\left(o_{i} - e_{i}\right)^{2}}{e_{i}} = \left(\frac{(2 - 2.57)^{2}}{2.57}\right) + \left(\frac{(4 - 3.86)^{2}}{3.86}\right) + \left(\frac{(3 - 2.57)^{2}}{2.57}\right) + \left(\frac{(2 - 1.43)^{2}}{1.43}\right) + \left(\frac{(2 - 2.14)^{2}}{2.14}\right) + \left(\frac{(1 - 1.43)^{2}}{1.43}\right) = 0.57$$

# Tree learning

- Top-down recursive divide and conquer algorithm
  - Start with all examples at root
  - Select best attribute/feature
  - Partition examples by selected attribute
  - Recurse and repeat
- Other issues:
  - How to construct features
  - · When to stop growing
  - Pruning irrelevant parts of the tree

# When to stop growing

- Full growth methods
  - All samples for at a node belong to the same class
  - There are no attributes left for further splits
  - There are no samples left
- What impact does this have on the quality of the learned trees?
  - Trees overfit the data and accuracy decreases
  - Pruning is used to avoid overfitting

# Pruning

- Postpruning
  - Use a separate set of examples to evaluate the utility of pruning nodes from the tree (after tree is fully grown)
- Prepruning
  - Apply a statistical test to decide whether to expand a node
  - Use an explicit measure of complexity to penalize large trees (e.g., Minimum Description Length)

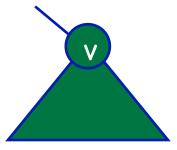
# Algorithm comparison

- CART
  - Evaluation criterion:Gini index
  - Search algorithm:
     Simple to complex,
     hill-climbing search
  - Stopping criterion:
     When leaves are pure
  - Pruning mechanism:
     Cross-validation to select gini threshold

- C4.5
  - Evaluation criterion:Information gain
  - Search algorithm:
     Simple to complex,
     hill-climbing search
  - Stopping criterion:
     When leaves are pure
  - Pruning mechanism:Reduce error pruning

# Example: reduced error pruning

- Use pruning set to estimate accuracy in sub-trees and for individual nodes
- Let T be a sub-tree rooted at node v



Define:

Gain from prunning at v = # misclassification in T - # misclassification at v

- Repeat: Prune at node with largest gain until until only negative gain nodes remain
- "Bottom-up restriction": T can only be pruned if it does not contain a sub-tree with lower error than T

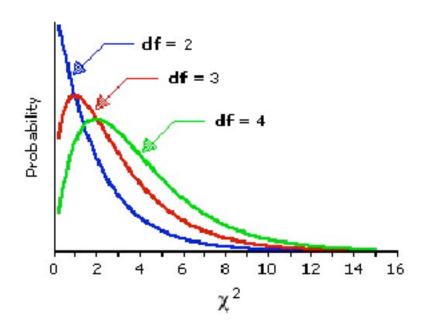
# Pre-pruning methods

- Stop growing tree at some point during top-down construction when there is no longer sufficient data to make reliable decisions
- Approach:
  - Choose threshold on feature score
  - Stop splitting if the best feature score is below threshold

# Determine chi-square threshold analytically

- Stop growing when chi-square feature score is not statistically significant
- Chi-square has known sampling distribution, can look up significance threshold
  - Degrees of freedom= (#rows-1)(#cols-1)
  - 2X2 table:3.84 is 95% critical value

$$\chi^2 = \sum_{i=1}^k \frac{\left(o_i - e_i\right)^2}{e_i}$$



How do these pruning approaches change the search procedure?